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DEVELOPMENT OF ANALYSIS CODE FOR THERMAL HYDRO-
DYNAMICS OF MARINE REACTOR UNDER MULTI-DIMENSIONAL
SHIP MOTIONS, RETRAN-02/GRAV
(IMPROVEMENT OF RETRAN-02 AND EXPERIMENTAL ANALYSES)

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Development of Analysis Code for Thermal Hydro-dynamics of
Marine Reactor under Multi-dimensional Ship Motions, RETRAN-02/GRAV
(Improvement of RETRAN-02 and Experimental Analyses)

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We have improved a computer code RETRAN-02/GRAV for analysing thermal-hydro dynamics of a marine reactor plant under ship motions as a tool for research and development of marine reactor. The RETRAN-02 bases originally on one-dimensional model. Some improvement of the original RETRAN code has been made in analysis of thermal hydro-dynamics of a heaving (vertical movement) and a rolling (rotational movement), as well as a stationary inclination, on vertical acceleration by one-dimensional model, on inclination by two-dimensional model, on vertical and horizontal acceleration by two-dimensional model, and on arbitrary rotation by three-dimensional model.

We have checked the improved models by analyses of some experiments: single-phase and two-phase natural circulation flows under heaving, single-phase natural circulation with rolling and the single-phase natural circulation at stationary inclination attitude. The analyzed results verify the presented model to be capable to simulate well the ship motions.

As an application of RETRAN-02/GRAV, the nuclear powered ship Mutsu has been analysed to provide useful information for planning of the experiment in the Mutsu experimental voyage.

Keywords: Thermal Hydraulic Analysis, RETRAN-02, Marine Reactor, Ship Motion, Three-dimensiona, Mutsu Experimental Vapor, Heaving, Rolling

* IEA of Japan CO., Ltd.

多次元船体運動下での船用炉熱水力挙動解析コード
RETRAN-02/GRAVの開発
(RETRAN-02コードの改良及び実験解析)

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船体運動条件下での原子炉プラント熱水力挙動を解析できるRETRAN-02/GRAVを開発した。RETRAN-02コードはもともと一次元モデルを対象としているが、船体運動による原子炉プラント熱水力挙動への影響として、ヒービング（上下動加速度運動）、ローリング（横揺れ運動）及びピッチング（縦揺れ運動）、ならびに船体定傾斜の組合せが考慮できるよう多次元モデルへの拡張を行った。

この改良したコードの機能を、これまで行われたいくつかの実験、すなわち、ヒービング状態での単相及び二相自然循環実験、ローリング状態下での単相自然循環実験、及び定傾斜状態下での単相自然循環実験について解析を行い、十分実験結果を模擬できることを明らかにした。

実機への応用として、船体運動が原子力「むつ」炉に及ぼす影響を把握するために、ヒービング、ローリング及び定傾斜状態でのプラント挙動を解析し、「むつ」実験航海の実験海域の条件選定に役立てた。

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1. Introduction

The marine reactor plant is influenced thermal-hydraulically by various ship motions. There are six ship motions caused mainly by swell, wind wave or ship maneuvering : heaving, swaying, surging, pitching, rolling, and yawing as shown in Fig. 1.1 The former three are linear motions and the latter three are rotational motions. Thermal-hydraulic behavior of a marine reactor is influenced by ship stationary inclining as well as by above mentioned ship motions. The effects of heaving, rolling and stationary inclining are dominant in ship motions and very important for design and operation of marine reactors.

Although several experimental studies have been found about the effect of heaving on the critical heat flux⁽¹⁻³⁾ and about the effect of heaving or rolling on natural circulation flow in the primary side⁽⁴⁻⁶⁾, little research has so far been conducted on analytical research i.e. code development.

We have improved the RETRAN-027) so as to be capable of simulating the thermal hydraulic transients under ship motions, named RETRAN-02/GRAV in order to apply to designing future marine reactors, and to analysis of the first Japanese nuclear powered ship N.S. Mutsu for predicting the transient behavior in her experimental voyages.

N.S. Mutsu had been tested with heavy load changes during power-up test from March 29th to December 14th of 1990, and accordingly JAERI got the operational licence of Mutsu reactor. Experimental voyages commenced on February 25 of 1991 to obtain mainly the data upon the effect of ship motion and ship maneuvering on the reactor under four sea states : calm sea, ordinary sea, rough sea and tropical sea.

Some of the Mutsu power-up test have been analysed using RETRAN-02/GRAV code developed by us and a good agreement between the tests and the RETRAN-02/GRAV analyses have been obtained. The power-up test was performed in the calm sea condition, although the effects of the ship motions on reactor were small. The experimental voyages are scheduled to be done on various sea conditions in order to study the effects of ship motions on

scheduled to be done on various sea conditions in order to study the effects of ship motions and ship maneuverings on reactor. The analyses of Mutsu reactor using RETRAN-02/GRAV have been done to provide quantitative information for planning of the experiment in the Mutsu experimental voyage.

Present report describes the improvements in RETRAN-02/GRAV, the verification through some experiments, and the analyses of the Mutsu experimental voyage. The report includes the following items :

- a. improvement for stationary inclination,
- b. improvement for heaving,
- c. improvement for rolling,
- d. improvement for three-dimensional ship motion,
- e. verification through experiment under stationary inclination,
- f. verification through experiments under heaving,
- g. verification through experiment under rolling, and
- h. analyses of N.S. Mutsu reactor under ship motions.

We believe that the present code improvement for simulation of two-dimensional motion and three-dimensional ship movement is a first trial over the world as an expansion of large thermal hydro-dynamic code RETRAN which bases on one-dimensional analysis with a node-junction method for general use.

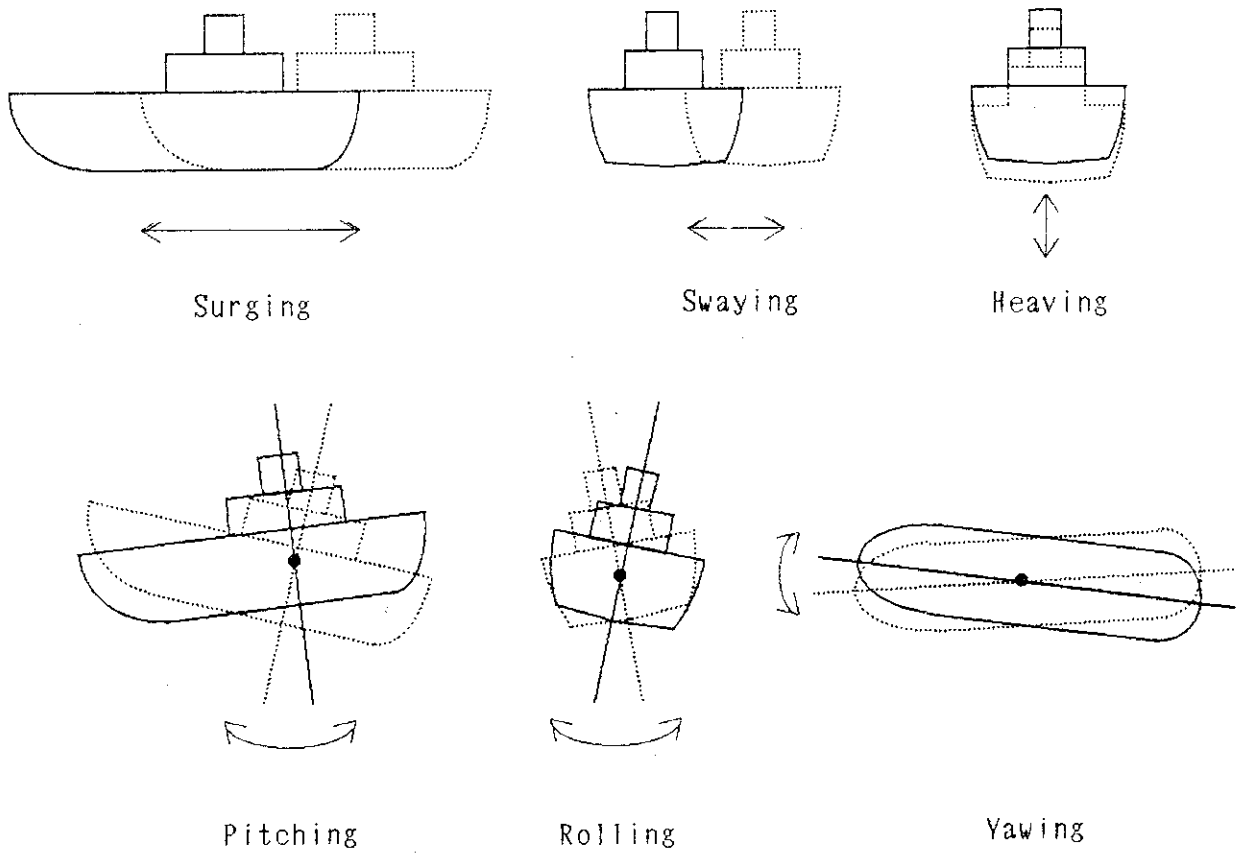


Fig. 1.1 Six Types of Ship Motion

2. Description of Improvement in RETRAN-02/GRAV Code

The RETRAN-02 is a code widely used for best-estimate transient thermal-hydraulic analysis of light water reactor systems. The RETRAN code has been originally developed based on the RELAP4/003 UPDATE 85 code and by taking up the function of control logic in to the RELAP/E code which has been improved mainly using the experimental data. We have improved the RETRAN-02 code to be capable of simulating some ship motions : We named it RETRAN-02 /GRAV code.

The technical nomenclature found in the following equations were listed in in pages 81 and 82.

2.1 Basic Conservation Equations and Model Geometry in RETRAN-02

In the RETRAN-02, the fluid balance equations of mass, momentum and energy are based on the integral macroscopic balances between average flow and state of fluid volume. These equations are applied to volume-junction (or node-flowpass) basis, as illustrated in Fig. 2.1.1 (see reference⁽⁷⁾ for the details). A hydraulic network can be represented by a number of control control volumes connected by junctions. While the conservation equations for for mass and energy and the state equation are applied to each volume, the momentum equation is applied to the junction. That is , the staggered mesh method is adopted in the RETRAN. The geometry of the volume is taken as a straight tube. Thus, the geometric characteristics of the network must be supplied in the RETRAN-02 based on the fixed spatial locations.

The conservation equations of mass and energy are scalar equations and then the sign of mass flow rate is very important. With the mass inflow at point point 'i-1' and the mass outflow at point 'i' , the conservation equation of of mass for volume 'k' is given as follows :

$$\frac{dM_k}{dt} = W_{i-1} - W_i, \quad (2.1.1)$$

where,

$$M_k = \bar{\rho}_k V_k, \quad (2.1.1a)$$

$$W_{i-1} = (\rho A v)_{i-1}, \quad (2.1.1b)$$

and

$$W_i = (\rho A v)_i \quad (2.1.1c)$$

The conservation of energy for volume 'k' is also given as follows:

$$\begin{aligned} \frac{dU_k}{dt} = & -\frac{1}{2} \frac{L_k}{A_k} \frac{d}{dt} \left(\frac{\bar{W}_k^2}{\rho_k} \right) + W_{i-1} \left[h_{i-1} + \left(\frac{W}{\rho A} \right)_{i-1} + g (Z_{i-1} - Z_k) \right] \\ & - W_i \left[h_i + \left(\frac{W}{\rho A} \right)_i + g (Z_i - Z_k) \right] + Q_{wm}, \end{aligned} \quad (2.1.2)$$

where,

$$U_k = M_k u_k, \quad (2.1.2a)$$

$$\bar{W}_k = \bar{\rho}_k A_k v_k, \quad (2.1.2b)$$

The pressure in the volume 'k' is obtained from the mass and energy.

$$P_k = P_k(M_k, U_k), \quad (2.1.2c)$$

These conservation laws are a general representation of mass and energy for control volume.

Next, the following momentum equation for a homogeneous mixed flow is given by assuming that all the directions of inflow and outflow are perpendicular to, respectively, the surfaces 'Ak' and 'Ai'.

$$\begin{aligned}
\left[\frac{1}{2} \frac{L_k}{A_k} + \frac{1}{2} \frac{L_{k+1}}{A_{k+1}} \right] \frac{dW_i}{dt} = & \frac{\bar{W}_k^2}{\rho_k A_k^2} - \frac{\bar{W}_{k+1}^2}{\rho_{k+1} A_{k+1}^2} + P_k - P_{k+1} \\
& - \frac{1}{A_k} F_{w,k} - \frac{1}{A_{k+1}} F_{w,k+1} \\
& - \bar{\rho}_k (Z_i - Z_k) g_{z,k} - \bar{\rho}_{k+1} (Z_{k+1} - Z_i) g_{z,k+1} \\
& + \frac{1}{2} \frac{W_i^2}{\rho_i} \left[\frac{1}{A_{k+1}^2} - \frac{1}{A_k^2} \right] - \frac{1}{2} W_{i1} W_{i2} \frac{e_i}{\rho_i A_i^2},
\end{aligned} \tag{2.1.3}$$

where the first and the second terms in the right hand are the momentum flux, flux, the sum of the third and the fourth terms are the pressure difference, the fifth and the sixth terms are the wall frictions, the seventh and the eighth terms are the water head, and the sum of the ninth and the tenth terms is the dynamic energy balance.

These equations used in the RETRAN-02 are based on the one-dimensional model. In the RETRAN-02/GRAV these equations will be modified to consider ship motion simulation as shown in the following sections. Keep in mind in simulation of ship motions that the relative positions of the control volumes and volumes and junctions do not change, even when the whole system changes owing to ship motions : the solid state model is maintained through transient.

2.2 Stationary Inclination

2.2.1 Analytical Model

The stationary inclination of ship (called as heeling) changes the vertical height and the elevation of the volume and junction which are originally fixed to an initial spatial location used in the RETRAN-02. Three analytical models to be modified are shown in the following.

(1) Vertical volume

Figure 2.2.1 shows a simple vertical tube, which is modelled as a RETRAN noding (see Fig. 2.2.2). When the tube is inclined at degrees of θ as shown in

in Fig. 2.2.3, the actual volume height changes from L to $L \cdot \cos \theta$ while the volume inventory and flow area remain the same ones (see Fig. 2.2.4).

(2) Horizontal volume

Figure 2.2.5 shows a simple horizontal tube which is modelled as a RETRAN nodding (see Fig. 2.2.6). The horizontal tube, which does not have substantial volume height from the beginning in the RETRAN nodding, will have the vertical height by inclination of the volume. When the tube is inclined at the degree of θ as shown in Fig. 2.2.7, a relationship between upper and lower sides in the volume ends should be taken account : The volume height changes from zero to $-L \cdot \sin \theta$ viewing from the left side and to $L \cdot \sin \theta$ viewing from the right side, as shown in Fig. 2.2.8.

(3) Water level

Water level is modelled in a RETRAN volume as shown in Fig. 2.2.9. Steam flows out through the junction J1 of which elevation is higher than the water level. Water flows out through the junction J2 of which elevation is lower than the water level. In inclination it sometimes happens to occur that that the junction J1 becomes lower than the water level or the junction J2 becomes higher than the water level as shown in Fig. 2.2.10. This means that an enthalpy of junction flow will change also by inclination.

Those models are taken into the momentum and the energy equations, as shown in the following.

2.2.2 Momentum Equation

The water head term in the momentum equation of RETRAN should be modified as follows. The water head is represented as head from the center of upstream volume to the center of downstream volume. For example, as shown in Fig. 2.2.11 the water head is given as follows:

$$\begin{aligned} H &= -\bar{\rho}_k (Z_j - Z_k) g_z - \bar{\rho}_{k+1} (Z_{k+1} - Z_i) g_z \\ &= \bar{\rho}_1 \{c_1 - (e_j - e_1)\} g_z - \bar{\rho}_2 \{c_2 - (e_j - e_2)\} g_z, \quad (2.2.1) \end{aligned}$$

where c_i is the height from bottom to center of volume i , e_i is the height from a base line to the bottom of the volume i or of a junction level. That is, the water head is the vertical length between volumes or junctions.

We consider the volume configuration shown in Fig. 2.2.12. The blank circle marks are the junction levels and the solid circle mark is the geometric center of volume. Length $RELZl$ is the height of junction connected to the volume from left side, $RELZr$ from right side, and $CMAS$ is the height of volume center. Inclination of the volume configuration is represented in Fig. 2.1.13. Actual height changes from $RELZl$ to $RELZl'$, from $RELZr$ to $RELZr'$, and from $CMAS$ to $CMAS'$ according to inclination. We have introduced a new parameter of the horizontal volume length BOT . Relationship of the length between before and after inclination is given using BOT and θ as follows:

$$CMAS' = CMAS \cdot \cos \theta, \quad (2.2.2)$$

$$RELZl' = RELZl \cdot \cos \theta + 0.5 \cdot BOT \cdot \sin \theta, \quad (2.2.3)$$

$$RELZr' = RELZr \cdot \cos \theta - 0.5 \cdot BOT \cdot \sin \theta. \quad (2.2.4)$$

We need to define whether a junction should be connected to the right side or left side of the volume, since the original one-dimensional RETRAN code can not distinguish the sides of the volume. In the RETRAN-02/GRAV a new parameter of flag 'iflag' is introduced. With 'iflag', the length of $RELZl'$ and $RELZr'$ are given as follows:

$$RELZ' = RELZ \cdot \cos \theta + 0.5 \cdot BOT \cdot \sin \theta \cdot iflag. \quad (2.2.5)$$

The parameter 'iflag' is set to +1 for the junction of which position goes upward (as $RELZl'$ in Fig. 2.2.13) and to -1 for the junction downward (see $RELZr'$ in the figure). If a position of junction is the top or bottom of the volume, the 'iflag' is set to zero.

2.2.3 Energy Equation

Elevation energy term and flow-out enthalpy term from junction should be modified. The elevation energy term is treated the same as the water head term in the momentum equation. The flow-out enthalpy term is described for the volume with water level as follows.

Figure 2.2.14 shows the water level in the upright state. The water level is ZM from the bottom. Blank circle marks are the positions of junction. Steam flows out through the junction of which level is higher than the water level and saturated water flows out through the junction lower than the water level. When the volume inclines by degree of θ as shown in Fig. 2.2.15, the water level changes from ZM to ZM' , and the junction positions change from $RELZl$ to $RELZl'$, and from $RELZr$ to $RELZr'$. The water level ZM' is given by ZM and θ . That is,

$$ZM' = ZM \cdot \cos \theta, \quad (2.2.6)$$

Comparing the $RELZl'$ or $RELZr'$ to ZM' , the junction enthalpy can be decided by whether the junction property is steam or saturated water.

2.3 Heaving

Heaving gives a plant system a uniform time-dependent vertical acceleration. This acceleration adds to the momentum equation and energy equation under the steady gravitational acceleration. We call the vertical acceleration due to heaving as $g(t)$ and the gravitational acceleration as g_z , and the ratio of $g(t)/g_z$ as the normalized acceleration $\beta(t)$ in the present paper.

2.3.1 Momentum Equation

The momentum equation (see Eq. 2.1.3) is divided by g_z to treat the

pressure as engineering unit in RETRAN code as follows:

$$\begin{aligned}
 \frac{1}{g_z} \left[\frac{1}{2} \frac{L_k}{A_k} + \frac{1}{2} \frac{L_{k+1}}{A_{k+1}} \right] \frac{dW_i}{dt} = & \left[\frac{\bar{W}_k}{\rho_k A_k^2} - \frac{\bar{W}_{k+1}}{\rho_{k+1} A_{k+1}^2} \right] \frac{1}{g_z} + P'_k - P'_{k+1} \\
 & + \left[-\frac{1}{A_k} F_{w,k} - \frac{1}{A_{k+1}} F_{w,k+1} \right] \frac{1}{g_z} \\
 & - \bar{\rho}_k (Z_i - Z_k) - \bar{\rho}_{k+1} (Z_{k+1} - Z_i) \\
 & + \left\{ \frac{1}{2} \frac{W_i^2}{\rho_i} \left[\frac{1}{A_{k+1}^2} - \frac{1}{A_k^2} \right] - \frac{1}{2} W_{i1} W_{i2} \frac{e_i}{\rho_i A_i^2} \right\} \frac{1}{g_z},
 \end{aligned} \tag{2.3.1}$$

where the relationship of $g_{z,k} = g_{z,k+1} = g_z$ is used.

To take account of the uniform time-dependent vertical acceleration $g(t)$, we $g(t)$, we replace the $g_{z,k}$ and $g_{z,k+1}$ with $g(t)$ in the Eq. 2.1.3. Thus, we obtain, obtain,

$$\begin{aligned}
 \left[\frac{1}{2} \frac{L_k}{A_k} + \frac{1}{2} \frac{L_{k+1}}{A_{k+1}} \right] \frac{dW_i}{dt} = & \frac{\bar{W}_k}{\rho_k A_k^2} - \frac{\bar{W}_{k+1}}{\rho_{k+1} A_{k+1}^2} + P'_k - P'_{k+1} \\
 & - \frac{1}{A_k} F_{w,k} - \frac{1}{A_{k+1}} F_{w,k+1} \\
 & - \bar{\rho}_k (Z_i - Z_k) g(t) - \bar{\rho}_{k+1} (Z_{k+1} - Z_i) g(t) \\
 & + \frac{1}{2} \frac{W_i^2}{\rho_i} \left[\frac{1}{A_{k+1}^2} - \frac{1}{A_k^2} \right] - \frac{1}{2} W_{i1} W_{i2} \frac{e_i}{\rho_i A_i^2},
 \end{aligned} \tag{2.3.2}$$

Dividing both sides of Eq. 2.3.2 by g_z , the following equation is obtained.

$$\begin{aligned}
\frac{1}{g_z} \left[\frac{1}{2} \frac{L_k}{A_k} + \frac{1}{2} \frac{L_{k+1}}{A_{k+1}} \right] \frac{dW_i}{dt} = & \left[\frac{\bar{W}_k^2}{\rho_k A_k^2} - \frac{\bar{W}_{k+1}^2}{\rho_{k+1} A_{k+1}^2} \right] \frac{1}{g_z} + P'_k - P'_{k+1} \\
& + \left[-\frac{1}{A_k} F_{w,k} - \frac{1}{A_{k+1}} F_{w,k+1} \right] \frac{1}{g_z} \\
& - \left[\bar{\rho}_k (Z_i - Z_k) + \bar{\rho}_{k+1} (Z_{k+1} - Z_i) \right] \frac{g(t)}{g_z} \\
& + \left\{ \frac{1}{2} \frac{W_i^2}{\rho_i} \left[\frac{1}{A_{k+1}^2} - \frac{1}{A_k^2} \right] - \frac{1}{2} W_{i1} W_{i1} \frac{e_i}{\rho_i A_i^2} \right\} \frac{1}{g_z}
\end{aligned} \tag{2.3.3}$$

Comparing to Eq. 2.3.1, it is found that the water head term in the Eq. 2.3.3 is multiplied by $g(t)/g_z$. The pressure terms of Eq. 2.3.1 remain as the same as in the Eq. 2.3.3. The pressure is not affected by even gravitational acceleration change since the pressure term in Eq. 2.1.3 is a parameter of the absolute unit in the general steam table.

As a result, the momentum equation for heaving can be represented by multiplying by $\beta(t) (= g(t)/g_z)$ to the water head term in the original RETRAN RETRAN equation. In the code, the water head is obtained in the subroutine HEADC and it is used by multiplying by $\beta(t)$.

2.3.2 Energy Equation

The gravitational acceleration relates to only the elevation energy term in term in Eq. 2.1.2. Hence the energy equation for heaving is obtained by replacing g_z with $g(t)$ in the Eq. 2.1.2. Thus, we obtain,

$$\begin{aligned}
\frac{dU_k}{dt} = & -\frac{1}{2} \frac{L_k}{A_k} \frac{d}{dt} \left(\frac{\bar{W}_k^2}{\rho_k} \right) + W_{i-1} \left[h_{i-1} + \left(\frac{W^2}{\rho A} \right)_{i-1} + g(t) (Z_{i-1} - Z_k) \right] \\
& - W_i \left[h_i + \left(\frac{W^2}{\rho A} \right)_i + g(t) (Z_i - Z_k) \right] + Q_{wm}
\end{aligned} \tag{2.3.4}$$

In modification of the code the $g_{z(t)}$ is replaced with $g_z \cdot \beta(t)$.

2.3.3 Time-Dependent Acceleration

Acceleration due to heaving can be represented for a simple periodical oscillation as follows.

$$g(t) = g_z \cdot \left(1 + A \cdot \sin\left(\frac{2\pi}{T_g} t\right) \right), \quad (2.3.5)$$

$$\beta(t) = 1 + A \cdot \sin\left(\frac{2\pi}{T_g} t\right), \quad (2.3.6)$$

where A is the amplitude, and T_g is the period of oscillation. It is convenient in practice to use the control logic system of RETRAN for simulation of the normalized acceleration $\beta(t)$.

2.4 Rolling

Rolling is a kind of rotation which gives the plant system a time-dependent inclination with a centrifugal force and a tangential force. Figure 2.4.1 shows a schematic diagram of the volume under rolling. The time-dependent inclination of the volume by rolling can be represented by the same way as the stationary inclination except the time-dependency.

The tangential force which is zero for the rotation with iso-angular velocity usually is predominant in rolling. The fluid of the unit mass in the volume receives the centrifugal force as a function of angular velocity and the length from the center of rotation to the volume, that is $R \dot{\theta}^2$ as shown in the figure. The tangential force is a function of angular acceleration and length from the center of rotation to the volume, that is, $R \ddot{\theta}$.

These forces can be divided into the vertical and the horizontal components as follows.

$$f_v = R \dot{\theta}^2 \cos \theta - R \ddot{\theta} \sin \theta, \quad (2.4.1)$$

$$f_h = R \dot{\theta}^2 \sin \theta + R \ddot{\theta} \cos \theta. \quad (2.4.2)$$

The force f_v acts downward on the fluid as shown in the Fig. 2.4.1 when the

volume is below than the center of rotation, and the force f_v acts upward when the volume is above the center of rotation.

2.4.1 Momentum Equation

Rolling is the two-dimensional rotational motion. Since the RETRAN model is originally based on one-dimension, the two-dimensional forces, the vertical force and the horizontal force should be taken in account newly for rolling.

The vertical force f_v can add to the water head term in the momentum equation. On the other hand, there is not a horizontal water head term for the horizontal force f_h in the original RETRAN equation. We introduce the horizontal term using the horizontal length of the volume for tangential force $BOT \cdot \cos \theta$, where θ is the angle of volume to the horizontal axis.

$$\begin{aligned} \frac{1}{g_z} \left[\frac{1}{2} \frac{L_k}{A_k} + \frac{1}{2} \frac{L_{k+1}}{A_{k+1}} \right] \frac{dW_i}{dt} = & \left[\frac{\bar{W}_k}{\rho_k A_k} - \frac{\bar{W}_{k+1}}{\rho_{k+1} A_{k+1}} \right] \frac{1}{g_z} + P'_k - P'_{k+1} \\ & + \left[-\frac{1}{A_k} F_{w,k} - \frac{1}{A_{k+1}} F_{w,k+1} \right] \frac{1}{g_z} \\ & - \left[\bar{\rho}_k (Z_i - Z_k) + \bar{\rho}_{k+1} (Z_{k+1} - Z_i) \right] \frac{g(t) + f_v}{g_z} \\ & - \frac{1}{2} \left[\bar{\rho}_k \cdot BOT_k \cdot \cos \theta + \bar{\rho}_{k+1} \cdot BOT_{k+1} \cdot \cos \theta \right] \frac{f_h}{g_z} \\ & + \left\{ \frac{1}{2} \frac{W_i^2}{\rho_i} \left[\frac{1}{A_{k+1}^2} - \frac{1}{A_k^2} \right] - \frac{1}{2} W_i |W_i| \frac{e_i}{\rho_i A_i^2} \right\} \frac{1}{g_z} \end{aligned} \quad (2.4.3)$$

For the vertical volume, the tangential force is zero ($\theta = 90^\circ$, $\therefore \cos \theta = 0$) and for the horizontal volume, the force is $0.5 \cdot BOT \cdot A \cdot \rho \cdot f_h$ ($\theta = 0^\circ$, $\therefore \cos \theta = 1$).

