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IMPLEMENTATION OF REACTOR SAFETY ANALYSIS CODE
RELAP5/MOD3 AND ITS VECTORIZATION ON
SUPERCOMPUTER FACOM VP2600

March 1991

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Implementation of Reactor Safety Analysis Code RELAP5/MOD3
and Its Vectorization on Supercomputer FACOM VP2600

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RELAP5/MOD3 is an advanced reactor safety analysis code developed at Idaho National Engineering Laboratory (INEL) under the sponsorship of USNRC. The code simulates thermohydraulic phenomena involved in loss of coolant accidents in pressurized water reactors. The code has been introduced into JAERI as a part of the technical exchange between the JAERI and USNRC under the ROSA-IV Program.

First, the conversion to FACOM (= FUJITSU) M-780 version was carried out based on the IBM version extracted from the original INEL RELAP5/MOD3 source code. Next, the FACOM version has been vectorized for efficient use of new supercomputer FACOM VP2600 at JAERI. The computing speed of vectorized version is about three times faster than the scalar. The present vectorization ratio is 78%.

In this report, both the implementation and vectorization methods on the FACOM computers are described.

Keywords: RELAP5/MOD3, Thermohydraulics, Reactor Safety, Computer Codes, Transient Analysis, Supercomputer, Vectorization, FACOM VP2600

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軽水炉安全性解析コード RELAP5/MOD3 の変換と
FACOM VP2600 用ベクトル化

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RELAP5/MOD3 は、アイダホ国立研究所 (INEL) で開発された最新の軽水炉安全性解析コードで、加圧水型原子炉の熱流動現象をシミュレートするために使用されている。コードは、原研と米国原子力規制委員会との間の ROSA-IV 協定における技術情報交換の一環として原研に導入された。

まず、INEL から提供された元版から IBM バージョンを抽出し、それを原研の FACOM M-780 用に変換し、その後、FACOM VP2600 で効率的に処理するためにベクトル化した。ベクトル化版コードは、スカラー計算に比較して約3倍速くなっている。現在のベクトル化率は78%である。

本報告書では、FACOM 計算機への変換方法とベクトル化方法について述べる。

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1. Introduction

RELAP5/MOD3 code has been developed by Idaho National Engineering Laboratory (INEL) under the sponsorship of USNRC. The code simulates thermohydraulic phenomena involved in loss of coolant accidents in pressurized water reactors. The code has been introduced into Japan Atomic Energy Research Institute (JAERI) as a part of the technical exchange between the JAERI and USNRC under the ROSA-IV Program.

RELAP5/MOD3 code was originally developed on CRAY X-MP/24 under a UNICOS operating system. But the present INEL source code in update format covers the various computer hardware/software environments: CRAY, IBM, VAX, CDC under both UNIX or mainframe dependent operating systems. Then each code-user can chose a coding type which is suited for his own computer system. The developmental version (RELAP5/MOD2.5 *¹) was first delivered at JAERI in early Summer in 1989. After then we implemented FACOM version in order for preliminary use at the Thermohydraulic Safety Engineering Laboratory of JAERI. The developmental assessment of RELAP5/MOD3 code was reported *².

The overall goals of RELAP5/MOD3*³ code from the previous RELAP5/MOD2 *⁴ are explained as follows:

- (1) Improved physical modeling,
- (2) Faster execution speed,
- (3) Easy portability,
- (4) Improved documentation.

The FACOM version at JAERI is based on the coding extracted with IBM option from INEL source code in update format. The IBM code has been first converted into FACOM M-780 environment. The M-780 computer is compatible with IBM 370 series.

It is of great important to accelerate the computation of RELAP5 code on vector supercomputer. Therefore, the FACOM versions of RELAP5 codes implemented so far have been vectorized for efficient use of supercomputer VPs installed at JAERI. In the past, JAERI succeeded in the vectorization of RELAP5/MOD1 *⁵ and MOD2 *⁶ codes. In response to the request from USNRC, the vectorized RELAP5/MOD2 code was supplied to INEL. The computing speed for the MOD2 is four times faster than the scalar calculation on the new supercomputer FACOM VP2600 of JAERI to the sample problem TYPPWR for a small break LOCA analysis. The JAERI

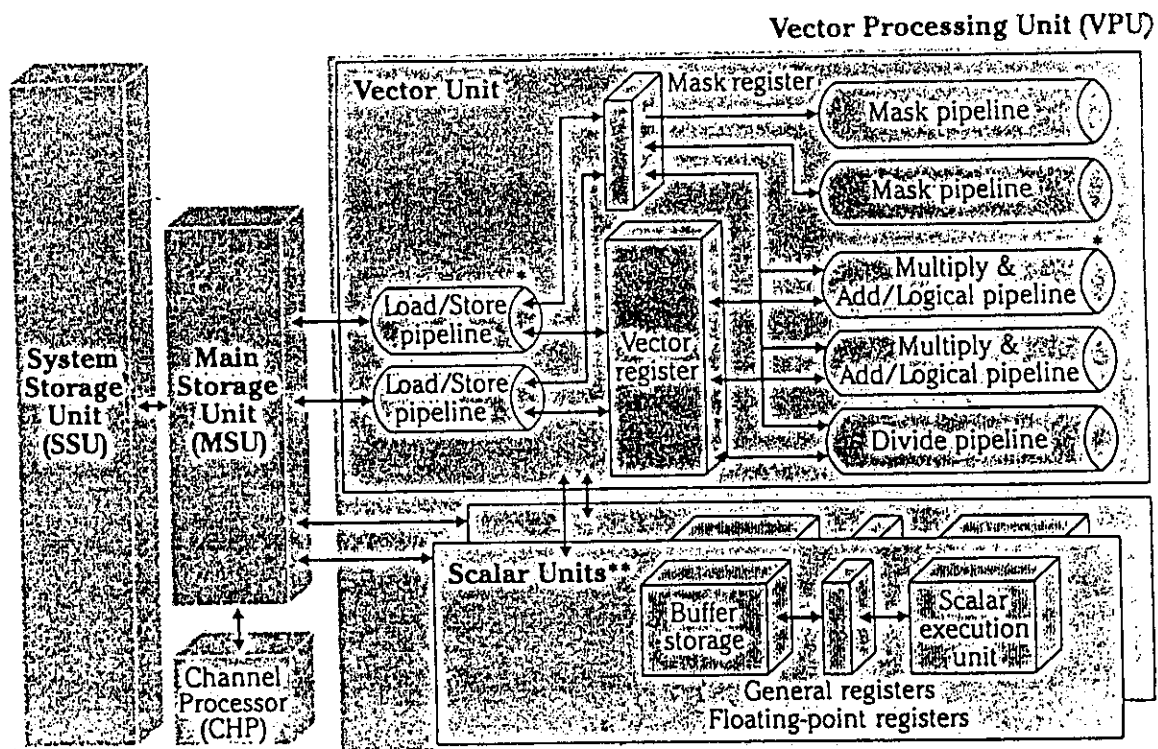
vectorized program structure is applied to most part of the present RELAP5/MOD3 code, except that the heat transfer calculations. The vectorization of RELAP5/MOD3 code has been carried out at JAERI to get complete vectorized version. The manpower required at JAERI was less than before. The table look-up of steam table is newly vectorized, but the obtained speedup is 2.8 times that is less than the MOD2 for the same sample problem. This is because lower vectorization ratio. At present, 53 subroutines are modified and the vectorization ratio 78% is achieved. Further effort is required.

The vectorized RELAP5/MOD3 of JAERI is also supplied to USNRC.

The FACOM VP2600 hardware block diagram is shown in Fig. 1.1 The clock period is about 3.2 ns. The peak speed of the VP2600 is 5 GFLOPS, but the actual computing speed of RELAP5/MOD3 is about 100 MFLOPS for practical scale applications .

In this report, both the implementation method and vectorization method are described, in Chapters 2 and 3.

FUJITSU VP2000 Series Hardware Block diagram



**One scalar unit with uni-processor models.

Fig. 1.1 FACOM (=FUJITSU) VP-2600 hardware block diagram

2. Implementation of RELAP5/MOD3 Code on FACOM M-780 Computer

2.1 Overview

The original source code transmitted from INEL involves various coding types in order to keep a portability of the code. In fact, the INEL source code was created so as to be used by various computer users such like CRAY, IBM, VAX, CDC under both UNIX or mainframe-dependent operating systems. Users can extract their own code by specifying options appropriate for their computer.

At JAERI, implementation of RELAP5 code on FACOM M-780 has been performed automatically using software tools in order to decrease troublesome tasks and avoid careless mistakes. The M-780 computer is an IBM compatible one but the software environment is somewhat different. The operating system is FACOM F4 MSP. Therefore, some modification was required to obtain FACOM version from IBM version. The implementation procedure applied at JAERI is illustrated in Fig.

2.1.1. The procedure is summarized as follows:

- (1) Extraction: IBM coding type is extracted from the original source code transmitted from INEL using a tool SELECTX
- (2) Compare: Each statement of the new IBM code is compared with that of old IBM code which was extracted from the previous INEL source code, using the tool FORTCOMP. The statements different between two codes are marked and edited based on the sequence numbers assigned to the old IBM code. After then they are reserved as update cards.
- (3) Conversion: Since the update cards are still aimed at 64-bit Fortran, they are converted into the coding for 32-bit Fortran. For this purpose the tool CONV32 which was transmitted from INEL is used.
- (4) UPDATE: The first step is to renumber the old FACOM version, where the numbers correspond to those assigned to the old IBM code. The tool used for this purpose is SEQNUM. In the second step, the converted update Fortran statements are embedded into the old FACOM version using the tool UPDATE.
- (5) Hand modification, if necessary: Finally new FACOM version is created.

Here SELECTX, FORTCOMP, SEQNUM, and UPDATE are conversion tools from Cray or CDC environment to FACOM. The tools have been developed at JAERI in cooperation with FUJITSU visited engineers.

2.2 Transmittal files

The contents of files involved in the transmittal magnetic tape sent from INEL are given by Table 2.2.1. Environmental library of the RELAP5 code was separate from RELAP5 main stream. The conversion procedure that will be described hereafter is the same between RELAP5/MOD3 main stream and environmental library.

The files used for the implementation at JAERI is shown in Table 2.2.2.

2.3 Extraction

Base version (= IBM base code) is extracted from the original INEL source code by specifying options appropriate for JAERI environment. The options specified for RELAP5/MOD3 main stream are:

IBM, IN32, MASS, COUPLD, CHNG8, CHNG9, CHNG10, BLKDTA, TIMED, PLOTS.

The options specified for environmental library are:

IBM, IN32, SCOPE1, CH8.

In the original INEL source code, a kind of directives beginning with `¥IF...` are inserted to select the Fortran statements corresponding to the specified options. The directives are illustrated in Fig. 2.3.1

At JAERI, the tool SELECTX, similar as INEL transmittal tools SELECTF and SELECTM, is used to perform the extraction according to the directives.

The input/output files for SELECTX are shown in Fig. 2.3.2 and the Job Control Languages (JCLs) on FACOM for extracting RELAP5/MOD3 and environmental library are shown in Figs. 2.3.3 and 2.3.4, respectively. Here the INEL original source file ORGNEW and the select options CONTROL are inputted. The extracted source code file IBMNEW, INCLUDE source file INC (= COMDECK file on CRAY), and check list are outputted. In the JCLs, the following file definition names are used:

INEL source file	INSOC,
Select options (CONTROL)	SYSIN,
New IBM base code (extracted)	OUTSOC, PO file,
Include file	OUTINC, PO file.

2.4 Comparison

Each Fortran statement of the extracted new IBM (base) code is compared with that of old IBM code step by step. As the result, update card set which involves modification cards to the old IBM code is generated. The update cards consist of designations of 'insert' or 'delete' of sequence numbers, as shown in Fig. 2.4.1. Note that the sequence numbers here correspond to the old IBM code.

We used a tool FORTCOMP to find the differences of Fortran statements between two source codes and edit them as the update cards. The input/output files for FORTCOMP and JCL of it are shown in Figs. 2.4.2 and 2.4.3, respectively.

File definition names are as follows:

New IBM code	NEWSOC,
Old IBM code	OLDSOC,
Update cards set	UPDATED.

2.5 Conversion

In the conversion step, update cards are converted from CRAY Fortran (64-bit) to the IBM Fortran (similar to FACOM Fortran), since the update cards extracted so far are aimed at CRAY except for bit-processing. Therefore, a conversion tool CONV32 was transmitted from INEL. We used modified CONV32 which was turned up for JAERI environment. The function of CONV32 is as follows:

- (1) Double precision real number constants: 1.0 ==> 1.0D0
- (2) Double precision REAL declarations: REAL FA(1) ==> REAL*8 FA(1)
- (3) 32-bit integer array treatment: INTEGER IA(1) ==> INTEGER IA(2,1)
(array names are specified as input data)
- (4) Treatment of 32-bit integers in EQUIVALENCE statement:
(array names are specified as input data) EQUIVALENCE (FA(1), IA(1)) ==>
EQUIVALENCE (FA(1), IA(1,1))
- (5) Use of integer arrays IA(N)=M ==> IA(2,N)=M
(array names are specified as input data) M=IA(N) ==> M=IA(2,M)
CALL ABC (IA(N),...) ==> CALL ABC (IA(1,N),...)
- (6) Packing of blank characters when a statement overs 72 columns.
- (7) Global declaration of specified array names: 'Dimension-up' such as the conversion (3), (4), and (5) is carried out for all the statements which involves the specified array names, over all subroutines.

The input/output files of CONV32 is shown in Fig. 2.5.1. Here the MLIST5M and MLISTE6 are files transmitted from INEL. The MLIST5M provides us with the array names for global declaration to RELAP5/MOD3 main stream and the file MLISTE6 provides with the array names to environmental library. After the execution of CONV32, a converted update file FCMUP is generated.

The CONV32 is used in conversational mode. The TSS command procedure for the CONV32 and example of how-to-use of commands are given by Figs. 2.5.2 and 2.5.3, respectively.

It should be noted that a kind of hand rewriting is necessary before the execution of CONV32. That is, when an argument at subroutine call is array variable which is specified for dimension-up and the corresponding virtual argument is non-array variable, the following rewriting is required, where in this example, the value IA(N) is referred and value IA(N+1) is updated in the subroutine ABC:

•	•	
•		IARG1 = IA (N)
•		IARG2 = IA (N+1)
CALL ABC (IA(N), IA(N+1))	==>	CALL ABC (IARG1, IARG2)
•		IA(N+1) = IARG2
•		•
•		•

2.6 Update

In update phase, the old FACOM version is updated using the converted update cards and new FACOM version is created. Update is carried out with two steps. In the first step, renumbering of old FACOM version is performed. For each Fortran step, a number corresponding to the old IBM code is assigned. The tool used for this purpose is SEQNUM (see Fig. 2.6.1).

In the second step, the converted update statements are embedded into the old FACOM version using the tool UPDATE (Fig. 2.6.2).

The input/output files of the tool SEQNUM and its JCL are shown in Figs. 2.6.3 and 2.6.4, respectively. The input/output files of the tool UPDATE and its JCL are shown in Figs. 2.6.5 and 2.6.6, respectively. The file definition names are as follows.

Old IBM base code	CHKSOK,
Old FACOM version	INSOC,
Old FACOM version with sequence number	OUTSOC for tool SEQNUM, OLDSOC for tool UPDATE,
Update cards set	UPDATECD,
New FACOM version	NEWSOC.

2.7 Hand modification

Special care has to be given to avoid the inconsistent coding: inconsistent use of argument type and dimension between real and virtual variables at

subroutine calls, incorrect Boolean variable definition, and incorrect memory sharing between local integer arrays and real arrays by EQUIVALENCE statements. In the third case dimension-up may be required. For these situations, hand rewrittings were carried out. The inconsistencies are usually found as conversion errors after automatic code conversion. These error corrections should be added to the update cards for the future code conversion.

Finally new FACOM version is created (see Fig. 2.6.2).

Table 2.2.1 RELAP5/MOD3 transmittal tape contents version 5M5

RELAP5/MOD3
TRANSMITTAL TAPE CONTENTS
VERSION 5M5

	<u>CDC Name</u>	<u>UNIX Name</u>	<u>Contents</u>
File 1:	CONTENT	contents	Contents of this transmittal.
File 2:	CONTALL	contentall	Master list of transmittal tape files.
File 3:	CODETAB	codetable	Code versions and corresponding auxiliary file versions.
File 4:	RTESTS	rtests	Fortran coding for dummy installation without compiling.
File 5:	RE5M5S	re5m5.s	RELAP5/MOD3 Version 5M5 source in Update source format.
File 6:	TAPCHK1	tapchk1	Dummy file to check tape position.
File 7:	REEN611	reen611.s	Environmental library version 611 source in Update source format.
File 8:	UPEML	upeml	Fortran coded version of an Update very similar to the Update Program on CDC and Cray computers.
File 9:	USPLITS	usplit.s	Source for Utility program for systems without Update.
File 10:	CNV32S	cnv32.s	Source for convert program for 32 bit machines.
File 11:	SEGDIRC	segdirc	Segloader input used by the install_scripts.
File 12:	MLISTE6	mliste	File used with application of cnv32 to environmental source on Vax computer.
File 13:	MLIST5M	mlistm	File used with application of cnv32 to material property source on Vax computer.
File 14:	EXBLANK	exendblank	Program to remove trailing blanks from scripts (must be run on the install script). Fixed format tapes have added blanks to fill out to column 80. Since UNIX continuation lines are a backslash immediately followed by a carriage return, the extra blanks would destroy all of the continuation characters at the end of the lines.
File 15:	INSTALG	instal'cray	Master Cray installation script.
File 16:	AWKSPLI	awksplitw	Program to split routines from an envi source.

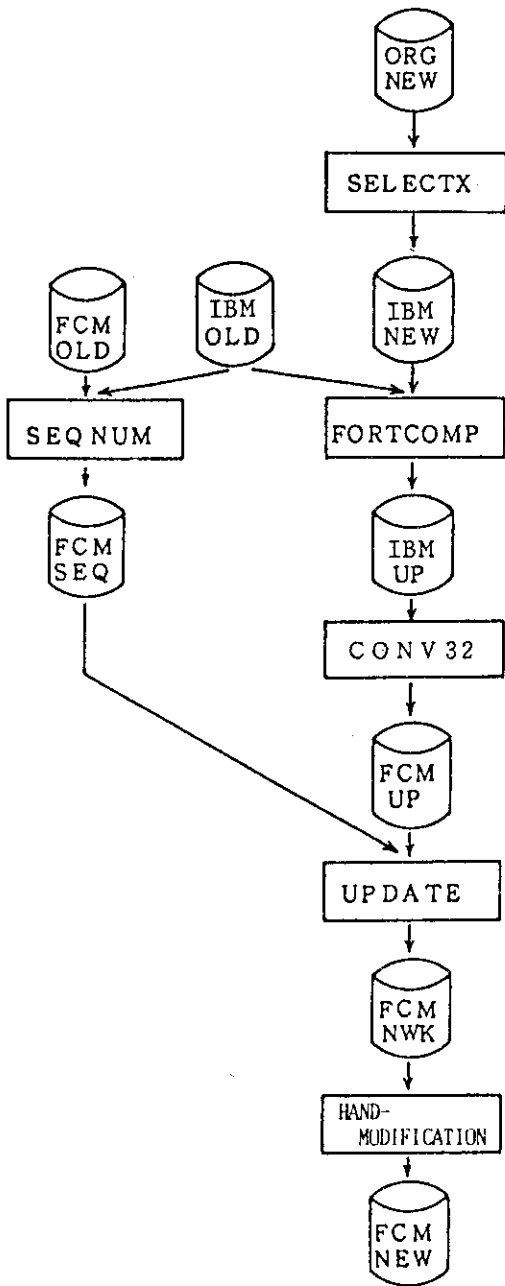
Table 2.2.1 (Continued)

RELAP5/MOD3
TRANSMITTAL TAPE CONTENTS
VERSION 5M5

	<u>CDC Name</u>	<u>UNIX Name</u>	<u>Contents</u>
File 17:	MASTERM	mastermake	Makefile for UNIX installations.
File 18:	MAKEUTI	makeutil	Create utility scripts for the master make script.
File 19:	DUK5K5	dukler5k5	Dukler problem sample input.
File 20:	EDH5M5	edhtrk5m5	Edwards pipe problem sample input.
File 21:	L315K3	l315k3	Loft L3-1 problem sample input.
File 22:	PR25K3	prob25k3	Workshop problem 2 sample input.
File 23:	TYA5K3	typpwr5k3	Typical PWR problem sample input.
File 24:	TYR5K3	typrst5k3	Typical PWR restart problem sample input.
File 25:	INSTRUC	instructions	Transmittal installation instructions.
File 26:	SELECTM	select.m	Compileable Select program for Masscomp.
File 27:	SELECTF	select.f	Compileable Select program (except for Masscomp).
File 28:	INSTALU	installunix	Master UNIX installation script.
File 29:	TITL5M5	title5m5	Short synopsis of all updates to create version 5m5.
File 30:	ODU5K3	odukler5k3	Output (version 5k3) from Dukler sample problem.
File 31:	OED5K3	oedhtrk5k3	Output (version 5k3) from Edwards pipe sample problem.
File 32:	OED5M5	oedhtrk5m5	Output (version 5m5) from Edwards pipe sample problem.
File 33:	OL35K3	ol315k3	Output (version 5k3) from Loft L3-1 sample problem.
File 34:	OP25K3	oprob25k3	Output (version 5k3) from Workshop problem 2 sample problem.
File 35:	OTA5K3	otyppwr5k3	Output (version 5k3) from Typical PWR sample problem.
File 36:	OTR5K3	otypr5k3	Output (version 5k3) from Typical PWR restart sample problem.
File 37:	TAPCHK2	tapchk2	Dummy file to check tape position.