2.4.2 Energy Equation

The horizontal head due to the tangential force together with the vertical force should be taken in energy equation. The elevation energy term are

represented using the vertical and horizontal terms as follows:

$$\begin{aligned} \frac{dU_k}{dt} = & -\frac{1}{2} \frac{L_k}{A_k} \frac{d}{dt} \left(\frac{\bar{W}_k^2}{\rho_k} \right) + Q_{wm} \\ & + W_{i-1} \left[h_{i-1} + \left(\frac{W^2}{\rho A} \right)_{i-1} + (g(t) + f_v) (Z_{i-1} - Z_k) \right. \\ & \qquad \qquad \qquad \left. + \frac{1}{2} f_h \cdot BOT_k \cdot \cos \theta \right] \\ & - W_i \left[h_i + \left(\frac{W^2}{\rho A} \right)_i + (g(t) + f_v) (Z_i - Z_k) \right. \\ & \qquad \qquad \qquad \left. - \frac{1}{2} f_h \cdot BOT_k \cdot \cos \theta \right], \end{aligned} \quad (2.4.4)$$

where the length of $1/2 \cdot BOT \cdot \cos \theta$ is used for the horizontal energy term. For the vertical volume, the horizontal energy term is zero, and for the horizontal volume, the energy term is $1/2 \cdot BOT \cdot f_h \cdot W$.

2.5 Three-Dimensional Motions

The ship motion practically works in three-dimensional movement since rolling and pitching do simultaneously. It is necessary to be capable of treating three-dimensional motion for estimation of the effect of real ship motion on the reactor plant system. We have improved that the RETRAN-02/GRAV can simulate the three-dimensional motions due to rolling and pitching in an arbitrary planes.

2.5.1 Modelling of Three-Dimensional Movement

(1) Rotation of co-ordinates

Let consider the vector $OP(x,y,z)$, in the three-dimensional rectangular co-ordinate as shown in Fig. 2.5.1. The OP is taken as the volume of which the point O fixed at the origin shows the flow inlet, and the point P the flow outlet.

The length of volume is γ . Each components of the vector to the x, y, z axes are

$$\begin{aligned}
 x &= \gamma \cos \theta \cdot \cos \phi, \\
 y &= \gamma \cos \theta \cdot \sin \phi, \\
 z &= \gamma \sin \theta.
 \end{aligned}
 \tag{2.5.1}$$

where $\phi = \angle xoy$, $\theta = \angle QOP$. The vector can move arbitrarily in the three-dimensional co-ordinates corresponding to ship motions with fixing the point 0 to the origin while the relationship between the volumes or junctions remains as the initial state. The movement of vector can be represented by rotations around each x axis, y axis, and z axis. The co-ordinate of point P(x,y,z) after rotation around each axis are obtained as follows.

First, when the vector rotates around z-axis by angle of ϕ_z the point P moves to Pz(xz, yz, zz). As shown in Fig. 2.5.2, the length of OP mapped on the xoy plane is rxy(= $\gamma \cos \theta$). The components xz, yz, zz are given as follows:

$$x_z = x \cos \phi_z - y \sin \phi_z, \tag{2.5.2}$$

$$y_z = y \cos \phi_z + x \sin \phi_z, \tag{2.5.3}$$

$$z_z = z, \tag{2.5.4}$$

Hence, the rotation around z-axis is represented by the matrix form.

$$\begin{bmatrix} x_z \\ y_z \\ z_z \end{bmatrix} = \begin{bmatrix} \cos \phi_z & -\sin \phi_z & 0 \\ \sin \phi_z & \cos \phi_z & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}.
 \tag{2.5.5}$$

Next, when the vector rotates around y-axis by angle of θ_y the point P moves to Py(xy, yy, zy). As shown in Fig. 2.5.3, the length of OP mapped on the xoz plane is taken as rxz. The components xy, yy, zy are given as follows:

$$x_y = x \cos \theta_y - z \sin \theta_y, \tag{2.5.6}$$

$$z_y = z \cos \theta_y + x \sin \theta_y, \tag{2.5.7}$$

$$y_y = y. \tag{2.5.8}$$

Hence, the rotation around y-axis is represented by the matrix form.

$$\begin{bmatrix} x_y \\ y_y \\ z_y \end{bmatrix} = \begin{bmatrix} \cos \theta_y & 0 & -\sin \theta_y \\ 0 & 1 & 0 \\ \sin \theta_y & 0 & \cos \theta_y \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad (2.5.9)$$

Finally, when the vector rotates around x-axis by angle of ζ_x the point P moves to $P_x(x_x, y_x, z_x)$. As shown in Fig. 2.5.4, the length of OP mapped on the xoz plane is ryz . The components x_x, y_x, z_x are given as follows:

$$z_x = z \cos \zeta_x - y \sin \zeta_x, \quad (2.5.10)$$

$$y_x = y \cos \zeta_x + z \sin \zeta_x, \quad (2.5.11)$$

$$x_x = x, \quad (2.5.12)$$

Hence, the rotation around x-axis is represented by the matrix form.

$$\begin{bmatrix} x_x \\ y_x \\ z_x \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \zeta_x & \sin \zeta_x \\ 0 & -\sin \zeta_x & \cos \zeta_x \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad (2.5.13)$$

The rotations of vector around z-axis by ϕ_z , around y-axis by θ_y , and around x axis by ζ_x are summarized as the matrix form.

$$\begin{bmatrix} X' \\ Y' \\ Z' \end{bmatrix} = \begin{bmatrix} \cos \phi_z & -\sin \phi_z & 0 \\ \sin \phi_z & \cos \phi_z & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos \theta_y & 0 & -\sin \theta_y \\ 0 & 1 & 0 \\ \sin \theta_y & 0 & \cos \theta_y \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \zeta_x & \sin \zeta_x \\ 0 & -\sin \zeta_x & \cos \zeta_x \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad (2.5.14)$$

The original position of the vector are set by three-dimensional co-ordinates. Therefore, the position of the vector expressed by rotation of arbitrary angle can be obtained by Eq. 2.5.14. The vertical height of the vector changes from z to z' by rotations.

(2) Centrifugal and tangential forces

Rotation induces the position change as well as the centrifugal and tangential forces in the fluid volume. Rotation of z -axis makes the point P' of volume acceleration on the x - y plane as shown in Fig.2.5.5, where the distances from the origin are R_x on the x -axis, R_y on the y -axis, and R_z on the z -axis.

$$\begin{aligned} \text{acceleration in centrifugal force} &: \overline{OP} \dot{\phi}^2 = (R_y^2 + R_x^2)^{1/2} \dot{\phi}^2, \\ \text{component of } x\text{-axis} &= R_x \dot{\phi}^2, \\ \text{component of } y\text{-axis} &= R_y \dot{\phi}^2, \end{aligned}$$

$$\begin{aligned} \text{acceleration in tangential force} &: \overline{OP} \ddot{\phi} = (R_y^2 + R_x^2)^{1/2} \ddot{\phi}, \\ \text{component of } x\text{-axis} &= R_y \ddot{\phi}, \\ \text{component of } y\text{-axis} &= -R_x \ddot{\phi}. \end{aligned}$$

The rotation of y -axis makes forces on the z - x plane as shown in Fig. 2.5.6.

$$\begin{aligned} \text{acceleration in centrifugal force} &: \overline{OP} \dot{\theta}^2 = (R_z^2 + R_x^2)^{1/2} \dot{\theta}^2, \\ \text{component of } x\text{-axis} &= R_x \dot{\theta}^2, \\ \text{component of } z\text{-axis} &= R_z \dot{\theta}^2, \end{aligned}$$

$$\begin{aligned} \text{acceleration in tangential force} &: \overline{OP} \ddot{\theta} = (R_z^2 + R_x^2)^{1/2} \ddot{\theta}, \\ \text{component of } x\text{-axis} &= R_z \ddot{\theta}, \\ \text{component of } z\text{-axis} &= -R_x \ddot{\theta}. \end{aligned}$$

The rotation of x -axis makes forces on the y - z plane as shown in Fig. 2.5.7.

$$\begin{aligned} \text{acceleration in centrifugal force} &: \overline{OP} \dot{\zeta}^2 = (R_y^2 + R_z^2)^{1/2} \dot{\zeta}^2, \\ \text{component of } y\text{-axis} &= R_y \dot{\zeta}^2, \\ \text{component of } z\text{-axis} &= R_z \dot{\zeta}^2, \end{aligned}$$

$$\begin{aligned} \text{acceleration in tangential force} &: \overline{OP} \ddot{\zeta} = (Ry^2 + Rz^2)^{1/2} \ddot{\zeta} \\ \text{component of y-axis} &= -Rz \ddot{\zeta} \\ \text{component of z-axis} &= Ry \ddot{\zeta} \end{aligned}$$

The acceleration components (α_x , α_y , α_z) of x-axis, y-axis, and z-axis are summarized in the matrix form as follows:

$$\begin{bmatrix} \alpha_x \\ \alpha_y \\ \alpha_z \end{bmatrix} = \begin{bmatrix} \dot{\phi}^2 + \dot{\theta}^2 & \ddot{\phi} & \ddot{\theta} \\ -\ddot{\phi} & \dot{\phi}^2 + \dot{\zeta}^2 & -\ddot{\zeta} \\ -\ddot{\theta} & \ddot{\zeta} & \dot{\theta}^2 + \dot{\zeta}^2 \end{bmatrix} \begin{bmatrix} R_x \\ R_y \\ R_z \end{bmatrix} \quad (2.5.15)$$

The distances of R_x , R_y , and R_z are obtained by multiplying the rotation matrix of co-ordinates (see Eq. 2.5.14) by initial co-ordinates of volume center.

2.5.2 Momentum Equation

The momentum equation for arbitrary three-dimensional rotation is represented by the following equation:

$$\begin{aligned} \frac{1}{g_z} \left[\frac{1}{2} \frac{L_k}{A_k} + \frac{1}{2} \frac{L_{k+1}}{A_{k+1}} \right] \frac{dW_i}{dt} &= \left[\frac{\bar{W}_k}{\rho_k A_k^2} - \frac{\bar{W}_{k+1}}{\rho_{k+1} A_{k+1}^2} \right] \frac{1}{g_z} + P_k - P_{k+1} \\ &+ \left[-\frac{1}{A_k} F_{w,k} - \frac{1}{A_{k+1}} F_{w,k+1} \right] \frac{1}{g_z} \\ &- [\bar{\rho}_k (Z_i - Z_k)' + \bar{\rho}_{k+1} (Z_{k+1} - Z_i)'] \frac{g(t) + \alpha_z}{g_z} \\ &- \frac{1}{2} [\bar{\rho}_k \cdot \gamma_{k,x} + \bar{\rho}_{k+1} \cdot \gamma_{k+1,x}] \frac{\alpha_x}{g_z} \\ &- \frac{1}{2} [\bar{\rho}_k \cdot \gamma_{k,y} + \bar{\rho}_{k+1} \cdot \gamma_{k+1,y}] \frac{\alpha_y}{g_z} \\ &+ \left(\frac{1}{2} \frac{W_i^2}{\rho_i} \left[\frac{1}{A_{k+1}^2} - \frac{1}{A_k^2} \right] - \frac{1}{2} W_{i1} W_{i2} \frac{e_i}{\rho_i A_i^2} \right) \frac{1}{g_z} \end{aligned} \quad (2.5.16)$$

To avoid the complexity of three-dimensional analysis and taking account of practicality we can model two-dimensional component of the forces for the flows. That is, the acceleration (see Eq. 2.5.15) due to the centrifugal force and the tangential force are mapped to the x-z plane: α_x , and α_z . This formation is the same as the equation for rolling (see Eq. 2.4.3) except that the elevation and horizontal length in Eq. 2.5.16 are obtained by the rotation matrix of co-ordinates (see Eq. 2.5.14).

2.5.3 Energy Equation

Energy equation for arbitrary three-dimensional rotation is represented by the following equation.

$$\begin{aligned} \frac{dU_k}{dt} = & -\frac{1}{2} \frac{L_k}{A_k} \frac{d}{dt} \left(\frac{W_k^2}{\rho_k} \right) + Q_{wm} \\ & + W_{i-1} \left[h_{i-1} + \left(\frac{W^2}{\rho A} \right)_{i-1} + (g(t) + \alpha_z) (Z_{i-1} - Z_k)' \right. \\ & \quad \left. + \frac{1}{2} \alpha_x \cdot \gamma_{k,x} + \frac{1}{2} \alpha_y \cdot \gamma_{k,y} \right] \\ & - W_i \left[h_i + \left(\frac{W^2}{\rho A} \right)_i + (g(t) + \alpha_z) (Z_i - Z_k)' \right. \\ & \quad \left. - \frac{1}{2} \alpha_x \cdot \gamma_{k,x} - \frac{1}{2} \alpha_y \cdot \gamma_{k,y} \right] \end{aligned} \quad (2.5.17)$$

This formation is also the same expression as the equation for rolling (Eq. 2.4.4), besides that the elevation and horizontal length in Eq. 2.5.17 are obtained by the rotation matrix of co-ordinates (see Eq. 2.5.14).

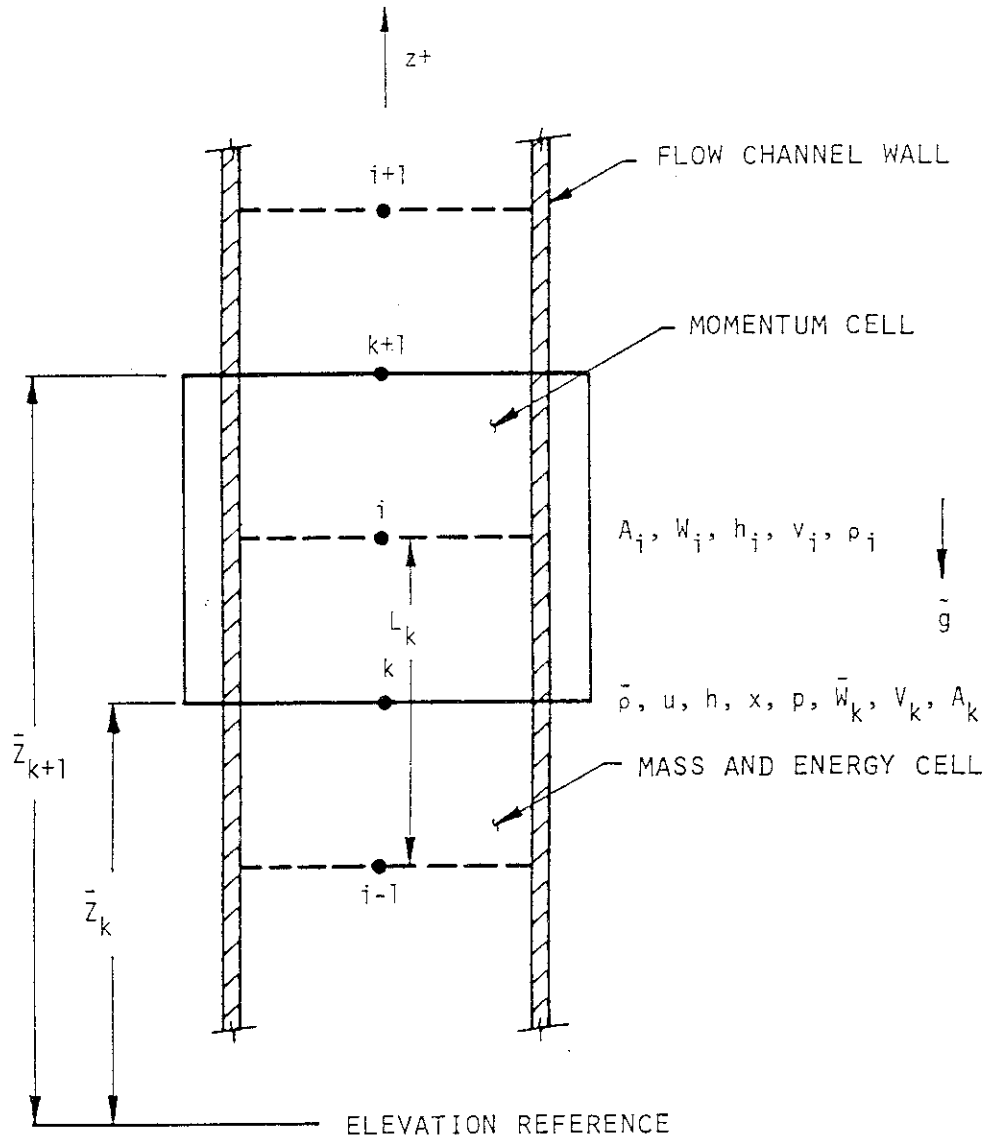


Fig. 2.1.1 Geometry for the RETRAN Equations
(See reference⁽⁷⁾ for detail)

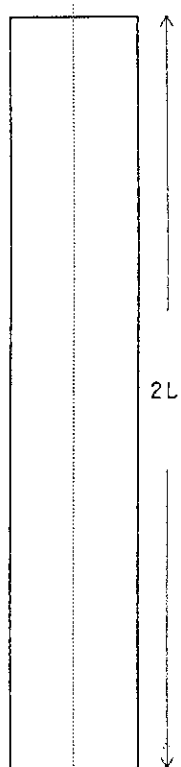


Fig. 2.2.1 Vertical Tube

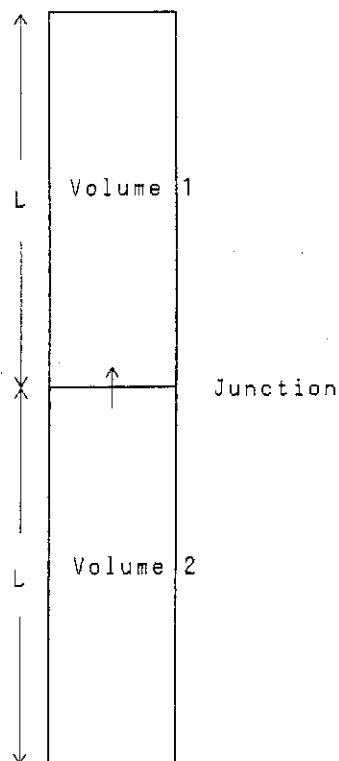


Fig. 2.2.2 RETRAN Noding Model

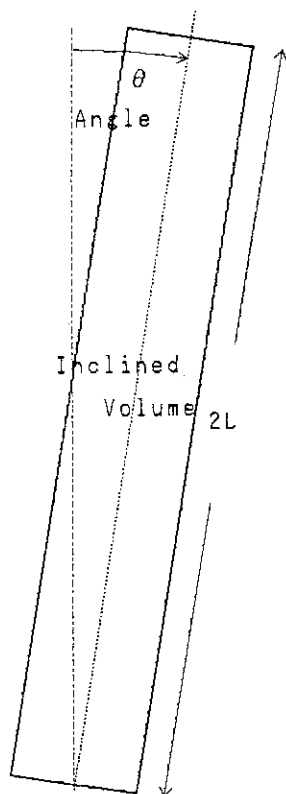


Fig. 2.2.3 Inclined Tube (Vertical Tube)

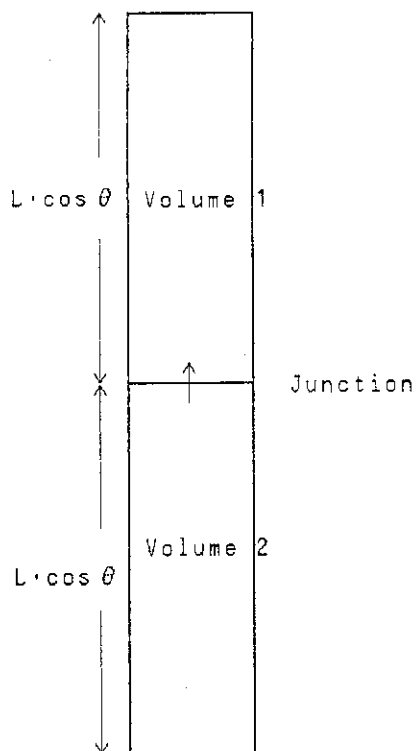


Fig. 2.2.4 RETRAN Noding Model for Inclined Vertical Tube

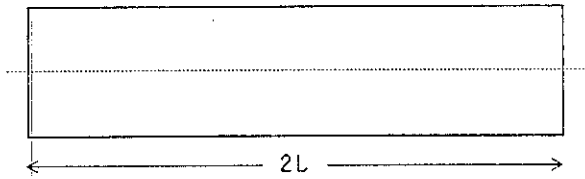


Fig. 2.2.5 Horizontal Tube

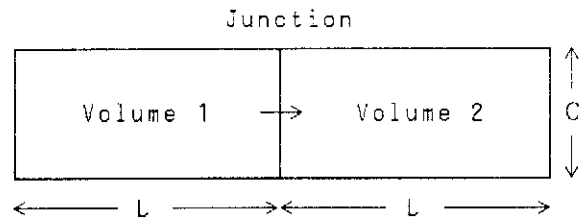


Fig. 2.2.6 RETRAN Noding Model for Horizontal Tube

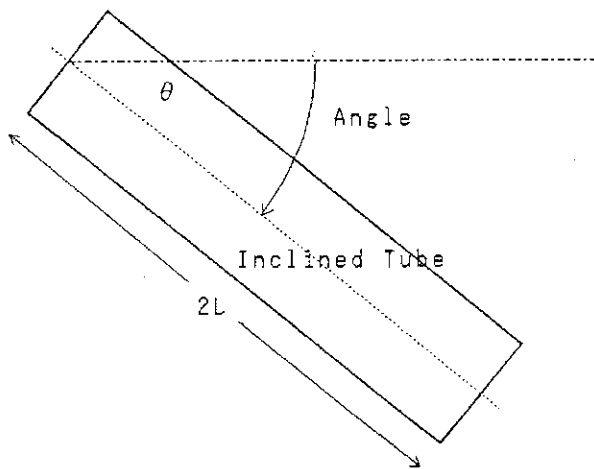


Fig. 2.2.7 Inclined Tube (Horizontal Tube)