Table 2.2.2 Files used at JAERI

File. 5	RE5M5S	RELAP5/MOD3 source
File. 7	REEN611	Environmental Library
File. 10	CNV32S	Source for convert program for 32 bit machines
File. 12	MLISTE6	Input data for CONV32 (for ENV lib)
File. 13	MLIST5M	Input data for CONV32 (for RELAP5)
File. 19	DUK5K5	DUKIER sample input data
File. 20	EDH5M5	EDHTRK sample input data
File. 21	L315K3	LOFT L3-1 sample input data
File. 22	PR25K3	PROB2 sample input data
File. 23	TYA5K3	TYPPWR sample input data
File. 24	TYR5K3	TYPPWR(Restart) sample input data
File. 30	ODU5K3	DUKIER output results
File. 31	OED5K3	EDHTRK output results
File. 32	OED5M5	EDHTRK output results
File. 33	OL35K3	LOFT L3-1 output results
File. 34	OP25K3	PROB2 output results
File. 35	OTA5K3	TYPPWR output results
File. 36	OTR5K3	TYPPWR(Restart) output results



- ORGNEW : New original program.
- IBMNEW : New source program of IBM version.
- IBMOLD : Old source program of IBM version.
- FCMOLD : Old source program of FACOM version.
- CDCUP : Update-card of IBM version.
- FCMSEQ : Old source program of FACOM version with the sequence number of Old source program of IBM version.
- FCMUP : Update-card of FACOM version.
- FCMNWK : Source program of FACOM version updated by UPDATE.
- FCMNEW : New source program of FACOM version.

Fig. 2.1.1 General flow for conversion of RELAP5 by using tools

```

C TEST FOR STEADY STATE.
C IF STEADY STATE IS ACHIEVED, DONE = -5 AND IECF = MASK(4).
  IF (IROUTE .EQ. 1) CALL SSTCHK(IECF, SSDTIM)
  IPRNT = PRINT
  39 CONTINUE
%IF DEF, TIMED, 2
  CALL TIMEL (SAFE1)
  TIMEI(1) = TIMEI(1) + SAFE1
  IF (STSCPU(FILNDX(20)) .GE. STSOLD) THEN
    STSOLD = STSCPU(FILNDX(20)) + 10.0
    WRITE (MESSG, 2099) STSCPU(FILNDX(20)), TIMEHY, DT, NCOUNT
  2099 FORMAT (' CPU=', F6.0, ' SEC, PROB TIME=', F11.4, ' SEC, DT=', F10.6,
    * ' SEC, ADV CNT=', I8)
%IF DEF, NPA, 1
  IF (IAND(PRINT, 32) .EQ. 0) THEN
%IF DEF, CTSS, 1
  CALL MSGTTY (MESSG, 132)
%IF -DEF, CTSS, 1
  WRITE (TTY, '(A)') MESSG(1:80)
%IF DEF, NPA
  ELSE
%IF -DEF, IN32, 1
  CALL FMESSG (M, 1, TIMEHY, MESSG)
%IF DEF, IN32, 2
  TIME4 = TIMEHY
  CALL FMESSG (M, 1, TIME4, MESSG)
  IF (M .NE. 0) WRITE (TTY, 2008)
  2008 FORMAT (' ERROR NUMBER', I5, ' RETURNED FROM NPA MESSAGE ROUTINE. ')
  ENDIF
%ENDIF
%IF -DEF, CTSS
%IF DEF, SELAP
  IF (IAND(PRINT, 32) .EQ. 0 .AND. NCVOL .GT. 0) THEN

```

Fig. 2.3.1 Example of directives

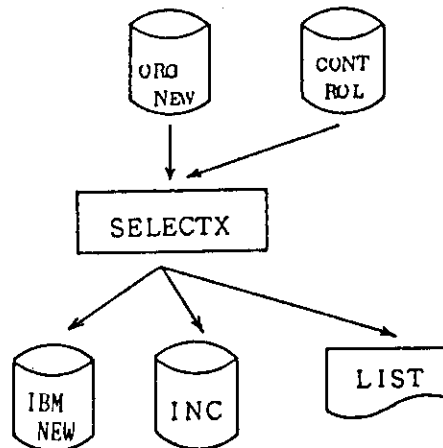


Fig. 2.3.2 Input/output files for SELECTX

```

//JCLG JOB
// EXEC JCLG
//SYSIN DD DATA,DLM='++'
// JUSER 12345678,W.ASANO,4126.99
   T.3 C.2 W.3 I.4 SRP
   OPTP PASSWORD=FUJITV
/**  T.3 W.3 I.5 C.2 SRP
/**
/** *****
/** ***** RELAPS/MOD2.5 SELECT-X FOR RELAPS *****
/** *****
/**
// EXEC PGM=SELECTX,PARM='ELM(*),MSGLEVEL(9)'
//STEPLIB DD DSN=J0001.RSTOOL.LOAD,DISP=SHR
//INSOC DD DSN=J9127.LT2.RELAPS,DISP=SHR,LABEL=(,/,IN)
//OUTSOC DD DSN=J9127.00.RELAPS.SELECT,
// DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=80,BLKSIZE=22000,RECFM=FB,DSORG=PO),
// SPACE=(TRK,(100,10,60),RLSE),UNIT=TSSWK
//OUTINC DD DSN=J9127.00.RELAPS.INCLUDE,
// DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=80,BLKSIZE=22000,RECFM=FB,DSORG=PO),
// SPACE=(TRK,(10,10,60),RLSE),UNIT=TSSWK
//SYSPRINT DD SYSOUT=*,DCB=(RECFM=FBA,LRECL=137,BLKSIZE=6850)
//SYSIN DD *
*DEFINE IBM,IN32,MASS,COUPLD,CHNG8,CHNG9,CHNG10,BLKDTA,TIMED,PLOTS
YDEFINE IBM,IN32,MASS,COUPLD,CHNG8,CHNG9,CHNG10,BLKDTA,TIMED,PLOTS
/*
++
//

```

Fig. 2.3.3 Example of JCL for SELECTX (RELAP5)

```

//JCLG JOB
// EXEC JCLG
//SYSIN DD DATA,DLM='++'
// JUSER 12345678,W.ASANO,4126.99
   T.3 C.2 W.3 I.4 SRP
   OPTP PASSWORD=FUJITV
/**  T.3 W.3 I.5 C.2 SRP
/**
/** *****
/** ***** RELAPS/MOD2.5 SELECT-X FOR ENV.LIB *****
/** *****
/**
// EXEC PGM=SELECTX,PARM='ELM(*),MSGLEVEL(9)'
//STEPLIB DD DSN=J0001.RSTOOL.LOAD,DISP=SHR
//INSOC DD DSN=J9127.LT2.ENVR,DISP=SHR,LABEL=(,/,IN)
//OUTSOC DD DSN=J9127.00.ENVR.SELECT,
// DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=80,BLKSIZE=22000,RECFM=FB,DSORG=PO),
// SPACE=(TRK,(10,10,30),RLSE),UNIT=TSSWK
//OUTINC DD DSN=J9127.00.ENVR.INCLUDE,
// DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=80,BLKSIZE=22000,RECFM=FB,DSORG=PO),
// SPACE=(TRK,(3,3,10),RLSE),UNIT=TSSWK
//SYSPRINT DD SYSOUT=*,DCB=(RECFM=FBA,LRECL=137,BLKSIZE=6850)
//SYSIN DD *
*DEFINE IBM,IN32,SCOPE1,CH8
YDEFINE IBM,IN32,SCOPE1,CH8
/*
++
//

```

Fig. 2.3.4 Example of JCL for SELECTX (Env.lib)

```

*DELETE      8 -      9
*INSERT      9
C
*INSERT      35
C
C LOCAL VARIABLES.
  INTEGER I,ICARD,ICORAN,IECF,IPLT,IPRNT,IV,IVSKP2,J,K,M,NWQA
  SAVE NWQA
  REAL DTADJ,DTREM,DTX,FACTOR,SSDTIM,STSOLD
  INTEGER IWRD8
*DELETE      38 -     38
*INSERT      38
  EXTERNAL INTERI,MAJOUT,MIREC,MOVER,PLTWRT,RSTREC,SSTCHK,TIMER
  EXTERNAL PLTREC
  EXTERNAL TIMEL
C
C DATA STATEMENTS.
*INSERT      41
  DATA IWRD8/8/
*DELETE      43 -     48
*INSERT      48
C
  ICORAN = 1
*DELETE      59 -     60
*DELETE      160 -    160
*INSERT      160
C IF ERRMAX IS SMALL, DOUBLE HALVED TIME-STEP.
*DELETE      166 -    169
*INSERT      169
  150 IF (IECF .NE. 0) GO TO 122
*DELETE      198 -    200
*INSERT      200
C GET NEW TIME-STEP AFTER SUCCESSFUL ADVANCEMENT TO ORIGINAL NEWTIME.
C DO NECESSARY EDITS AND PLOT RECORDS.
*DELETE      244 -    245
*INSERT      245
C TEST FOR STEADY STATE.
C IF STEADY STATE IS ACHIEVED, DONE = -5 AND IECF = MASK(4).
*DELETE      256 -    256
*INSERT      256
  WRITE (TTY,'(A)') MESSG(1:80)
*DELETE      265 -    277
*INSERT      277
  IF (IAND(IPLT,8) .NE. 0) THEN
    IF (IAND(IVSKP2,8) .NE. 0 .OR. IAND(IPRNT,32) .NE. 0) THEN
      CALL PLTWRT
    IF (IAND(IVSKP2,8) .NE. 0) THEN
      WRITE (RSTPLT) NWQA,IWRD8
      WRITE (RSTPLT) (FA(K),K=IXIPX,NWQ)
    ENDIF
  ENDIF

```

Fig. 2.4.1 Example of update cards

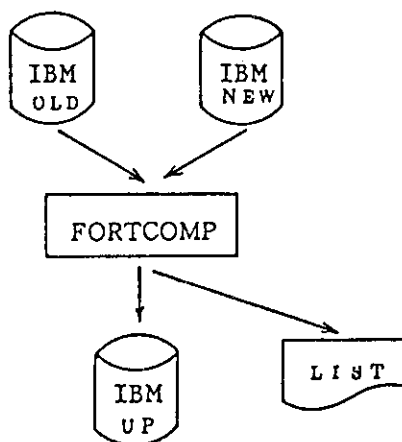


Fig. 2.4.2 Input/output files for FORTCOMP

```

//JCLG JOB
// EXEC JCLG
//SYSIN DD DATA,DLM='++'
// JUSER 12345678,W.ASANO,4126.99
   T.3 C.2 W.0 I.4 SRP
   OPTP PASSWORD=FUJITV
//*   T.2 W.4 I.5 C.2 SRP
//* *****
//* ***** RELAP5/MOD2.5 FORTRAN COMPARE PROGRAM *****
//* *****
//*
//COMPARE EXEC PGM=FORTCOMP
//STEPLIB DD DSN=J0001.R5TOOL.LOAD,DISP=SHR
//OLDSOC DD DSN=J9127.RE.RELAPS.IBMMOD2.SELECT,
// DISP=SHR,LABEL=(,/,IN)
//NEWSOC DD DSN=J9127.00.RELAPS.SELECT,DISP=SHR,LABEL=(,/,IN)
//UPDATECD DD DSN=J9127.0UPDTCD.DATA,DISP=(NEW,CATLG),
// UNIT=TSSWK,SPACE=(TRK,(100,10,50))
//SYSPRINT DD DSN=J9127.00.RELAPS.OUTLIST,DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=137,BLKSIZE=27400,RECFM=FBA,DSORG=PS),
// SPACE=(TRK,(50,20),RLSE),UNIT=TSSWK
++
//
  
```

Fig. 2.4.3 Example of JCL for FORTCOMP

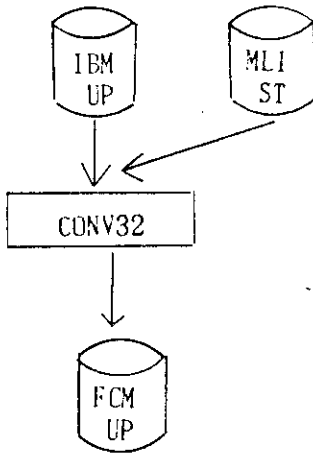


Fig. 2.5.1 Input/output files for CONV32

```
EX 'J9127.RELAP5.CLIST(CONV32)'
   'IN(@UPDTC.DATA)' 'OUT(@UPDTC.OUT.DATA)'
```

```
INPUT UPDATE-CARD : @UPDTC.DATA
OUTPUT UPDATE-CARD : @UPDTC.OUT.DATA
```

Fig. 2.5.3 Example of TSS command for CONV32

```
PROC 0 IN('J9127.@@.RELAP5.SELECT') OUT('J9127.KKK.DATA')
CONTROL LIST MSG
FREEALL
DEL (WWW W.DATA '&OUT')
ALLOC DA(WWW) NEW T CAT SP(1 1) F(W) UNIT(TSSWK) REU
OPENFILE W OUTPUT
SET W = &OUT
WRITE W
PUTFILE W
CLOSEFILE W
LIB 'J9909.SEAK.LOAD'
ALLOC DA(W.DATA) NEW T CAT SP(1 1) UNIT(TSSWK)
ALLOC DA(W.DATA) F(SYSPRINT) SHR REU
DI '&IN'
ATTR ABC LRECL(80) BLKSIZE(22000) RECFM(F B) DSORG(PO)
ALLOC DA('&OUT') NEW T CAT SP(10 10) DIR(50) RELEASE +
US(ABC) UNIT(TSSWK)
FREE F(W)
ALLOC F(FT02F001) DA(WWW) REU
ALLOC F(FT07F001) DUMMY
ALLOC F(FT08F001) DA('J9127.R5M3.MLIST5M') SHR
ALLOC F(FT66F001) DUMMY
ALLOC F(FT77F001) DUMMY
FORT77 RE.CONV32.FORT77 ELM(*) GO
EXIT
```

Fig. 2.5.2 Command procedure for CONV32

MEMBER NAME DTSTEP	
SUBROUTINE DTSTEP	00000001
*IN32 JECF	00000002
*IN32END	00000003
C	00000004
C CONTROLS TIME STEP SELECTION AND FREQUENCY OF OUTPUT AND PLOTTING	00000006
C EDITS DURING TRANSIENT ADVANCEMENT.	00000007
C	00000008
IMPLICIT REAL*8(A-H,O-Z)	00000009
*INCLUDE CMPDAT	00000010
*INCLUDE COMCTL	00000011
*INCLUDE CONTRL	00000012
*INCLUDE FAST	00000013
*INCLUDE INTRAC	00000014
*INCLUDE JUNDAT	00000015
*INCLUDE LCNTRL	00000016
*INCLUDE MACHDS	00000017
*INCLUDE NPACOM	00000018
C25CLUE SCDDAT	00000019
*INCLUDE STATC	00000020
*INCLUDE TIMEC	00000021
*INCLUDE TRNHLP	00000022
*INCLUDE TRPBLK	00000023
*INCLUDE TSCTLC	00000024
*INCLUDE TSTPCT	00000025
*INCLUDE UFILES	00000026
*INCLUDE VOLDAT	00000027
*INCLUDE STATEC	00000028
C25 INTEGER JECF(5)	00000029
INTEGER JECF(2,5)	00000029
C25 REAL DTNM(5)	00000030
REAL*8 DTNM(5)	00000030
C25 EQUIVALENCE (PROP(1),JECF(1)),(S(1),DTNM(1))	00000031
EQUIVALENCE (PROP(1),JECF(1,1)),(S(1),DTNM(1))	00000032
C25CLUE SCDOUT	00000033
C25CLUE SLUMPV	00000034
C25CLUE NDXARA	00000035
C25CLUE TBLSP	00000035
LOGICAL LAST	00000036
CHARACTER MESSG*132	00000037
C DATA STATEMENTS	00000038
C25 DATA DTREM/100.0/	00000039
DATA DTREM/100.0DO/	00000039
C25 DATA STSOLD/0.0/	00000040
DATA STSOLD/0.0DO/	00000040
C DATA ICORAN/2/	00000041
*INCLUDE MACHDF	00000042
C	00000043
IF (CHNGNO(8)) THEN	00000044
ICORAN = 1	00000045
ELSE	00000046
ICORAN = 2	00000047
ENDIF	00000048
AFLAG = .FALSE.	00000049
LAST = .FALSE.	00000050
IECF = 0	00000051
C25 ICARD = CURCTL(FILNDX(2))	00000052
ICARD = CURCTL(2,FILNDX(2))	00000052
I = FILNDX(2) + ICARD	00000053
C	00000054
IF (SKIPT) GO TO 10	00000055
NWQA = FILSIZ(17)/2	00000056
NWQ = NWQA + IXIPX	00000057
NWQA = NWQA + 1	00000058
NPANWX = FILSIZ(17) - 1	00000059
NPANW = NPANWX	00000060
C25 PRINT = IOR(IAND(PRINT,NOT(192)),IAND(ISHFT(TSPAC(1),4),192))	00000061
PRINT = IOR(IAND(PRINT,NOT(192)),IAND(ISHFT(TSPAC(2,1),4),192))	00000061
IF (NCOUNT .NE. 0) SKIPT = .TRUE.	00000062
IECF = 15	00000063
DTHY = DTMAX(1)	00000064
DTHI = DTMAX(1)	00000065
IF (NREPET .NE. 0) GO TO 4	00000066
NREPET = 1	00000067
NSTSP = NSTSP - 1	00000068
C25 CURCMI(FILNDX(2)) = CURCMI(FILNDX(2)) + 1	00000069
CURCMI(2,FILNDX(2)) = CURCMI(2,FILNDX(2)) + 1	00000069
C25 CURCMJ(FILNDX(2)) = CURCMJ(FILNDX(2)) + 1	00000070
CURCMJ(2,FILNDX(2)) = CURCMJ(2,FILNDX(2)) + 1	00000070
C25 CURCRS(FILNDX(2)) = CURCRS(FILNDX(2)) + 1	00000071
CURCRS(2,FILNDX(2)) = CURCRS(2,FILNDX(2)) + 1	00000071

Fig. 2.6.1 Example of old source code with sequence number

```

C25 FACTOR = 5.0
    FACTOR = 5.000
    IF (IRROUTE .EQ. 1) FACTOR = 10.0
C25 IF (IRROUTE .EQ. 1) FACTOR = 10.000
    IF (IAND(PRINT,128) .NE. 0) DTX = FACTOR*DTX
    IF (DT .LE. DTX) GO TO 450
C2521 DT = 0.5*DT
    21 DT = 0.500*DT
    NREPET = NREPET + NREPET
    IF (DT .GT. DTX) GO TO 21
C25 IECF=JECF(ICORAN)
C25 STRCL2(IECF) = STRCL2(IECF) + 1
    450 STRCL2(2,IECF) = STRCL2(2,IECF) + 1
    TIMEHY = NCOUNT + 1
C25 IF (IAND(TSPAC(1),2) .EQ. 0) RETURN
    IF (IAND(TSPAC(2,1),2) .EQ. 0) RETURN

```

Old FACOM version



UPDATE

(converted) UPDATE-CARD

```

00000341
00000341
00000342
00000342
00000343
00000343
00000344
00000344
00000345
00000345
00000346
00000346
00000347
00000347
00000348
00000348
00000349
00000349
00000350
00000351
00000352
00000352

```

~~*DELETE 344 - 344~~
~~*INSERT 344~~
~~CM3 IF(DT .LE. 2.0*DTX) GO TO 450~~
~~IF(DT .LE. 2.000*DTX) GO TO 450~~
~~*DELETE 347 - 347~~
~~*INSERT 347~~
~~CM3 IF(DT.GT.2.0*DTX) GO TO 21~~
~~IF(DT.GT.2.000*DTX) GO TO 21~~
~~*INSERT 351~~
~~C STORE NEW-TIME VALUES FOR DT ADVANCEMENT.~~
~~IF (SUCCE .EQ. 0) CALL MOVER~~

```

C25 FACTOR = 5.0
    FACTOR = 5.000
    IF (IRROUTE .EQ. 1) FACTOR = 10.0
C25 IF (IRROUTE .EQ. 1) FACTOR = 10.000
    IF (IAND(PRINT,128) .NE. 0) DTX = FACTOR*DTX
    IF( DT .LE. 2.0*DTX ) GO TO 450
    IF( DT .LE. 2.000*DTX ) GO TO 450
C2521 DT = 0.5*DT
    21 DT = 0.500*DT
    NREPET = NREPET + NREPET
    IF( DT.GT.2.0*DTX ) GO TO 21
    IF( DT.GT.2.000*DTX ) GO TO 21
C25 IECF=JECF(ICORAN)
C25 IECF=JECF(2,ICORAN)
    450 STRCL2(IECF) = STRCL2(IECF) + 1
    STRCL2(2,IECF) = STRCL2(2,IECF) + 1
    NCOUNT = NCOUNT + 1
    TIMEHY = TIMEHY + DT
C STORE NEW-TIME VALUES FOR DT ADVANCEMENT.
    IF (SUCCE .EQ. 0) CALL MOVER
C25 IF (IAND(TSPAC(1),2) .EQ. 0) RETURN
    IF (IAND(TSPAC(2,1),2) .EQ. 0) RETURN

```

New FACOM version

Fig. 2.6.2 Example of update processes

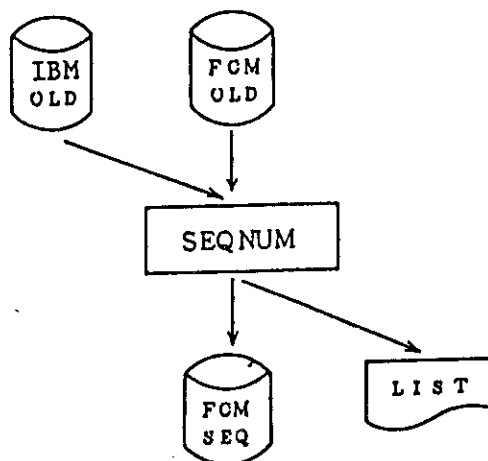


Fig. 2.6.3 Input/output files for SEQNUM

```

//JCLG JOB
// EXEC JCLG
//SYSIN DD DATA,DLM='++'
// JUSER 12345678,W.ASANO,4126.99
   T.2 C.2 W.1 I.4 SRP
   OPTP PASSWORD=FUJITV
//*   T.2 W.1 I.5 C.2 SRP
//*
//*   *****
//*   ***** RELAP5/MOD2.5 SEQNUMBER PROGRAM *****
//*   *****
//*
// EXEC PGM=SEQNUM
//STEPLIB DD DSN=J0001.R5TOOL.LOAD,DISP=SHR
//CHKSOC DD DSN=J9127.RE.RELAPS.IBMMOD2.SELECT,DISP=SHR,LABEL=(,IN)
//INSOC DD DSN=J9127.RE.RELAPS.MOD25.FORT77,DISP=SHR,LABEL=(,IN)
//OUTSOC DD DSN=J9127.DD.RELAPSW.FORT77,
// DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=80,BLKSIZE=22000,RECFM=FB,DSORG=PO),
// SPACE=(TRK,(200,50,60),RLSE),UNIT=TSSWK
//SYSPRINT DD SYSOUT=*,DCB=(RECFM=FBA,LRECL=137,BLKSIZE=6850)
++
//
  
```

Fig. 2.6.4 Example of JCL SEQNUM

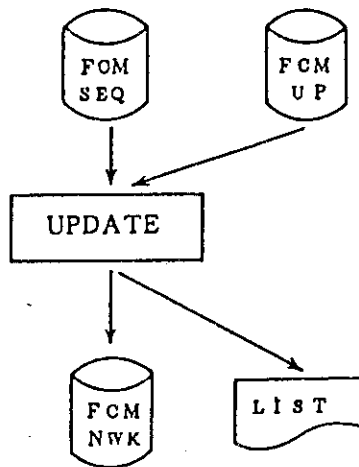


Fig. 2.6.5 Input/output files for tool UPDATE

```

//JCLG JOB
// EXEC JCLG
//SYSIN DD DATA,DLM='++'
// JUSER 12345678,W.ASANO,4126.99
// T.2 C.2 W.0 I.4 SRP
// OPTP PASSWORD=FUJITY
// * T.2 W.4 I.5 C.2 SRP
// *
// * *****
// * ***** RELAP5/MOD2.5 UPDATE PROGRAM *****
// * *****
// *
//UPDATE EXEC PGM=UPDATE
//STEPLIB DD DSN=J0001.R5TOOL.LOAD,DISP=SHR
//UPDATCD DD DSN=J9127.00UPDTCO.DATA,DISP=SHR,LABEL=(,IN)
//OLDSOC DD DSN=J9127.00.RELAPSW.FORT77,DISP=SHR,LABEL=(,IN)
//NEWSOC DD DSN=J9127.00.RELAPSN.FORT77,DISP=(NEW,CATLG,DELETE),
// DCB=(LRECL=80,BLKSIZE=22000,RECFM=FB,DSORG=PO),
// SPACE=(TRK,(200,30,60),RLSE),UNIT=TSSWK
//SYSPRINT DD DSN=J9127.00.RELAPS.UPD.OUTLIST,
// DISP=(NEW,CATLG,DELETE),
// SPACE=(TRK,(100,50),RLSE),UNIT=TSSWK,
// DCB=(LRECL=137,BLKSIZE=27400,RECFM=FBA,DSORG=PS)
++
//
  
```

Fig. 2.6.6 Example of JCL for tool UPDATE

3. Vectorization Method for RELAP5/MOD3 Code

3.1 Overview

The high speed simulation of nuclear reactor plant transient is very important in quickly predicting the anticipated danger at the nuclear accidents. A few of the present advanced thermohydraulic nuclear reactor codes for the transient analysis, however, have a computing speed necessary for real time simulation, even on the world highest speed computer. A lot of efforts have been made for reducing the computing time of RELAP5 *³.

The FACOM version, converted from the IBM-coding type extracted from INEL transmittal source, has been vectorized. In the code, since a staggered mesh method is applied for discretization, then the code can be potentially vectorizable on volumes and/or junctions for hydrodynamic calculations. And the heat transfer calculations can be vectorized on the heat mesh points or intervals, and/or heat structures.

Although very much effort has been given by INEL group to improve the code for faster calculation, but the present RELAP5/MOD3 code still has the following vectorization difficulties:

- (1) Program structure unsuitable for vectorization,
- (2) Data structure unsuitable for vectorization,
- (3) Many IF tests depending on the state of fluid (=> short vector),
- (4) Huge program size (=> a lot of manpower for vectorization).

The problems (1)~(3) are affected by the memory size of the past computer on which the early RELAP5 series codes were designed. Development of the first RELAP5 series code, RELAP5/MOD1, began about fifteen years ago. The RELAP5/MOD1 was designed to reduce memory requirements because the code was aimed at CDC computers with small memory. In the present code, the program structure, except for the heat transfer calculation, has been considerably improved. CDC or CRAY dependent bit-processings are removed. But the data structure has not been changed.

From above reasons, very much effort has been still necessary for the vectorization of MOD3 code: the manpower required was 3 months by two persons at JAERI, even started from the recent vectorized version of RELAP5/MOD2.

3.2 Vectorization difficulties and solution to them

Program structure unsuitable for vectorization

The subroutines at the top level had DO-loop and many subroutines were called within the DO-loop in order to keep the data on the small memory. An example of a typical program structure of RELAP5 is shown in Fig. 3.2.1. Fig. 3.2.1(a) illustrates the program structure of subroutine HTADV and its called subroutines in the original code.

The HTADV is the top-level subroutine which controls the heat advancements of heat structures and computes the heat added to hydrodynamic volumes. The DO-loop for heat structures, which can model fuel pins or plates with nuclear or electrical heating, etc., exists in the HTADV subroutine. However, this loop can not be vectorized because a subroutine HT1TDP is called in the DO-loop. The subroutine HT1TDP, in turn, calls the subroutines MADAT, HTPCOND, These bottom-level subroutines calculate the thermal conductivities and boundary conditions, and so on. The HT1TDP subroutine, called from HTADV, can not be vectorized too, since this subroutine do not have DO-loops.

This type of program structure appears in RELAP5 frequently. The vectorization of these subroutines can be achieved by the transfer of DO-loop from HTADV to HT1TDP and to its slave subroutines as shown in Fig. 3.2.1(b).

The original and vectorized codings are presented in Figs. 3.2.2(a) and 3.2.2(b), respectively.

Data structure unsuitable for vectorization

An example of data structure in RELAP5/MOD3 is shown in Fig. 3.2.3. The data, which belong to the same volume or junction, are grouped by using EQUIVALENCE statements. In each group of volumes or junctions, physical quantities are ordered as indicated in EQUIVALENT statements. As shown in DO-loops of Fig. 3.2.3, when the physical quantities such as HV are referred over the total volumes, the memory is accessed by every IVSKP*8 byte.

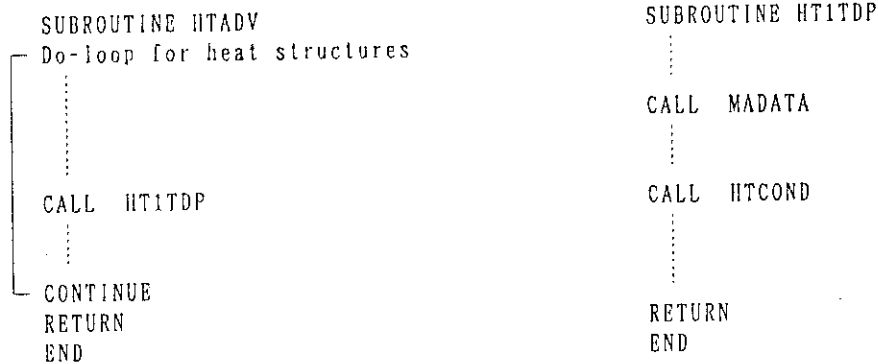
This memory structure is suited for small memory computer, because the data belonging to one volume or junction would be stored on the memory. For the vector processor, however, the distanced memory access causes a memory conflict. However, we could not change this data structure for vectorization, since the whole program would be rewritten.

Many IF tests depending on the state of fluid

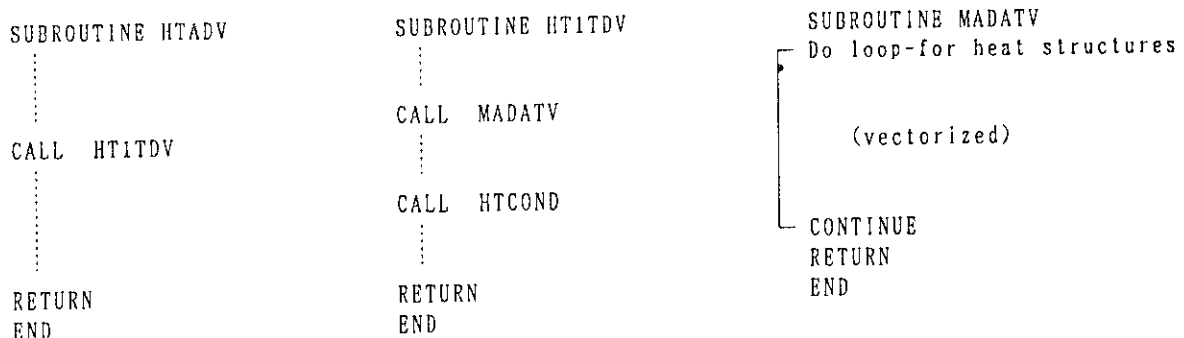
The code contained many IF statements depending on the fluid state. The IF tests are replaced into a list vector in order to process efficiently in vector

processing. Fig. 3.2.4(a) shows the program of DO-loop transferred from the top-level subroutine. The same IF statements on the fluid state appeared several times in different positions of different subroutines. These IF statements are modified in vector version as shown in Fig. 3.2.4(b). At the top-level subroutine, the list vectors LIST1 and LIST2 are generated once. The list vector keeps the volume or junction numbers which should be calculated for a certain condition. At the bottom-level subroutines, the list vectors are used instead of IF statements. By using the list vectors, the redundant IF statements in the program are removed.

Another problem of IF statements is short vector length. Typical volume or junction number is 150~300 and the number of volumes or junctions in the vectorized DO-loop is decreased by the IF branches.



(a) Original program structure



(b) Vectorized program structure

Fig. 3.2.1 Example of typical program structure

```

SUBROUTINE HTADV
  ...
  IH = FILNDX(8)
  DO M = 1, NHTSTR(IH)
    ...
    Lower level subroutines
    ...
  IH = IH + 1
  CONTINUE
  RETURN
  END
  
```

Lower level subroutine

```

  ...
  HINDEX = IHTPTR(2, IH) + FILNDX(8)
  K       = HTBVO(2, HINDEX) + FILNDX(11)
  I       = GTBPTR(2, K) + FILNDX(11)
  ...
  RETURN
  END
  
```

(a) Original program coding

```

SUBROUTINE HTADV
  ...
  IH = FILNDX(8)
  NH# = NHTSTR(IH)
  DO M = 1, NH#
    HINX#(M) = IHTPTR(2, IH) + FILNDX(8)
    K = HTBVO(2, HINX#(M)) + FILNDX(11)
    GINX#(M) = GTBPTR(2, K) + FILNDX(11)
    ...
  IH = IH + 1
  CONTINUE
  ...
  Lower level subroutines
  ...
  RETURN
  END
  
```

Lower level subroutine

```

  DO M = 1, NH#
    HINDEX = HINX#(M)
    I       = GINX#(M)
    ...
  CONTINUE
  RETURN
  END
  
```

(b) Vectorized program coding

Fig. 3.2.2 DO-loop transfer in HTADV subroutine

```

INTEGER LFSIZ
PARAMETER (LFSIZ=270000)
PARAMETER (NCOMS=80, NFILES=40)
COMMON /FAST/ FA(LFSIZ)
COMMON /COMCTL/ COMDAT(NCOMS) , COMDLN(NCOMS) , FILID(NFILES) ,
*     FILSIZ(NFILES) , FILNDX(0:NFILES) , FILFLG(NCOMS+1) , SAFE1
REAL*8 FA
INTEGER IA(2,LFSIZ)
EQUIVALENCE (FA(1),IA(1,1))
INTEGER NVOLS(2,1) , VCTRL(2,1) , VOLNO(2,1) , IMAP(2,1),
*     VOLMAT(2,1)
REAL*8 V(1) , RHOGO(1) , RHOG(1)
EQUIVALENCE (NVOLS(1,1) , IA(1,1)) , (VCTRL(1,1) , IA(1,2)) ,
*     (VOLMAT(1,1) , IA(1,3)) , (VOLNO(1,1) , IA(1,4)) ,
*     (IMAP(1,1) , IA(1,5)) , (V(1) , FA(6) ) ,
*     (RHOG(1) , FA(33) ) , (RHOGO(1) , FA(101)) ,
INTEGER NJUNS(2,1) , IJ1(2,1) , IJ2(2,1) , JC(2,1),
*     IJ1VN(2,1) , IJ2VN(2,1),
REAL*8 ARAT(1)
EQUIVALENCE (NJUNS(1,1) , IA(1,1)) , (IJ1(1,1) , IA(1,2)) ,
*     (IJ2(1,1) , IA(1,3)) , (JC(1,1) , IA(1,4)) ,
*     (IJ1VN(1,1) , IA(1,5)) , (IJ2VN(1,1) , IA(1,6)) ,
*     (ARAT(1) , FA(11) )
INTEGER IJSK1
PARAMETER (IJSK1=80)
INTEGER IJSK2
PARAMETER (IJSK2=0)
INTEGER IJSKP
PARAMETER (IJSKP=IJSK1+IJSK2)
INTEGER IVSK1
PARAMETER (IVSK1=128)
INTEGER IVSK2
PARAMETER (IVSK2=0)
INTEGER IVSK3
PARAMETER (IVSK3=IVSK1+IVSK2)
INTEGER IVSK4
PARAMETER (IVSK4=0)
INTEGER IVSKP
PARAMETER (IVSKP=IVSK3+IVSK4)
C
IV   = FILNDX(4)
IVE  = IV + IVSKP * (NVOLS(2,IV) - 1)
IJ   = FILNDX(5)
IJE  = IJ + IJSKP * (NJUNS(2,IJ) - 1)
C
DO 2 I = IJ, IJE, IJSKP
  ARAT(I+1) = 1.0D0
2 CONTINUE
C
DO 3 I = IV, IVE, IVSKP
  RHOGO(I) = RHOG(I)
3 CONTINUE

```

Fig. 3.2.3 Data structure of RELAP5/MOD3 code

<p>(a) ORIGINAL CODING</p> <pre> DO ** I=IB,IE,ISKP IF(.....) THEN Process A ELSE Process B ENDIF CONTINUE </pre>	<p>(b) VECTORIZED CODING TOP-LEVEL SUBROUTINE</p> <pre> L1=0 L2=0 DO ** I=IB,IE,ISKP IF(.....) THEN L1=L1+1 LIST1(L1)=I ELSE L2=L2+1 LIST2(L2)=I ENDIF CONTINUE </pre>		
<p>(c) BOTTOM LEVEL SUBROUTINE</p> <table border="0" style="margin-left: auto; margin-right: auto;"> <tr> <td style="vertical-align: top; padding-right: 20px;"> <pre> DO ** II=1,L1 I=LIST1(II) Process A : </pre> </td> <td style="vertical-align: top;"> <pre> DO ** II=1,L2 I=LIST2(II) Process B : </pre> </td> </tr> </table>		<pre> DO ** II=1,L1 I=LIST1(II) Process A : </pre>	<pre> DO ** II=1,L2 I=LIST2(II) Process B : </pre>
<pre> DO ** II=1,L1 I=LIST1(II) Process A : </pre>	<pre> DO ** II=1,L2 I=LIST2(II) Process B : </pre>		

LIST VECTOR METHOD

Fig. 3.2.4 List vector method

3.3 Static and dynamic profiles of RELAP5/MOD3 code

Huge program size

Finally, the thermohydraulic reactor transient analysis code such as RELAP5 is very large, since the real large scale complicated physical models are tested. For example, the number of subroutines is 355 including environmental library routines, and the number of Fortran statements is 110,000. This program size is the problem on vectorization.

The static profile of RELAP5/MOD2 code is presented by Fig. 3.3.1. Program tree of subroutines for the time consuming route is given by Fig. 3.3.2. In order to know the computing time distribution among subroutines, a dynamic profile of RELAP5/MOD3 code has been investigated for a typical PWR sample problem TYPPWR. The results are shown in Fig. 3.3.3. Here the subroutine name, number of Fortran statements, number of subroutine calls, relative computing time estimate in scalar calculation, time percent, and bar graph are listed for the time-consuming 100 subroutines. From this figure we can see, no matter how we would make effort, we could not achieve the vectorization ratio 90%. At present, we have vectorized 53 subroutines and the vectorization ratio 78% is resulted.

THE CLASSIFICATION OF FORTRAN STATEMENTS (WITHOUT INCLUDED)		REAL*16	ASSIGNED GO TO
COMMENT	27708	0	2
GLOBAL CONTROL DIRECTIVE	0	0	343
LOCAL CONTROL DIRECTIVE	0	0	0
CRAY COMPILER DIRECTIVE	174	0	0
OPTIMIZATION CONTROL LINE	0	0	6884
PROCESS	0	0	0
INCLUDE	1966	0	169
EJECT	0	0	0
LIST ON/OFF	0	0	0
OVERLAY	0	0	0
OVCAP	0	0	0
PROGRAM	2	0	0
SUBROUTINE	308	0	0
FUNCTION	43	0	0
NO TYPE SPECIFICATION	43	167	0
INTEGER	0	0	0
INTEGER*2	0	0	0
INTEGER*4	0	74	0
INTEGER*8	0	242	0
LOGICAL	0	100	0
LOGICAL*1	0	18	0
LOGICAL*4	0	1103	0
REAL	0	0	239
REAL*4	0	0	67
REAL*8	0	0	2
REAL*16	0	28	0
DOUBLE	0	0	0
DOUBLE PRECISION	0	0	1142
COMPLEX	0	1976	0
COMPLEX*8	0	141	0
COMPLEX*16	0	2322	5265
COMPLEX*32	0	9	0
CHARACTER	0	0	0
CHARACTER	0	0	0
BOOLEAN	0	0	0
BLOCK DATA	2	0	0
ENTRY	12	0	1047
IMPLICIT	352	1	66
PARAMETER	51	0	273
INTEGER	364	1	1047
NO LENGTH SPECIFICATION	364	14	1763
PREFIX TYPE	0	0	0
INTEGER*2	0	0	0
INTEGER*4	0	0	355
INTEGER*8	0	0	0
LOGICAL	197	0	0
NO LENGTH SPECIFICATION	197	0	0
PREFIX TYPE	0	0	0
LOGICAL*1	0	1838	0
LOGICAL*2	0	480	0
LOGICAL*4	0	11	0
LOGICAL*8	0	0	0
REAL	481	1816	0
NO LENGTH SPECIFICATION	481	29873	56580
PREFIX TYPE	0	4	29848
REAL*4	2	2624	0
REAL*8	479	70	0
			NO OF FORTRAN STATEMENTS == 56580
			NO OF COMMENTS & DIRECTIVES == 29848