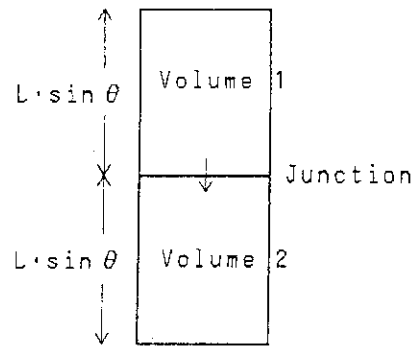


Fig. 2.2.8 RETRAN Noding Model for Inclined Horizontal Tube

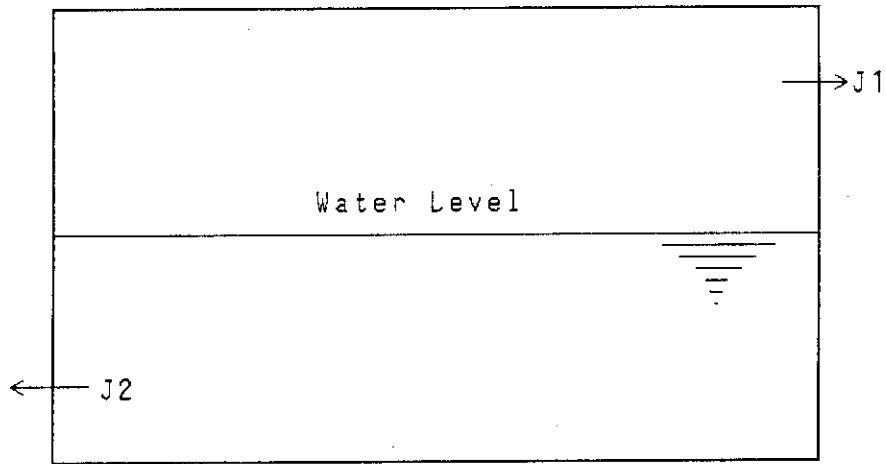


Fig. 2.2.9 Water Level Model

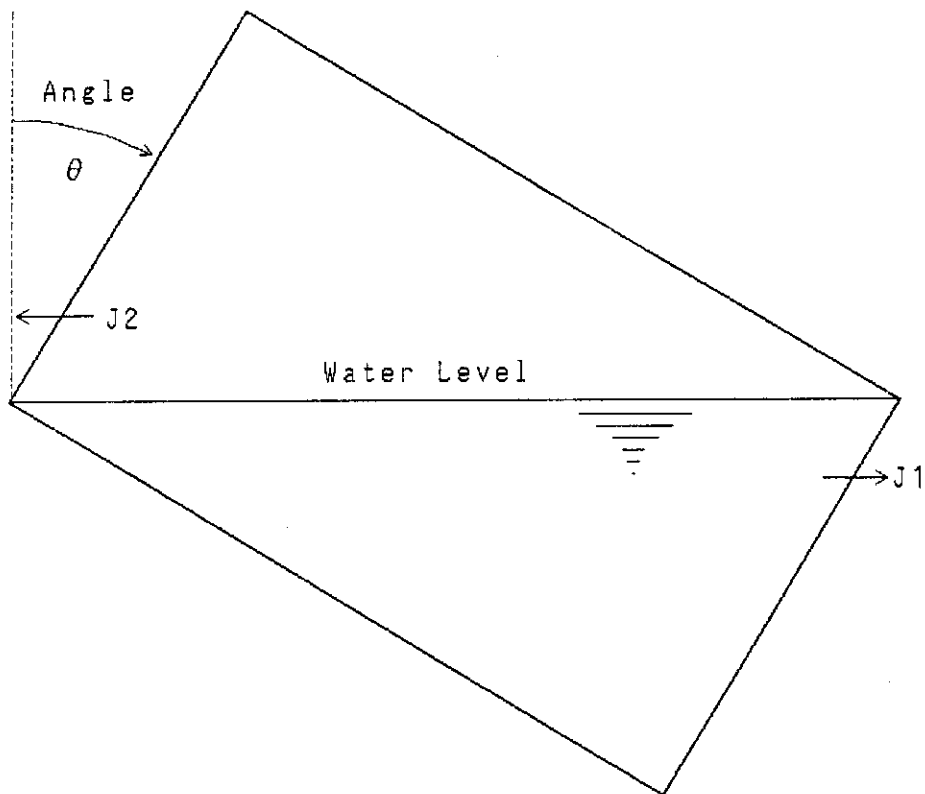


Fig. 2.2.10 Water Level Model at Inclination

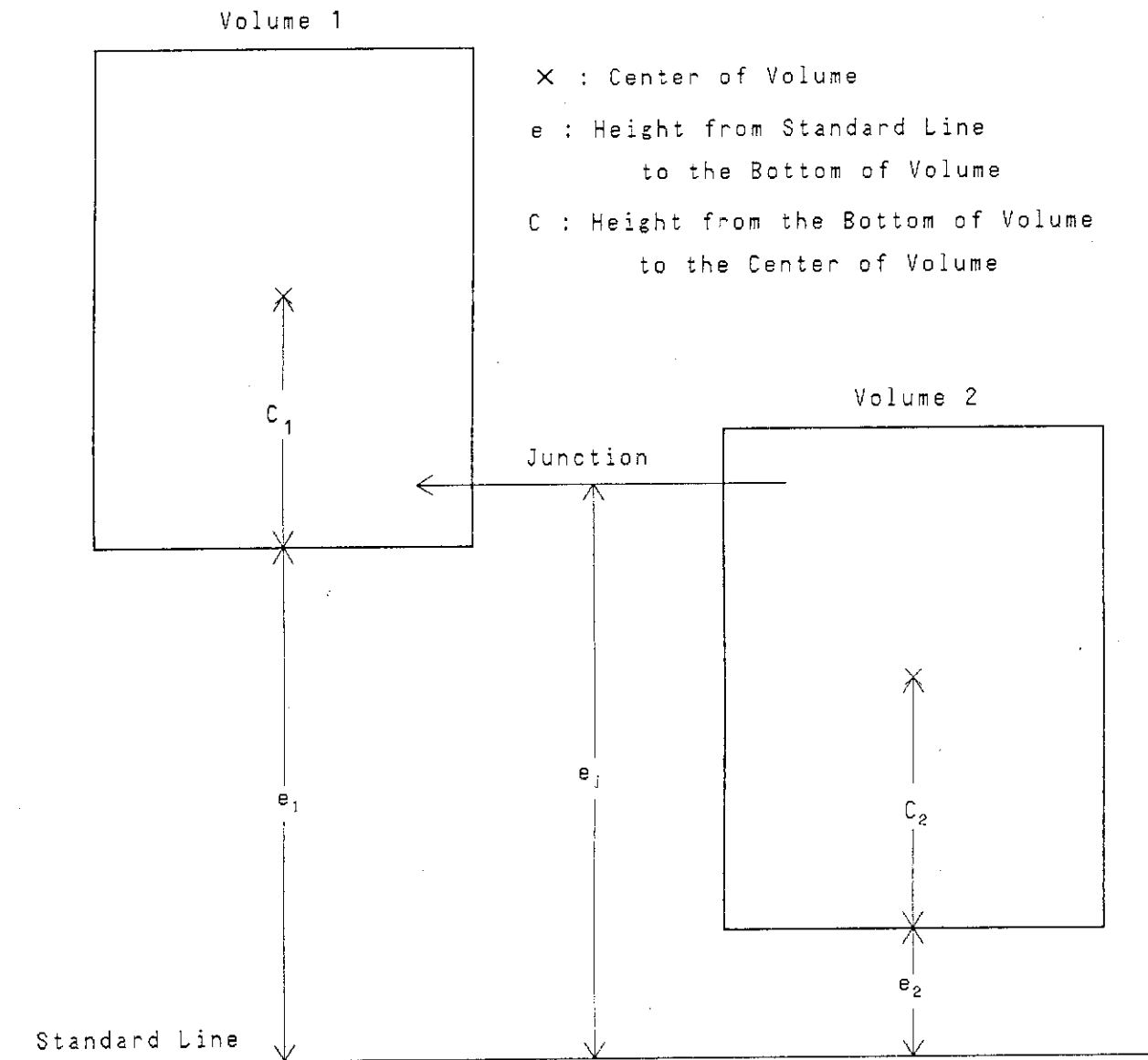


Fig. 2.2.11 Relationship of Elevation and Water Head in RETRAN Noding

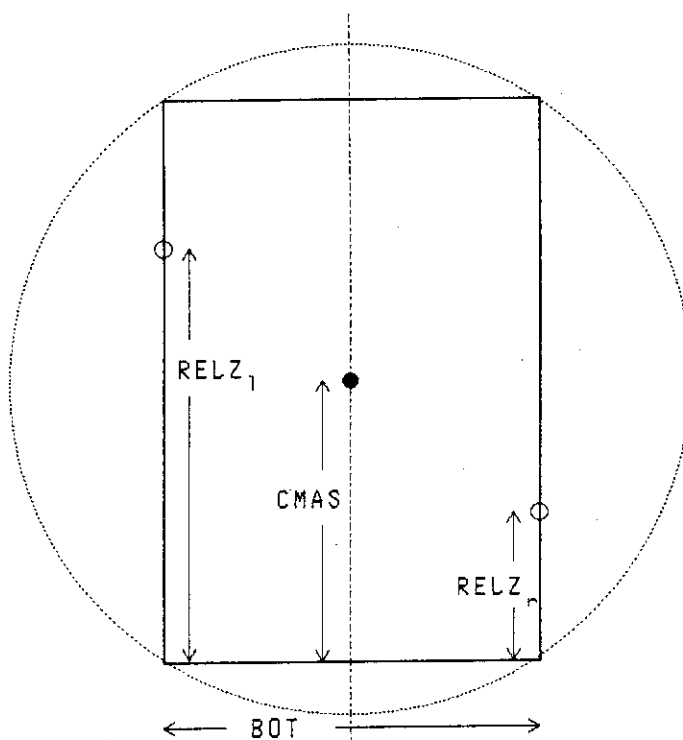


Fig. 2.2.12 Junction Elevation Before Inclination

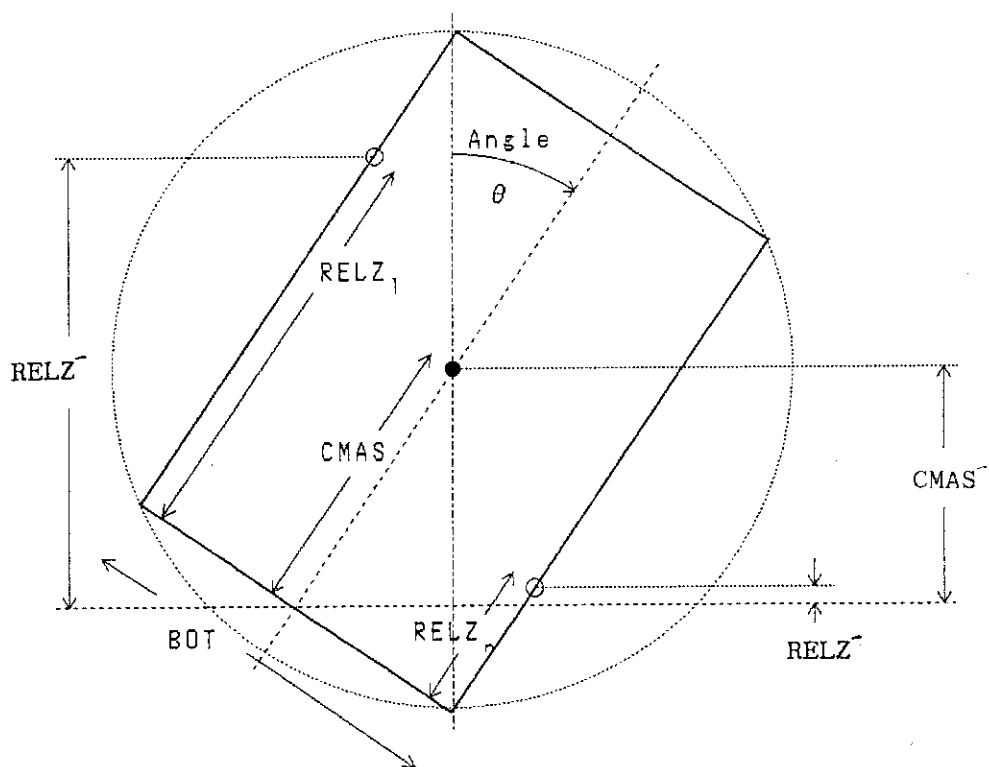


Fig. 2.2.13 Junction Elevation at Inclination

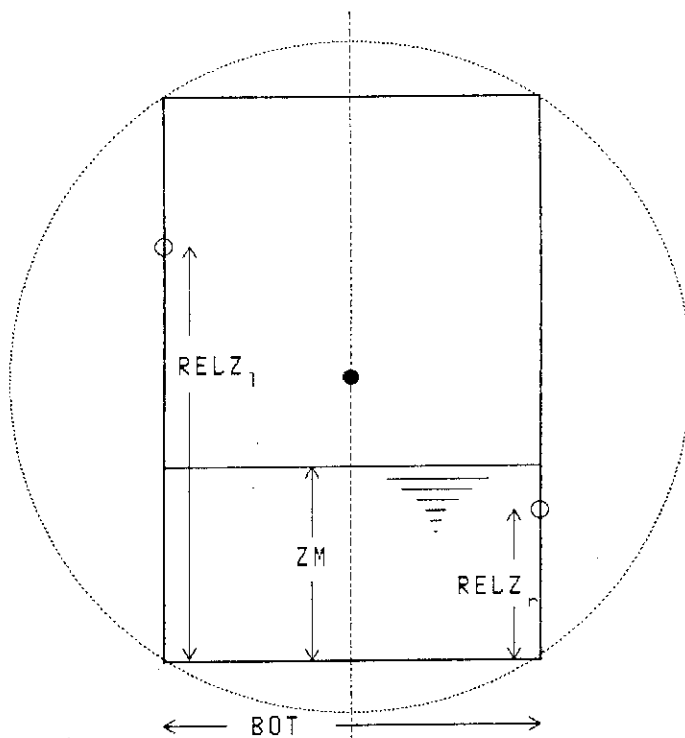


Fig. 2.2.14 Water Level Before Inclination

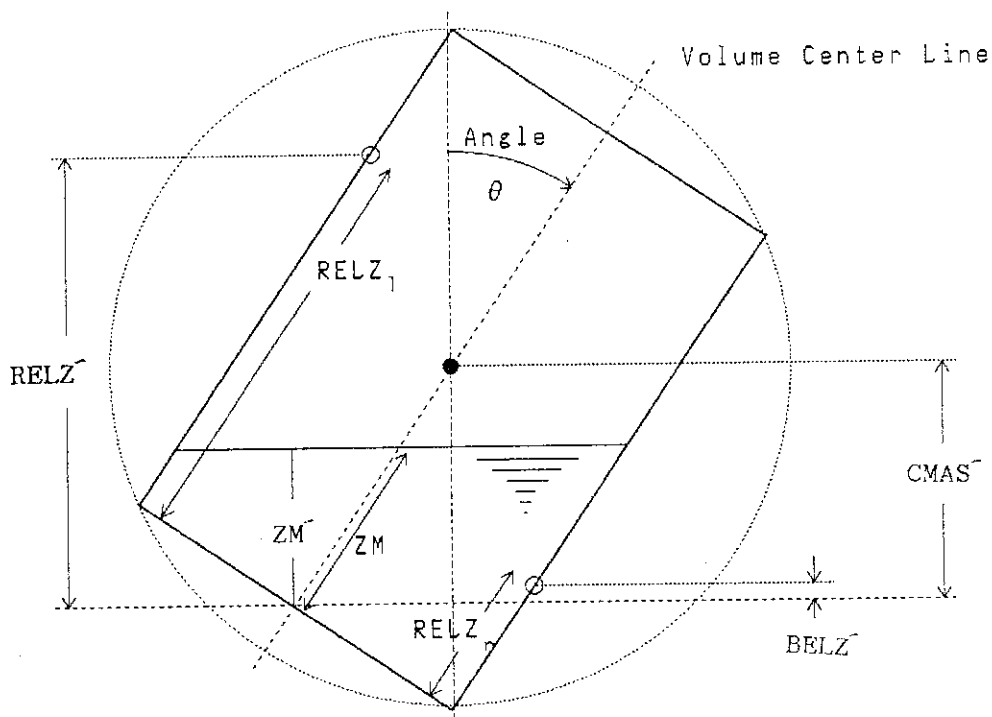


Fig. 2.2.15 Water Level at Inclination

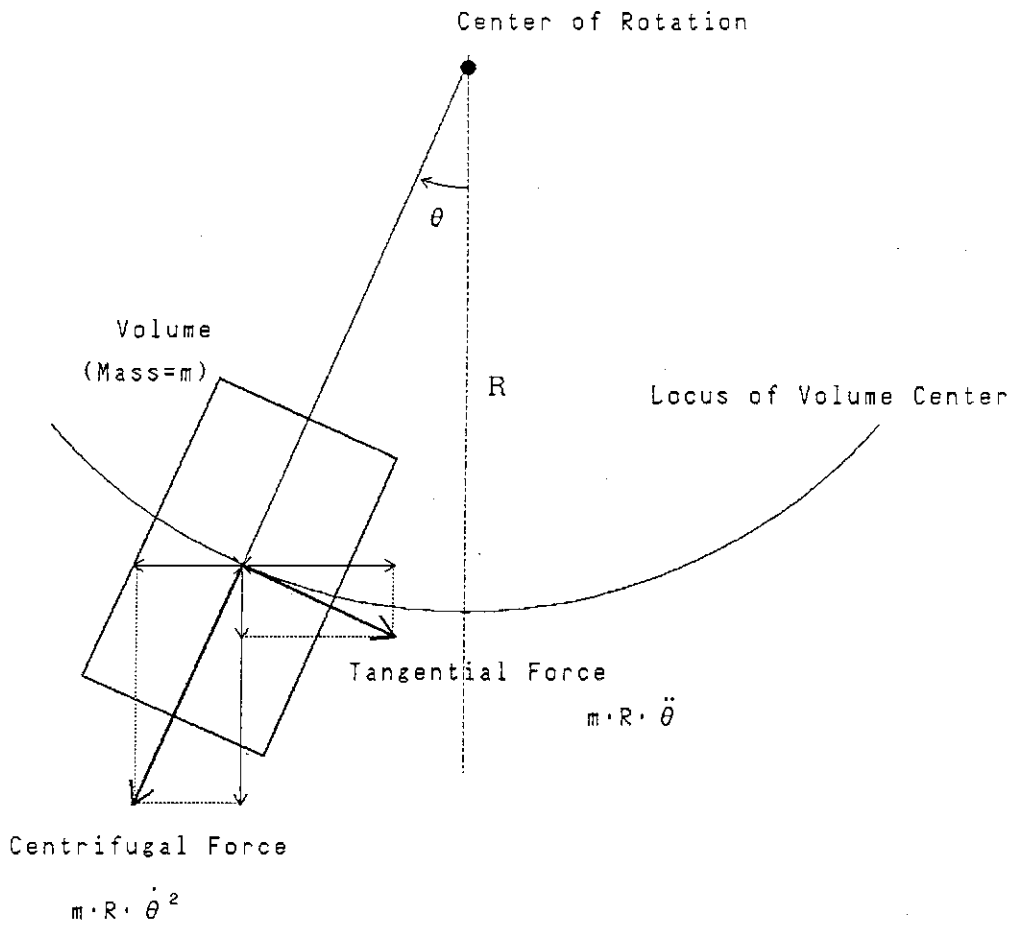


Fig. 2.4.1 Forces on the Fluid of Volume Under Rolling

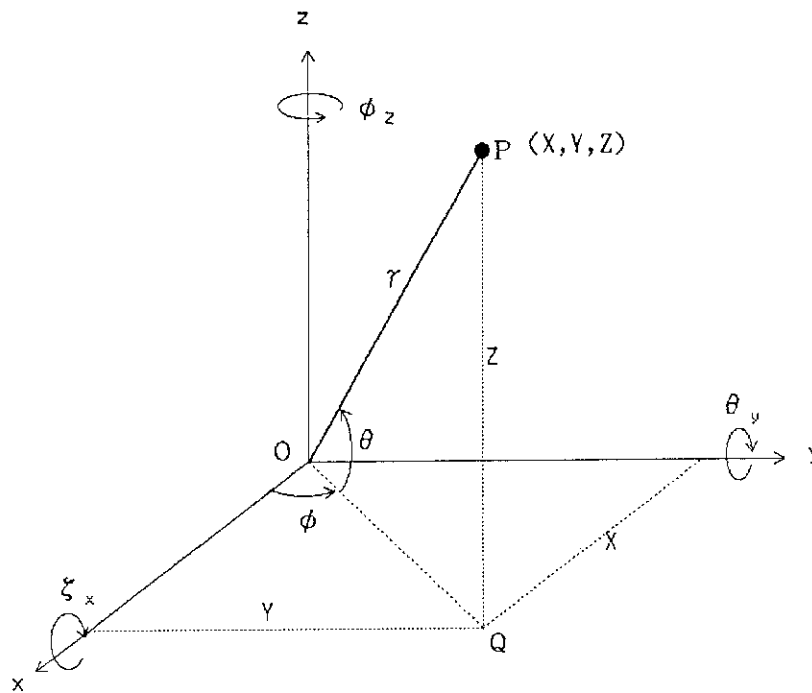


Fig. 2.5.1 Vector in Three-Dimensional Co-ordinates

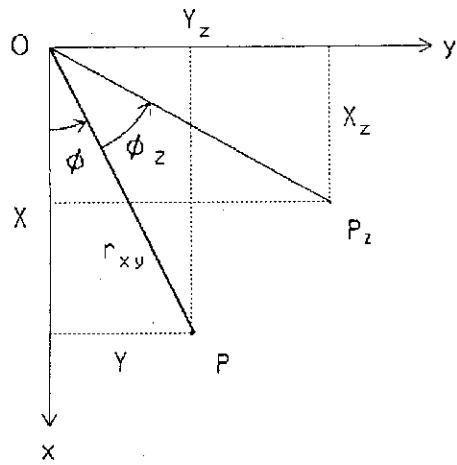


Fig. 2.5.2 Rotation of OP Around z-Axis

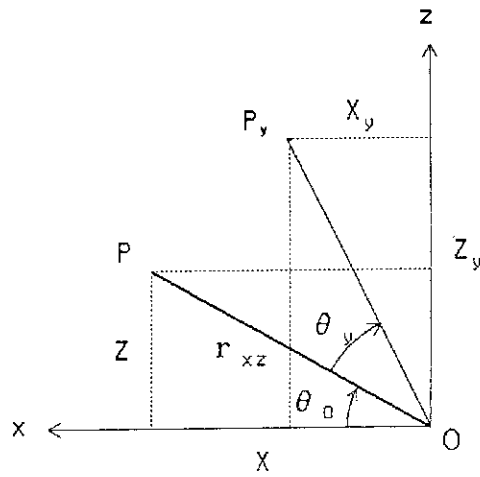


Fig. 2.5.3 Rotation of OP Around y-Axis

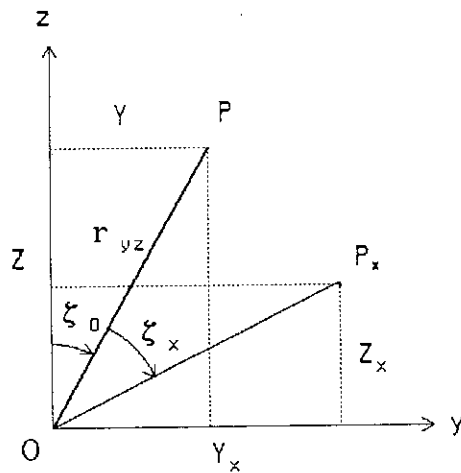


Fig. 2.5.4 Rotation of OP Around x-Axis

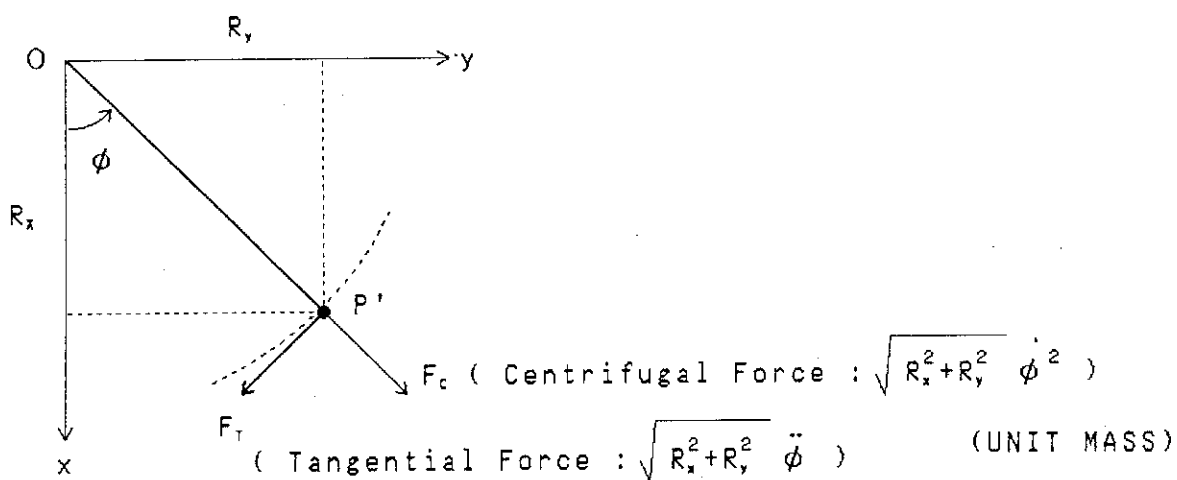


Fig. 2.5.5 Forces Under Rotation Around z-Axis

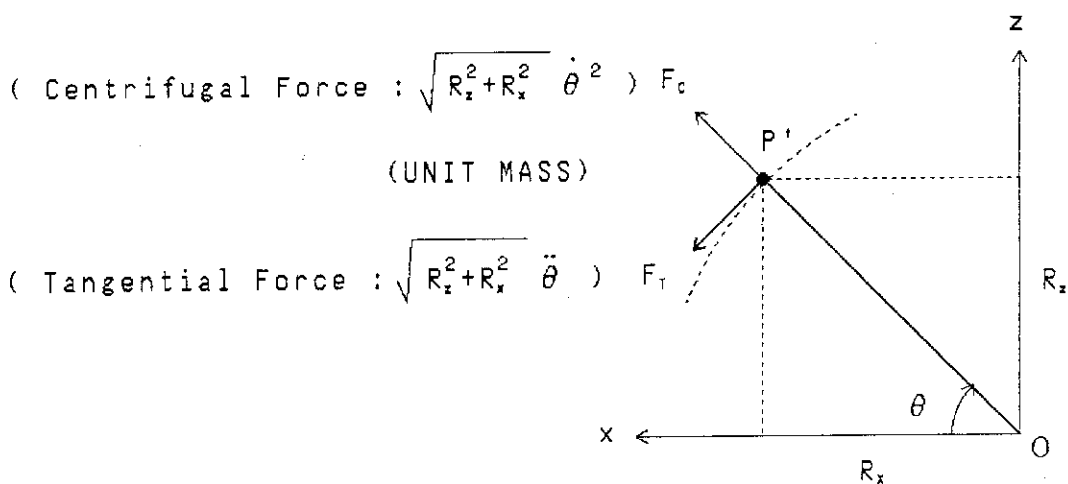


Fig. 2.5.6 Forces Under Rotation Around y-Axis

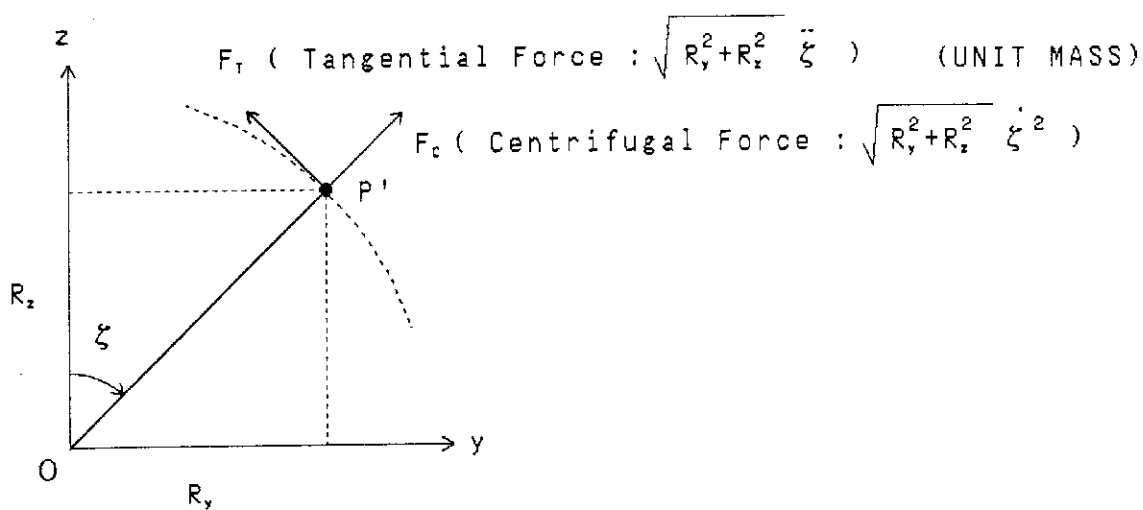


Fig. 2.5.7 Forces Under Rotation Around x-Axis

3. Verification of The RETRAN-02/GRAV with Experimental Data

The present code has been verified for the stability of numerical calculation, and then the physical validity of the calculated results has been checked using some simple idealized models and experimental data. The following three experimental analyses are introduced for code verification : the first is the single-phase natural circulation flow at inclined attitude ; the second is the single-phase and two-phase natural circulation flow under heaving ; and the third is the single-phase natural circulation flow during rolling motion.

3.1 Single-Phase Natural Circulation Experiment at Inclined Attitude

Experiments of the single phase natural circulation flow at inclined attitude in stationary state were conducted by Iyori et al⁵⁾. Figure 3.1.1 shows the experimental rig which consists of two coolers, heater and connecting pipes. The experimental rig simulates a hybrid marine pressurized water cooled reactor. Total height of the rig is about three meters. Working fluid is fresh water. The operating pressure is atmospheric pressure (0.1 MPa) and core heater power is 60 kW. In the experiment, the steady natural circulation flows of two loops were measured with small propeller flowmeters installed in the hot and cold arm sections.

Figure 3.1.2 shows the experiments and analyses by RETRAN-02/GRAV together with the simple analysis by Iyori et al⁵⁾. The analysis by RETRAN-02/GRAV was made as follows. The steady flow at zero inclination angle (that is, the upright state) was firstly set to equal the flow in the experiment by adjusting flow resistance factor. Then, the flow loop of the analytical model was inclined slowly to a certain angle. When the steady state of the analytical model at the certain inclination angle was established, the flows in each loop and the heater power were compared with those of the experiment.

The results show that the flow rate in the descending loop decreases, while the flow in the ascending loop increases with inclination angle. The reason is

why the elevation difference between the heater and the cooler of the descending loop becomes smaller and one of the ascending loop becomes larger with inclination. As a result, the flow in the heater and the average of the both loop flow rates retain about 60% of the stationary state's flow rate even at 60 to 90 degrees of inclination.

The flow rate calculated by the RETRAN-02/GRAV analysis agrees fairly well with the experimental data, though the analytical model did not take account of the effect of the intrusion of the 'cold front' temperature into the descending legs and arm, which has a two-dimensional effect on driving force as described in reference⁵⁾.

3.2 Single- and Two-Phase Natural Circulation Flows Under Heaving

Heaving was simulated by Teshima and Yamaguchi⁴⁾ using a periodically and vertically moving experimental rig, which had been established on a carriage. Figure 3.2.1 shows the experimental rig. Table 3.2.1 shows the experimental conditions used for verification analysis. The rig with a single loop consists of the heater, the separator, the condenser and the connecting pipes (inner diameter = about 35 mm). The working fluid is water, the operating pressure is 0.1 MPa, and the heater power is 9.6kW.

Figure 3.2.2 shows the results of the single-phase experiments and analyses for the period of two oscillation cycles. In the analyses, the steady state was set so as to equal to the experiment, and the apparent gravitational acceleration of the experiment was used as an analytical boundary condition.

In the natural circulation, the apparent gravitational acceleration dominates the driving head of the flow. It is shown that the flow velocity in the single phase flow experiment varies with the center of the steady state velocity. The flow follows the acceleration change induced by heaving motion, with a few second time delay. The calculated velocity simulates well the experiment.

Figures 3.2.3 shows the results of the two-phase experiments and analyses for the period of two oscillation cycles. The flow at the heater inlet and the steam void fraction at the heater outlet were measured but not the heater

outlet velocity. The heater inlet velocity changes together with the acceleration in the same manner as the case of the single phase experiment but accompanying a larger delay time. Since the heater power was held at a constant during the experiment, the change of void fraction at the heater outlet are seen to subject to the change of velocity at the heater inlet.

The analysis was performed with two different homogeneous models used in the RETRAN-02 for the two-phase thermal hydraulic dynamics : one was with the slip model of RETRAN-02 ; and the other was without slip model (homogeneous model). The velocity of the slip model shows smaller change than those of the homogeneous model and the experiment. The total amount of void fraction of the slip model approaches closer to the experiment than that of the homogeneous model. From the results of analyses, the features of two models are revealed : The general trends of the velocity and void fraction in both models are consistent with the experiments. Two models, however, differ in the heater outlet flow rate, though they were not measured and not presented here. The heater outlet flow rate by the slip model results in a wild oscillation, while that by the homogeneous model shows a smooth change following the heater inlet velocity. The wild oscillation seems to prove that the dynamic slip model of the present RETRAN-02 is not suitable to this experimental conditions and it should be improved.

3.3 Single-Phase Natural Circulation Flow Under Rolling

Experiments of the single phase natural circulation under the rolling condition were conducted by Murata et al⁶⁾. The model rig with two flow loops consists of the heater, the coolers, and connecting pipes (see Fig. 3.3.1). The experimental rig simulates a hybrid marine pressurized water cooled reactor NSR-7⁸⁾. The total height of rig is about 3m the same as one of the NSR-7. The working fluid is water, the operating pressure is atmospheric pressure (0.1 MPa), and the maximum heater power is 60 kW. The rolling angle is ± 22.5 degrees, and the rolling period is five to 20 seconds.