Fig. 3.3.1 Static Profil of RELAP5/MOD3 code

THE CLASSIFICATION OF FORTRAN STATEMENTS (WITH INCLUDED)			
COMMENT.....	41948	REAL*16	0
GLOBAL CONTROL DIRECTIVE.....	0	DOUBLE.....	0
LOCAL CONTROL DIRECTIVE.....	0	NO PREFIX	0
CRAY COMPILER DIRECTIVE.....	174	PREFIX TYPE	0
OPTIMIZATION CONTROL LINE.....	0	DOUBLE PRECISION.....	0
PROCESS.....	0	NO PREFIX	0
INCLUDE.....	1966	PREFIX TYPE	0
EJECT.....	0	COMPLEX.....	0
LIST ON/OFF.....	0	NO LENGTH SPECIFICATION.....	0
OVERLAY.....	0	PREFIX TYPE	0
OVCAP.....	0	COMPLEX*8	0
PROGRAM.....	2	COMPLEX*16	0
SUBROUTINE.....	308	COMPLEX*32	0
FUNCTION.....	43	CHARACTER.....	215
NO TYPE SPECIFICATION		BOOLEAN.....	0
INTEGER	43	MCHARACTER.....	0
INTEGER*2	0	DIMENSION.....	70
INTEGER*4	0	COMMON.....	993
INTEGER*8	0	EQUIVALENCE.....	3432
LOGICAL	0	EXTERNAL.....	100
LOGICAL*1	0	INTRINSIC.....	0
LOGICAL*4	0	SAVE.....	781
REAL	0	DATA.....	1159
REAL*4	0	POINTER.....	0
REAL*8	0	LEVEL.....	0
REAL*16	0	STATEMENT FUNCTION.....	31
DOUBLE	0	NAMELIST.....	0
DOUBLE PRECISION	0	DEFINEFILE.....	0
COMPLEX	0	FORMAT.....	1976
COMPLEX*8	0	READ.....	141
COMPLEX*16	0	WRITE.....	2322
COMPLEX*32	0	PRINT.....	9
CHARACTER	0	PUNCH.....	0
BOOLEAN	0	FIND.....	0
BLOCK DATA.....	2	OPEN.....	3
ENTRY.....	12	CLOSE.....	0
IMPLICIT.....	352	INQUIRE.....	1
PARAMETER.....	1377	BACK SPACE.....	0
INTEGER.....	3426	ENDFILE.....	1
NO LENGTH SPECIFICATION	3426	REWIND.....	14
PREFIX TYPE	0	WAIT.....	0
INTEGER*2	0	BUFFER IN.....	0
INTEGER*4	0	BUFFER OUT.....	0
INTEGER*8	0	DECODE.....	0
LOGICAL	599	ENCODE.....	0
NO LENGTH SPECIFICATION	599	DELETE.....	0
PREFIX TYPE	0	REWRITE.....	0
LOGICAL*1	0	CALL.....	1838
LOGICAL*2	0	RETURN.....	480
LOGICAL*4	0	STOP.....	11
LOGICAL*8	0	PAUSE.....	0
REAL.....	2982	CONTINUE.....	1816
NO LENGTH SPECIFICATION	0	ASSIGNMENT.....	29873
PREFIX TYPE	0	GO TO.....	4
REAL*4	2	COMPUTED GO TO.....	2624
REAL*8	2980		70
		ASSIGNED GO TO.....	2
		ARITHMETIC IF.....	343
		2-BRANCH ARITHMETIC IF.....	0
		INDIRECT LOGICAL IF.....	6884
		LOGICAL IF.....	0
		READ	169
		WRITE	0
		PRINT	0
		PUNCH	0
		FIND	0
		OPEN	0
		CLOSE	0
		INQUIRE	0
		BACK SPACE	0
		ENDFILE	0
		REWIND	0
		WAIT	0
		BUFFER IN	0
		BUFFER OUT	0
		DECODE	0
		ENCODE	0
		DELETE	0
		REWRITE	239
		CALL	67
		RETURN	2
		STOP	0
		PAUSE	0
		CONTINUE	0
		ASSIGNMENT	1142
		ASSIGN	0
		GO TO	5265
		COMPUTED GO TO	0
		ASSIGNED GO TO	0
		ARITHMETIC IF	0
		2-BRANCH ARITHMETIC IF	0
		INDIRECT LOGICAL IF	1047
		BLOCK IF.....	0
		ELSE IF.....	66
		ELSE.....	273
		END IF.....	1047
		DO.....	1763
		DO WHILE.....	0
		DO UNTIL.....	0
		END.....	355
		DEBUG.....	0
		AT.....	0
		TRACE.....	0
		INIT.....	0
		DISPLAY.....	0
		END DEBUG.....	0
		-- SYNTAX ERROR --	3
		NO OF FORTRAN STATEMENTS ==	68850
		NO OF COMMENTS & DIRECTIVES ==	44088

Fig. 3.3.1 (Continued)

S T R E A M 7 7 (C) V01/L04 (19860901) DATE (90.12.25) TIME (20:06:11)

SUMMARY OF MESSAGES

(1) MESSAGE CODES AND NUMBER OF PRINTOUTS

CODE	PRINT
600.....	3
.....TOTAL NUMBER OF MESSAGE PRINTOUTS.....	3.....

Fig. 3.3.1 (Continued)

ANALYSIS INFORMATION OUTPUT INDEX

NO.	NAME	LINES	PAGE	NO.	NAME	LINES	PAGE	NO.	NAME	LINES	PAGE	NO.	NAME	LINES	PAGE
1	AAETIT	36		91	HTADV	119		181	PHANTJ	1436		271	SCREQ	981	
2	AATL	120		92	HICOND	159		182	PHANTV	1368		272	SEARCH	37	
3	ACGUM	428		93	HTCSOL	44		183	PIMPLT	509		273	SETNDF	15	
4	BINDMX	143		94	HIMETA	56		184	PLOTMD	28		274	SIGMA	22	
5	CORA	36		95	HIRCI	199		185	PLOTRS	464		275	SIMPLT	606	
6	CONU	79		96	HIRC2	163		186	PL0T2D	431		276	SIMUL	151	
7	EDER	30		97	HTINP	885		187	PLSTRN	184		277	SMOOTH	393	
8	FUNK	103		98	HT1SST	287		188	PLTREC	47		278	SORPTR	98	
9	GIBBAB	242		99	HT1TOP	423		189	PLTWT	181		279	SPLINT	101	
10	HELMCD	119		100	HTZDOP	603		190	PMINVD	498		280	SPLIN2	46	
11	INDEXX	17		101	HVDRO	111		191	ENBLK	8		281	SPLD1	216	
12	POLATT	47		102	HYSAT	39		192	PMINVF	155		282	SPLD2	51	
13	POLYN	70		103	HYSATT	93		193	PMINVM	77		283	SPL2D1	39	
14	PSATK	42		104	HVTHC	36		194	PMINVR	58		284	SPL2D2	82	
15	PSATL	17		105	HVISC	27		195	PMINV1	179		285	SPL2D3	18	
16	ROOT	232		106	HZFLOW	1353		196	PMINV4	29		286	SQ0Z	23	
17	UNITS	47		107	ICMPF	26		197	POLAT	65		287	SRESTF	155	
18	WRITEA	68		108	ICMPN1	438		198	POLATR	82		288	SSYCHK	841	
19	IASME	162		109	ICMPN	735		199	PREDNB	241		289	STACC	496	
20	ASMEB0	295		110	ICMPT	282		200	PRESEQ	779		290	STATE	289	
21	AXISDV	37		111	ICONVR	749		201	PSATPD	95		291	STATEP	1625	
22	BLKDTA	143		112	IDFIND	31		202	PSET	26		292	STD2X3	430	
23	BRYCEJ	71		113	IEDIT	392		203	PSTDNB	309		293	STD2X4	546	
24	CCFL	157		114	IELVTM	356		204	PSTD25	95		294	STD2X5	642	
25	CDENTH	74		115	IGNTBL	77		205	PSTPHY	58		295	STHYX1	32	
26	CELMOR	32		116	HTCMP	938		206	PUMP	179		296	STHYXJ	32	
27	CHFCAL	2457		117	IJPROP	220		207	PUMP2	134		297	STHYX0	28	
28	CHRINT	146		118	IMIEDT	127		208	GFTRC	125		298	STHYX1	137	
29	CKPCRD	210		119	IMLP	809		209	GFMOVE	571		299	STHYX3	357	
30	CKTCD5	184		120	INP	289		210	GFSRCH	420		300	STHYX6	540	
31	CONDEN	235		121	INPLNK	74		211	GMWR	137		301	STHZXG	153	
32	CONVAR	394		122	INPMOD	86		212	RACCUH	1117		302	SAT1	94	
33	CPLXP	37		123	INPPCK	25		213	RADHT	132		303	SAT2	98	
34	CRAMER	70		124	INPUK	26		214	RBRNCH	1387		304	SNPH	142	
35	CTHPR	64		125	INPUTD	127		215	RCARDS	97		305	INTGRC	123	
36	CVIC	394		126	INP10	106		216	RCOELT	104		306	DELS	108	
37	CVIRC	15		127	INP2	146		217	RCHNG	35		307	STHZXI	35	
38	DETMNT	133		128	INP4	43		218	RGKPLT	469		308	STHZXJ	35	
39	DITUS	81		129	INP5	162		219	RCOMPN	260		309	STHZXU	202	
40	DMPFIL	92		130	INP6	19		220	RCOMPT	417		310	STHZX0	30	
41	DMPST	50		131	INP7	10		221	RCORVR	1610		311	STHZX1	205	
42	DOLEND	120		132	INP8	38		222	RCRVSP	159		312	STHZX3	375	
43	OPSAT	33		133	INP9	99		223	RREDIT	16		313	STHZX4	484	
44	DTSTEP	439		134	INTER1	103		224	REEDIT	16		314	STHZX5	599	
45	ECCMXJ	525		135	INVJT	134		225	RELAP5	201		315	STHZX6	594	
46	ECCMXV	696		136	INXGET	15		226	RENTIM	8		316	STOLST	37	
47	EPR1J	236		137	IPIPE	42		227	RNTBL	480		317	STRIP	200	
48	EQFINL	881		138	IPILOT	270		228	RHTCMP	1082		318	SURTEM	35	
49	FABEND	9		139	IPL0T	229		229	RINTRV	181		319	SURINW	42	
50	FIDIS	82		140	IPLT2D	591		230	RKIN	553		320	SURIN2	31	
51	FIDISJ	510		141	IPUMP	331		231	RMADAT	701		321	SVH2X2	307	
52	FIDIS2	99		142	IRADHT	317		232	RMBLNK	39		322	SWAPL	80	
53	FOURT	555		143	IRFLHT	342		233	RMFLDS	121		323	SYSTR	217	
54	FTBCL	46		144	IRKIN	473		234	RMLD0T	109		324	SYSSOL	135	
55	FTBCPY	30		145	ISFDES	13		235	RMPLJ	776		325	TCNVSL	68	
56	FTBDEL	51		146	ISTOPN	16		236	RNEUP	223		326	THCNV	76	

Fig. 3.3.1 (Continued)

57 FTBUSB	47	147 ISNGJ	160	237 RNONCN	165	327 THNGV	51
58 FTBERR	14	148 ISSI	619	238 RNPLNK	52	328 THCON	59
59 FTBEXP	17	149 ISTATE	1543	239 RNP2	73	329 THCOR2	70
60 FTBFTB	17	150 ITRIP	303	240 RONOFF	24	330 TIMSET	29
61 FTBGET	32	151 ITRSCN	55	241 RPIPE	1340	331 TRAWHT	74
62 FTBINT	64	152 IUSRVR	79	242 RPLDPS	282	332 TRAN	130
63 FTBLCT	95	153 IVELST	140	243 RPLOT	98	333 TRIP	105
64 FTBEM	14	154 IVLVEL	206	244 RPLOTF	342	334 TRMCTL	17
65 FTBRDV	15	155 JCHOKE	884	245 RPLOTN	422	335 TRMFIN	73
66 FTBRID	42	156 JPROP	420	246 RPL2D	437	336 TRNSET	955
67 FTBOPN	110	157 KATOKJ	168	247 RPPMDC	480	337 TSETSL	366
68 FTBCHK	9	158 KLOSS	77	248 RPPMVD	164	338 TSTATE	828
69 FTBIN	18	159 LABRT	26	249 RPMVNJ	892	339 TURBST	87
70 FTBOUT	19	160 LAVAIL	8	250 RPUMP	1188	340 UNSQ02	24
71 FTBPR1	75	161 LCNTGS	33	251 RPUNIT	116	341 VALVE	544
72 FTBPR2	8	162 LCONTG	23	252 RRADHT	704	342 VEXPLT	910
73 FTBPR3	9	163 LIEDPN	41	253 RRESTF	382	343 VFIAL	388
74 FTBPR4	10	164 LOCF	14	254 RRKIN	1583	344 VIMPLT	1238
75 FTBRDC	46	165 LOCFI	14	255 RRKINH	241	345 VISCG2	67
76 FTBRSD	29	166 LOCFI4	14	256 RRSTD	71	346 VISCOG	56
77 FTBSFT	66	167 LOCF4	14	257 RSIZPL	33	347 VISCOL	77
78 FTBSLK	64	168 MADATA	225	258 RSNGL	546	348 VISCVG	84
79 FTBTNC	67	169 MAINS	119	259 RSNGL	665	349 VISCVL	119
80 FDRAG	450	170 MAJOUT	1387	260 RSSI	458	350 VLVELA	332
81 GAPCON	186	171 MDATA2	435	261 RSTREC	80	351 VOLVEL	490
82 GASCON	165	172 META	8	262 RSTRIP	147	352 WFRICJ	293
83 GASTHC	68	173 MIREC	83	263 RTMDJ	500	353 WRITPL	81
84 GNMIT	214	174 MOVER	186	264 RTMDV	925	354 WRPLID	328
85 GRDRNJ	114	175 MYSETS	23	265 RTrip	471	355 ZFSLGJ	99
86 GTINF	64	176 NPSETS	14	266 RTSC	181		
87 HELPHD	21	177 NFSIZE	15	267 RTURB	1327		
88 HELPLT	230	178 NFUNIT	16	268 RUPLAS	65		
89 HIFBUB	73	179 NUMCHR	28	269 RUSRVR	103		
90 HLOSS	386	180 PACKER	142	270 RVALVE	1372		
=====	TOTAL	=====	NUMBER OF LINES.....	92780	(WITH INCLUDED)	133716	
			NUMBER OF STEPS.....	56580	(WITH INCLUDED)	68850	

Fig. 3.3.1 (Continued)

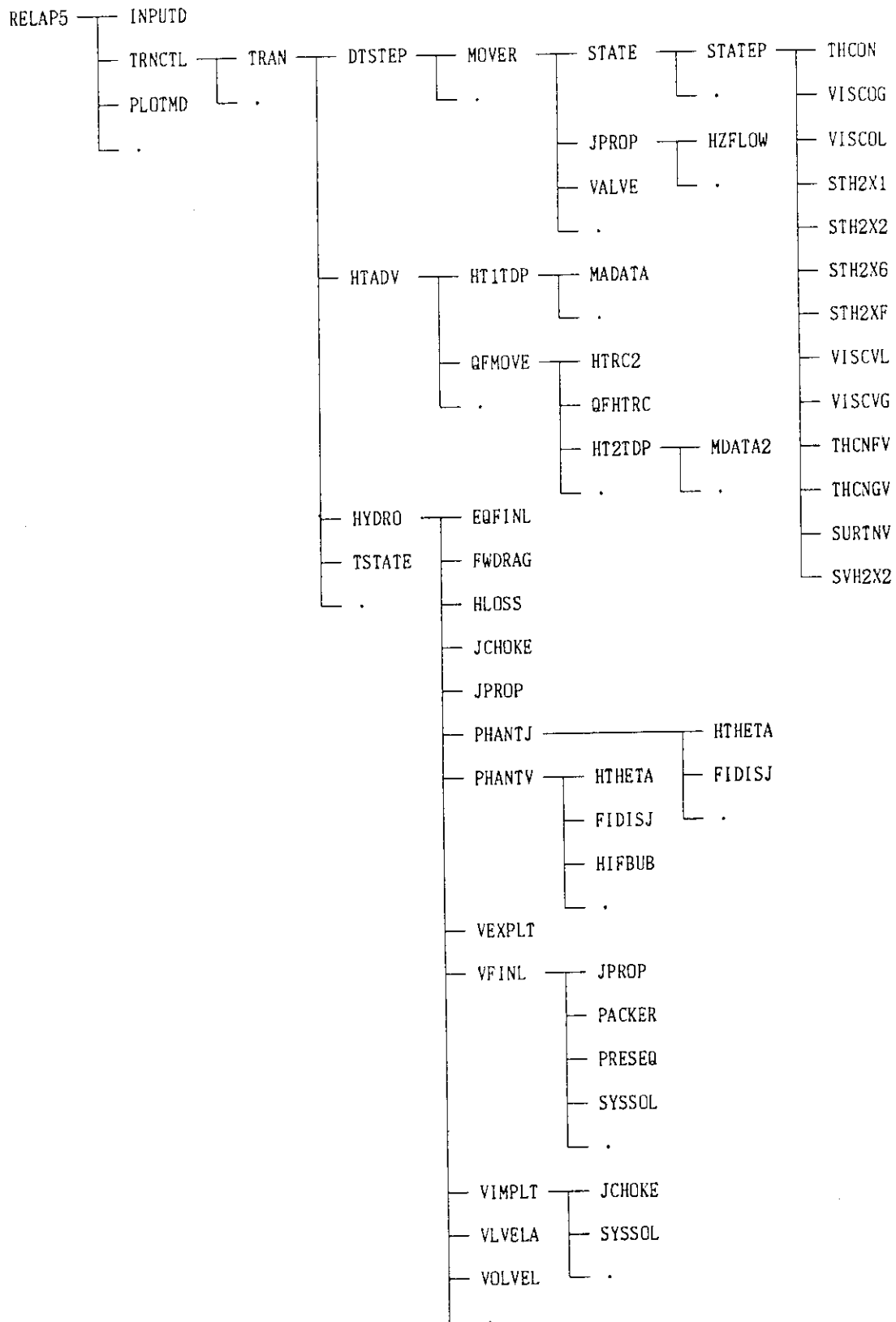


Fig. 3.3.2 Program tree of the time-consuming subroutines

NO.	ROUTINE	UNITS	LINES	ERR.	EXECUTIONS	COST	X	0
I 0001	PHANTJ	1	1735	0	686	138081087	9.1	I
I 0002	PHANTV	1	1667	0	686	107479638	7.0	I
I 0003	PRESEQ	1	1113	0	1268	102591187	6.7	I
I 0004	VEPLT	1	1301	0	686	74276255	4.9	I
I 0005	FHDRAG	1	709	0	686	72075775	4.7	I
I 0006	SVR2X2	1	424	0	2085	67419228	4.4	I
I 0007	STR2X6	1	602	0	1893	65609402	4.3	I
I 0008	STR2XF	1	92504	0	686	58207022	3.8	I
I 0009	EQFINL	1	1160	0	686	56977226	3.7	I
I 0010	PMINVF	1	164	0	1266	52981836	3.5	I
I 0011	MADATA	1	379	0	57765	48616243	3.2	I
I 0012	STATEP	1	1847	0	695	41222499	2.7	I
I 0013	MAJOUT	1	2103	0	6	33420664	2.2	I
I 0014	HT1TOP	1	824	0	686	32002146	2.1	I
I 0015	VOLVEL	1	764	0	686	31870209	2.1	I
I 0016	JCHOKE	1	1135	0	686	30272925	2.0	I
I 0017	IMP	1	298	0	2	25240810	1.7	I
I 0018	CONDEN	1	449	0	41094	24744536	1.6	I
I 0019	IMP9	1	107	0	131	24111484	1.6	I
I 0020	PREDNB	1	486	0	18291	23685608	1.6	I
I 0021	HTHETA	1	58	0	64360	22259742	1.5	I
I 0022	KAIOKJ	1	349	0	40808	22082427	1.4	I
I 0023	HL0SS	1	646	0	686	19876303	1.3	I
I 0024	VISCVL	1	230	0	2085	19729822	1.3	I
I 0025	VFINL	1	645	0	686	19437896	1.3	I
I 0026	VLVELA	1	606	0	627	18783985	1.2	I
I 0027	EPR1J	1	429	0	17674	18361544	1.2	I
I 0028	JPROP	1	706	0	2744	17753499	1.2	I
I 0029	F1015	1	180	0	92565	16377296	1.1	I
I 0030	PMINVM	1	79	0	1268	15341590	1.0	I
I 0031	HIFRUB	1	180	0	58687	13790201	0.9	I
I 0032	DIT1US	1	295	0	68494	12281772	0.8	I
I 0033	H2FLOW	1	1604	0	2744	11969837	0.8	I
I 0034	F101S2	1	280	0	42672	10627947	0.7	I
I 0035	FTBMOV	1	17	0	53190	9713323	0.6	I
I 0036	F101S1	1	735	0	58482	8944209	0.6	I
I 0037	CHFCAL	1	2689	0	18291	8396112	0.5	I
I 0038	THCNGV	1	53	0	2085	7280414	0.5	I
I 0039	HTCOND	1	428	0	57765	7569745	0.5	I
I 0040	PSET	1	78	0	175974	6773837	0.4	I
I 0041	PMINVR	1	61	0	88392	6604808	0.4	I
I 0042	HTRC1	1	431	0	687	6404889	0.4	I
I 0043	DTSTEP	1	822	0	56938	6101568	0.4	I
I 0044	STR2X0	1	52	0	695	5460903	0.4	I
I 0045	STATE	1	623	0	1520	5324265	0.3	I
I 0046	CVIC	1	403	0	686	4870560	0.3	I
I 0047	PACKER	1	393	0	686	4419106	0.3	I
I 0048	HTADV	1	414	0	686			
I 0049	VISCVG	1	195	0	2085			
I 0050	TIMSET	1	31	0	1			
I 0051	TIMEL	1	137409	0	687			
I 0052	TIMER	1	687	0	686	4374835	0.3	I
I 0053	MOVER	1	444	0	686	4374021	0.3	I
I 0054	TSTATE	1	1120	0	686	3948686	0.3	I
I 0055	PSATPD	1	97	0	19663	3886120	0.3	I
I 0056	THCMFV	1	78	0	2085			

Fig. 3.3.3 Dynamic profil of RELAP5/MOD3 code

I 0054	IEDIT	1	743	0	1	3624709	0.2	I*
I 0055	RKIN	1	925	0	627	3420345	0.2	I*
I 0056	RPIPE	1	1582	0	23	2717330	0.2	I*
I 0057	WRPLD	1	785	0	1	2711380	0.2	I*
I 0058	SURTIV	1	44	0	2085	2434045	0.2	I*
I 0059	RHTCMP	1	1346	0	1	2367075	0.2	I*
I 0060	SH2X1	1	213	0	3487	2153658	0.1	I
I	SH2X8	0						
I	SH2X2	258						
I 0061	SDDZ	1	31	0	101	1601961	0.1	I
I 0062	RBRMCH	1	1638	0	15	1476371	0.1	I
I 0063	CONVAR	1	579	0	627	1297890	0.1	I
I 0064	POLAT	1	67	0	19309	1242658	0.1	I
I 0065	RCONVR	1	1699	0	1	1223267	0.1	I
I 0066	IHTCMP	1	1249	0	1	1129106	0.1	I
I 0067	CCFL	1	420	0	686	1094328	0.1	I
I 0068	ACCUM	1	783	0	686	1049772	0.1	I
I 0069	PLIWR	1	774	0	101	924958	0.1	I
I 0070	HTIMP	1	1027	0	16	918397	0.1	I
I 0071	IHLP	1	1081	0	1	905142	0.1	I
I 0072	STACC	1	791	0	695	829914	0.1	I
I 0073	RSNGJ	1	788	0	16	808924	0.1	I
I 0074	PHINVD	1	507	0	2	757000	0.0	I
I 0075	TRAN	1	279	0	1	739485	0.0	I
I 0076	RTMDV	1	1167	0	14	738832	0.0	I
I 0077	IELVTN	1	580	0	1	603104	0.0	I
I 0078	MIREC	1	137	0	102	582829	0.0	I
I 0079	TRIP	1	180	0	627	462655	0.0	I
I 0080	INPLNK	1	82	0	2803	413140	0.0	I
I 0081	RSNGV	1	907	0	11	392196	0.0	I
I 0082	FTDLCT	1	116	0	1225	384606	0.0	I
I 0083	HIISS	1	651	0	83	378936	0.0	I
I 0084	VALVE	1	897	0	745	376822	0.0	I
I 0085	RIMDJ	1	736	0	10	374660	0.0	I
I 0086	IMPMD	1	94	0	1672	321815	0.0	I
I 0087	TSETSL	1	668	0	1	278396	0.0	I
I 0088	INVJT	1	360	0	1	268004	0.0	I
I 0089	RVALVE	1	1658	0	4	255269	0.0	I
I 0090	SCNREQ	1	1644	0	186	252127	0.0	I
I 0091	RPHVNJ	1	1173	0	2	242708	0.0	I
I 0092	IMP2	1	155	0	1244	221758	0.0	I
I 0093	PUMP	1	465	0	686	197764	0.0	I
I 0094	PUMP2	1	410	0	1374	189612	0.0	I
I 0095	TRMFIN	1	119	0	1	187395	0.0	I
I 0096	RACCU	1	1385	0	2	173220	0.0	I
I 0097	RRXIH	1	1672	0	1	150504	0.0	I
I 0098	ICONVR	1	973	0	1	146998	0.0	I
I 0099	TRMSET	1	1723	0	1	144261	0.0	I
I 0100	RMADAT	1	778	0	1	137124	0.0	I
I 0101	IMPS	1	165	0	309	130887	0.0	I
I 0102	RSIREC	1	141	0	3	130403	0.0	I
I 0103	ITRIP	1	382	0	1	129065	0.0	I
I 0104	DMPNST	1	72	0	1	125674	0.0	I
I 0105	SYSSOL	1	367	0	1	121190	0.0	I
I 0106	SETMDF	1	17	0	135	119713	0.0	I
I 0107	POLATR	1	84	0	1374	113354	0.0	I
I 0108	SH2X3	1	381	0	161	106349	0.0	I
I 0109	RPMAMD	1	434	0	1	100458	0.0	I
I 0110	PHIRV4	1	51	0	4	95660	0.0	I
I 0111	HYDRO	1	181	0	686	91729	0.0	I
I 0112	ISTATE	1	1817	0	1	91247	0.0	I
I 0113	IMPURK	1	34	0	1672	84679	0.0	I

Fig. 3.3.3 (Continued)

3.4 Vectorization methods for heat transfer calculation

The heat transferred across solid boundaries of hydrodynamic volumes is calculated using heat structures^{*4}. The heat structures are able to model fuel pins or plates with nuclear or electrical heating, heat transfer across steam generator tubes, and heat transfer from pipe and vessel walls, and so on. The heat structures are represented by one-dimensional heat conduction. Finite differences are used to advance the heat conduction solutions.

Fig 3.4.1 illustrates the layout of mesh points at temperatures to be calculated. The finite difference approximation for mesh points leads to a tri-diagonal system of M_i equations, where M_i denotes the number of mesh points for the heat structure i . In the original code, these equations were solved using the Gaussian elimination method. And the heat transfer rate κ , and the heat capacity coefficient ρC_p are obtained by table look-up.

The present vectorized subroutines at JAERI are summarized in Table 3.4.1.

The vectorization methods used are summarized as follows^{*9}:

(1) Since the heat advancement can be calculated in parallel for all the heat structure, the heat structure DO-loop in the subroutine HTADV, which is the top-level subroutine for heat transfer calculation, is transferred into the invoked subroutine HT1TDP (see Fig. 3.2.1).

(2) Program block which contains a calculation on heat mesh points or intervals is doubly nested DO-loops in nature since heat structure loop exists in the outer. In this case, the double DO-loops are reformed as a single DO-loop, if possible, in order to enlarge the vector length.

<Index transformation from doubly-nested DO-loop to a single loop>

The heat structure geometry data and temperatures are treated for each mesh point or mesh interval. The calculated data were stored in a two-dimensional array $XXX\forall(\ell, i)$ as shown in Fig. 3.4.2. In order to process these data efficiently, doubly nested DO-loops are transformed into a single loop as follows, where the arrays $XXX\forall(L, I)$ and $ZXXX\forall(LCOLS \forall(J))$ share a memory by EQUIVALENCE statement:

```

DO 1 I=1, %NH                      DO 1 J=1, %LCOLS
  DO 1 L=1, COLS %1)                ==> 1 ZXXX% (LCOLS%1(J)) = .....
1 XXX%(L, I) = .....

```

(3) The original method which was applied to the solution of heat transfer equations was the Gaussian elimination which includes unvectorizable recursive formula. In the vectorized code, the inner/outer DO-loops are changed in position and then the heat structure-loop is vectorized.

<Vectorized solution of the heat transfer equation>

The data structure of the coefficient matrix of heat transfer equations is not changed in the vector version. Use of the data area of coefficient matrix for a heat structure is shown in Fig. 3.4.3. Here three arrays HTE¥, HTB¥, and HTF¥ are used for keeping values "a and c", "b", and "d" when general form

$$a_j T_{j-1} + b_j T_j + c_j T_{j+1} = d_j$$

is assumed, where the matrix is not necessarily symmetric because values c_1 and a_m become zero depending on the heat structure geometry.

The vectorization method applied to solve the one-dimensional heat conduction calculation is shown in Fig. 3.4.4. In the original code, the program is coded as doubly nested DO-loops. The inner loop index m is for heat mesh points, and the outer loop index i is for heat structures as shown in Fig. 3.4.4(a). The maximum number of heat mesh points and heat structures is indicated ¥MNN and ¥NH, respectively.

This nested DO-loops solved N-set of tri-diagonal system of equations for heat mesh points of N-heat structures (= ¥NH). For the vectorization, the DO-loop indices are inverted because the DO-loop for the heat mesh points is recursive and the vector length is very small (3~10), but the heat structures have no data dependency each other.

Besides, the indices of heat structure "i" are changed in ascending order of number of mesh points in heat structures as shown in Fig. 3.4.4(b). A list vector is provided to keep the maximum heat mesh numbers corresponding to heat mesh indices. By using this list vector, we could avoid the IF tests in the inner loop when number of mesh points is different among heat structures.

(4) The forced convection heat transfer correlations and so on were originally calculated on the left and right boundaries of each heat structure in serial. The program is reformed in order to calculate on left and right boundaries over all heat structures in parallel. From this reform, the vector length becomes double.

<Integration of the left and right boundary treatments>

Data structure of boundaries is illustrated as Fig. 3.4.5, where the left and

right boundaries are arranged alternatively for each heat structure. By applying this layout, the calculation order does not change in vector version. The change of calculation order in heat boundaries sometimes brings a discrepancy of the computed results. Especially, in the top-level subroutine HTADV (see Fig. 3.3.1), heat transfers from heat boundaries are added into the hydrodynamic volumes. The order of the summation at this time is one of the factors which cause the difference of computed results between vector and scalar processings.

The list vectors generated for the boundary treatments are as follows:

- LB1 Ψ (k) to transform the boundary indices assigned as Fig. 3.4.5 into the indices for a heat structure,
- LBL Ψ (k) to extract boundary mesh points,
- LBN Ψ (k) to extract boundary intervals,
- LBNO Ψ (k) to distinguish the left and right boundaries (left = 0, right = 1).

(5) List vectors are generated once and later used when IF branch conditions in a DO-loop are fixed during a time step. In the vectorized version, a DO-loop is constructed corresponding to a branch condition. The data reference or update in the DO-loop is replaced to indirectly addressed ones using the list vector which satisfies the branch condition (see Fig. 3.2.4).

(6) The invariable list vectors which are frequently used are reserved as one-dimensional tables. We make tables for two purposes: for the index transformation from doubly nested DO-loop to a single loop as described in (2) and for the integration of the left and right boundary treatments as described in (4).

Table 3.4.1 Vectorized subroutines for heat transfer calculation

Subroutine name		Contents	Vectorized index
Original	Vectorized		
HTADV	HTADV	Controls advancements of heat structures and computes heat added to hydrodynamic volumes.	Left and right heat boundaries
HT1TDP	HT1TDV	Advance one heat structure one time step by advancing the transient heat transfer equations.	Heat structures, Heat meshes, etc.
MADATA	MADATV	Computes thermal conductivity and volumetric heat capacity for each mesh intervals.	Total mesh-intervals
HTCOND	HTCONV	Returns left and right boundary conditions for a heat structure.	Heat boundaries
HTRC1	HTRC1V	Computes heat transfer coefficient from correlations.	Heat boundaries connected with hydrodynamic volumes
DITTS	DITTSV	Computes Dittus-Boelter forced convection heat transfer correlation.	"
CONDEN	CONDEV	Computes condensation heat transfer correlations.	"
PREDNB	PREDNV	Computes Pre-DNB forced convection heat correlations.	"
CHF CAL	CHFCAV	Computes the critical heat transfer flux using ZUBER and BIASI CHF correlations.	"

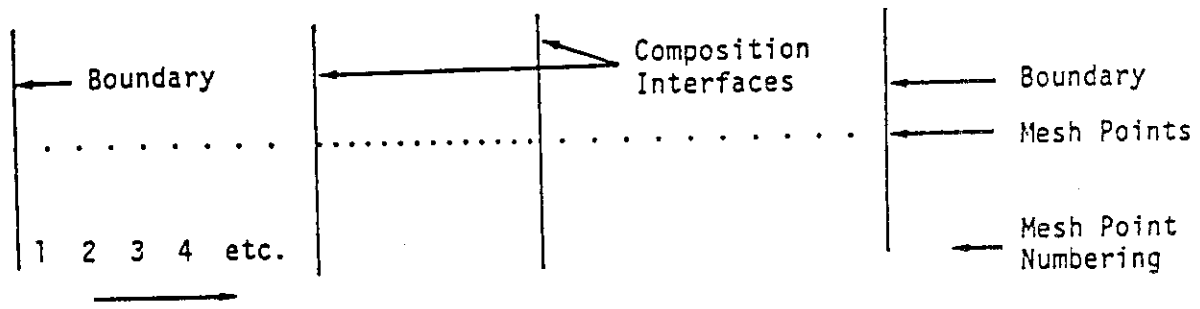
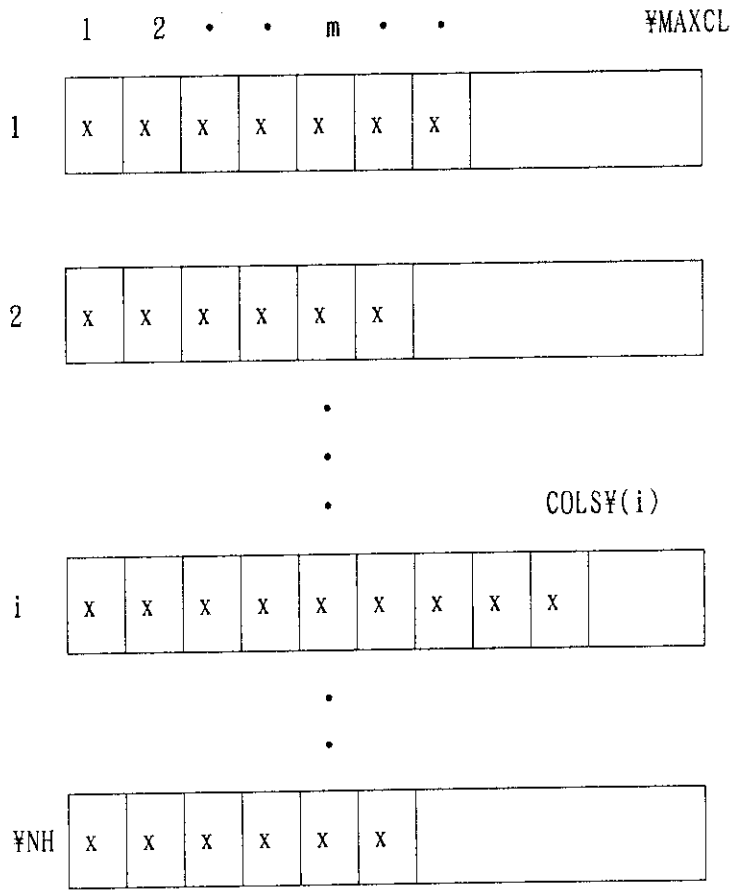


Fig. 3.4.1 Mesh point layout

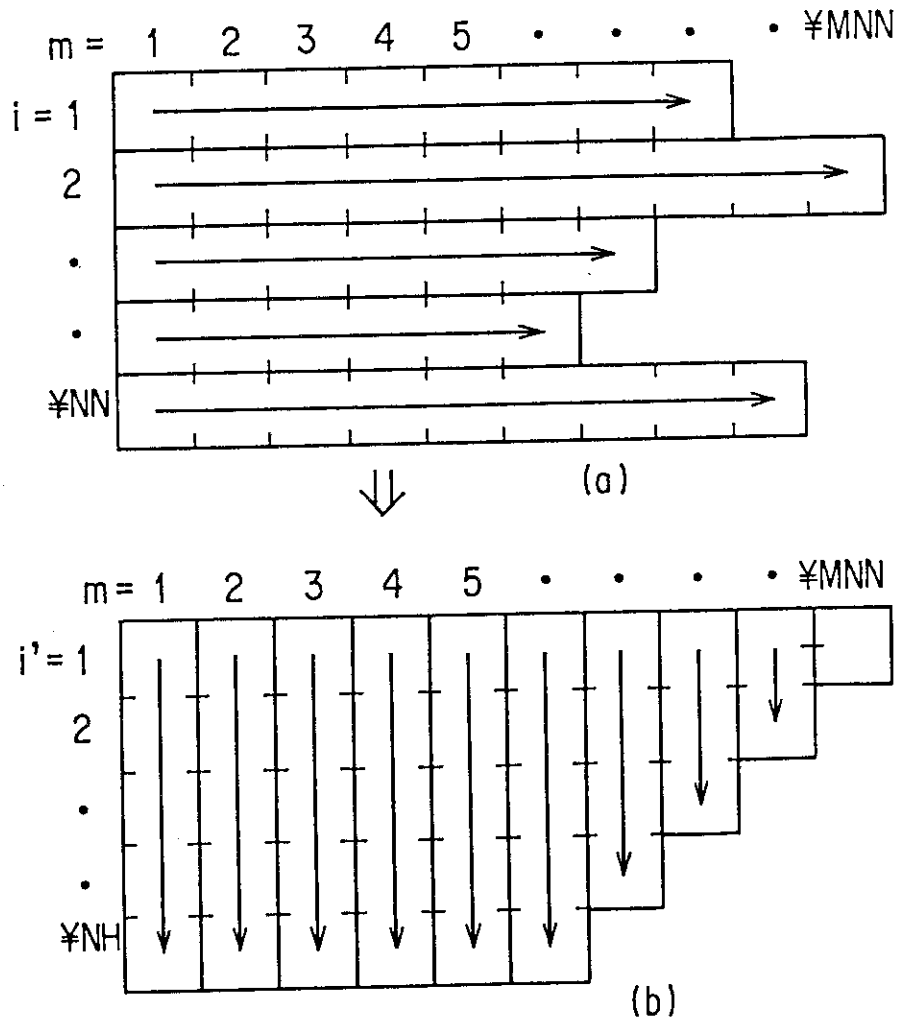


%MAXCL: Upper limit of the mesh number of heat structure (not large)
 %NH: Number of heat structures
 COLS %(i): Number of mesh points for a heat structure i

Fig. 3.4.2 Data structure of heat mesh points in the original code

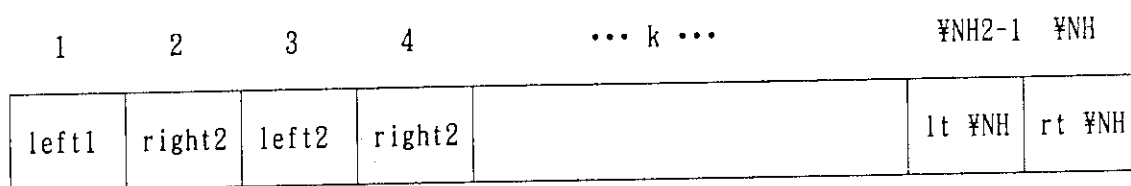
	1	2	3	M-1	M	M+1
HTE¥	c_1	$a_2=c_3$	$a_3=c_4$		$a_{M-1}=c_{M-2}$	c_{M-1}	a_M
HTB¥	b_1	b_2	b_3			b_M	
HTF¥	d_1	d_2	d_3			d_M	

Fig. 3.4.3 Use of data area for coefficient matrix of heat transfer equations



METHOD FOR DO-LOOP INTERCHANGE

Fig. 3.4.4 Method of DO-loop inversion



$\#NH2$: = number of boundaries

= number of heat structures($\#NH$) * 2

Fig. 3.4.5 Data structure of boundaries

3.5 Vectorization method for hydrodynamic calculation

The RELAP5 hydrodynamic model *4 is a one-dimensional, transient two-fluid model for flow of two-phase steam water nature which can contain a noncondensable component in the steam phase and/or nonvolatile component in the water. Six equation model with an additional equation for noncondensable gas components is applied as the field equation.

The two-fluid equations of motion which are used as the basis for the RELAP5 hydrodynamic model are formulated in terms of space and time averaged parameters of flow. The system model is solved numerically using a semi-implicit finite difference method *4.

Program structure of the hydrodynamic model is rather serial and each submodels is called sequentially (see Fig. 3.3.2). Most of the calculation can be performed in parallel for spatial meshes. Since the staggered mesh method is applied, nodes (=volumes) or junctions can become vectorizable indices. For most part of the DO-loops, vectorizable codings were already prepared by INEL.

The vectorized subroutines at JAERI are summarized in Table 3.5.1.

The vectorization method of each subroutine is as follows *9:

(1) Subroutine EQFINL

Most of DO-loops in this subroutine can be vectorized on junctions or volumes without restructuring. Only problem is several junction loops which contains multiple assignment statements. Such recursive loops appear for adding the convective terms to the source terms and for computing the Boron density, and so on. These loops are, therefore, isolated and scalar option is specified.

(2) Subroutine FWDRAG

This subroutine consists of volume-loops, so the vectorization is very easy. Insert of compiler directives (*VOCL on FACOM vectorizing compiler) is the useful means.

(3) Subroutine HLOSS

This subroutine consists of a junction-loop. The calculation is skipped for most junctions by an IF branch appearing at the top of the program. Therefore, in the vectorized version, the DO-loop is divided into several blocks before the IF statements and list vectors are generated if sufficiently large vector length is expected.

(4) Subroutine JCHOKE

The last half of this subroutine contains a type of recursive formula to compute the flow with sound speed but the computing time spent in this part is very small. So, we vectorize only the first half by making use of the parallelism of junctions.

(5) Subroutine JPROP

As similar as subroutine FWDRAG, modification is not so much. The compiler directives are inserted.

(6) Subroutine HZFLOW

This subroutine consists of a junction-loop with big program body but the most part of calculation is skipped for all most all junctions, except for the last program sequence. Therefore, the last program sequence is isolated as a DO-loop and vectorized on the junctions.

(7) Subroutine PHANTJ

The subroutines PHANTJ and FHANTV are new ones in the RELAP5/MOD3 code. The PHAINT subroutine of RELAP5/MOD2 are divided into PHANTJ and PHANTV which mainly contains junction-loops and volume-loops, respectively.

PHANTJ consists of doubly nested DO-loops of plant-components and their junctions. In the vectorized version, this double loops are reformed into a single loop. Number of statements in the DO-loop is so many that can be effectively vectorized. So, we divide the loop into several blocks. Flow of the vectorized PHANTJ is illustrated in Fig. 3.5.1.