Figure 3.3.2 shows a typical example during one cycle of rotation by the

heater power of 60 kW. The experimental results are shown by dotted line and the analysis by solid line. In the analysis, the steady flow in the stationary state was firstly obtained the same way as mentioned above by adjusting flow resistance. Then, the rolling motion is added to the the RETRAN-02/GRAV model rig. When the amplitude and period of flow oscillation become almost constant (after about 600 seconds), the analysed result is compared with the experimental results.

The flow rates in the heater W_{CORE} are almost constant during rotation. The flow rate during rotation of analysis is smaller than the experiment by about 100 kg/h (5 %). In the experiment, the flow rate during rotation increases with water temperature profile change in the heater and the cooler from the stationary state, and with decrease of flow resistance⁵⁾. In the analysis, these effects due to the change of the temperature profile and the flow resistance are not taken an account of. These effects make the difference of the flow rate in the heater between the analysis and the experiment.

The flow rates of hot leg W_{BH} and of cold leg W_{BC} change with the rotation angle of θ . As the rotation angle is large to positive in the loops, the flow rates in the loops increase, vice versa. The variation of cold leg's flow rate is larger than that of hot leg's one because the tangential force becomes larger in proportion to the length from the center of rotation as shown in the Fig. 3.3.1.

The flow rates in the hot leg and the cold leg change with the delay time for the rolling angle. The delay time and the amplitude of the flow variation depend on rolling angular velocity. Figure 3.3.3 shows the delay time and the ratio of amplitude of flow variation in the loops to the heater flow rate ($\Delta W / W_{CORE}$) for the angular velocity, in comparison with the result of RETRAN-02/GRAV analysis. The delay time and the ratio of amplitude of flow variation are shown to increase with the angular velocity. The analysis result agrees quantitatively well with the experiment.

Forces causing the flow variation in rolling are considered to be water head driving head (F_1), the radial force (the centrifugal force, F_2) and the tangential force (F_3). Effects of these forces on the flow variation are analytically studied using RETRAN-02/GRAV. Figure 3.3.4 the shows the change

of forces F1 only, the change of F1 and F2, and the change of F1, F2 and F3 for the change of hot leg flow rate in one cycle of rolling. This reveals that the tangential force dominates the flow change of the hot leg (or cold leg) in the rolling motion. As the result, the response of WCORE, WBH, and WBC to the rotation from RETRAN-02/GRAV calculation are well agreed with the experimental flow rate.

It is concluded that the physical validity of analyses results obtained from RETRAN-02/GRAV calculation has been verified.

Table 3.2.1 Experimental Conditions of the Natural Circulation Under Heaving Motion

| Parameters | Single-Phase Flow Experiment ⁽⁴⁾ | Two-Phase Flow Experiment ⁽⁴⁾ |
|--|---|--|
| 1. Fluid Material | Water | Water |
| 2. Pressure (MPa) | ca. 0.1 | ca. 0.9 |
| 3. Heater Inlet Subcooled Temperature (°C) | ca. 75 | 22.5 |
| 4. Heater Power (kW) | 9.6 | 12.5 |
| 5. Apparent Gravity Oscillation | | |
| Max.Magnitude (g) | ca. 0.2 | ca. 0.3 |
| Period (second) | ca. 4.0 | ca. 4.0 |

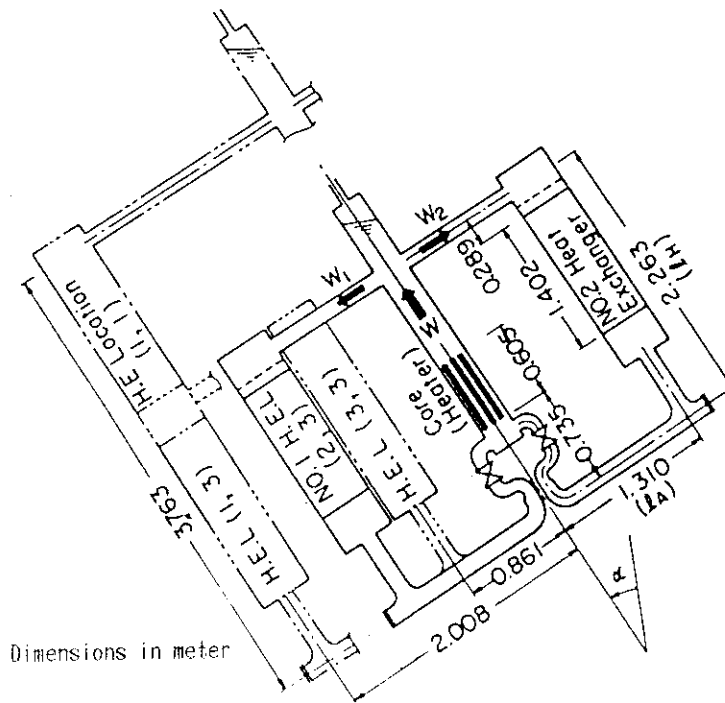


Fig. 3.1.1 Experimental Rig for Natural Circulation at Inclined Attitude with Angle α ⁽⁵⁾

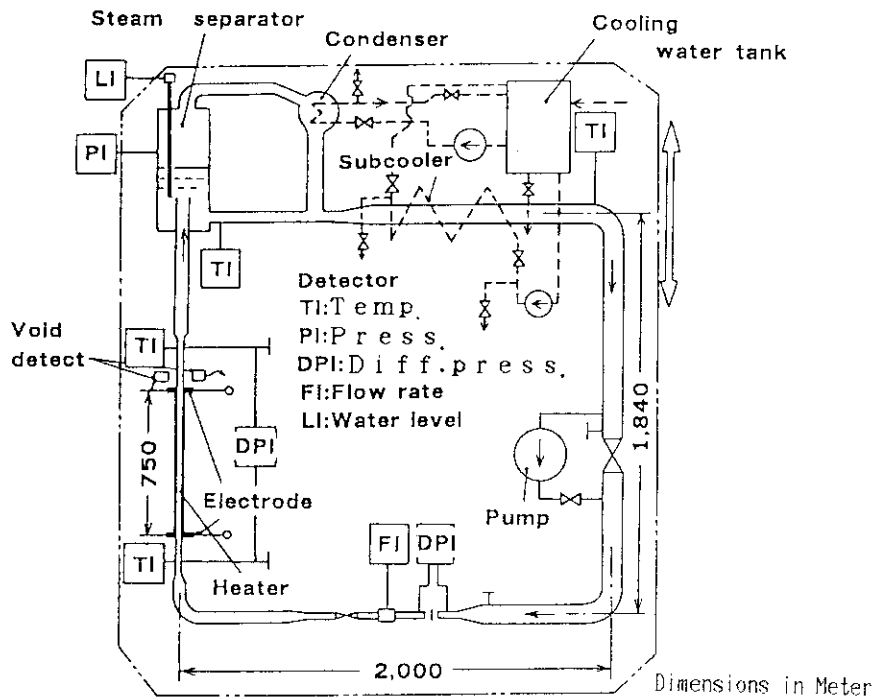


Fig. 3.2.1 Experimental Rig for Natural Circulation Under Heaving

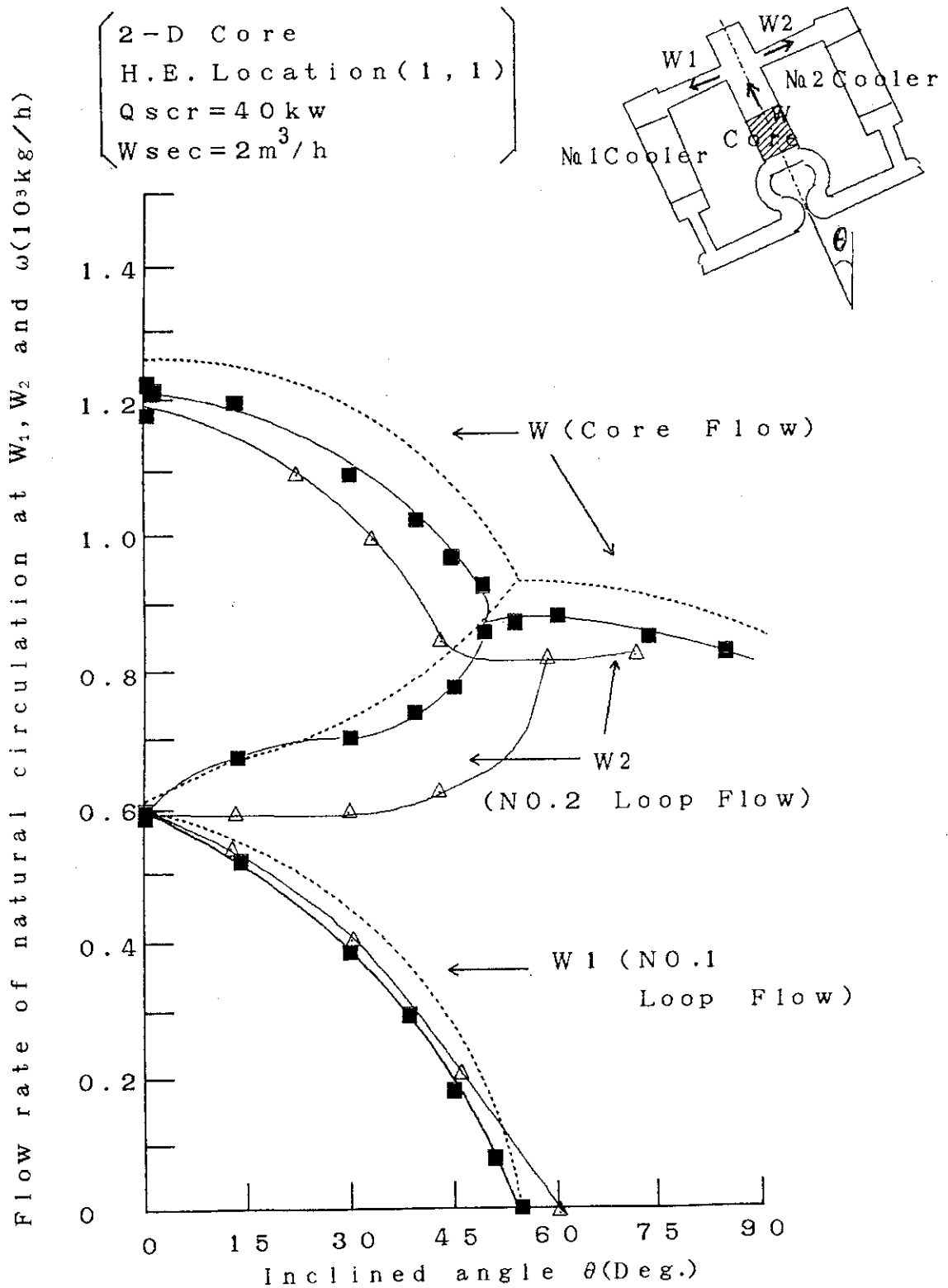


Fig. 3.1.2 Comparison Between RETRAN Analysis and Experiment for Natural Circulation at Inclined Attitude with Angle θ

- Experiment
- Iyori et al's calculation
- △ RETRAN-02/GRAV

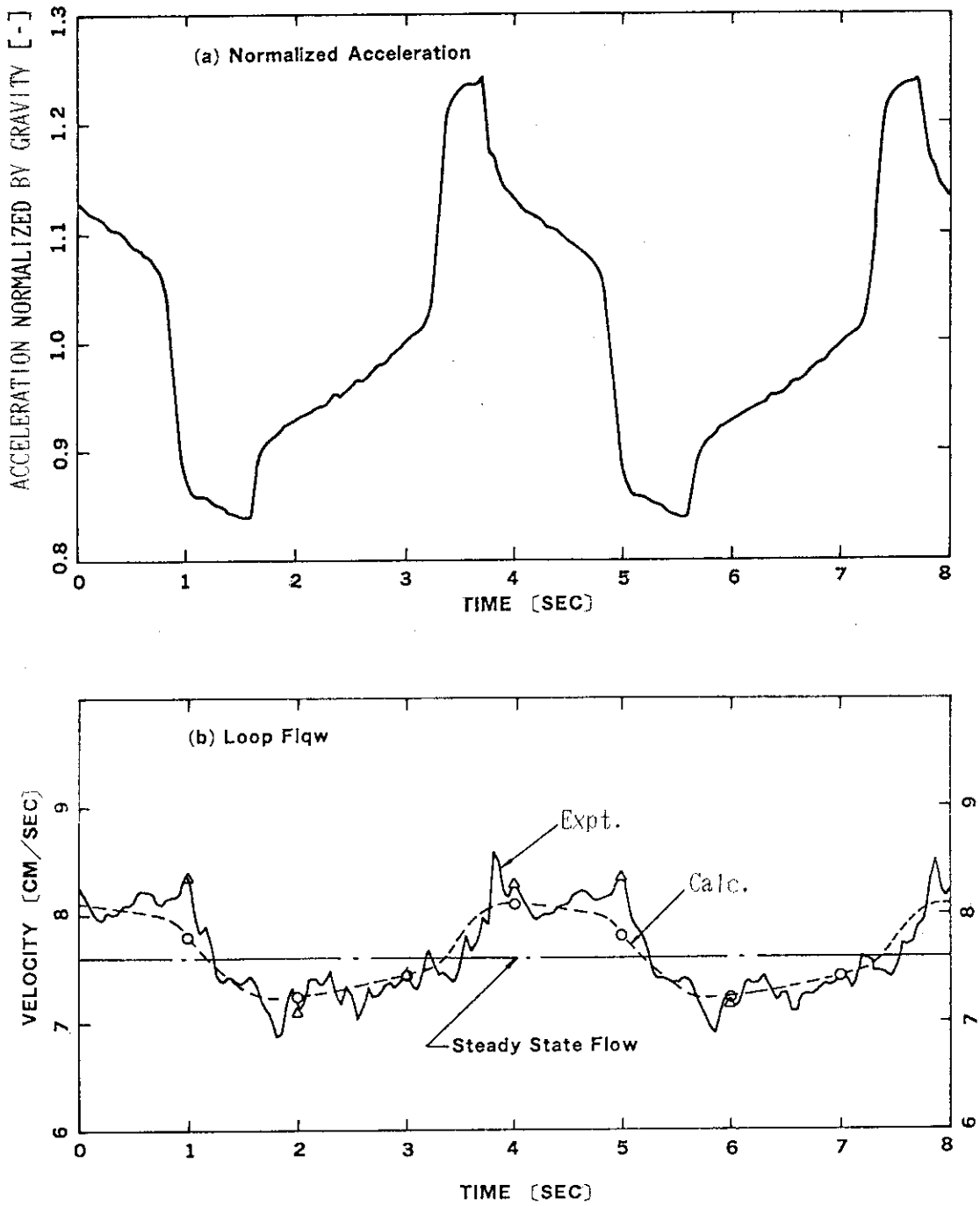


Fig. 3.2.2 Comparison of Between Analysis and Experiment for Single-Phase Natural Circulation Under Heaving

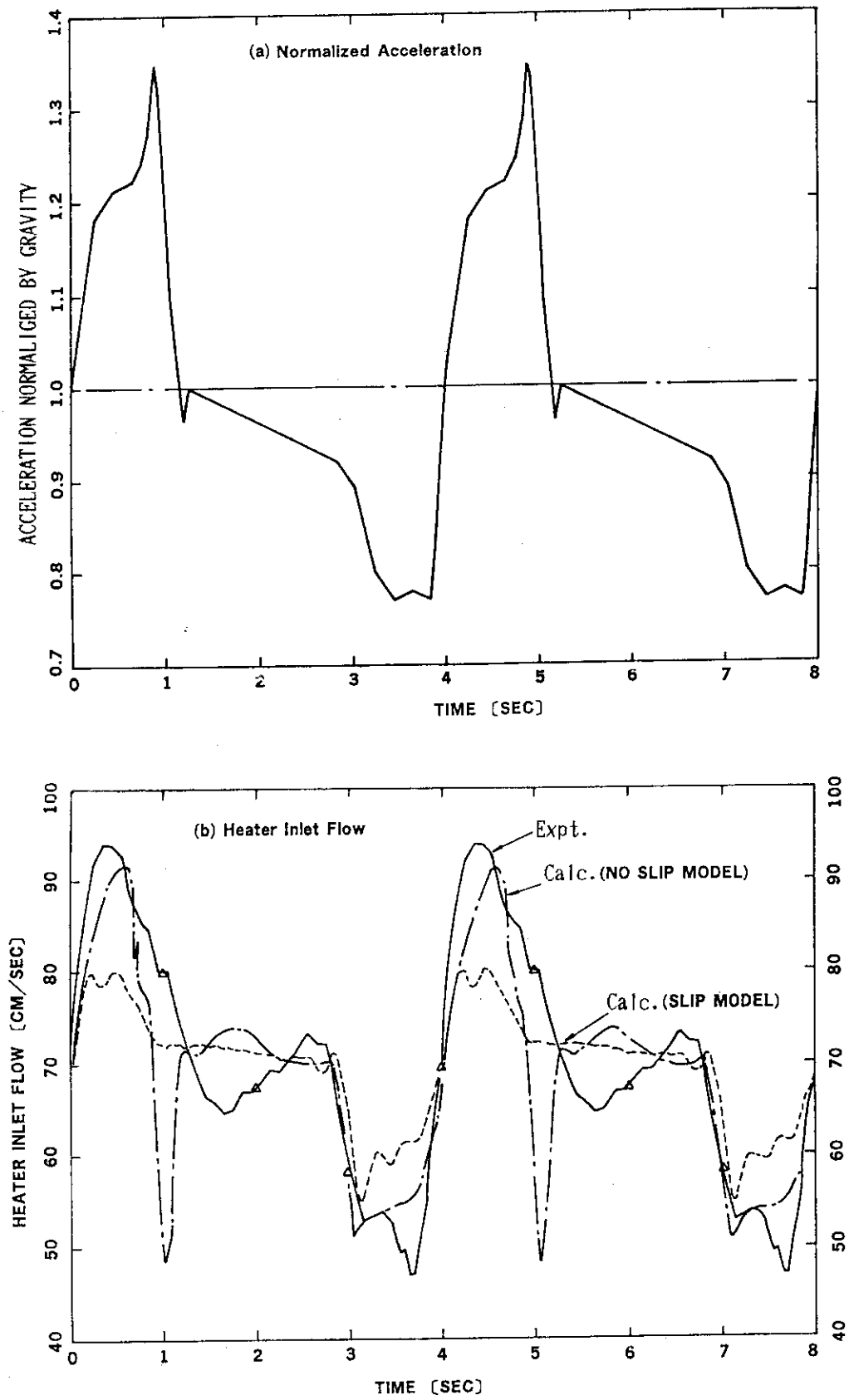


Fig. 3.2.3 Comparison Between RETRAN Analysis and Experiment for Two-Phase Natural Circulation Under Heaving

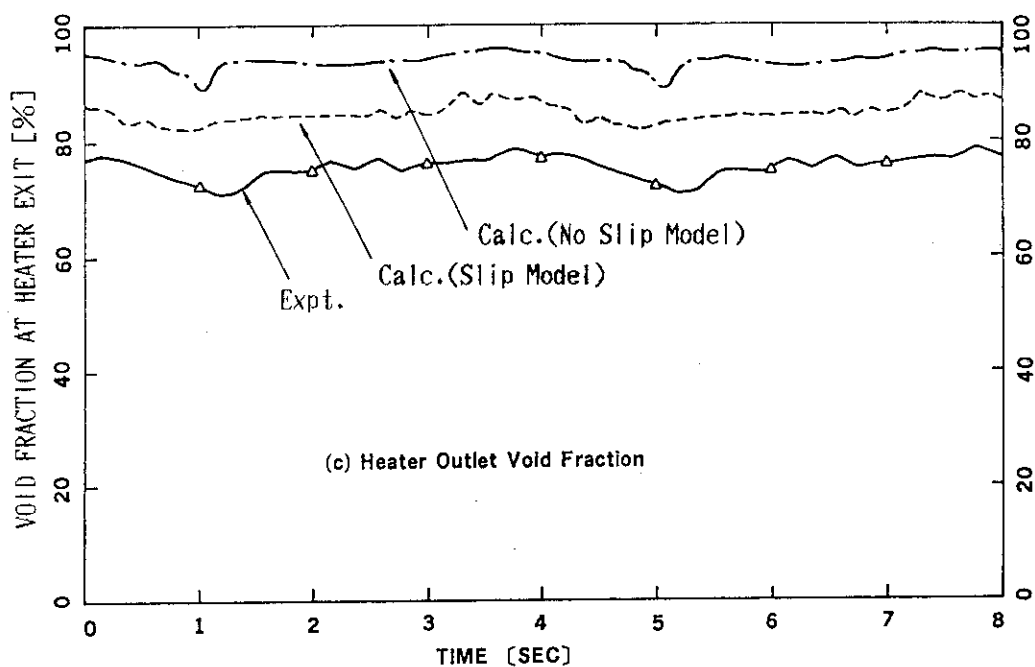


Fig. 3.2.3 (Continued)

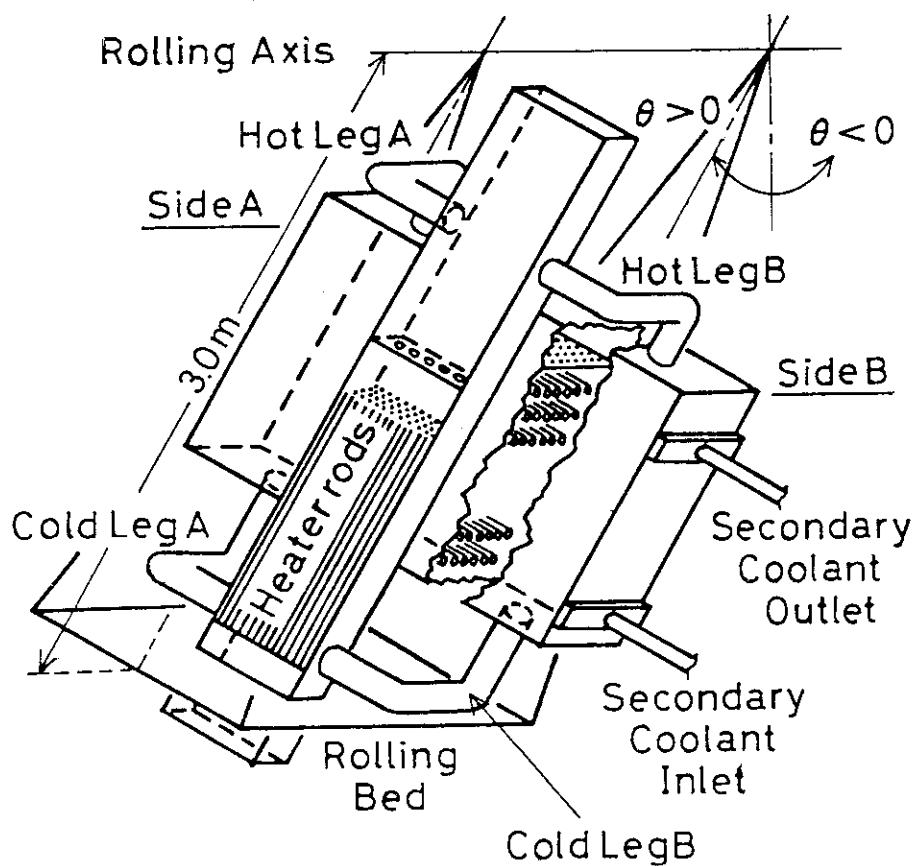


Fig. 3.3.1 Experimental Rig for Natural Circulation Under Rolling⁵⁾

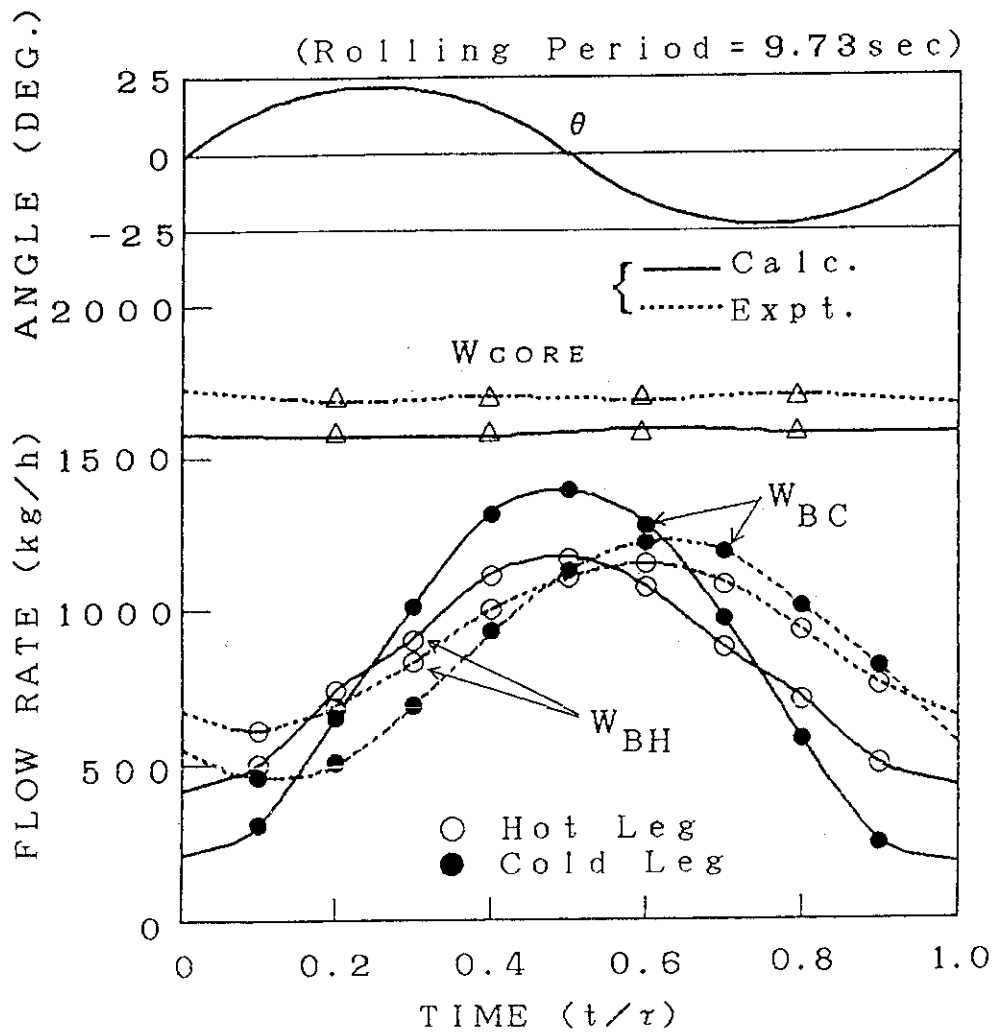


Fig. 3.3.2 Comparison Between RETRAN Analysis and Experiment for Natural Circulation Under Rolling
 (W_{CORE} : Core Flow Rate, W_{BH} : Hot Leg Flow Rate,
 W_{BC} : Cold Leg Flow Rate.)

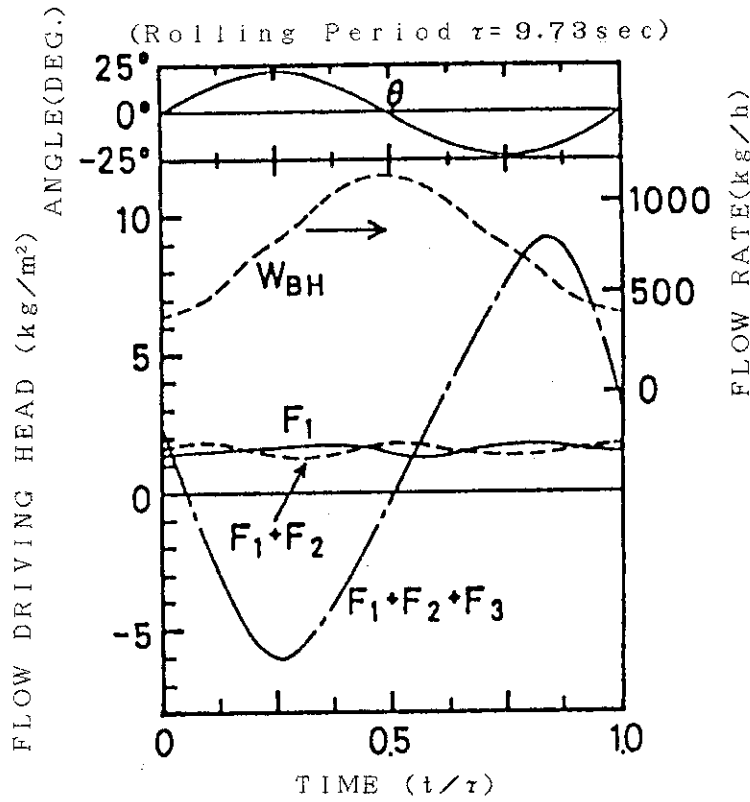


Fig. 3.3.3 Amplitude for Flow Variation and Delay Time of Flow Rate to Rolling Angle

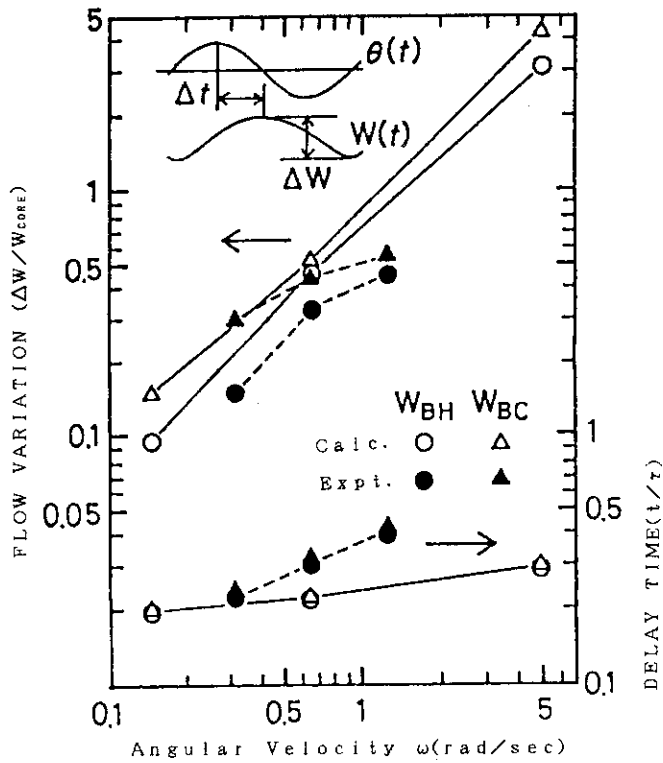


Fig. 3.3.4 Change of Forces in Case of F_1 , $F_1 + F_2$ and $F_1 + F_2 + F_3$ Under Rolling
 (F_1 : Water Head, F_2 : Head of Radial Force)
 (F_3 : Head of Tangential Force)

4. Application of the RETRAN-02/GRAV to Predicting Analyses of Thermal Hydraulic Behavior of N.S. Mutsu Reactor in Experimental Voyages

4.1 Description of N.S. Mutsu Reactor and Analysis Model

The reactor of nuclear-powered ship N.S. Mutsu is a two-looped PWR with a rated core power of 36 MW (thermal). Figure 4.1.1 shows the arrangement of the reactor coolant system (RCS). The RCS consists of the reactor vessel, two coolant loops with steam generators (SGs), two main coolant pumps (MCPs) and a pressurizer. The main coolant pipes are U-shaped to allow the thermal expansion. The specific features of the reactor design in comparison with those of the land based PWR is presented in Table 4.1.1. The detailed description is given in reference⁽⁹⁾. The Mutsu reactor is a compact one comparing the land based PWR.

The thermal hydraulic performance in the marine reactor system is characterized by the frequent heavy load changes caused by maneuvering a main steam turbine for ship propulsion and by ship motion. Table 4.1.2 shows the comparison of design-base conditions between three marine nuclear ships of Mutsu⁽¹⁰⁾, Otto Hahn⁽¹¹⁾, and Savannah⁽¹²⁾. These design conditions were determined by taking account of maneuvering in ordinary marine cargo ships, and those of land based PWRs.

On ship motion, Table 4.1.3 presents the design-base conditions of Mutsu, which were determined based on the statistics of the sea weather data. Although these severe conditions will rarely encountered in the experimental voyages, the reactor control system is designed to follow heavy load conditions and the ship motion with operation of an automatic control system.

The automatic control system consists of mainly the reactor power control system, the SG feed water control system, the pressurizer pressure control system and the pressurizer water level control system. The average temperature in the reactor is controlled to be a constant by reactor power

control system (called as Tav-constant control method). In general, the reactor power in marine PWR is controlled not by chemical shim but by control rods since the chemical shim will be not useful in case of ship sinking.

The SG water level is controlled by a feed water control system with feed water pumps and feed water control valves. One of feed water pump is required to provide a pump outlet pressure depending the SG pressure since the SG pressure changes with the steam flow rate. The cascade control method is adopted for feed water pump controller : the deviation signal of pressure difference through the feed valve is controlled to become the desired value of the pump outlet pressure controller (see Fig. 4.1.2).

The feed water valve is actuated by a controller having three signals of detected water level, feed water flow rate, and steam flow rate. It is noticed that the detected water level contains the effect of the apparent gravity, since the water level gauge is of a type of measuring of pressure difference of the water heads.

The detected water level (gauge level: h_g) is expressed as,

$$h_g = \frac{(1 - \beta)(\rho_s - \rho_g)H + \beta(\rho_1 - \rho_g)h_{r.e1}}{(\rho_1 - \rho_g)} \quad (4.1)$$

where, β is the acceleration normalized by the gravity, ρ_s is the water density of a standard leg, ρ_g is the density of SG steam, ρ_1 is the density of SG saturated water, $h_{r.e1}$ is the SG water level (actual water level), and H is total gauge length. From this relationship, for the apparent gravity of, for example, 1.6g, the gauge level becomes lower about 20% level from the nominal water level.

Figure 4.1.3 shows the nodalization scheme used in the RETRAN-02/GRAV model. The model is composed of 42 volumes, 61 junctions, and 11 heat conductors. Figure 4.1.4 shows RETRAN-02/GRAV computational model of SG feed water control system containing the feed water pump and feed water

control valve. Besides the SG water control system, the automatic control system is modelled for the reactor power control system, the pressurizer pressure control system and the pressurizer water level control system.

4.2 Effects of Inclination on N.S. Mutsu Reactor

4.2.1 Steady State Operation at the Normal Power

Figure 4.2.1 shows the analysed result of the reactor system response to the ship inclination during the normal power operation (90% of the full power). Inclination is given instantaneously to 30 degrees at time zero and then the attitude is held. Inclination of 30 degrees is the design-base value and only for to study analytically the behavior of the reactor plant.

The water level and the pressure of SG secondary side parameters oscillate due to the disturbance of inclination, and the oscillation remains for a long period. This causes the cold leg temperature to oscillate. But, the hot leg temperature is almost constant. The reactor power varies due to the feed back effect of moderator temperature coefficient in the early period after completion of inclination, but after 60 seconds it becomes negligibly small. After about 100 seconds, the reactor power returns to the initial steady state together with variations of the parameters in the SG secondary side. Decay of the oscillation of the SG water level or the SG pressure take a long time.

From these result, it can lead that the effect of stationary inclination on the reactor system at the normal operation is negligibly small.

4.2.2 Natural Circulation

Natural circulation at inclination attitude of Mutsu is also studied analytically. Figure 4.2.2 shows the flow rates in the core, the cold leg and the hot leg after main coolant pumps tripped at inclination of 15 and 30 degrees. The reactor is tripped from the normal power operation (90% of the rated power) at 30 seconds, and then the main coolant pumps are tripped at 75 seconds.

The flow rate of descending loop (No.1 loop) decreases to almost zero in

case of 30 degrees inclination. On the contrary, the flow rate of ascending loop (No.2 loop) increases. The core flow rate at 900 seconds is about 1.7% of the rated flow with pump running. The fluid temperatures in the core, the cold leg and the hot leg change according to change of the flow rates and the core power : the water temperature difference between the hot leg and the cold leg becomes almost constant while these temperatures decrease with core power decreasing. Quasi-steady state natural circulation in the ascending loop is established after about 600 seconds.

In the case of 15 degrees inclination, on the other hand, the quasi-steady natural circulation is attained earlier. The flow rate in the descending loop is about 60 % of the flow rate in the ascending loop, and the core flow rate is 1.3 times larger than that in the case of 30 degrees inclination.

The general trend of natural circulation at inclination attitude of Mutsu is consistent with the experimental results by Iyori et al⁵⁾ : the flow rate in a descending loop decrease and the flow in this loop stagnate at a certain angle of inclination (i.e. one loop flow). From these analysis results, the natural circulation of Mutsu with two loops can be established at inclination angle of at least below 15 degrees, and even at 30 degrees the core heat is able to be removed steadily only by one loop operation .

4.3 Effects of Heaving on N.S. Mutsu Reactor

4.3.1 Steady State Operation at the Rated Powers

Since the SG secondary side has water level and its flow is the two-phase natural circulation, the water level and re-circulation flow of the SG will be mostly affected by the heaving. Figures 4.3.1(1),(2) and (3) shows the response of the SG water level and the re-circulation flow to the oscillation period of four seconds of the apparent gravity the heaving during the rated power operation (100% power). The apparent gravitational acceleration is given as sinusoidal oscillation of which amplitude is 0.6g (the design value) and the oscillation period is from 4 to 30 seconds. In the figure, the water level obtained from a simple design analysis assuming the constant feed water and

the constant heat transfer rate from the primary side is shown as dotted line.

The analyses show that as the apparent gravity acceleration becomes larger, the water level becomes lower ; the longer oscillation period of acceleration results in the larger variation in both of the water level and the re-circulation flow rate. The magnitude of variation in the water level obtained by RETRAN-02/GRAV calculation is by almost two times larger than that of the design analysis. But, the general response of the water level to the acceleration change is qualitatively consistent in those analyses.

Figure 4.3.2 shows the variation of the SG water level (the actual water level) and the detected water level (the wide ranged gauge water level) for the magnitude of acceleration for the period of 15 seconds. The variations becomes greater with the magnitude of acceleration. The variation of wide ranged gauge water level is smaller than that of the SG water level. This is the reason why the gauges have the low pass filtering ($\tau = 10$ seconds) of input signal of the water levels from the differential pressure transmitter. The results shows that the wide ranged gauge water level does not reach the high alarm level and the reactor trip level (the reactor scram level) even for the oscillation magnitude of 0.6g.

The RETRAN-02/GRAV analysis also shows that the effect of heaving on the primary side parameters such as reactor power and primary loop water temperature are negligibly small at steady state operation with a constant steam flow rate of SG.

4.3.2 Turbine Trip

As one of typical heavy load transient, the turbine trip under heaving motion is analysed. The turbine trip test of the power-up test without the ship motion is analysed for an analytical base.

Figures 4.3.3(1), (2), (3) and (4) show the results of the test of the turbine trip and the RETRAN-02/GRAV analysis without ship motion. A transient began with complete loss of the turbine steam flow from 100% of the full-power operation. The total steam flow decreased from about 100% to about 25% in a few seconds. With decreasing total steam flow, the reactor power decreased in early

period with insertion of the control rod due to the mismatch signal of power-load, and the power decreased in later period due to a negative reactivity insertion given by temperature rise of the coolant. The changes of the average temperature of the primary coolant were by about five degrees (°C) and the pressurizer pressure by about 2 kg/cm² in the transient.

The SG pressure increased to about 55 kg/cm²G due to load decrease, but the pressure was under the main steam dump operation pressure (62.5 kg/cm²G). The SG gauge water level (the narrow ranged water level) shrank by about 13% from the initial level owing to pressurization in the SG, afterward the water level recovered to the normal operating one. The reactor attained the steady state after about 20 minutes from the main turbine trip. The analysis results shows a good agreement with the test. Details of the RETRAN-02/GRAV analyses of power-up test will be discussed in other report.

Figures 4.3.4(1),(2),(3),(4) and (5) show the analysed result of transient with heaving and without heaving as comparison. Heaving of sinusoidal oscillation of magnitude 0.6g and period 15 seconds adds to the transient. The steam flows are almost same in both cases, while the SG feed water flow in the case of heaving oscillates due to SG water level oscillation. The SG gauge water level oscillates in heaving by about 25 cm span at the core power of 100%, and by about 6 cm span at the power of 25%. The amplitude of water level oscillation becomes larger with increase of reactor power since circulation flow increases with reactor power. The SG pressure and the SG re-circulation flow show small oscillation due to effect of acceleration change. The reactor power, the primary loop average temperature, and the pressurizer pressure of the primary side parameters are not influenced much by heaving as shown in Fig. 4.3.4.

The results show that the Mutsu reactor responds to the load change due to heaving even without operation of any relief valve and the reactor trip.

4.4 Effects of Rolling on N.S. Mutsu Reactor

4.4.1 Steady State Operation at the Normal Power

Rolling also affects the behavior of SG secondary side. Figures 4.4.1(1), (2) and (3) show the analysis of response of the SG water level to rolling during the normal power operation. The rolling period is 15 seconds which equals the rolling period peculiar to Mutsu, and the rolling angles are 5, 10, and 30 degrees.

It is noted that the SG water levels oscillate with a half period of rolling. The reason is that the driving force due to the water head term in the SG oscillates with a half period of rolling and the water head term dominates the oscillation rather than the tangential force or the centrifugal force which vary with the same period as rolling one. Therefore, the oscillation amplitude of the SG water level becomes larger with rolling angle rather than rolling period. The analysis shows the SG water level varies nearly in the range from 10 cm to 15 cm. These variation corresponds to those with heaving of 0.1g amplitude and 15 seconds period.

4.4.2 Natural Circulation

Analysis of natural circulation under rolling is performed to study the effect of rolling on the core cooling by natural circulation. Figure 4.4.2 shows the flow rates in the core, the hot leg and the cold leg after the main coolant pumps trip under rolling with the period of 15 seconds and the angle of 30 degrees. The reactor is tripped from the normal power operation at 30 seconds, and the main coolant pumps are tripped at 75 seconds.

The loop flow rates oscillate with the same period of the rolling period. The core flow rate also oscillates with a smaller amplitude than the loop flows. The oscillation period of the core flow rate is a half the rolling period because of two loop flow's oscillation. The general behavior is consistent with the experimental results by Murata et al(6).

Water temperatures in the cold legs in natural circulation are nearly constant by assuming a constant pressure for both of the two SGs through

transient. Water temperature in the hot legs decrease slowly with decrease of the core decay heat. It is clear that there is not the effect of rolling on the primary loop water temperature and that the core can be cooled down by natural circulation under the rolling with increased steam flow rate.

4.5 Effects of Ship Motions on N.S. Mutsu Reactor in the Experimental Voyage

In general, marine ships must travel through various sea weathers, not only an ordinary sea but also sometime a rough sea through her ship's life. Main purpose of Mutsu experimental voyage is to obtain the data about the effect of sea conditions such as swell or wind wave on reactor performance through ship motion in various sea weathers. To clarify the effect of these sea conditions, the sea zones in the experimental voyage are divided into the following four zones : ① a calm sea zone, ② an ordinal sea zone, ③ a rough sea zone, and ④ a tropical sea zone. Performances of the reactor system in these sea zones will be compared to clarify the effect of ship motion on the reactor.

The sea zones should be determined efficiently because of a limited term of the voyage. It is efficient that in planning of her voyage schedule, the sea zones of ①, ②, ③ are defined from the viewpoint of the magnitude of ship motion and the magnitude of swell or wind wave inducing the effect of ship motion on the reactor, aparting from a common definition in the shipping world : the rough sea gives a certain clear effect of ship motion on the reactor ; the calm sea does negligibly small effect ; and the ordinal sea does a larger effect than that on the calm sea but smaller one than that on the rough sea.

The results of RETRAN-02/GRAV analysis have been used to estimate the effect of ship motion on the reactor in deciding sea zones. The magnitude of ship motion by swell or sea wave has been estimated by another analyses of a ship dynamics.

In this section, the magnitude of ship motion on Mutsu reactor through the experimental voyage is discussed. First, the critical values of variation of the acceleration and the flow rate variations by ship motion which give a certain

clear effect on the process variables of reactor plant are evaluated using the analytical results. And then, applicable and realistic sea conditions are recommended to the four sea zones.

The process variables to be evaluated were chosen as SG water level, SG feed water flow rate, steam flow rate from the SG, and position of control rods. The other process variables such as the pressurizer's pressure are presumably affected smaller than those ones. The SG water level is considered to be affected mostly by the acceleration change due to heaving or rolling. The SG feed water flow rate is affected indirectly through the acceleration by operation of feed water control system. The steam flow rate varies by the load change of a propulsion turbine due to swell or sea wind in use of the turbine revolution feed back control system. The position of control rods also move indirectly through variation of load change by operation of the reactor control system owing to steam flow variation. The critical values giving a certain clear effect on the process variables of reactor plant are evaluated as follows.

(1) The SG water level

The critical value for the SG water level variation owing to acceleration is taken as 30 mm of the actual water level which equal one percent of wide ranged gauge water level span ($0.01 \times \text{full span (3000 mm)} = 30 \text{ mm}$). These acceleration are obtained from the analysis for the steady state operation at the rated power with heaving in the same way as described in sec. 4.3.1.

Figure 4.5.1 shows the relationship between the magnitude and the period of sinusoidal oscillations of acceleration which induce one percent (30 mm) variation of the actual SG water level. The variation of 30 mm of the SG actual water level equals almost that of one percent of the narrow ranged gauge water level, since the variation of input signal from the transmitter is mitigated by filtering the signal.

(2) The SG feed water flow rate

The critical value for variation of the SG feed water flow rate which stem from the SG water level changing due to the acceleration is taken as two percent of the rated flow rate by taking account of measuring errors. These acceleration are obtained from the analysis for the steady state operation at

the rated power with the heaving in the same way as SG water level.

Table 4.5.1 shows the magnitude of acceleration which induces two percent variation of the SG feed water flow rate for the period of acceleration. Because of low pass filtering of the signal of water level and delay times in the feed water control system, larger acceleration is necessary for SG feed water flow variation than SG water level variation.

(3) The steam flow rate from the SG

The critical value for the variation of steam flow rate from the SG due to change of the propulsion turbine load is taken as five percent of the rated steam flow rate by taking accounts of fluctuation of steam flow, change of base load and measuring errors. The conditions of swell or sea wind causing these steam flow change should be obtained from the other analysis about the turbine load variation by swell or sea wind through ship motions.

(4) The position of control rod

When a rate of the steam flow change due to variation of the propulsion turbine load is large, the control rod are withdrawn or inserted. The critical value of the steam flow rate change is taken as the variation of which speed makes a temperature difference signal of $0.6\text{ }^{\circ}\text{C}$ necessary for the control rod moving in the reactor control system. Table 4.5.2 shows the magnitude and the period of sinusoidal steam flow change which move the control rod. The conditions of swell or sea wind causing these steam flow change should be also obtained from other analysis.

The analyses of ship dynamics show the relationship between sea wind or swell and ship motion (the results is not yet published). For example, a head wave with wave height of 8 m (the period of 8 seconds) is necessary for the acceleration of $0.2g$ (the period of 8 seconds), and 6 m (12 seconds) is necessary for the acceleration of $0.11g$ (12 seconds). The wave height over 8m occurs rarely in statistic at ordinary sea even on the north pacific ocean. These two facts should be taken into account in deciding applicable and realistic sea conditions. Moreover, from the fact that SG water level is affected mostly by acceleration, the critical value for the SG water level is recommended

as one of parameters in decision of the sea zones in the experimental voyage, as follows.

It is recommended that the rough sea is a sea zone where the acceleration by ship motions is greater than that which varies the SG actual water level by 30 mm *); the calm sea is a sea zone where the acceleration by ship motions is smaller than that which varies the SG actual water level by 15 mm**), since the calm sea should give negligibly small effect; the normal sea is a sea zone where the acceleration by the ship motion ranges from that of the calm sea to that of the rough sea. Figure 4.5.2 shows the magnitude and the period of the acceleration due to ship motion recommended to deciding the sea zones in the Mutsu experimental voyage. The heights and the periods of swell or wind wave which are equivalent to those acceleration will be evaluated by analyses of ship dynamics in a near future.

*) It equals the variation of one percents of the narrow ranged water level and also equals four percents of the narrow ranged water level signal in front of filtering.

***) It equals the variation of 0.5 percent of the narrow ranged water level and also equals two percents of the narrow ranged water level signal in front of filtering.

Table 4.1.1 Specific Features of Mutsu Reactor Design in Comparison with Land-Based PWRs⁹⁾

| Design Parameter | Mutsu Reactor | Land-based PWRs |
|---|--------------------|-------------------------------------|
| 1. Reactor Power [MW(thermal)] | 36 | 1650 (Ikata-1,2) |
| 2. Average LHGR (kW/m) | 9.65 | 17.5 (RESAR-41) |
| 3. Reactor Operating Pressure (MPa) | 10.9 | 15.6 (RESAR-41) |
| 4. Average Coolant Temperature(°C) | 278 | 305.5 (Ikata-1,2) |
| 5. Subcooled Temperature of the Primary Coolant With Respect to Reactor Power (°C/MW) | 32 | 14 (RESAR-41) |
| 6. Specific Inventory of the Primary Coolant With Respect to Reactor Power (°C/MW) | 280 | 75 (Ikata-1,2) 68 (Takahama-3,4) |
| 7. Steam Generator Pressure at 100% Power (MPa) | 4.02 | 5.78 (Ikata-1,2) |
| Steam Flow Rate (kg/h/unit) | 3.06×10^4 | 1.62×10^6 (Ikata-1,2) |

Note: Ikata-1 and -2 are two-looped PWRs.

Takahama-3 and -4 are three-looped PWRs.

Table 4.1.2 Comparison of Design Base Conditions Between Three Marine Nuclear Ships of Mutsu, Otto Hahn and Savannah

| | Mutsu ⁽¹⁰⁾ | Otto Hahn ⁽¹¹⁾ | Savannah ⁽¹²⁾ |
|-----------------------------------|---|--|--------------------------|
| Load Increase (steam flow %) | 18% to 90% in 30 seconds | 10% to 100% in 90 sec. | 20% to 80% in 10 sec. |
| Load Decrease (steam flow %) | 100% to 18% in one second | 100% to 10% in one sec. | 100% to 20% in 3 sec. |
| Load Change (steam flow %) | 1) Ahead to Astern: 100% to 18% in 5 sec., 50 sec. holding, and 18% to 80% in 30 sec. 2) Astern to Ahead: 80% to 18% in 5 sec., 50 sec. holding and 18% to 100% in 30 sec. | ————— | ————— |
| Remarks | ————— | In emergency, maximum increase rate is 4% / sec. | ————— |

Table 4.1.3 Design-Base Conditions of Mutsu for Ship Motions

| | |
|---|--|
| 1. Vertical Acceleration Force due to Heaving | $g = g_0(1 \pm 0.6)$; 4 to 15 cpm ^{*)} |
| 2. Rolling | 30^θ ; 3 to 9 cpm |
| 3. Pitching | 10^θ ; 4 to 15 cpm |

*) cpm : cycle per minute

Table 4.5.1 Vertical Acceleration Necessary for Two Percent Variation of SG Feed Water Flow

| | | | | |
|---------------------------------|-----|-----|-----|-----|
| Period of Acceleration (second) | 5 | 7 | 10 | 15 |
| Magnitude of Acceleration (g) | 3.0 | 1.1 | 0.4 | 0.2 |

Table 4.5.2 Sinusoidal Steam Flow Variation Necessary for Control Rod Movement During Rated Power Operations

| | | | | |
|---|-----|-----|-----|-----|
| Period of Steam Flow Variation (second) | 5 | 7 | 10 | 15 |
| Magnitude of Steam Flow Rate (%) | 2.1 | 2.0 | 2.0 | 1.9 |

Remark : Control rod movement is taken equivalent to temperature difference signal (ϵ) 0.6°C

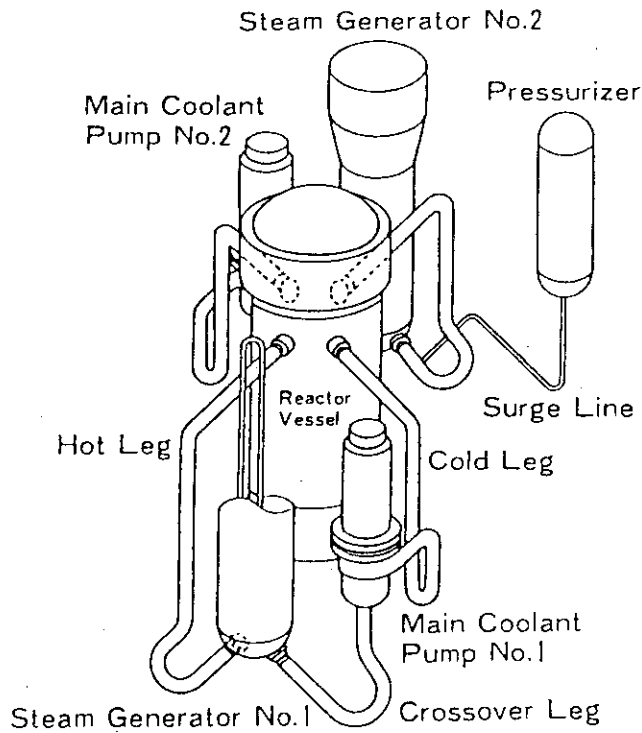
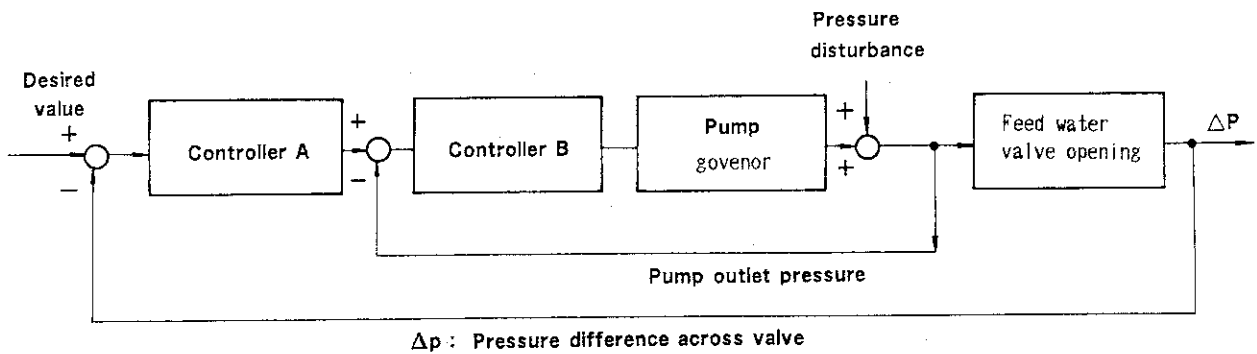


Fig. 4.1.1 Mutsu Reactor Coolant System



Controller A: Control of constant pressure difference across feed water valve
Controller B: Control of pump outlet pressure control