Subroutine calls for HTHETA in the DO-loop are isolated and the DO-loop are transferred into the invoked subroutine HTHETA to be vectorized in it. A backward GOTO statement exists for some junctions when the horizontal flow map calculation (HMAP) is required (see Fig. 3.5.1). We generate two kinds of list vectors; one is for the junctions used in usual program path and another is for the junctions on which the HMAP option is specified. If short vector length is expected such as dry wall correlation calculation, scalar loops are applied.

(8) Subroutine HTHETA

This subroutine is called from PHANTJ and PHANTV. The volume loop existing in both subroutines are transferred and vectorized on the volumes. The convergence calculation is explicitly written down in the vectorized DO-loop and solved for all volumes in parallel.

Different assignment statements are used in the subroutines PHANTJ and PHANTV after the calls for HTHETA. This assignment statement is to be moved into each child subroutine. Accordingly, we prepare two subroutines of vectorized HTHETA; one is named HTHEVJ for the subroutine PHANTJ and another is HTHETV for PHANTJ. Flow of the HTHETV is shown in Fig. 3.5.2.

(9) Subroutine PHANTV

As similar as the subroutine PHANTJ, doubly-nested DO-loops of components and volumes are reformed into a single DO-loop and the single loop is divided into several blocks in order for efficient vectorization. The subroutine calls for HTHETA, FIDIS and HIFBUS in the DO-loops are vectorized in each slave routines.

(10) Subroutine FIDIS

There is no DO-loop in the original FIDIS subroutine. The volume loop in the subroutine PHANTV is transferred into the FIDIS. Flow of the vectorized subroutine is shown in Fig. 3.5.3. In the subroutine PHANTV, the vectorized FIDIS (= FIDISV) is called when large vector length is expected but otherwise, such as dry wall correlation calculation, the original FIDIS is called.

(11) Subroutine HIFBUS

The vectorization method of this subroutine is similar to subroutine FIDIS. Both the vectorized subroutine HIFBUV and the original scalar subroutine HIBUS are used according to the vector length. Flow of the vectorized subroutine is shown in Fig. 3.5.4.

(12) Subroutine PRESEQ

Most of DO-loops of this subroutine are vectorizable on junctions or volumes. The problem is the multiple assignment statements in DO-loops to compute the coefficient matrix and source terms of pressure equation, where convective terms on adjacent volumes ("to volume" and "from volume") are added to each junction. The loops can not be vectorized. So, we leave them as scalar.

(13) Subroutine VEXPLT

Compiler directives are inserted.

(14) Subroutine VFINL

Compiler directives are inserted.

(15) Subroutine PACKER

WRITE statements in the DO-loop are moved outside and gathered as another loop so that the remaining part of the program can be vectorized

(16) Subroutine VLVELA

Compiler directives are inserted.

(17) Subroutine VOLVEL

Compiler directives are inserted.

Table 3.5.1 Vectorized subroutines for hydrodynamic calculation

Subroutine names		Contents	Vectorized index
Original	Vectorized		
EQFINL	EQFINL	This subroutine computes the new time pressure and carries out the back substitution to obtain the new time liquid specific internal energy, vapor specific internal energy, void fraction internal noncondensable quality, and boron density.	VOLUMES JUNCTIONS
FIDIS	FIDISV	Computes interphase drag terms.	VOLUMES
FWDRCG	FWDRCG	Computes wall drag terms...include flow regimes and correlation.	VOLUMES
HIFBUB	HIFBUB	Computes liquid HIF for bubbly flow.	VOLUMES
HLOSS	HLOSS	Calculates void fractions at throat and downstream of an abrupt area change and associated head loss terms.	JUNCTIONS
HTHETA	HTHEAV HTHEVJ	Calculation of horizontal stratification angle.	VOLUMES JUNCTIONS
HZFLOW	HZFLOW	Vapor pull-through and liquid entrainment model for stratified horizontal flow.	JUNCTIONS
JCHOK	JCHOK	Computation of choking theory.	JUNCTIONS
JPROP	JPROP	Donors junction properties from adjacent volume quantities.	JUNCTIONS
PACKER	PACKER	This subroutine determines if water packing occurs, and if it does, modifies terms used in the velocity equations.	VOLUMES
PHANTJ	PHANTJ	Computes interphase drag and also calculates some information for VEXPLT. (for junction loop)	JUNCTIONS
PHANTV	PHANTV	Computes heat transfer and also calculates some information for VEXPLT. (for volume loop)	VOLUMES
PRESEQ	PRESEQ	Using the phasic equations for mass and energy to eliminate liquid specific internal energy, vapor specific internal energy, void fraction, and noncondensable quality, this subroutine builds the matrix elements and the source vector elements for the resultant pressure equation.	VOLUMES JUNCTIONS
SYSSOL	SYSSOL	Solves system of equations using sparse matrix subroutines.	Non-zero matrix elements
VEXPLT	VEXPLT	Computes the explicit liquid and vapor velocities and the pressure gradient coefficients needed for the implicit pressure solution.	VOLUMES JUNCTIONS
VFINL	VFINL	Computes new velocities from the pressure solution.	JUNCTIONS
VLVELA	VLVELA	Calculates average volume velocities by averaging. The average junction velocities in and out of the volume.	VOLUMES
VOLVEL	VOLVEL	Calculates average volume velocities by averaging. The average junction velocities in and out of the volume.	JUNCTIONS

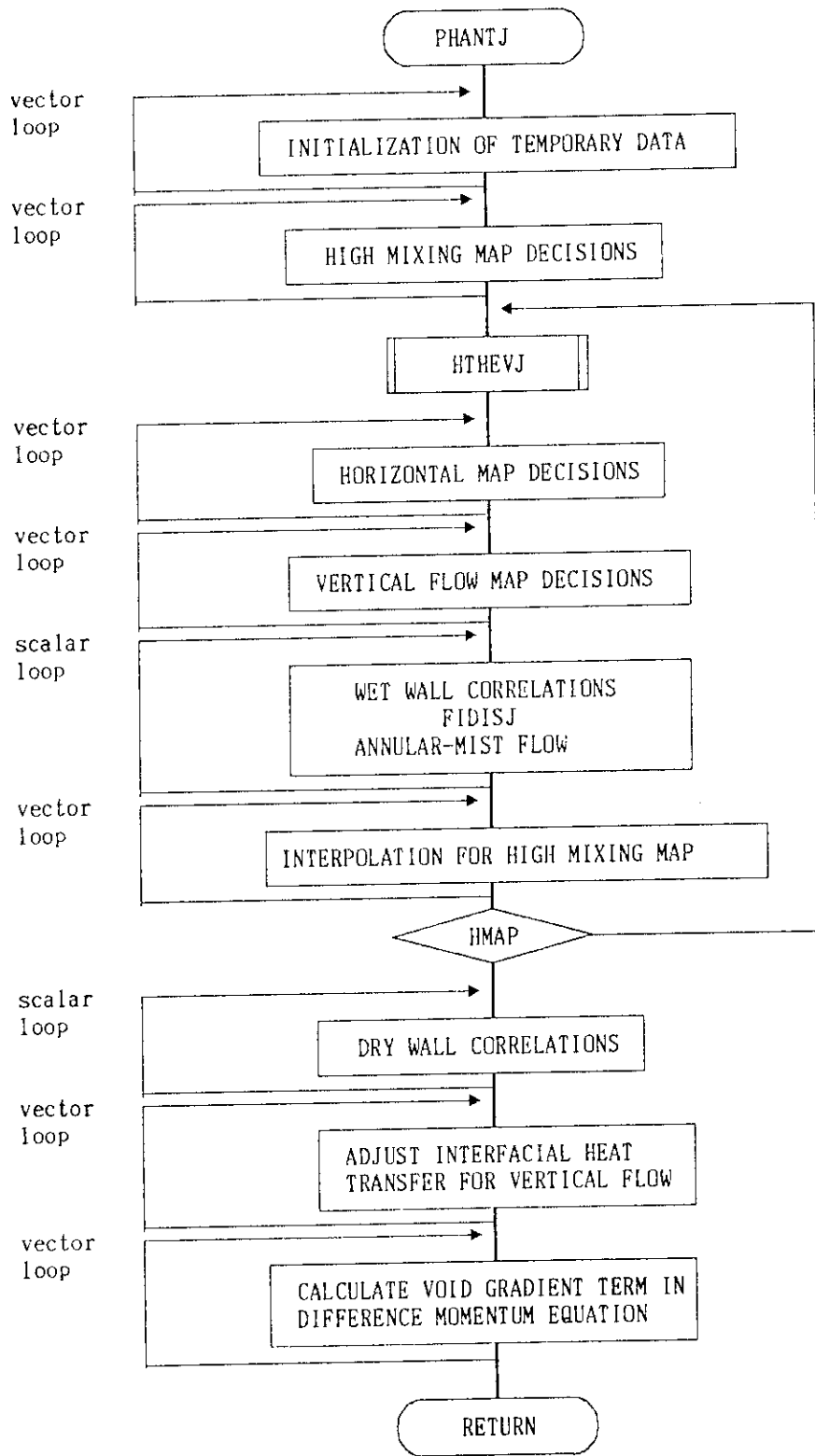


Fig. 3.5.1 Flow diagram of subroutine PHANTJ in vectorized version

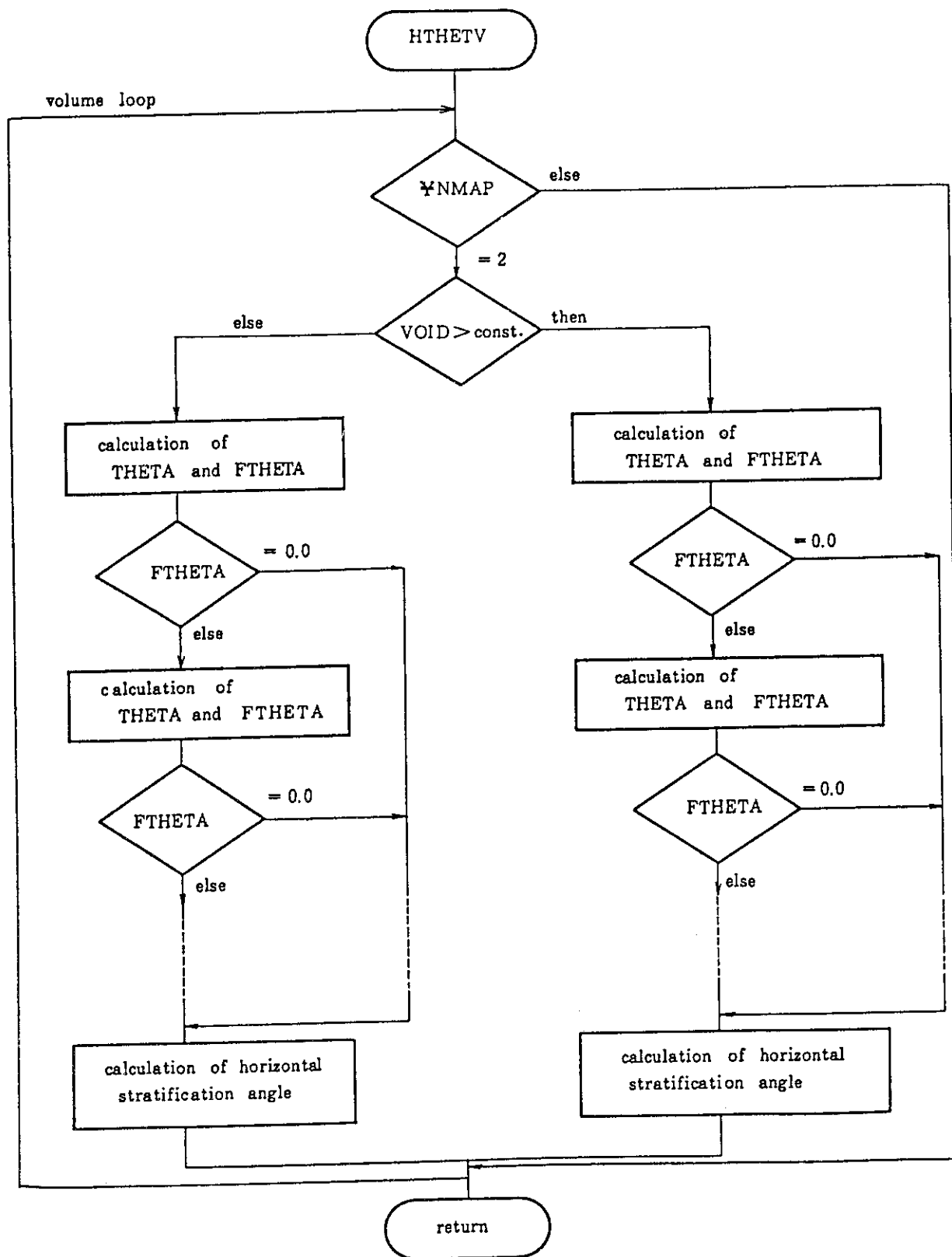


Fig. 3.5.2 Flow diagram of subroutine HTHETA in vectorized version

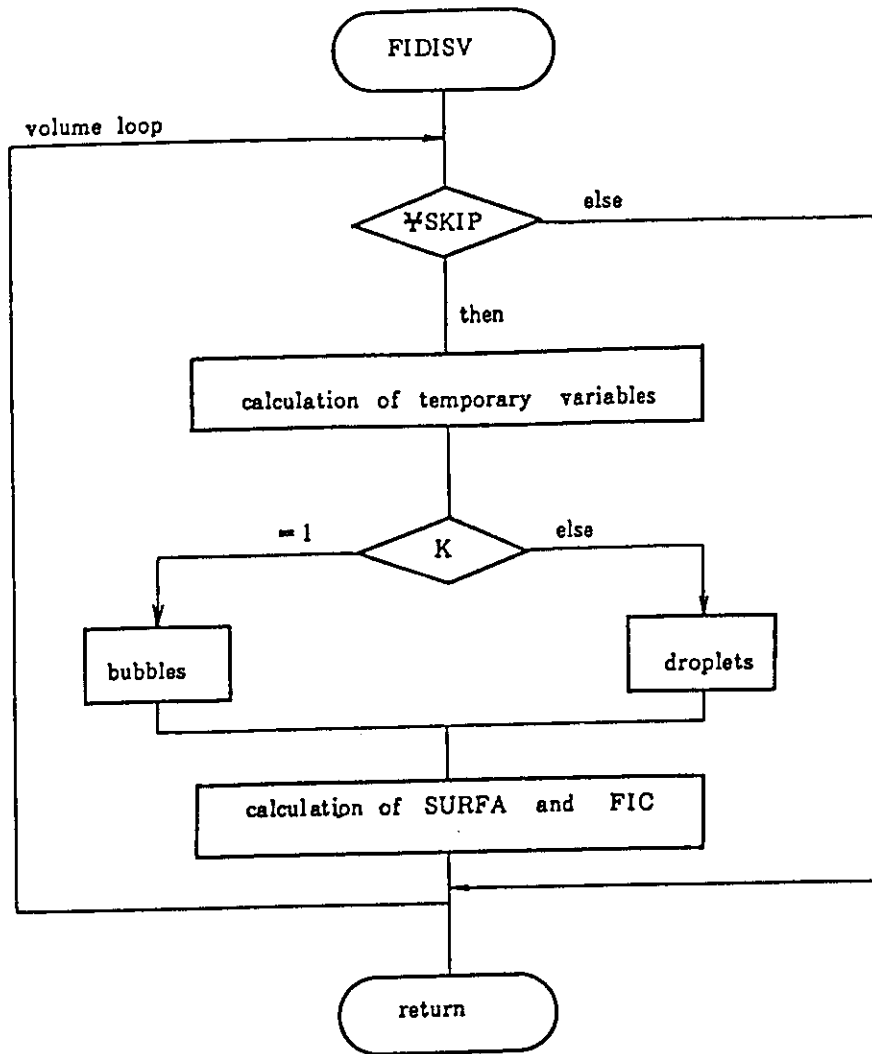


Fig. 3.5.3 Flow diagram of subroutine FIDIS in vectorized version

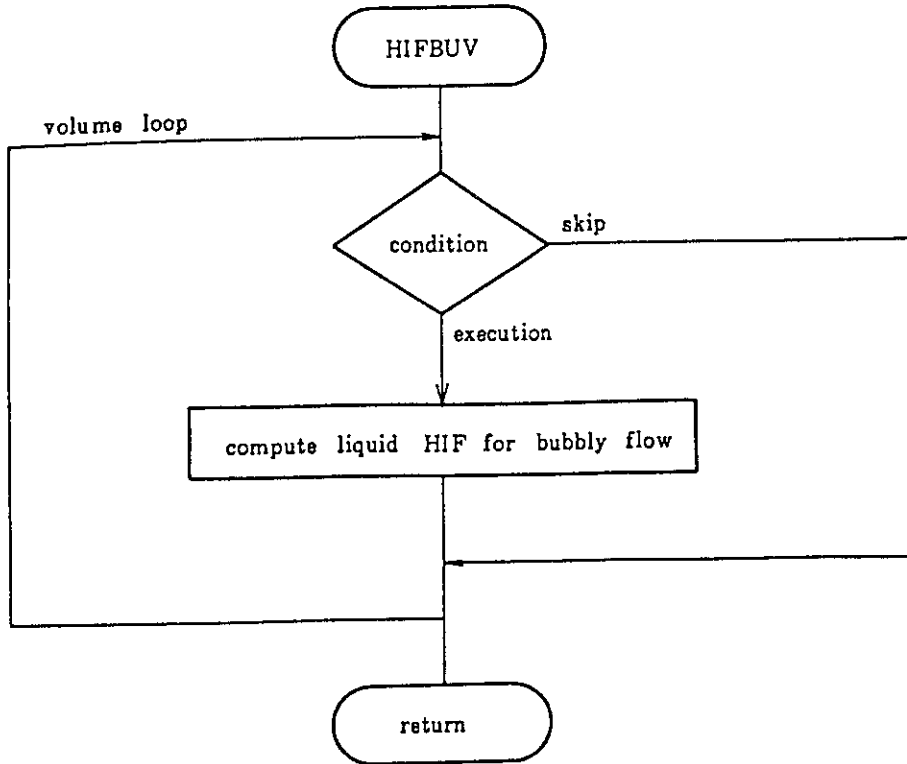


Fig. 3.5.4 Flow diagram of subroutine HIFBUS in vectorized version

3.6 Vectorization method for state relationship calculation

The six equation model with an additional equation for noncondensable gas component has the five independent variables; pressure, void fraction, vapor and liquid internal energies, noncondensable vapor phase mass fraction. All the remaining thermohydraulic variables; temperature, densities, partial pressure, quality, etc. are expressed as function of these five independent properties.

The state relationship calculation evaluates the dependent variables and their derivatives from equations of state *4.

The main program structure was doubly-nested loops of components and volumes. But in the JAERI vectorized version, the double loops are reformed into a single loop over the total volumes. The calculation mostly depends on the fluid state, that is, different subroutines are called depending on the fluid state. These lower-level subroutines can be vectorized on the volume-loop which is transferred from parent routine. For this purpose, list vector for each fluid state was already provided by INEL for most part of the program. We only turn up the DO-loop structure to vectorize on the single loop for all the volumes.

The vectorized subroutines are summarized in Table 3.6.1.

The vectorization method for each subroutine is as follows:

(1) Subroutine STATE

All the volume indices are gathered and reserved as a list vector NVOLSF at the first time-step. This list vector is used in the slave subroutines lower than the STATEP. The volume indices which compose a coolant loop system (preliminary and secondary loops, etc) are invariant throughout the calculation. Hence, list vectors are generated only once at the first time-step to keep the volume indices composing of systems. These list vectors are used in later time-steps to compute the system mass errors.

(2) STATEP

Flow diagram of subroutine STATEP in the original code is shown in Fig. 3.6.1. The outer component loop and inner volume loop are reformed into a single loop for all the volumes. Two list vectors were already created in the original code; one is for the volumes without air and another is for the volumes with air. Since the number of volumes with air is very small, a scalar loop is applied. But the volume-loop without air is vectorized. The DO-loop is divided into several blocks to isolate the subroutine calls to STH2X6 (= STH2XF). These

subroutine calls are vectorized in the subroutine STH2X6 by transferring the DO-loop from STATEP to STH2X6.

(3) STH2X6

Flow diagram of subroutine STH2X6 in the original code is shown in Fig. 3.6.2. The volume-loops transferred from STATEP were originally divided into several groups by the fluid states as shown in Fig. 3.6.2. Each calculational block is vectorized using the related list vector.

Table search of the steam table is newly vectorized. The original DO-loop structure could not be vectorized because of iterative GOTO loops which were used to table look-up. In the vectorized version, the GOTO loops were moved outside as the outer loop and, on the contrary, table search over volumes is vectorized. If the volume is found, it should be deleted at the next search. Accordingly, the list vector must be regenerated in every search time. The method is illustrated in Fig. 3.6.3. In order to clarify the method, new and old program flows are compared in Fig. 3.6.4.

(4) SVH2X2

Speedup of table search is not expected in this routine because of short vector length and then the remaining part of programs are vectorized.

(5) VISCVL, VISCGV, THCVGV, THCNFV

In the parent subroutine STATEP, list vectors were generated in each time-step to gather the volume indices according to the fluid states. After then, the fluid state calculations, which may be carried out by calling one of above subroutines, are vectorized using list vectors.

(6) SURTNV

This subroutine is vectorized for all the volumes.