Fig. 4.1.2 MUTSU Feed Water Pump Controller System

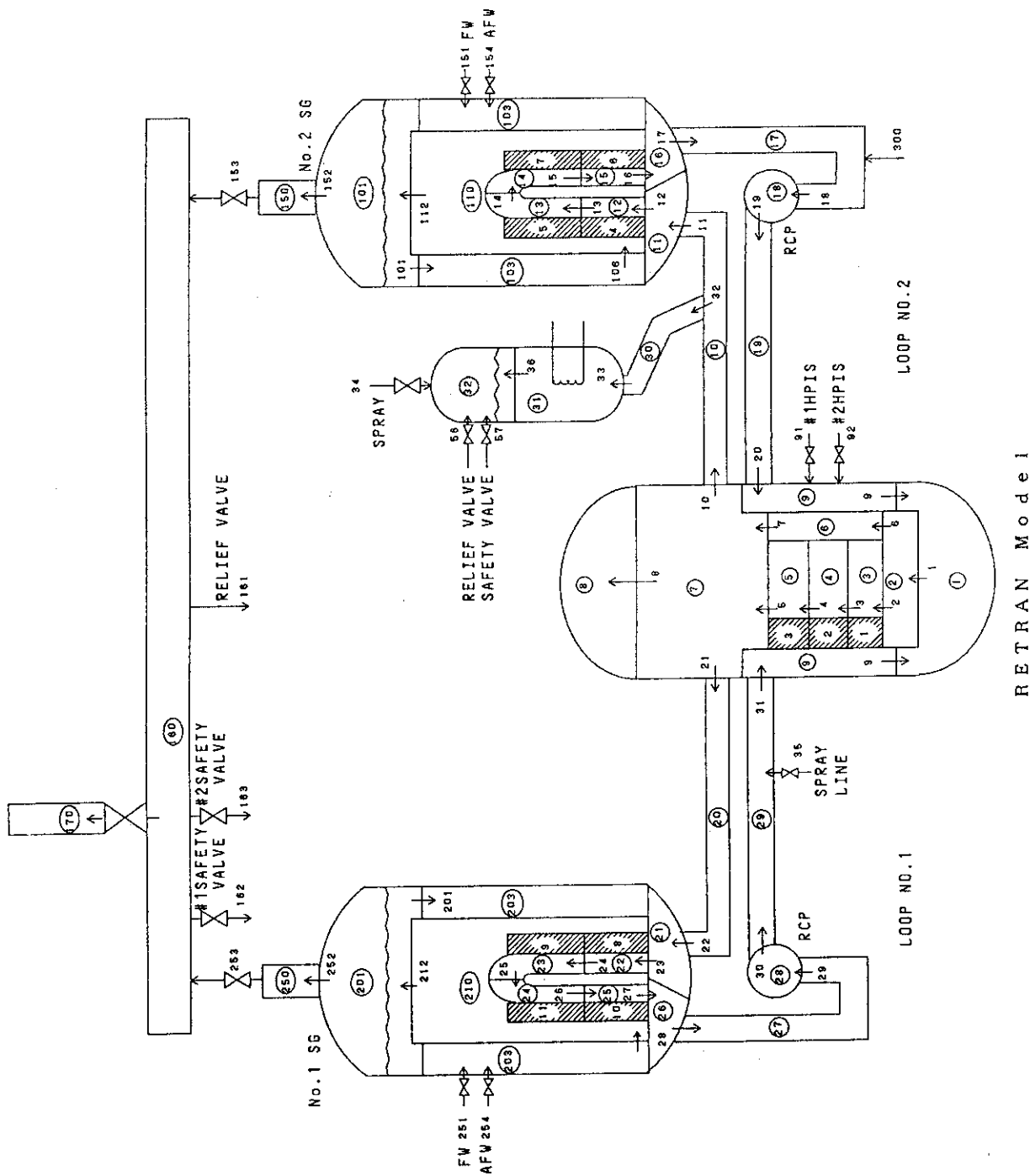


Fig. 4.1.3 RETRAN-02/GRAY Computational Nodalization for MUTSU Analysis

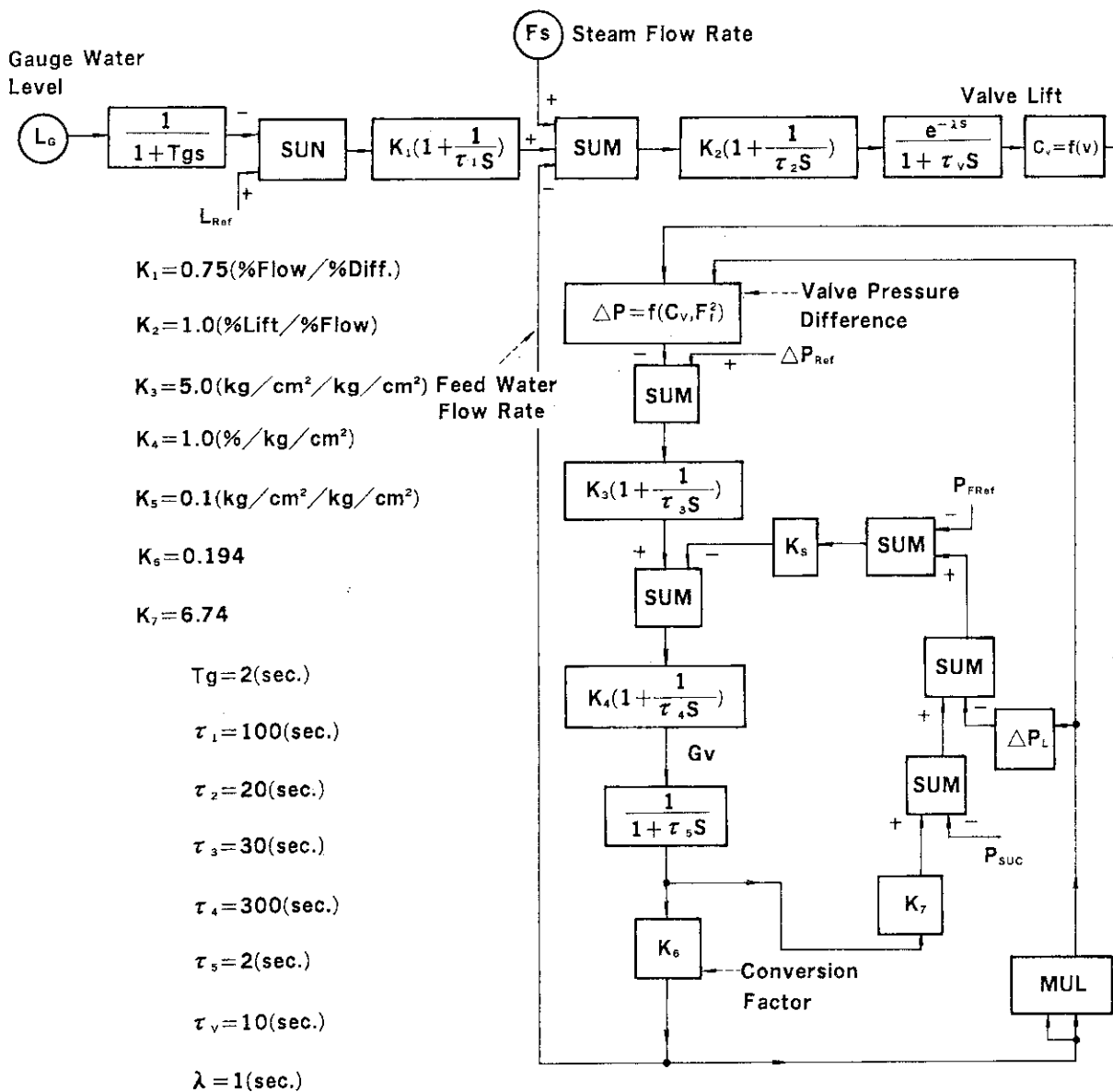
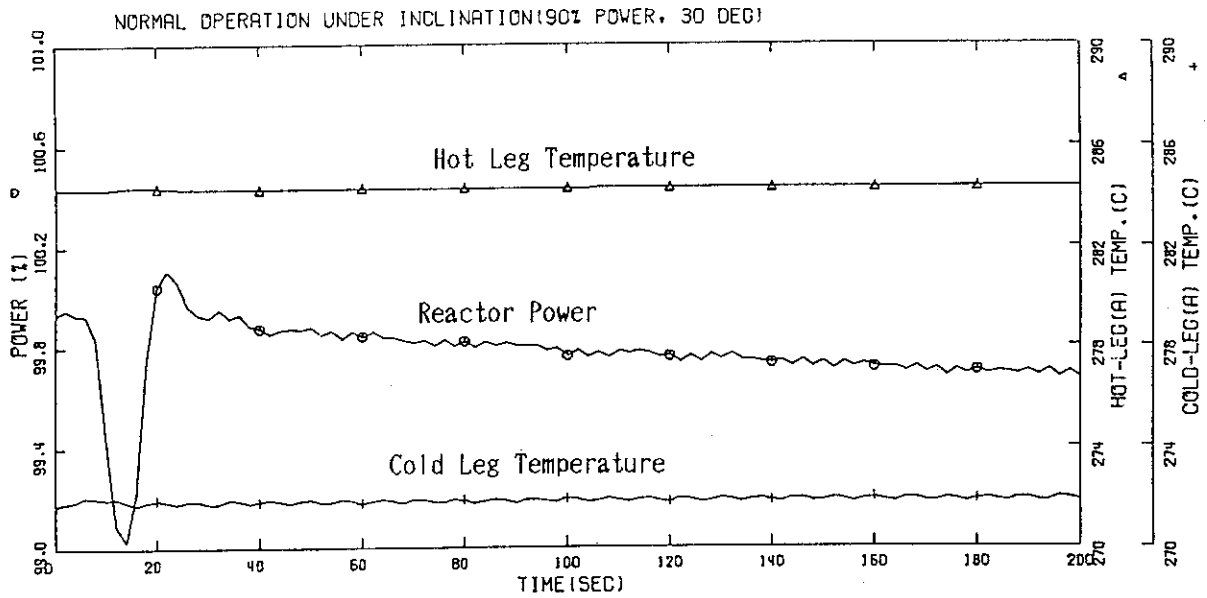
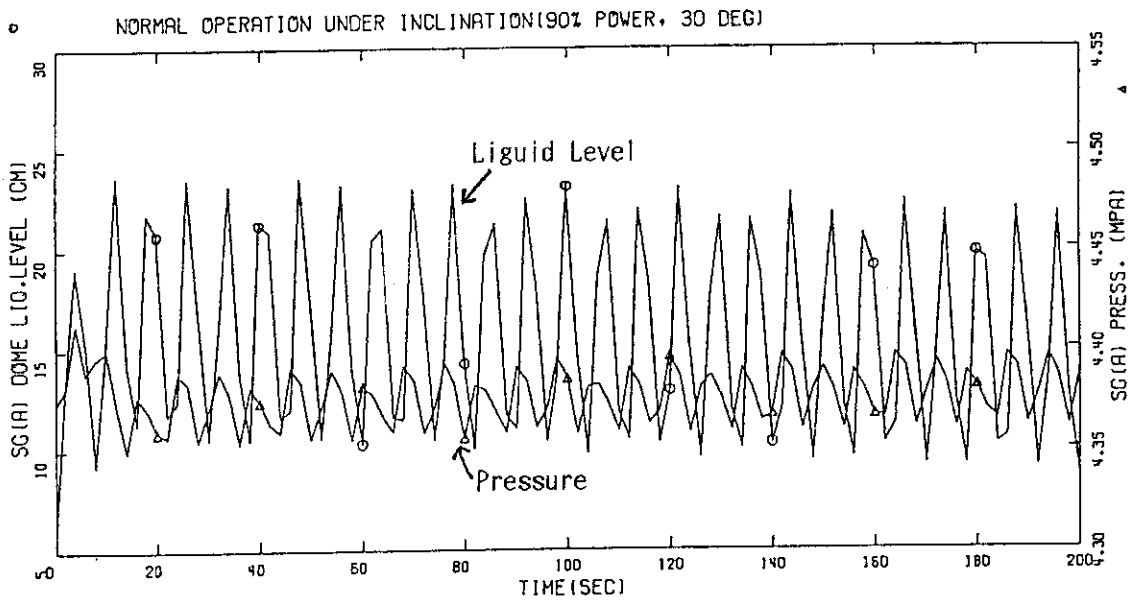


Fig. 4.1.4 RETRAN-02/GRAV Model of SG Feed Water Control System



(a) Primary Side Parameters (Power, Hot and Cold Leg Temperature)



(b) SG Secondary Side Parameters (Liquid Level and Pressure)

Fig. 4.2.1 Analysis of Mutsu Reactor Response to Ship Inclination During Normal Power Operation

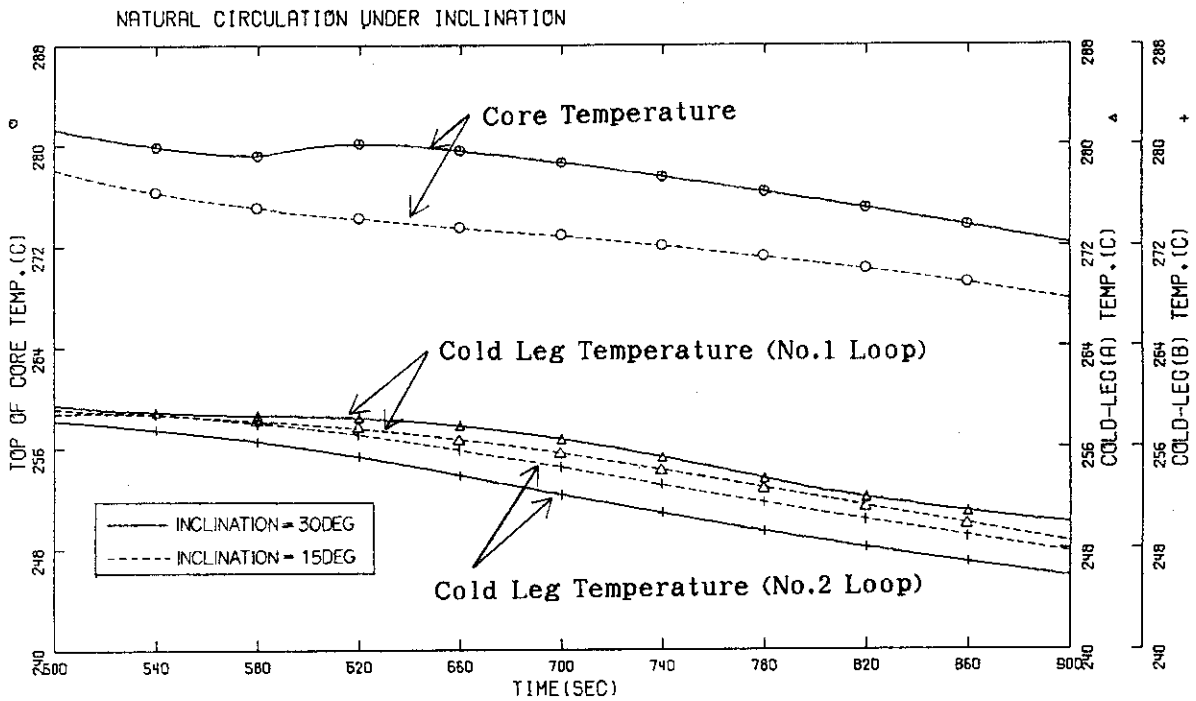
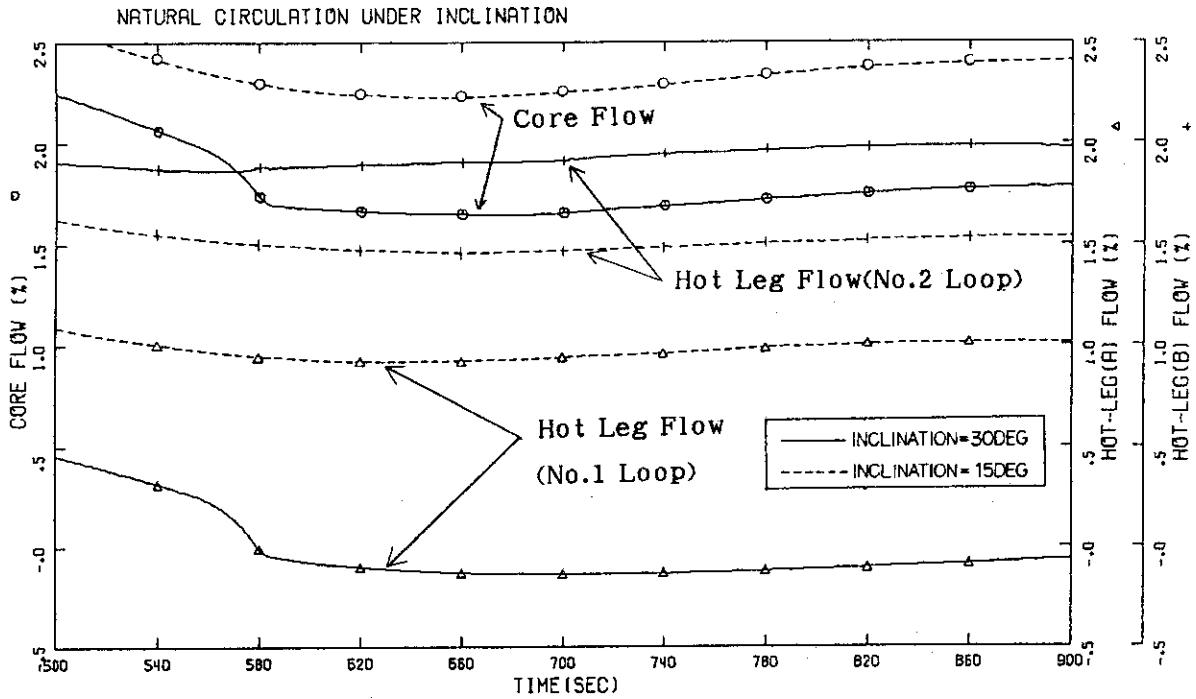


Fig. 4.2.2 Analysis of Natural Circulation at Inclination
 (Reactor Tripped at 30 Seconds and Main Coolant Pumps
 Tripped at 75 Seconds)

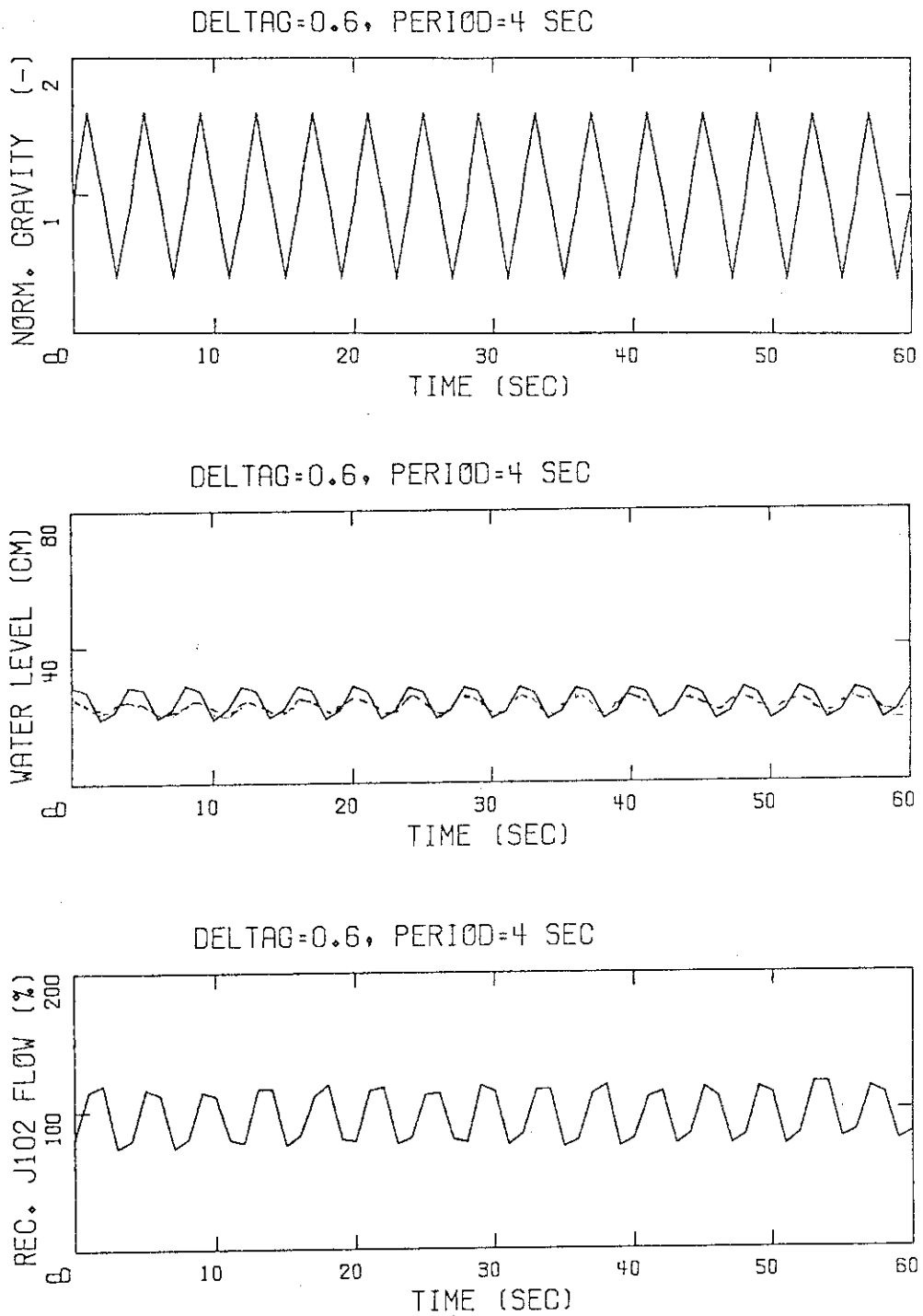


Fig. 4.3.1(1) Analysis of Response of Mutsu SG Water Level and Re-Circulation Flow at Heaving During Rated Power Operation

(a) $\Delta g = 0.6g$, Period = 4 sec.

(——— Present Analysis)
 (- - - Design Analysis)

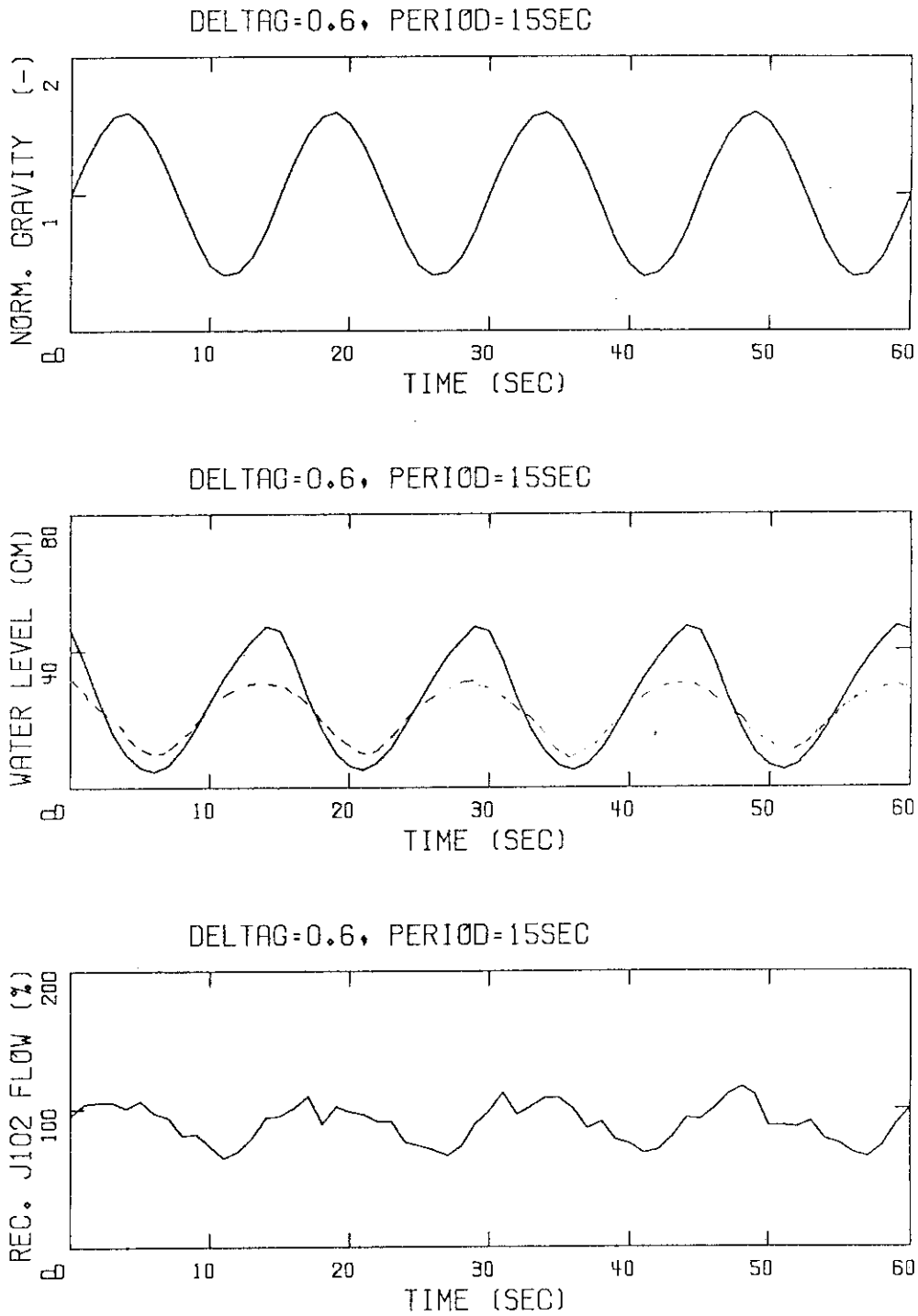


Fig. 4.3.1(2) Analysis of Response of Mutsu SG Water Level and Re-circulation Flow at Heaving During Rated Power Operation

(b) $\Delta g = 0.6g$, Period = 15 sec.
 (——— Present Analysis)
 (- - - Design Analysis)

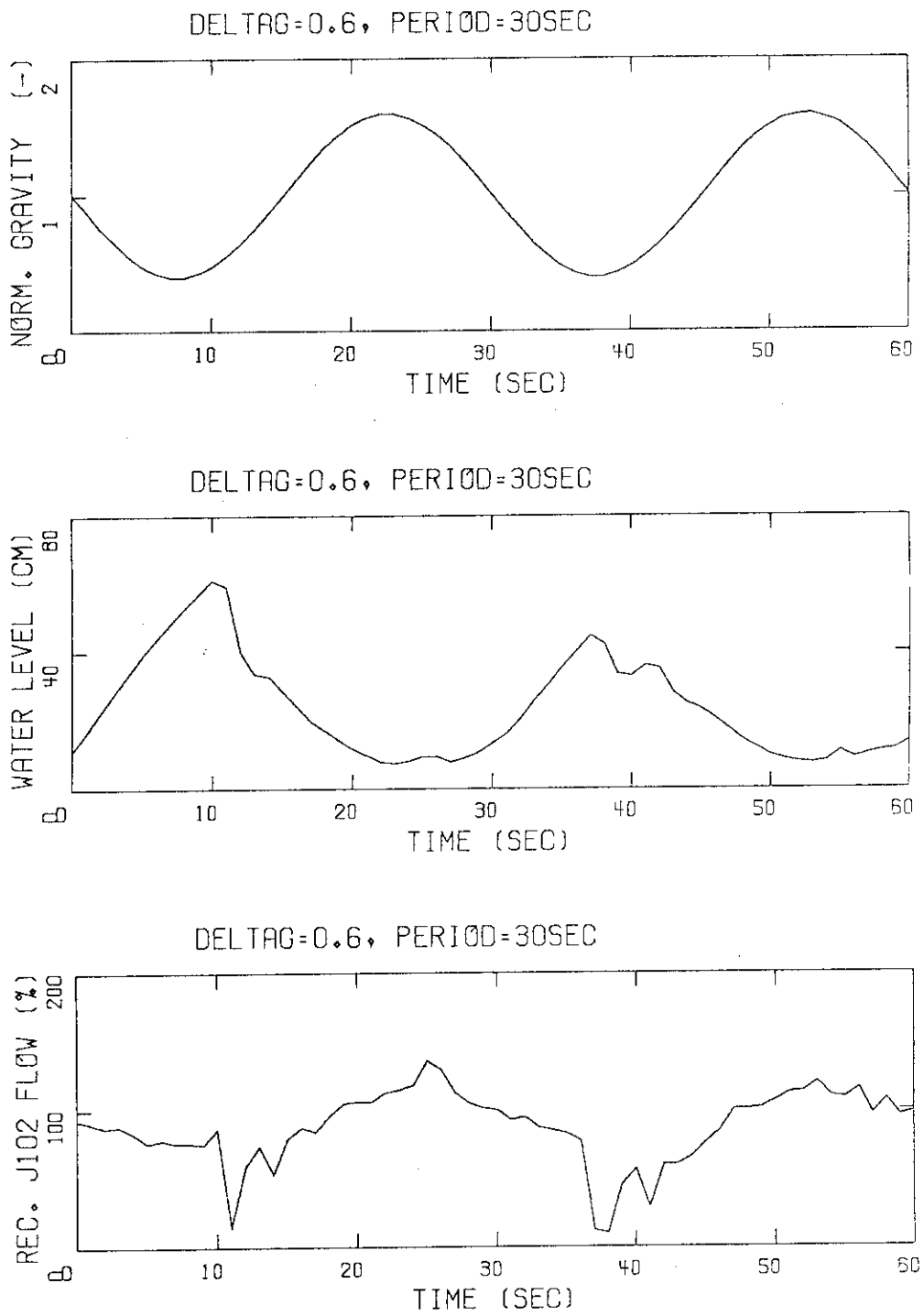


Fig. 4.3.1(3) Analysis of Response of Mutsu SG Water Level and Re-circulation Flow at Heaving During Rated Power Operation
 (c) $\Delta g = 0.6g$, Period = 30 sec.