Table 3.6.1 Vectorized subroutines for state relationship calculation

Subroutine names		Contents	Vectorized index
Original	Vectorized		
STATE	STATE	Controls the evaluation of the equation of state for all components.	Volumes
STATEP	STATEV	Computes equation of state and derivatives for time advanced volumes.	Volumes
STH2X6	STH2X6	Computes water thermohydraulic properties as function of pressure and internal energy.	Volumes
SVH2X2	STH2X2	Computes water thermohydraulic properties as a function of pressure and quality.	Volumes
VISCVL	VISCVL	Calculate water liquid viscosity	Volumes
VISCVG	VISCVG	Calculate water vapor viscosity	Volumes
THCNGV	THCNGV	Computes thermal conductivities of saturated or subcooled liquid.	Volumes
THCNFV	THCNFV	Computes thermal conductivities of saturated or superheated vapor.	Volumes
SURTNV	SURTNV	Determines H ₂ O surface tension from the fluid temperature.	Volumes

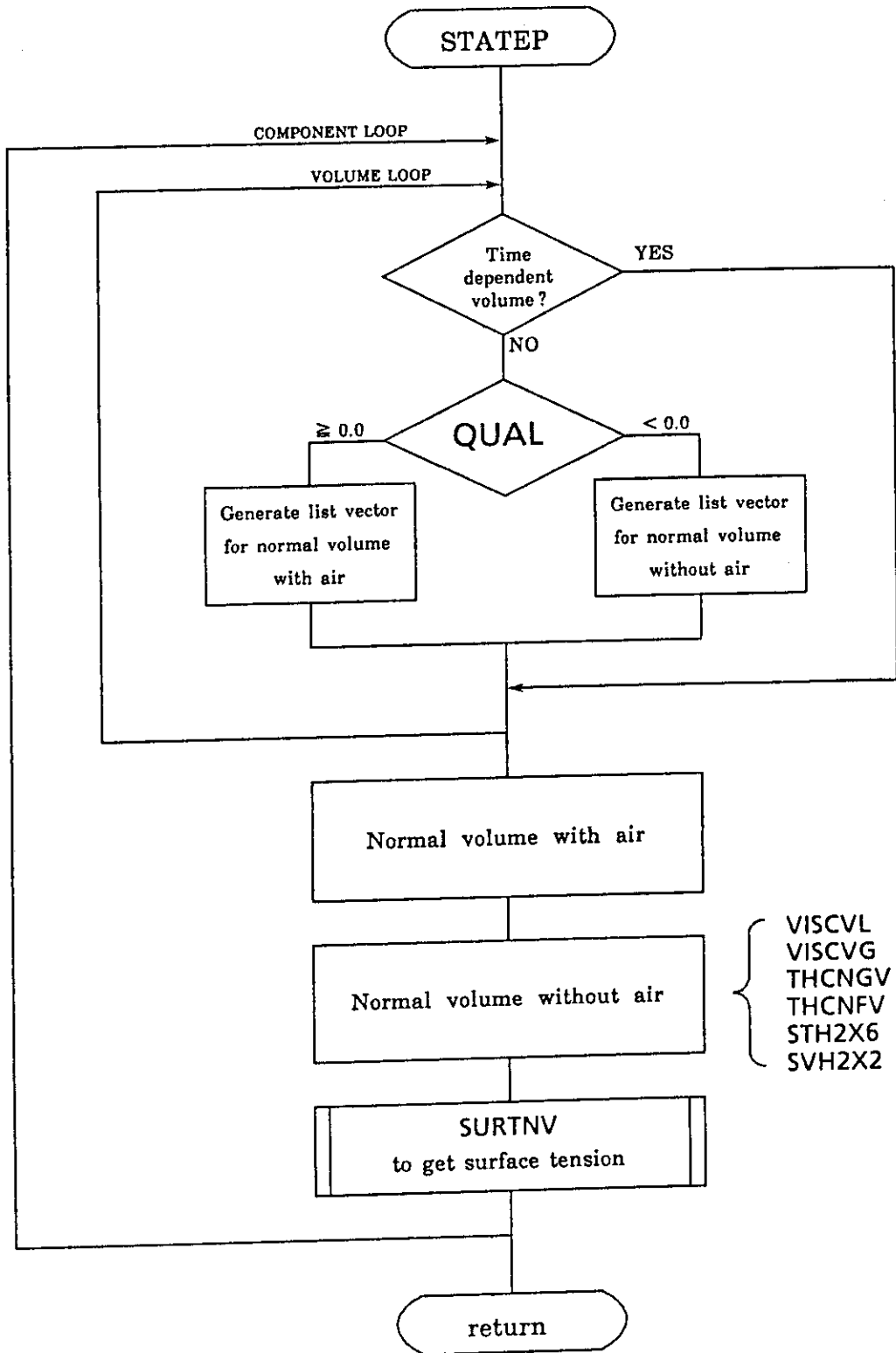


Fig. 3.6.1 Flow diagram of subroutine STATEP in the original code

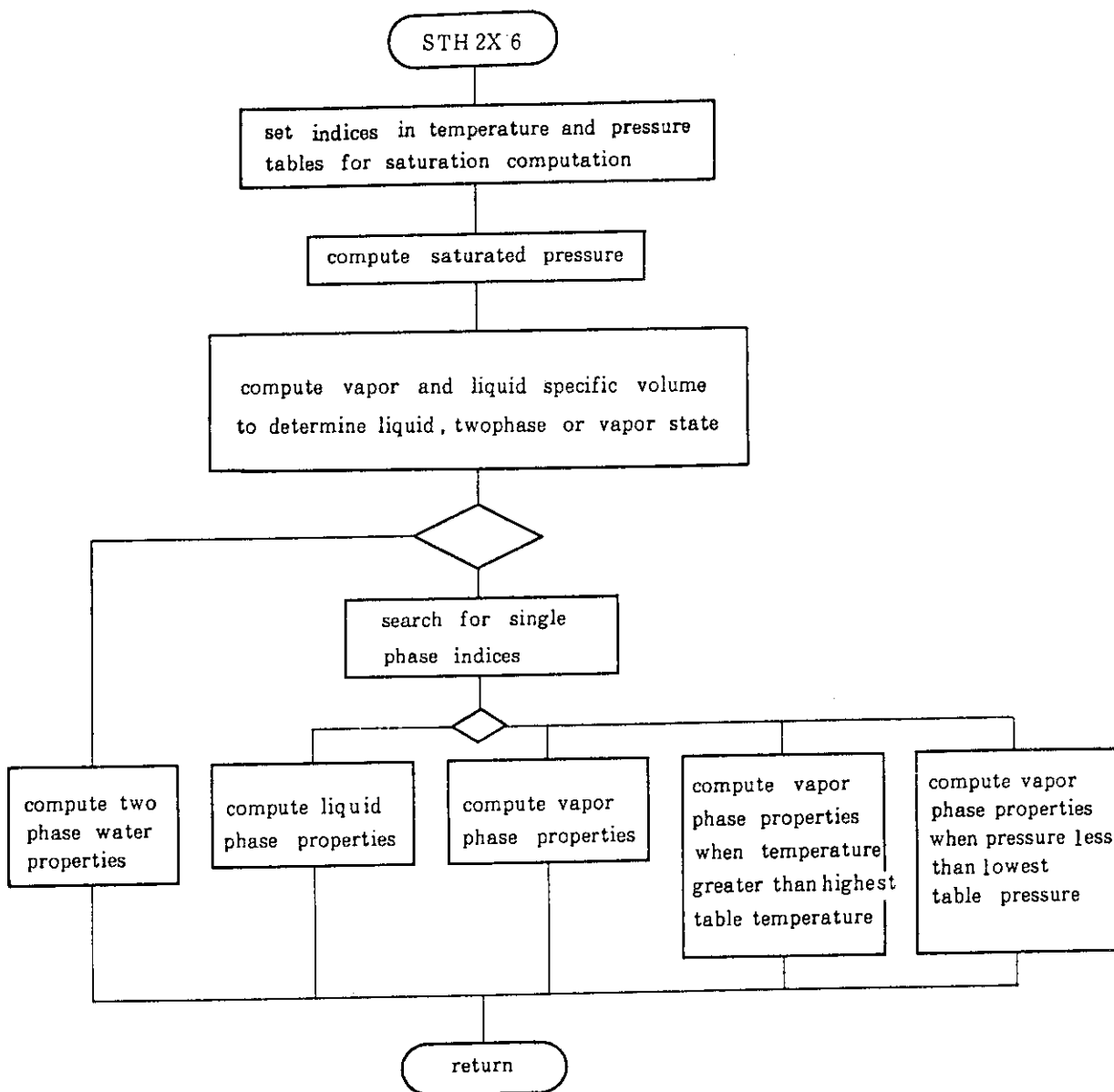


Fig. 3.6.2 Flow diagram of subroutine STH2X6 in the original code

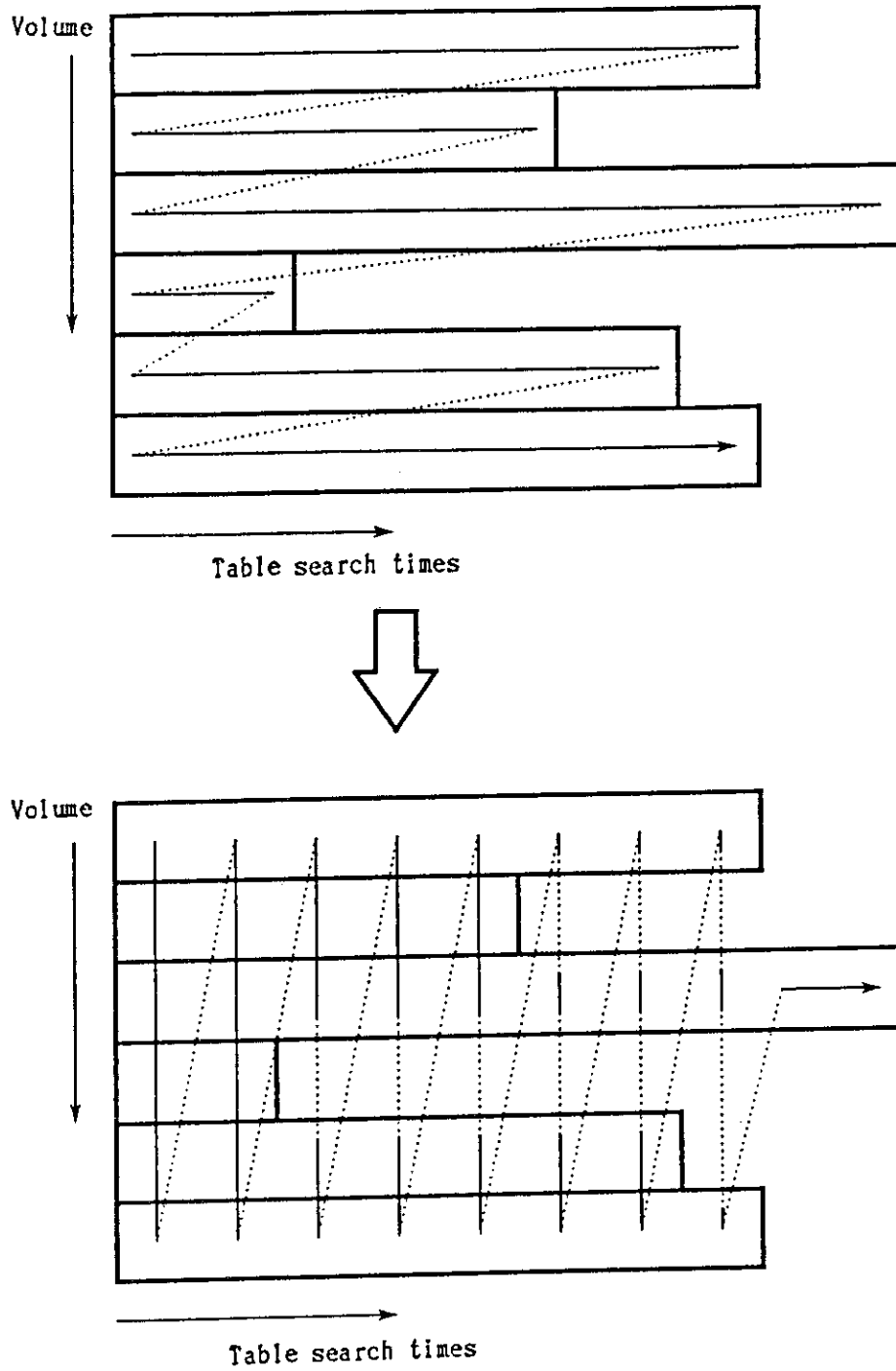


Fig. 3.6.3 Restructure for table look-up of steam table

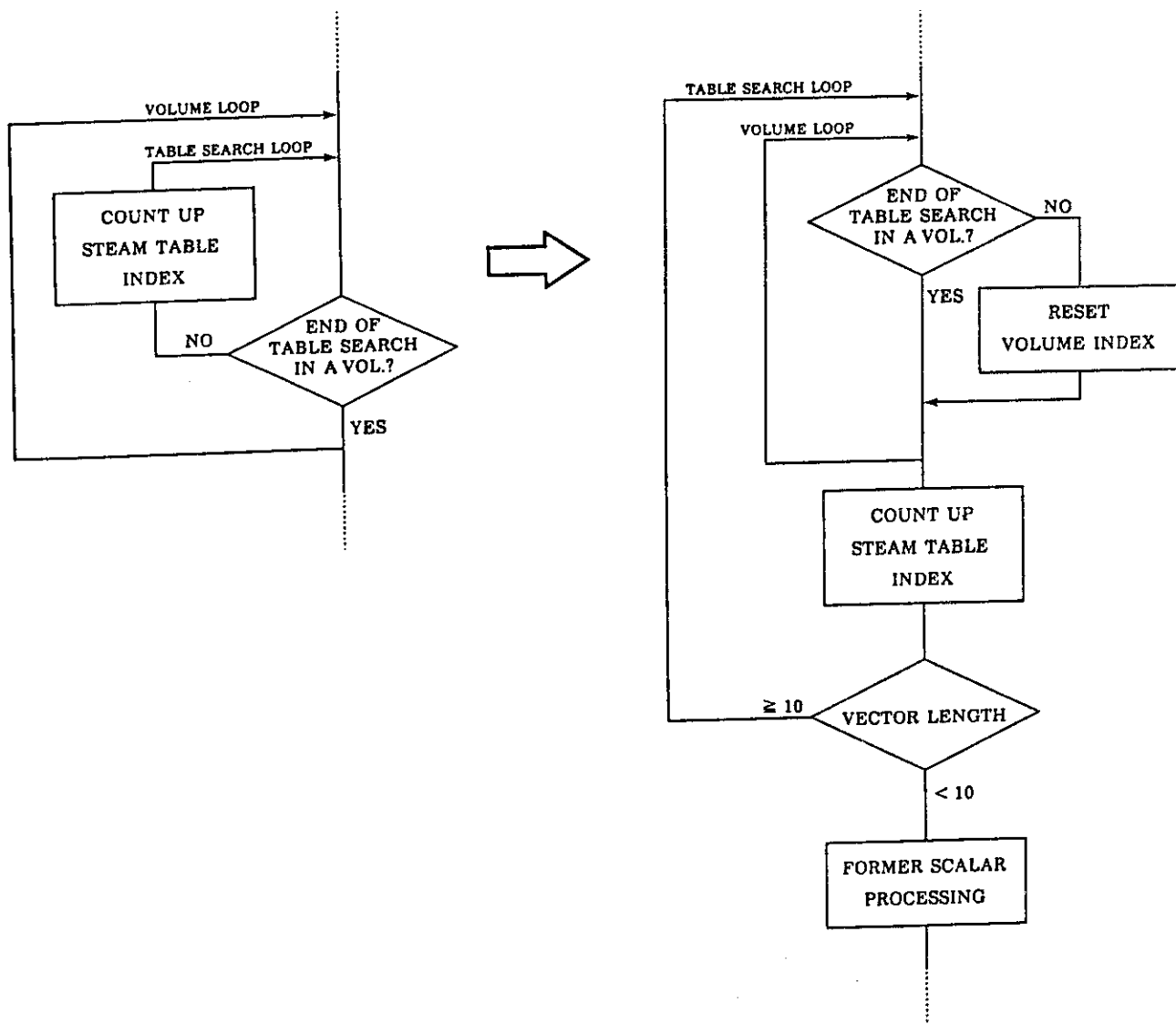


Fig. 3.6.4 Change of program flow for vectorized table look-up

3.7 Performance of vectorization

By these vectorization efforts, the vectorization ratio 78% was achieved. The vectorized RELAP5/MOD3 runs in the vector mode 2.8 times faster than in the scalar mode on FACOM VP2600 for the type TYPPWR problem (100 sec. small break loss of coolant flow accident). These performance numbers are obtained from the following measured data:

SS	Nonvectorized FACOM version in scalar mode	37.17 sec.
VS	Vectorized FACOM version in scalar mode	38.23 sec.
VV	Vectorized FACOM version in vector mode	13.88 sec. (VU time 5.24)

Here VU time is the time spent on the vector unit of VP2600 (see Fig. 1.1.1). Vectorization ratio (V) is derived using Amdahl's law ^{*10} as follows:

$$P = 1 / (1 - V + V / \alpha) \quad (1)$$

where P is the speedup ratio compared with the scalar mode and interpreted as

$$P = (\text{time on VS}) / (\text{time on VV}) = 2.8, \quad (2)$$

and α is acceleration ratio in vector mode.

The ratio

$$VU = (\text{VU time}) / (\text{time on VV}) = 0.378 \quad (3)$$

is as called as VU ratio. Then the VU means in the Amdahl's law as

$$VU = V / \alpha / (1 - V + V / \alpha), \quad (4)$$

it follows:

$$V / \alpha = (1 - V) / (1 - VU) * VU. \quad (5)$$

From eqs. (4) and (5)

$$P = VU / (V / \alpha) = (1 - VU) / (1 - V). \quad (6)$$

Consequently, we have

$$V = 1 - (1 - VU) / P = 1 - (1 - 0.378) * 0.363 = 0.78 \quad (7)$$

$$\alpha = P * V / VU = V * (1 - VU) / VU * (1 - V) = 5.7 \quad (8)$$

Tables 3.7.1, 3.7.2 and 3.7.3 represents the timing data for each calculational block of SS, VS, and VV, respectively, for the TYPPWR problem. Fig. 3.7.1 shows the program flow of the vectorized RELAP5/MOD3 accompanied with the time percents and speedup ratio to vector mode to scalar mode calculations for the same problem.

Table 3.7.4 is the summary of computing time of the vectorized RELAP5/MOD3, in scalar and vector modes. Here the vector to scalar speedup ratios in the vectorized version are presented in parentheses. The discrepancy of time step numbers among calculations is caused from the difference of arithmetic

operation order between nonvectorized and vectorized codes, and between vector and scalar modes such as summation.

From above performance tables and figure, we can see that the vectorized RELAP5/MOD3 runs 7.2 times faster than the real time (100sec.) on the FACOM VP2600. In the TYPPWR problem, the volume number 139, junction number 142, heat structure number 83, and heat mesh point or interval number 393 are calculated. But in the practical calculation at JAERI these numbers becomes larger and then higher speedup ratio is expected.

Table 3.7.1 CPU time table of nonvectorized code in scalar mode (SS)

TRANSIENT TIMING INFORMATION			
SUBROUTINE	ENTRIES	TIME(SEC)	FRACTION
DTSTEP	687	1.3126	0.0364
STATE(R)	59	0.4602	0.0128
TRIP	627	0.0188	0.0005
HTADV	686	2.3939	0.0664
HTCOND	56938	2.3350	0.0648
STATE(T)	686	0.0775	0.0022
JPROP	2803	0.5986	0.0166
VOLVEL	686	0.7893	0.0219
PACKER	686	0.1656	0.0046
PHAINT	686	7.1020	0.1970
HZFLOW	2744	0.3647	0.0101
FWDRAG	686	1.7796	0.0494
HLOSS	686	0.4560	0.0127
VEXPLT	686	2.4895	0.0691
VLVELA	627	0.5548	0.0154
PRESEQ	1268	3.9568	0.1098
SYSSOL	1268	1.6744	0.0465
VFINL	686	0.7108	0.0197
EQFINL	686	2.3719	0.0658
STATE(A)	636	5.2576	0.1459
RKIN	627	0.0901	0.0025
CONVAR	627	0.0595	0.0017
SBTRAN	0	0.0	0.0
SBNTAC	0	0.0	0.0
JCHOKE	686	1.0001	0.0277
FUELAN	0	0.0	0.0
CYLIN	0	0.0	0.0
SLABC	0	0.0	0.0
FPRTR	0	0.0	0.0
TSINT	0	0.0	0.0
ZSOLV	0	0.0	0.0
DERV1	0	0.0	0.0
DERV3	0	0.0	0.0
FMIX	0	0.0	0.0
VALVE	686	0.0245	0.0007
TOTAL		36.0436	
NO PLOTS MADE			

Table 3.7.2 CPU time table of vectorized code in scalar mode (SV)

TRANSIENT TIMING INFORMATION			
SUBROUTINE	ENTRIES	TIME(SEC)	FRACTION
DTSTEP	655	1.3034	0.0351
STATE(R)	44	0.3818	0.0103
TRIP	610	0.0191	0.0005
HTADV	654	2.4596	0.0662
HTCOND	654	1.9650	0.0529
STATE(T)	654	0.0731	0.0020
JPROP	2660	0.5800	0.0156
VOLVEL	654	0.7541	0.0203
PACKER	654	0.1721	0.0046
PHAINT	654	8.6012	0.2314
HZFLOW	2616	0.3383	0.0091
FWDRAG	654	1.6953	0.0456
HLOSS	654	0.4646	0.0125
VEXPLT	654	2.3750	0.0639
VLVELA	610	0.5414	0.0146
PRESEQ	1208	3.9361	0.1059
SYSSOL	1208	1.5945	0.0429
VFINL	654	0.6801	0.0183
EQFINL	654	2.2787	0.0613
STATE(A)	617	5.6875	0.1530
RKIN	610	0.0882	0.0024
CONVAR	610	0.0534	0.0014
SBTRAN	0	0.0	0.0
SBNTAC	0	0.0	0.0
JCHOKE	654	1.0942	0.0294
FUELAN	0	0.0	0.0
CYLIN	0	0.0	0.0
SLABC	0	0.0	0.0
FPRTR	0	0.0	0.0
TSINT	0	0.0	0.0
ZSOLV	0	0.0	0.0
DERV1	0	0.0	0.0
DERV3	0	0.0	0.0
FMIX	0	0.0	0.0
VALVE	654	0.0270	0.0007
TOTAL		37.1637	
NO PLOTS MADE			

Table 3.7.3 CPU time table of vectorized code in vector mode (VV)

TRANSIENT TIMING INFORMATION			
SUBROUTINE	ENTRIES	TIME(SEC)	FRACTION
DTSTEP	656	0.9828	0.0745
STATE(R)	44	0.1173	0.0089
TRIP	611	0.0174	0.0013
HTADV	655	0.4835	0.0367
HTCOND	655	0.7107	0.0539
STATE(T)	655	0.0733	0.0056
JPROP	2664	0.1922	0.0146
VOLVEL	655	0.1140	0.0086
PACKER	655	0.0741	0.0056
PHAINT	655	3.3333	0.2527
HZFLOW	2620	0.1091	0.0083
FWDRAG	655	0.2532	0.0192
HLOSS	655	0.3480	0.0264
VEXPLT	655	0.3756	0.0285
VLVELA	611	0.1088	0.0082
PRESEQ	1246	0.8531	0.0647
SYSSOL	1246	1.6057	0.1217
VFINL	655	0.1230	0.0093
EQFINL	655	0.4226	0.0320
STATE(A)	618	1.9112	0.1449
RKIN	611	0.0865	0.0066
CONVAR	611	0.0384	0.0029
SBTRAN	0	0.0	0.0
SBNTAC	0	0.0	0.0
JCHOKE	655	0.8327	0.0631
FUELAN	0	0.0	0.0
CYLIN	0	0.0	0.0
SLABC	0	0.0	0.0
FPRTR	0	0.0	0.0
TSINT	0	0.0	0.0
ZSOLV	0	0.0	0.0
DERV1	0	0.0	0.0
DERV3	0	0.0	0.0
FMIX	0	0.0	0.0
VALVE	655	0.0237	0.0018
TOTAL		13.1902	
NO PLOTS MADE			

Table 3.7.4 Timming comparison of vectorized RELAP5/MOD3 for TYPPWR
100 sec. small break LOCA

Version	Time-steps	Heat	Hydro	State	Others	Total
Nonvectorized scalar (SS)	687	4.7 (0.94)	23.1 (1.04)	5.3 (1.07)	2.8 (1.04)	36.0 (1.03)
Vectorized scalar (VS)	655	4.4 (1.0)	24.1 (1.0)	5.7 (1.0)	2.9 (1.0)	37.1 (1.0)
Vectorized Vector (VV)	656	1.19 (3.7)	7.98 (3.2)	1.91 (3.0)	2.10 (1.4)	13.19 (2.8)

Calculated problem: 139 volumes, 142 junctions, 83 heat structures, and 393 heat mesh points or intervals. Vectorization ratio 78%.

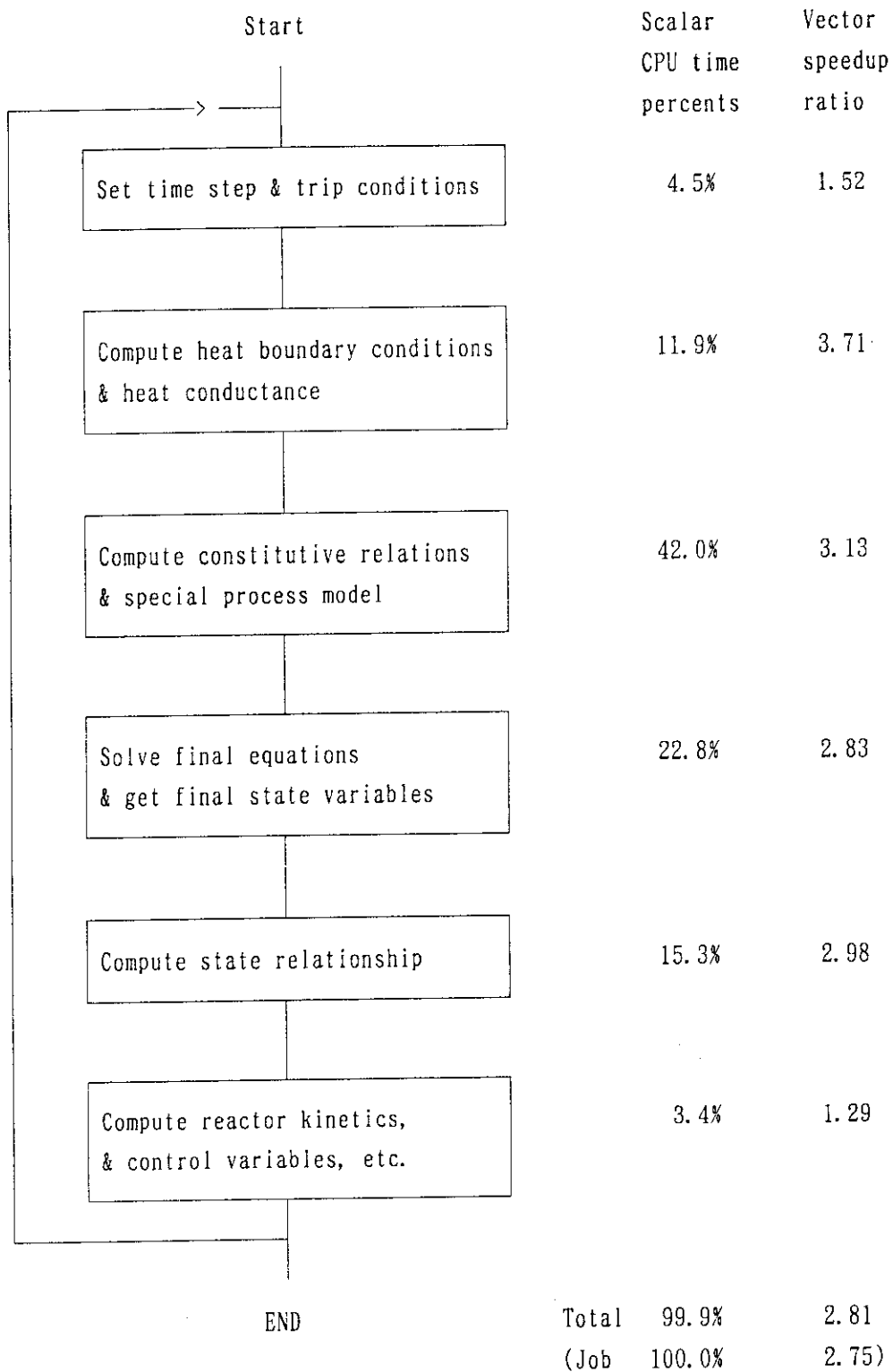


Fig. 3.7.1 Program flow, CPU time ratio in scalar mode, and speedup ratio of vector mode to scalar mode in vectorized RELAP5/MOD3

3.8 Verification of the computed results

In order to validate the vectorized RELAP5/MOD3, computed results are compared between INEL and JAERI codes and between nonvectorized and vectorized codes.

The computed results that were packed in the INEL transmittal tape are not always useful for verifying the JAERI RELAP5/MOD3 since out of seven results of problems only the EDHTRK problem was run with RELAP5/MOD3 on CRAY X-MP but the rest six problems were run with the preliminary code RELAP5/MOD2.5. Therefore, the results of EDHTRK have been compared between INEL CRAY and JAERI FACOM versions. Fig. 3.8.1 and Fig. 3.8.2 shows the comparison of water temperature and pressure at the outlet of the pipe, respectively. Here the nonvectorized scalar mode calculation (SS) is applied as the JAERI code. The computed results have a good agreement between two calculations.

Figs. 3.8.3 and 3.8.4 show the comparison between nonvectorized scalar (SS) and vectorized vector (VV) mode calculations of RELAP5/MOD3 of JAERI for the TYPPWR problem. In Fig. 3.8.2 and Fig. 3.8.3, the water temperature and pressure at the inlet of hotleg of regular side of the typical PWR is pictured, respectively. Agreement of the water temperatures is two figures. The discrepancy is caused from the difference of arithmetic operation order between scalar and vector operations such as summation, mathematical function evaluation (SIN, COS, LOG,), division, etc.*⁵ The computed results obtained from vectorized scalar mode calculation (VS) have the similar agreement with that of SS or VV.

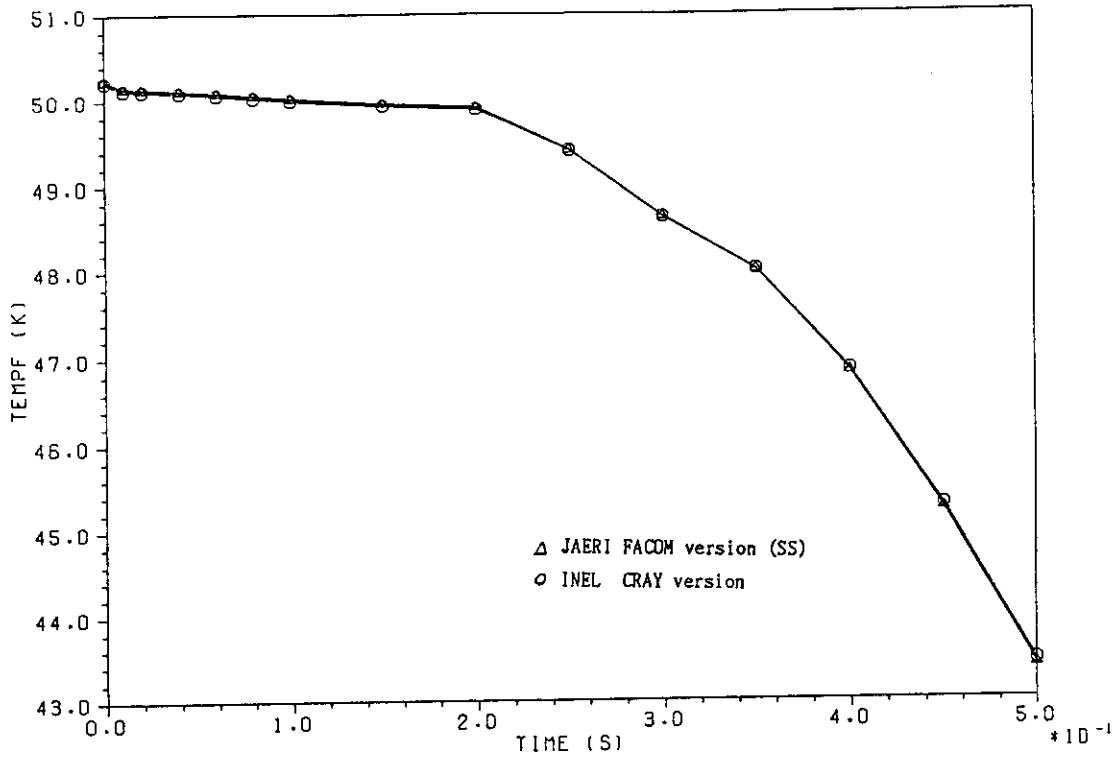


Fig. 3.8.1 Comparison of water temperatures between the INEL CRAY and JAERI FACOM versions for the problem EDHTRK

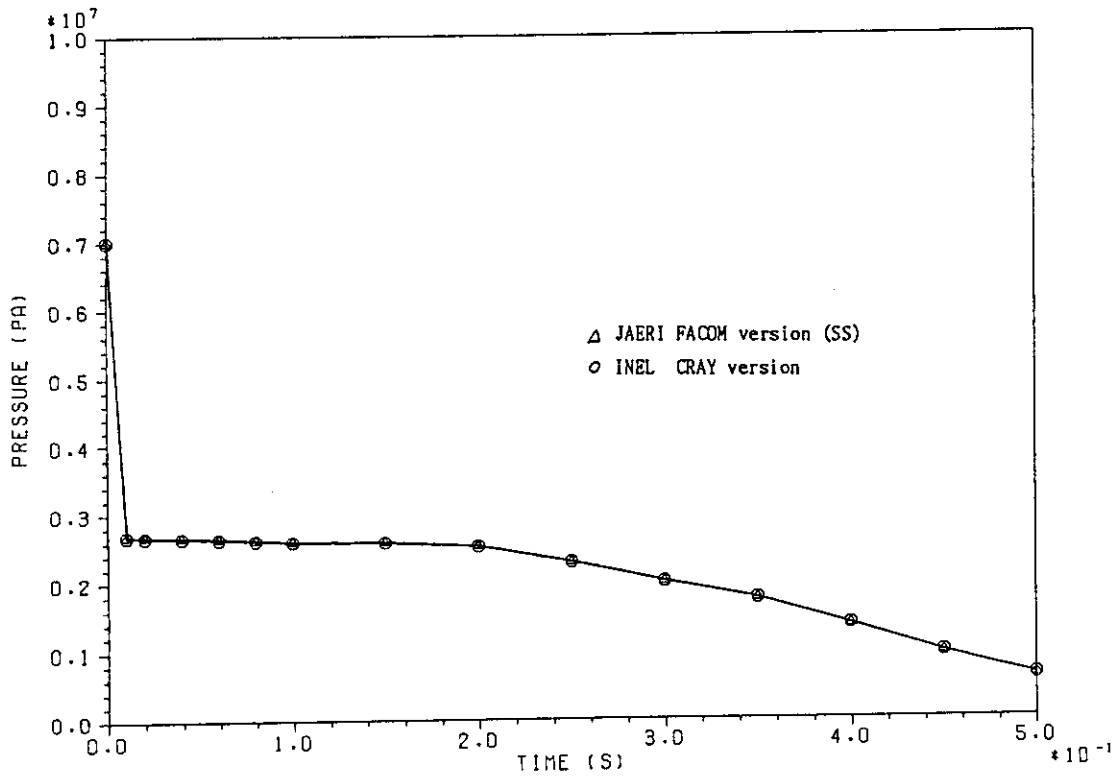


Fig. 3.8.2 Comparison of pressures between the INEL CRAY and JAERI FACOM versions for the problem EDHTRK

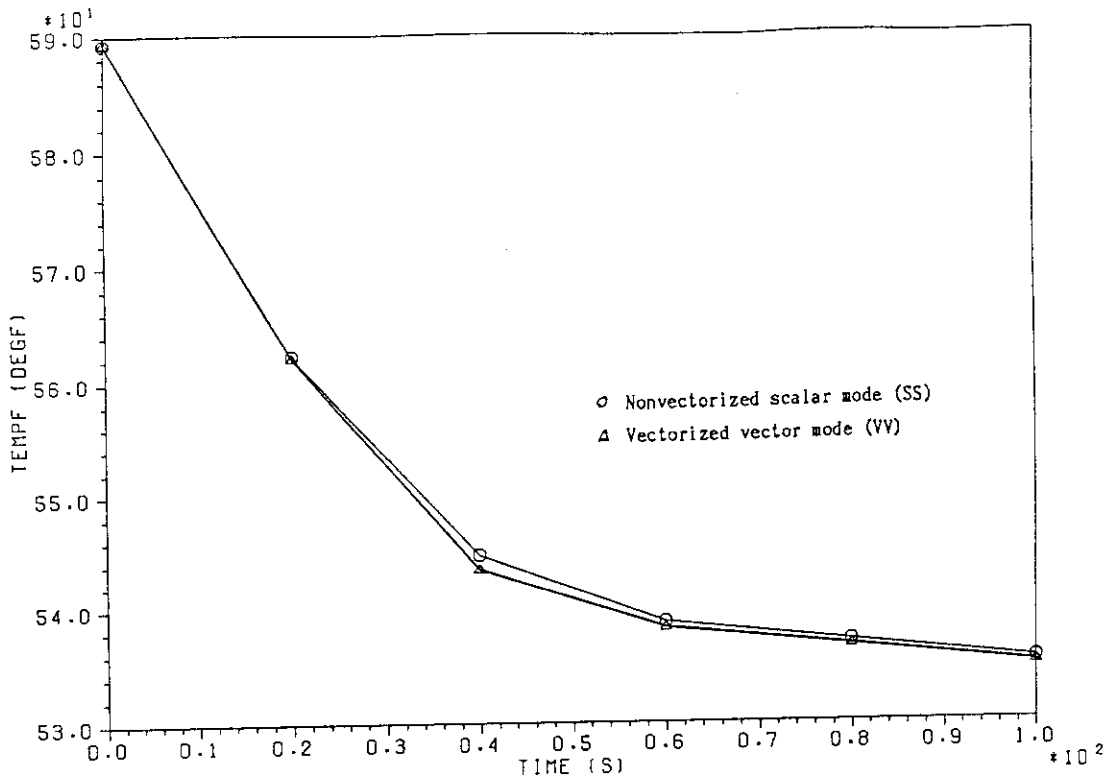


Fig. 3.8.3 Comparison of water temperatures between the JAERI nonvectorized scalar (SS) and JAERI vectorized vector (VV) mode calculations for the problem TYPWR

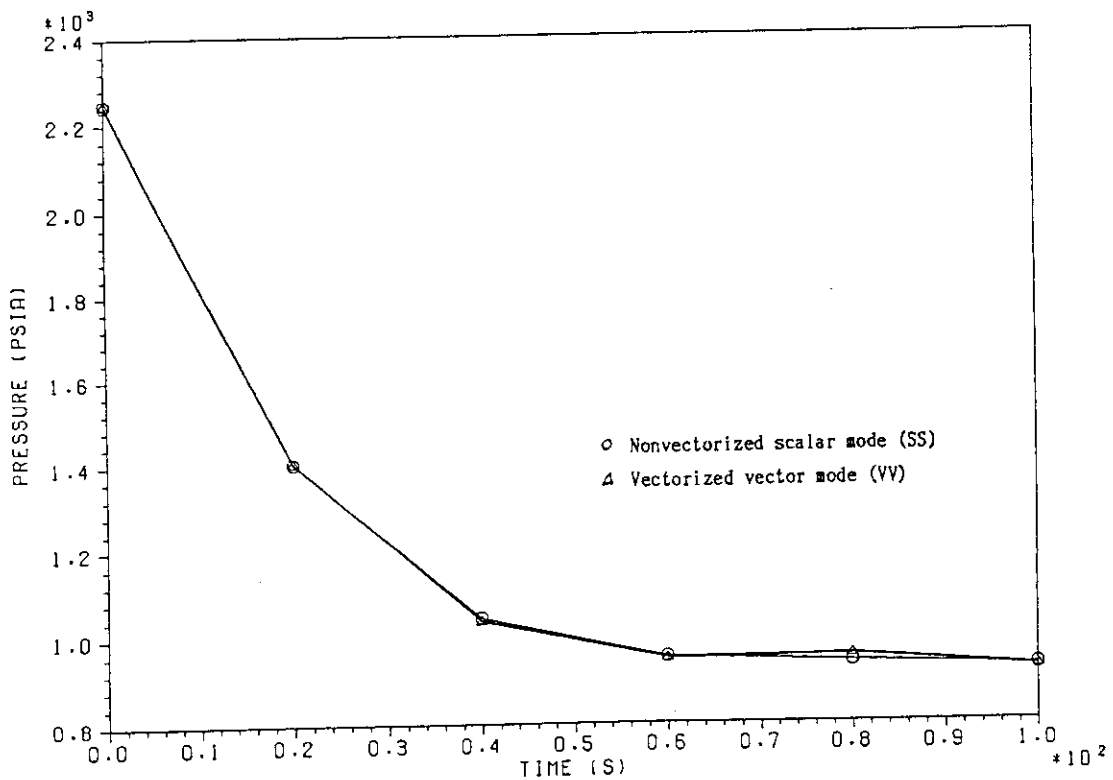


Fig. 3.8.4 Comparison of pressures between the JAERI nonvectorized scalar (SS) and JAERI vectorized vector (VV) mode calculations for the problem TYPWR

4. Concluding Remarks

The conversion from INEL IBM version to FACOM version was accomplished. The FACOM version has been vectorized for using FACOM VP2600 supercomputer. The vectorization ratio 78% is achieved and the obtained speedup ratio is 2.8 times compared with scalar calculation for the typical PWR problem (TYPPWR) which was provided by INEL. This ratio will increase for the practical problems at JAERI because longer vector length is expected. The computed results of the FACOM vectorized RELAP5/MOD3 have a good agreement with that of INEL CRAY version. The computed results also have a good agreement between scalar and vector mode calculations of the FACOM vectorized RELAP5/MOD3.

The manpower used for implementing FACOM nonvectorized version was three months by one person and another three months by two persons were required for the vectorization.

This report is firstly aimed at the information exchange between USNRC and JAERI under the ROSA-IV project to show the methods applied at JAERI and to help other IBM or FACOM users of the world to implement own version.

We also hope that the descriptions in this report are useful for the future code conversion and vectorization at JAERI.

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