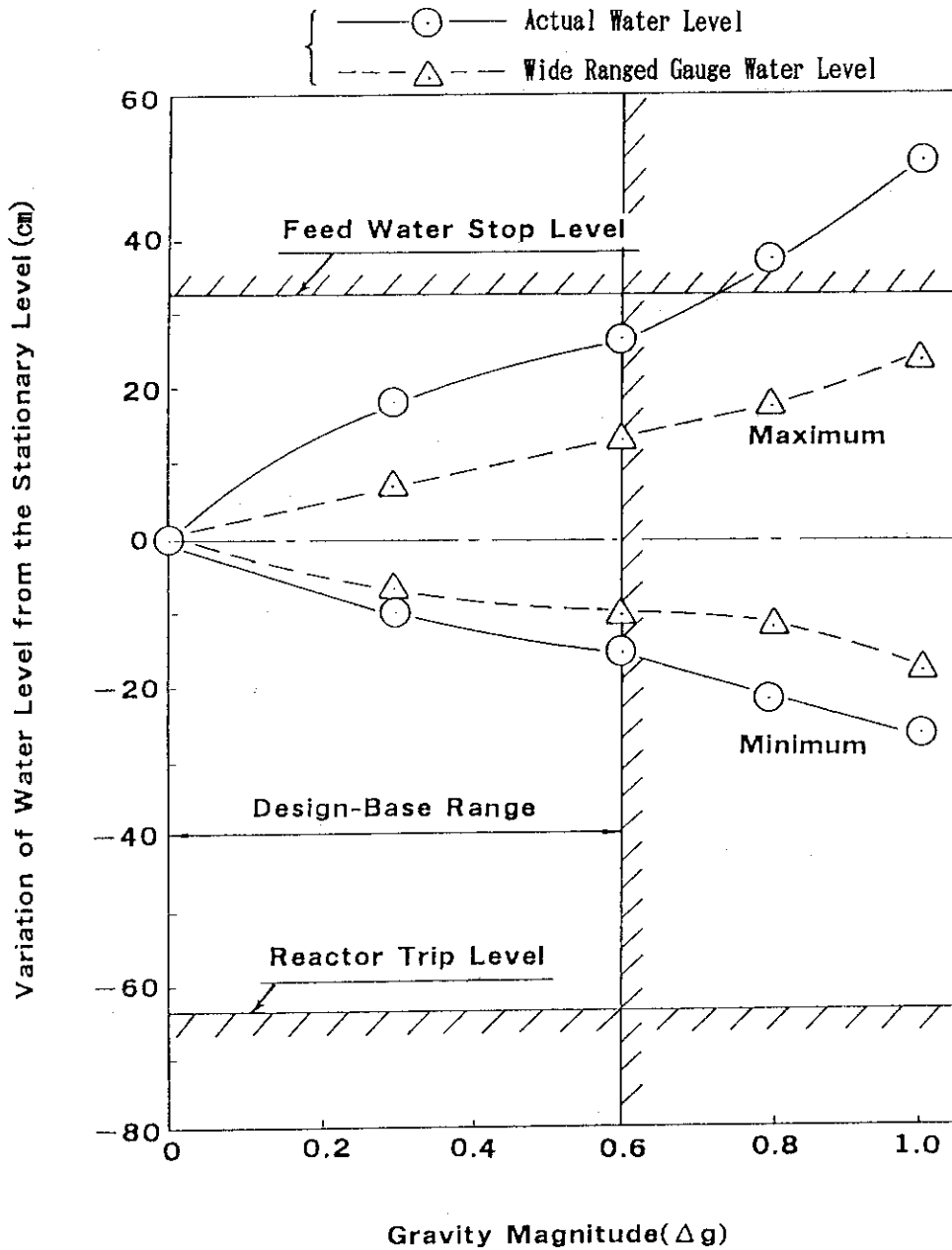
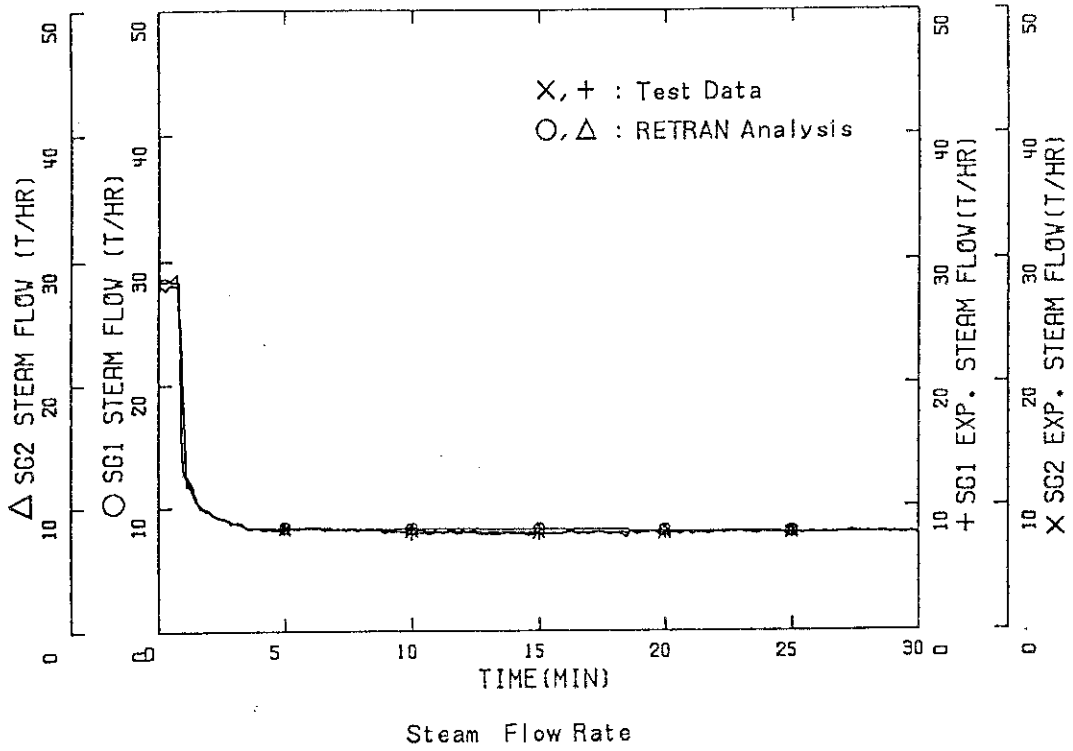


Fig. 4.3.2 Variation of SG Water Level and Gauge Water Level at Acceleration Period of 15 Seconds During Rated Power Operation

MUTSU : (CASE-23)



MUTSU : (CASE-23)

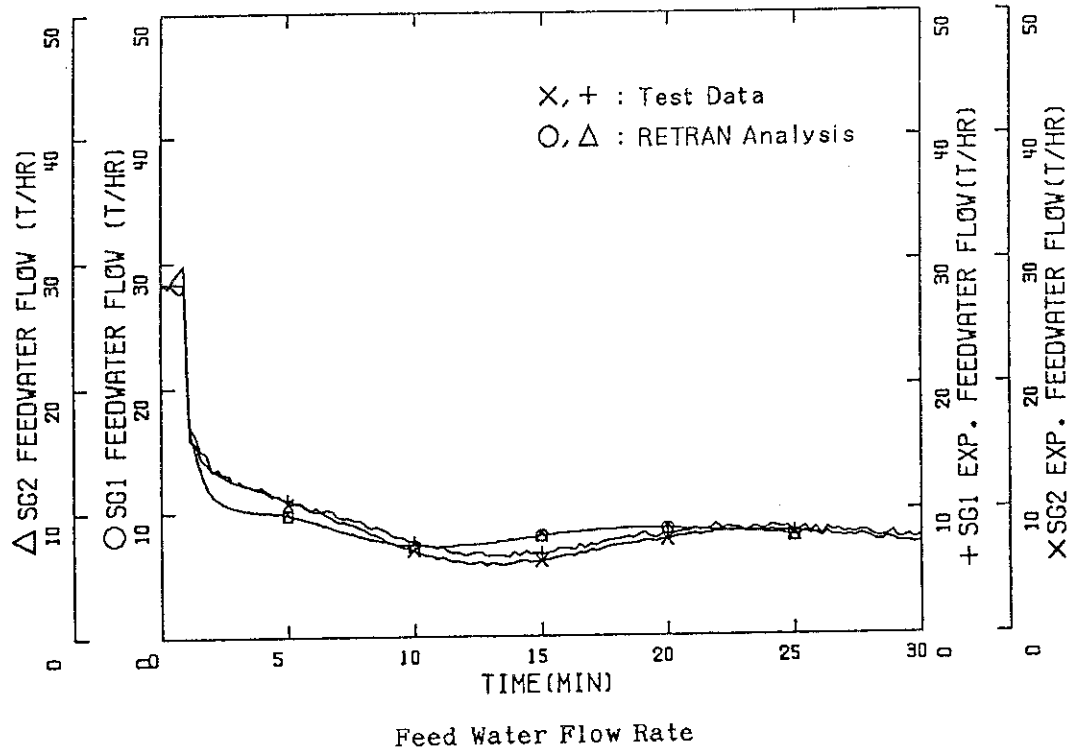


Fig. 4.3.3(1) Turbine Trip Test of Mutsu Without Ship Motion
 (Changes of Steam Flow Rate and Feed Water Flow Rate)

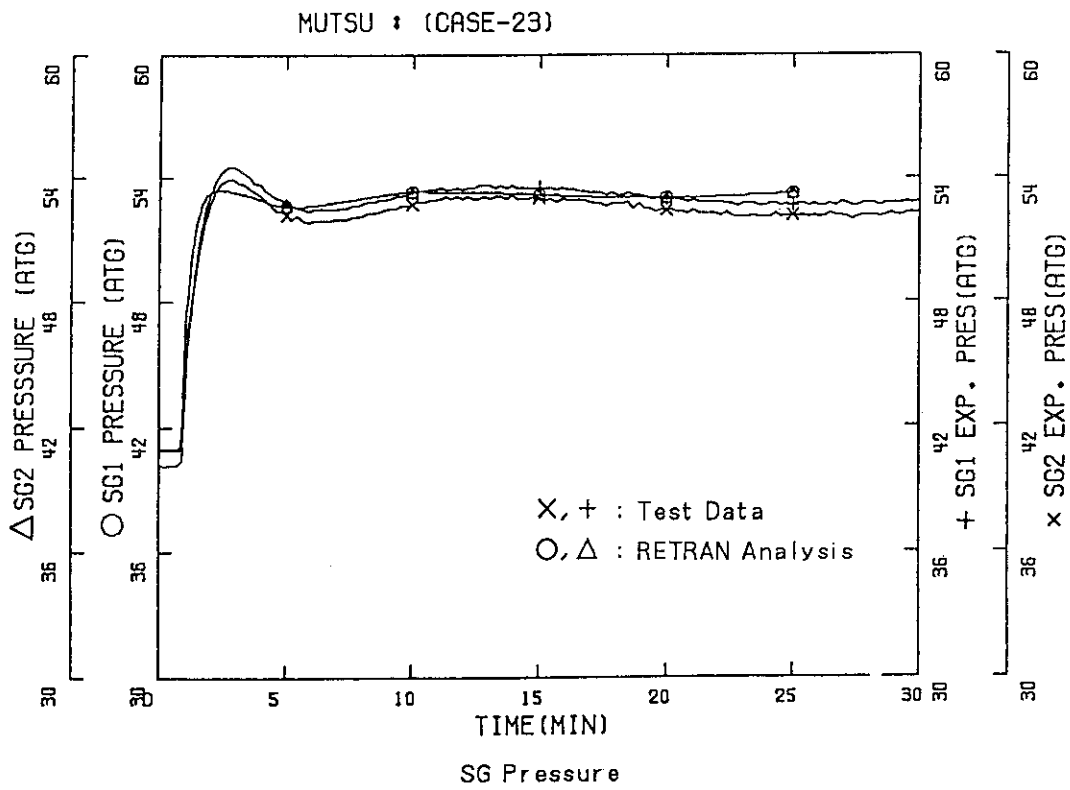
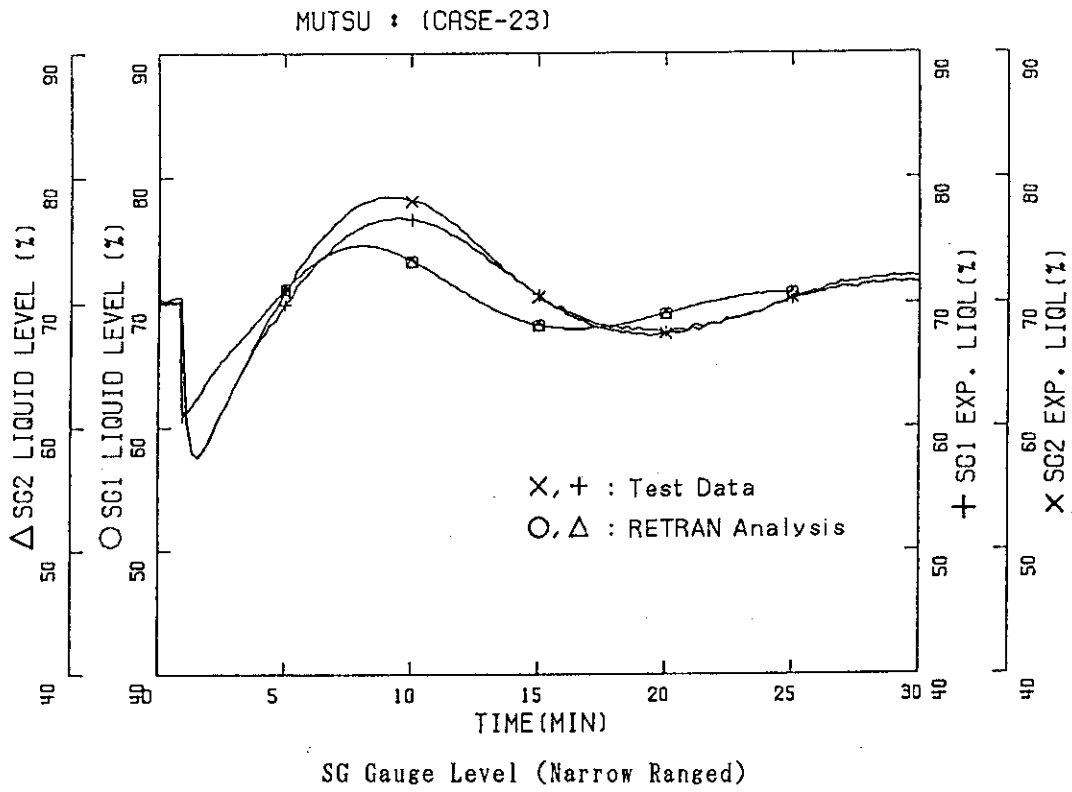
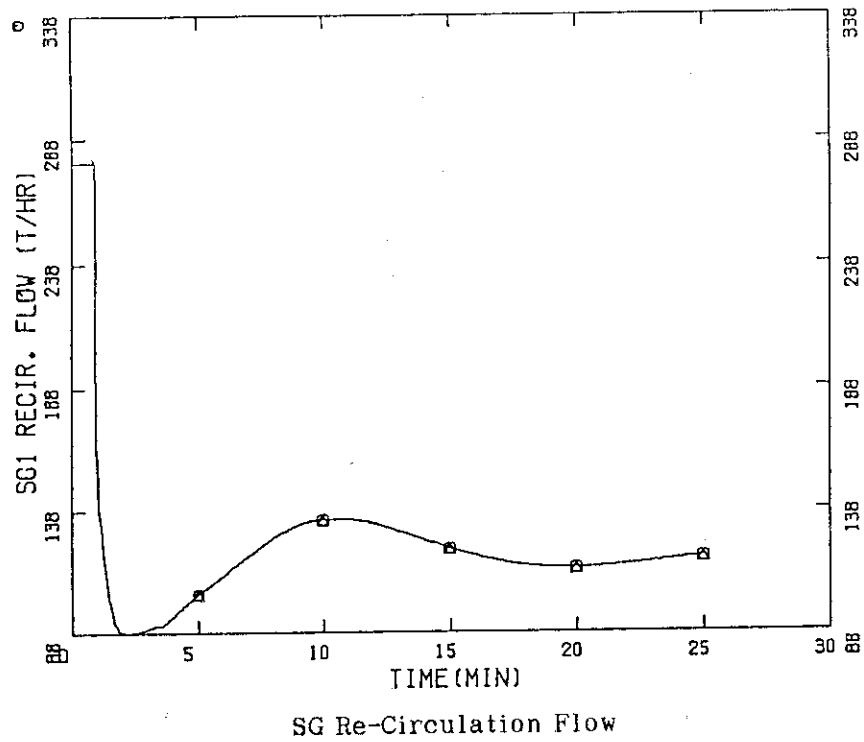


Fig. 4.3.3(2) Turbine Trip Test of Mutsu Without Ship Motion
(Changes of Narrow Ranged SG Water Level and SG Pressure)

MUTSU : (CASE-23)



MUTSU : (CASE-23)

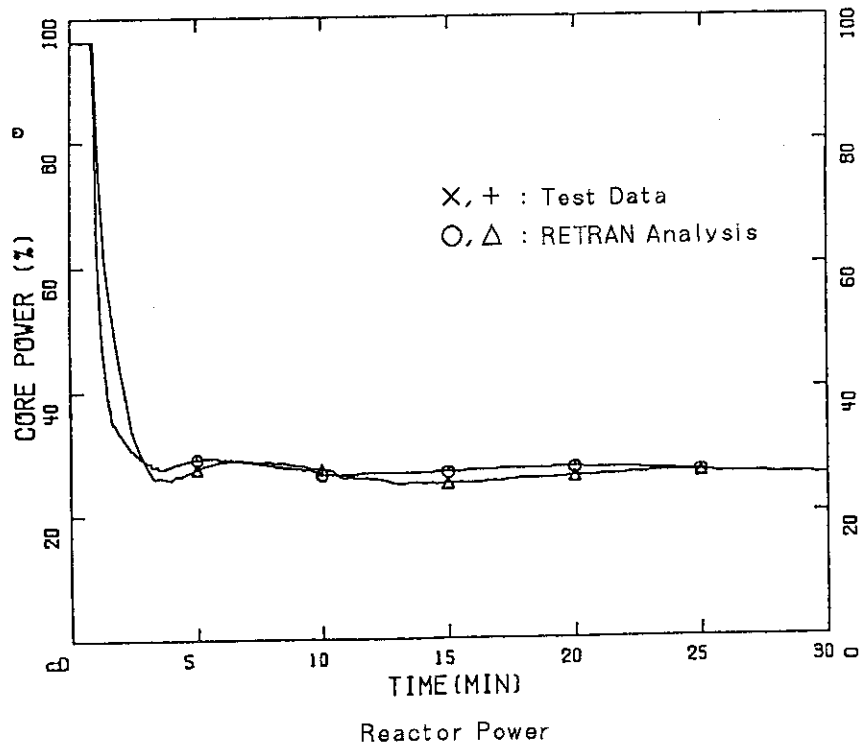


Fig. 4.3.3(3) Turbine Trip Test of Mutsu Without Ship Motion
(Changes of SG Re-Circulation Flow and Reactor Power)

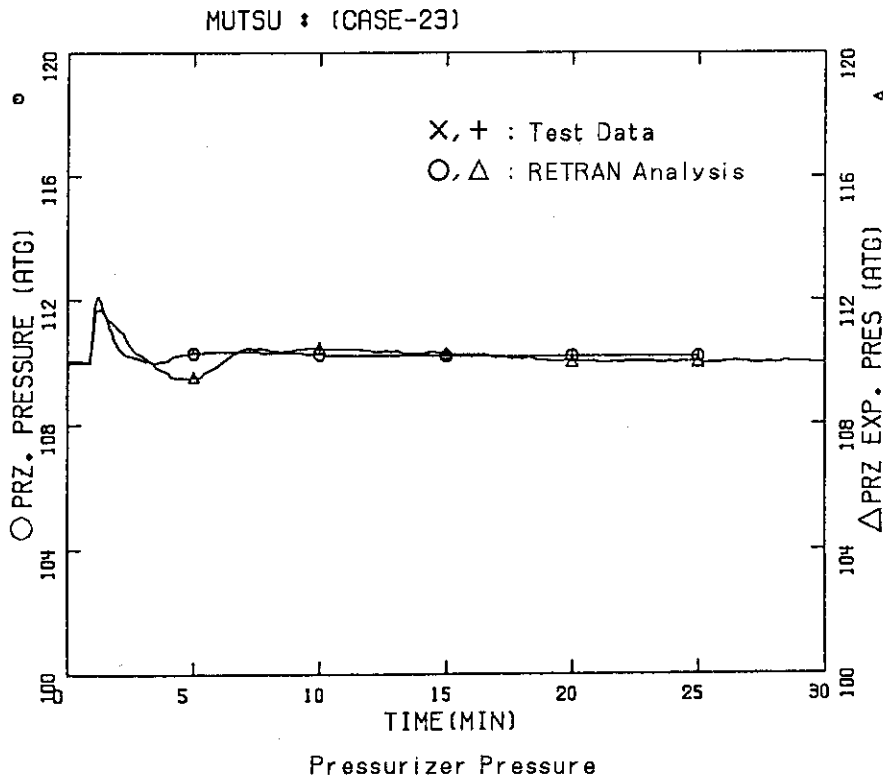
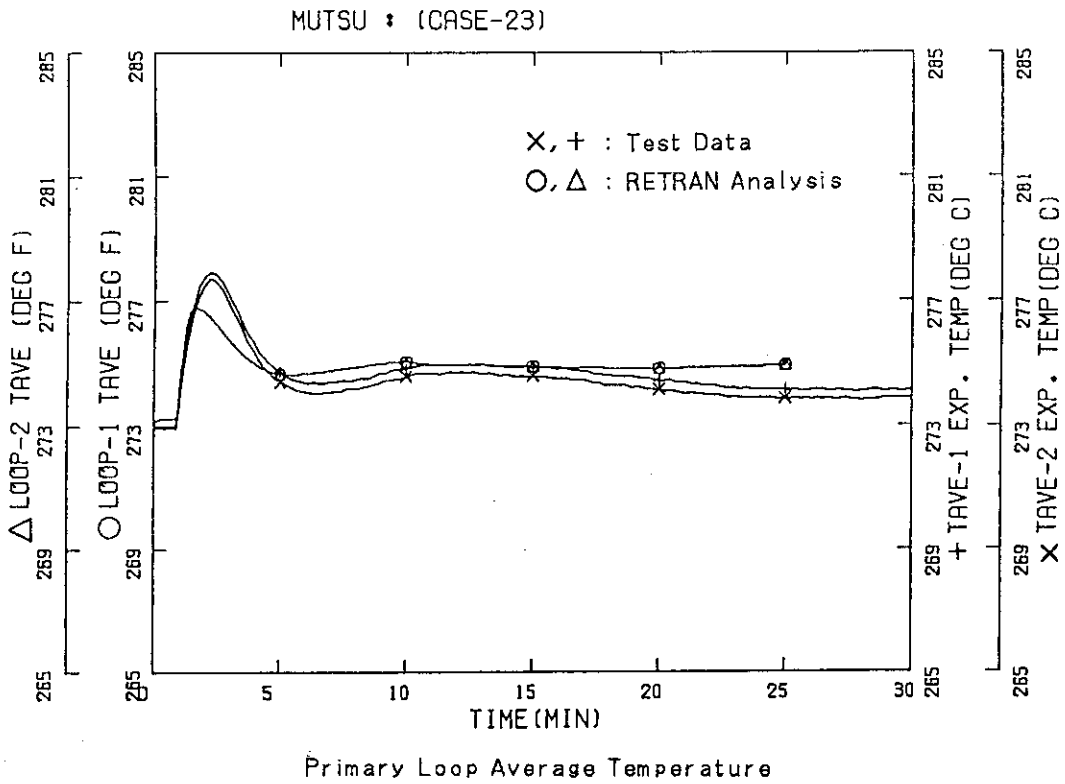


Fig. 4.3.3(4) Turbine Trip Test of Mutsu Without Ship Motion
(Changes of Primary Loop Temperature and Pressurizer Pressure)

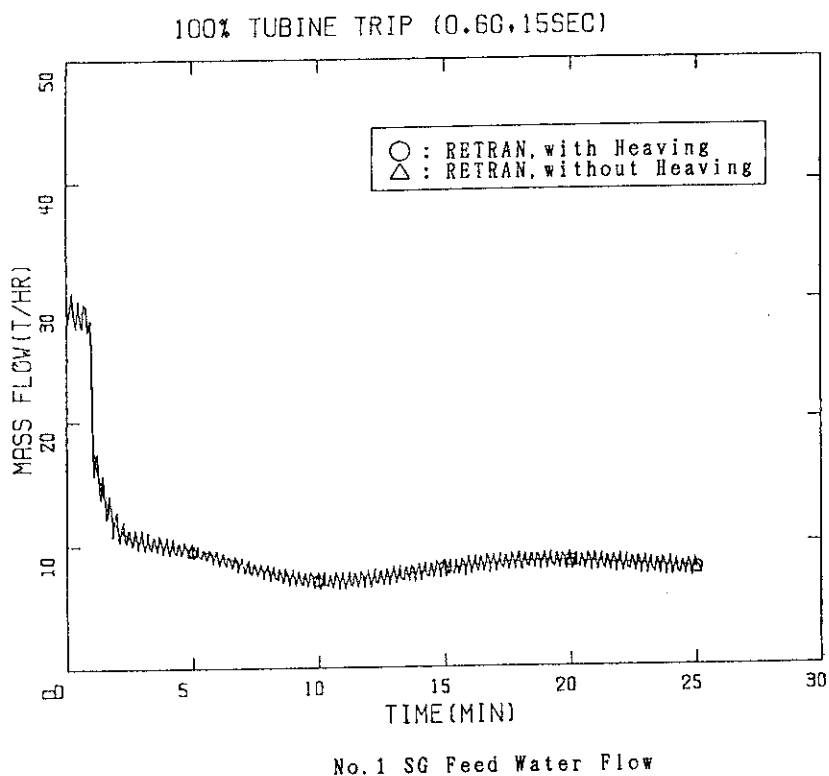
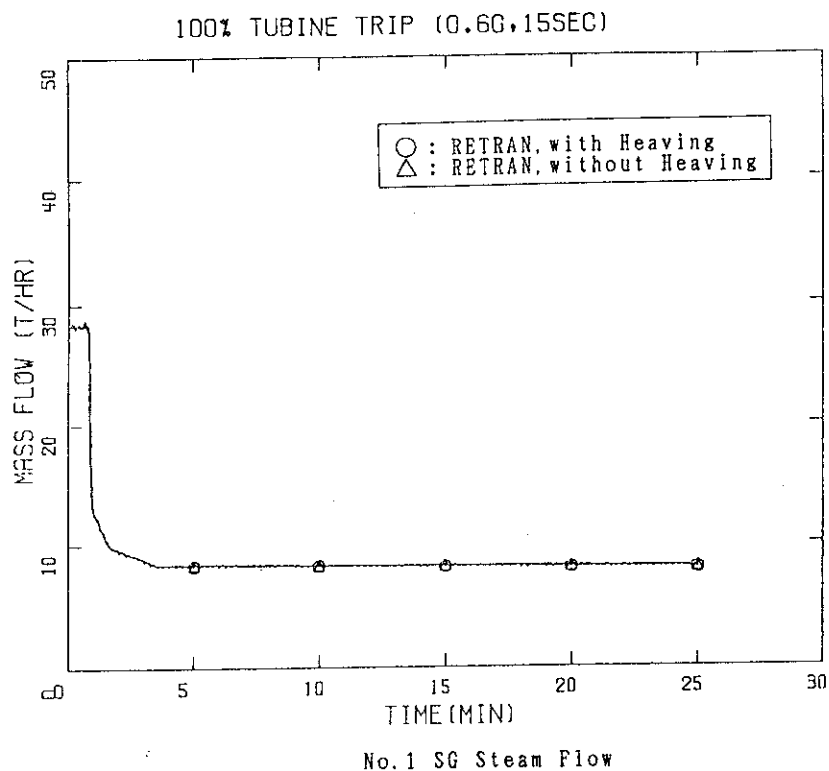


Fig. 4.3.4(1) Comparison of Transients With Heaving (0.6 g, 15 Seconds) and Without Heaving at Turbine Trip of Mutsu (Changes of No.1 SG Steam Flow and Feed Water Flow)

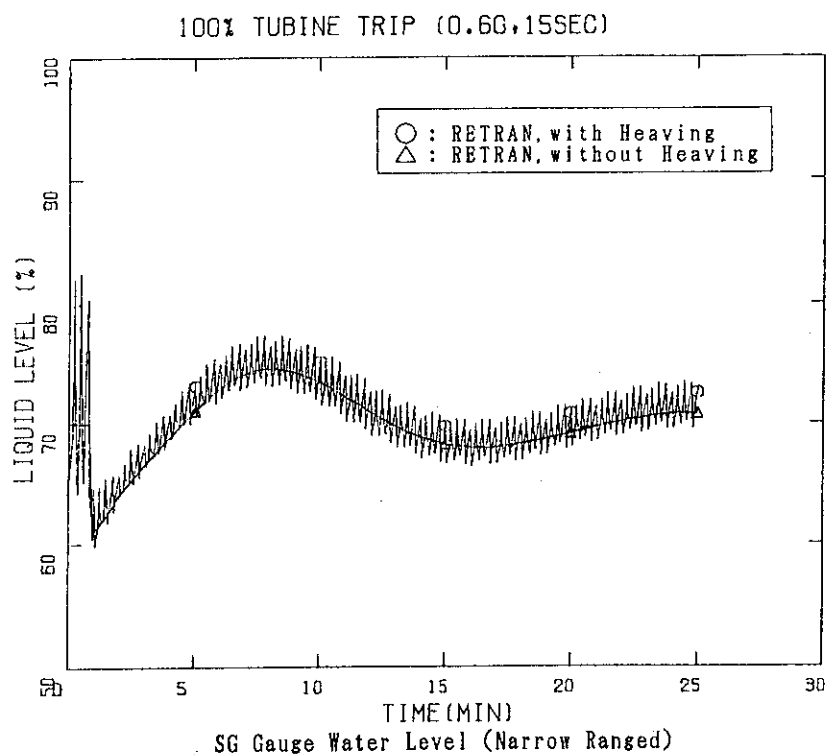


Fig. 4.3.4(2) Comparison of Transients With Heaving (0.6 g, 15 Seconds) and Without Heaving at Turbine Trip of Mutsu (Changes of No.1 SG Water Levels: Actual and Narrow Ranged Water Levels)

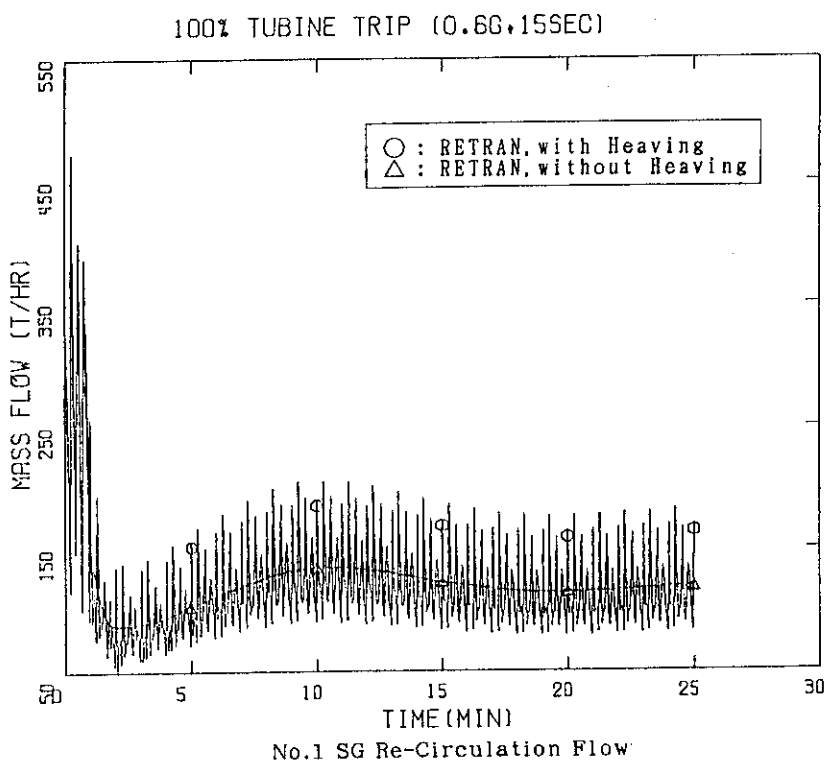
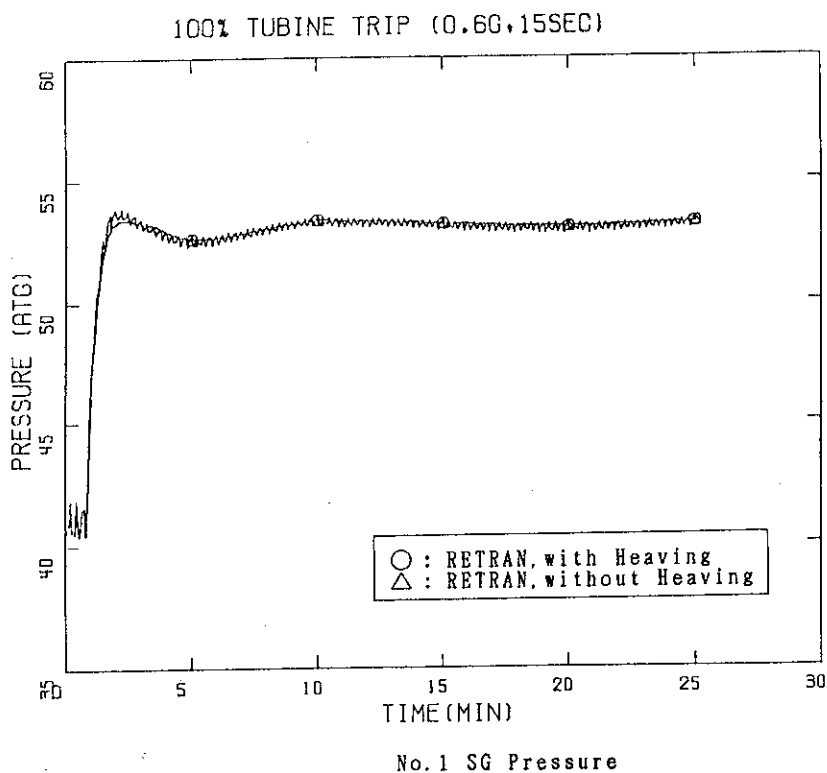


Fig. 4.3.4(3) Comparison of Transients With Heaving (0.6 g, 15 Seconds) and Without Heaving at Turbine Trip of Mutsu (Changes of No.1 SG Pressure and No.1 SG Re-Circulation Flow)

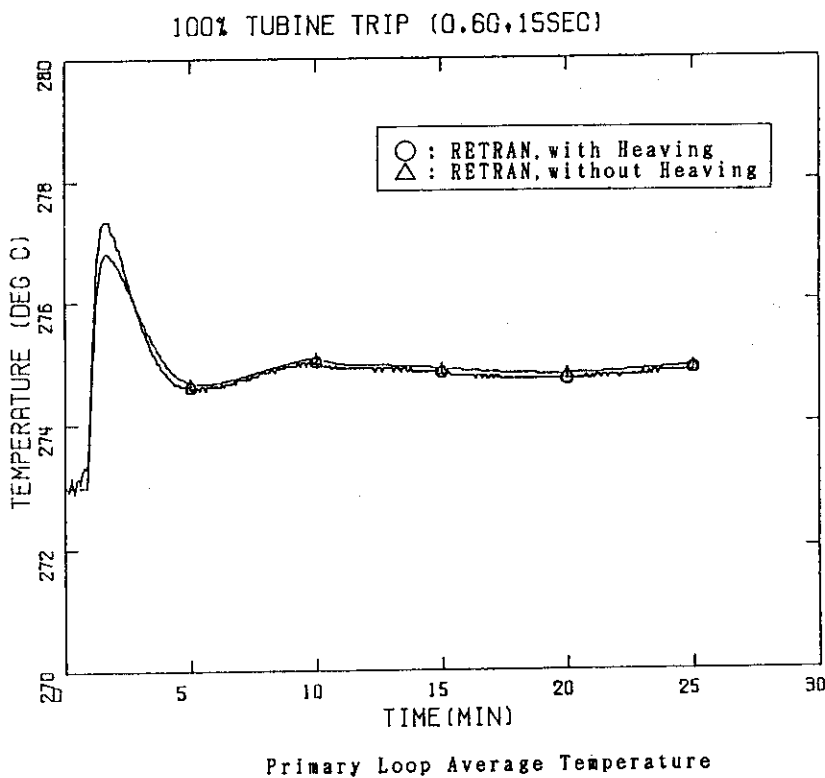
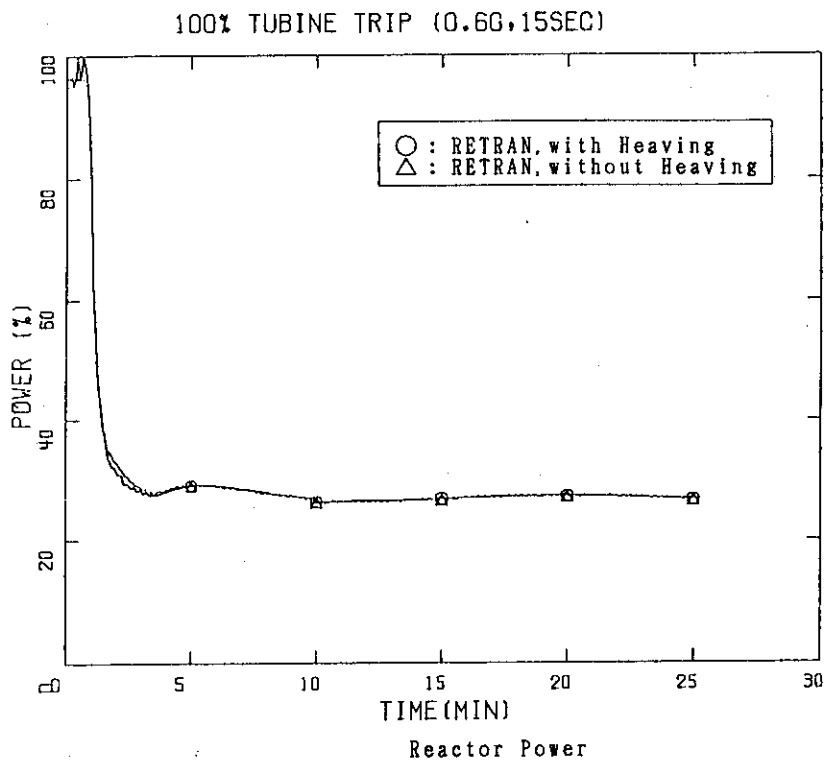


Fig. 4.3.4(4) Comparison of Transients With Heaving (0.6 g, 15 Seconds) and Without Heaving at Turbine Trip of Mutsu (Changes of Reactor Power and Primary Loop Average Temperature)

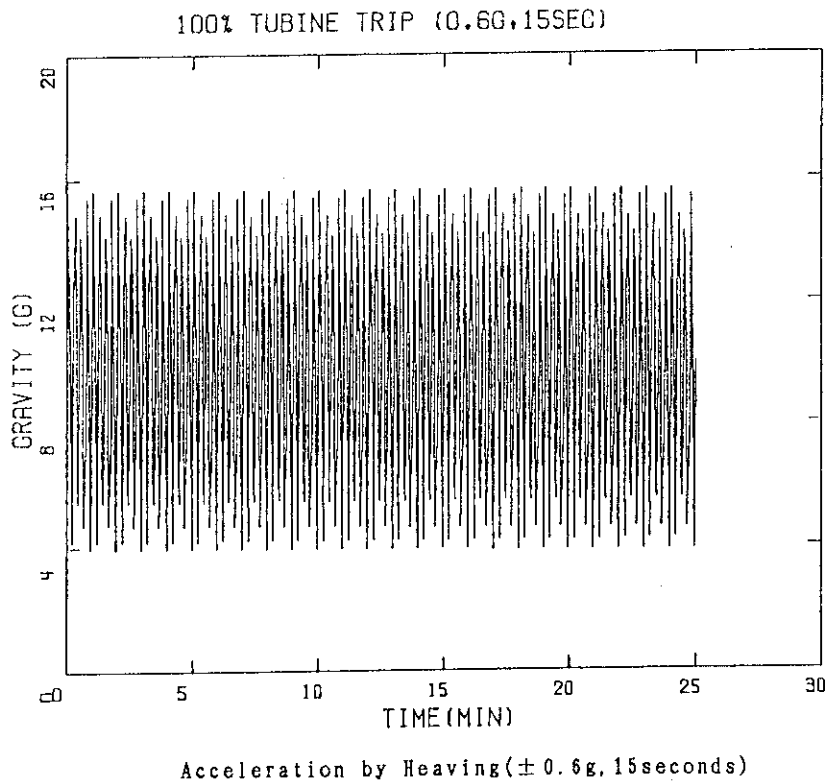
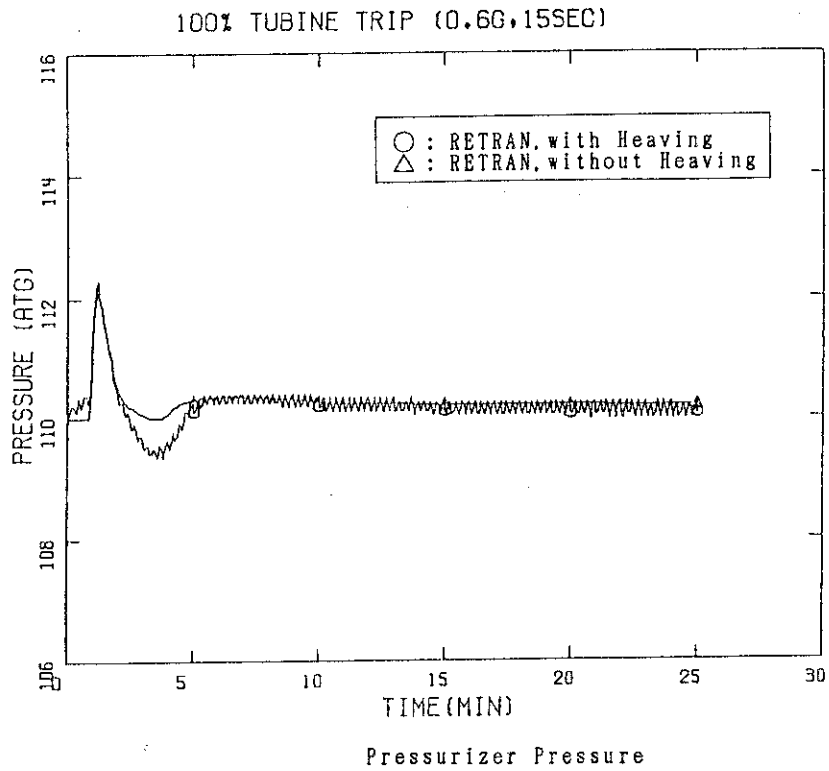


Fig. 4.3.4(5) Comparison of Transients With Heaving (0.6 g, 15 Seconds) and Without Heaving at Turbine Trip of Mutsu (Changes of Pressurizer Pressure and Acceleration by Heaving)

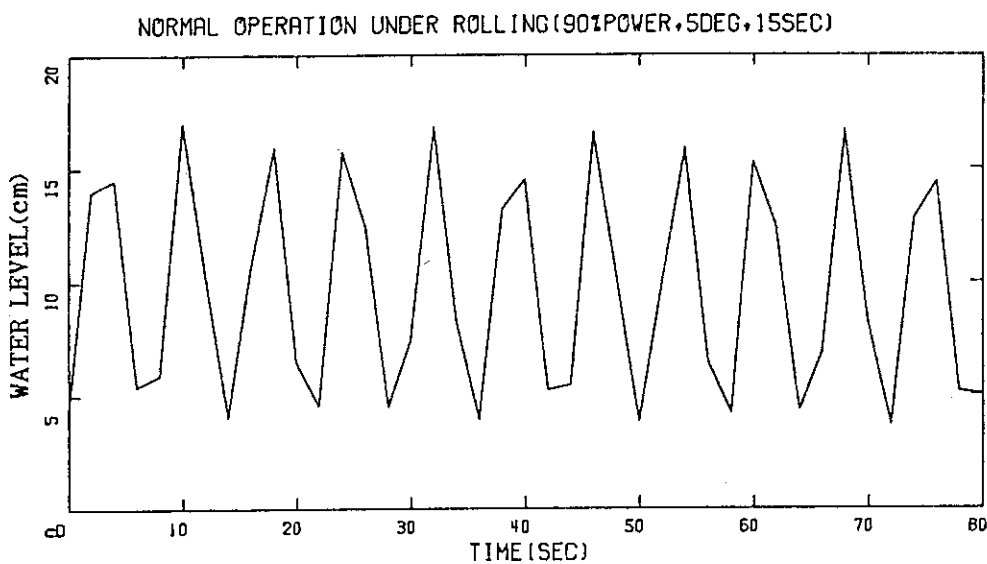
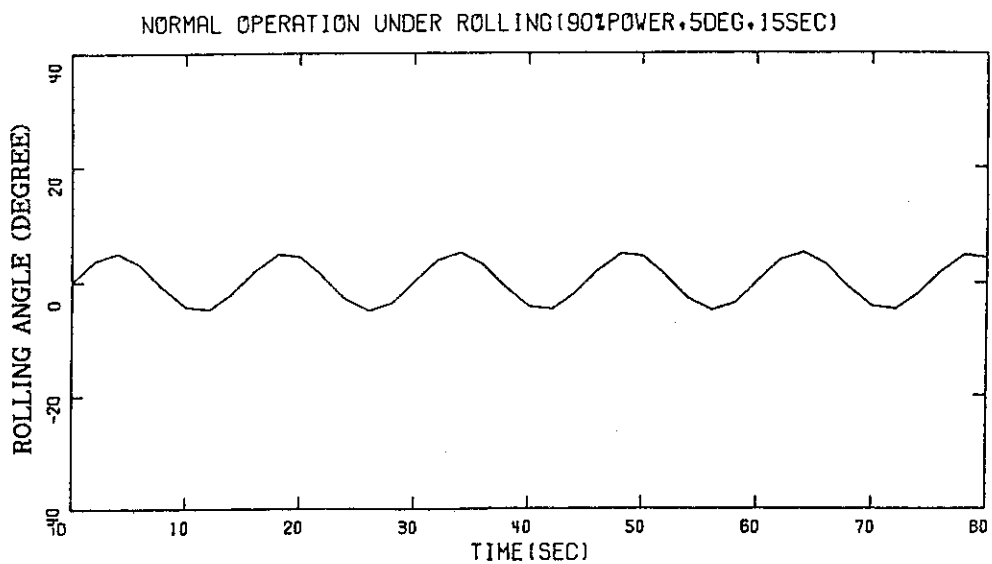


Fig. 4.4.1(1) Analysis of Response of Mutsu SG Water Level Under Rolling During Normal Power Operation (Angle=5 Degrees, Period=15 Seconds)

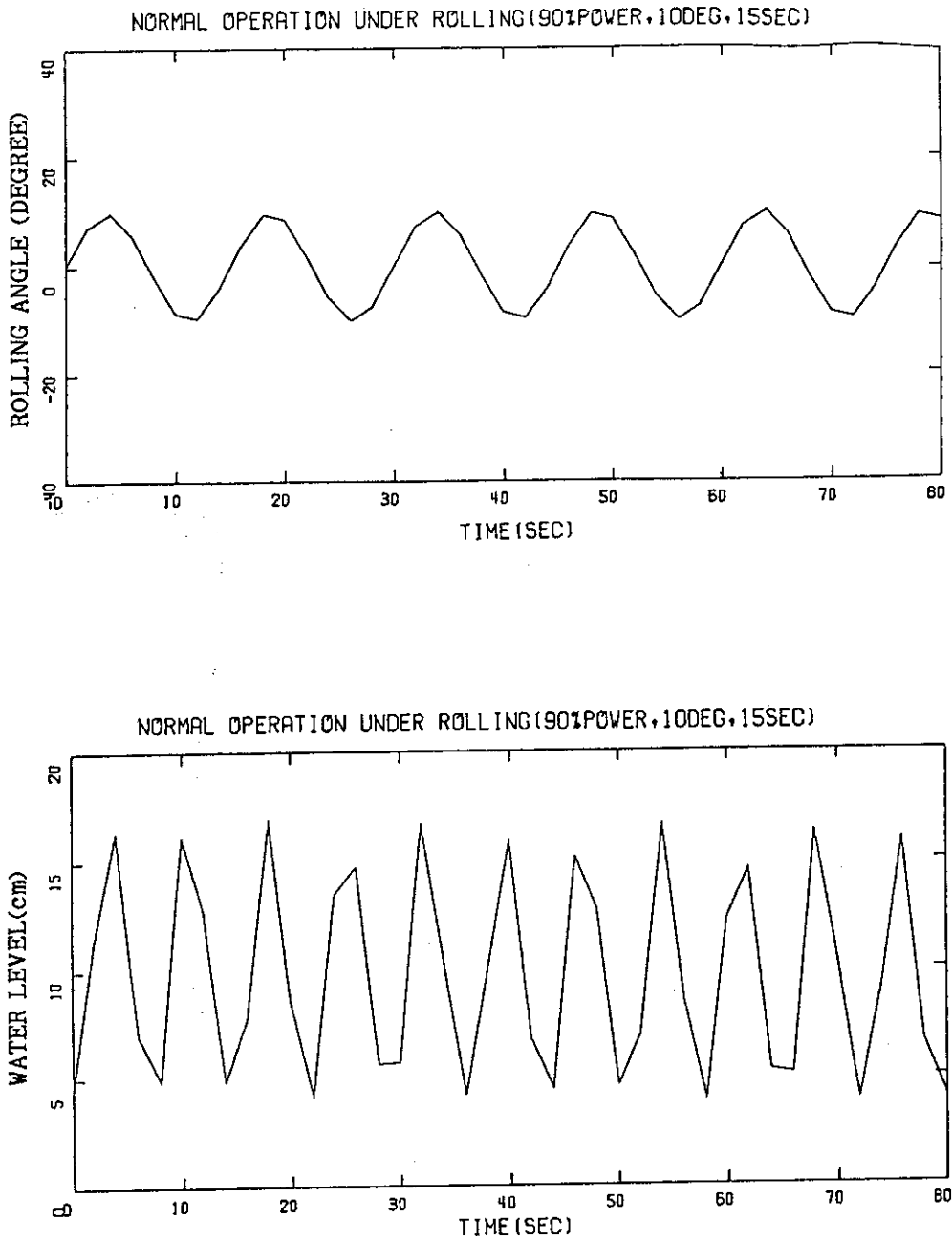


Fig. 4.4.1(2) Analysis of Response of Mutsu SG Water Level Under Rolling During Normal Power Operation (Angle=10 Degrees, Period=15 Seconds)

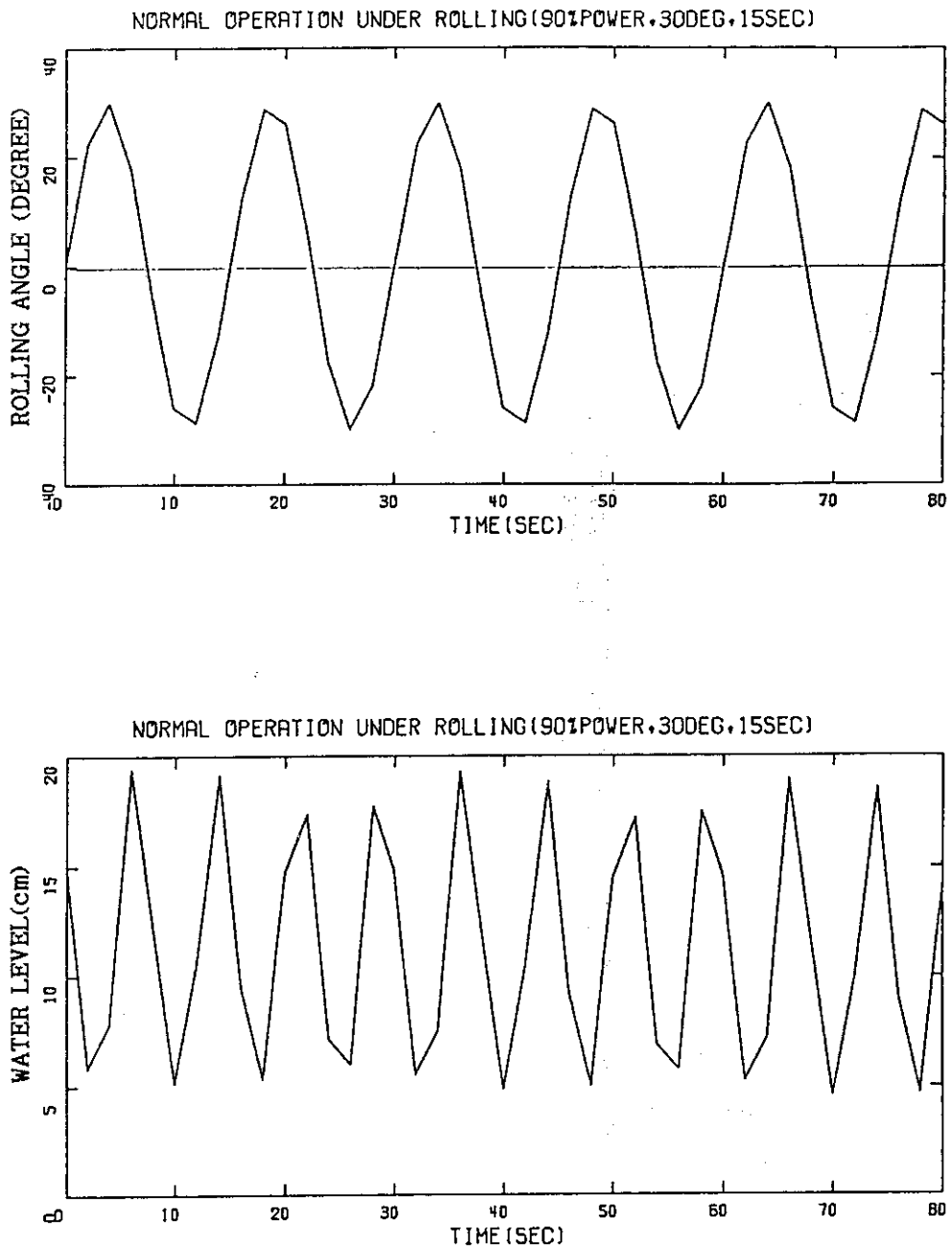


Fig. 4.4.1(3) Analysis of Response of Mutsu SG Water Level Under Rolling During Normal Power Operation (Angle=30 Degrees, Period=15 Seconds)

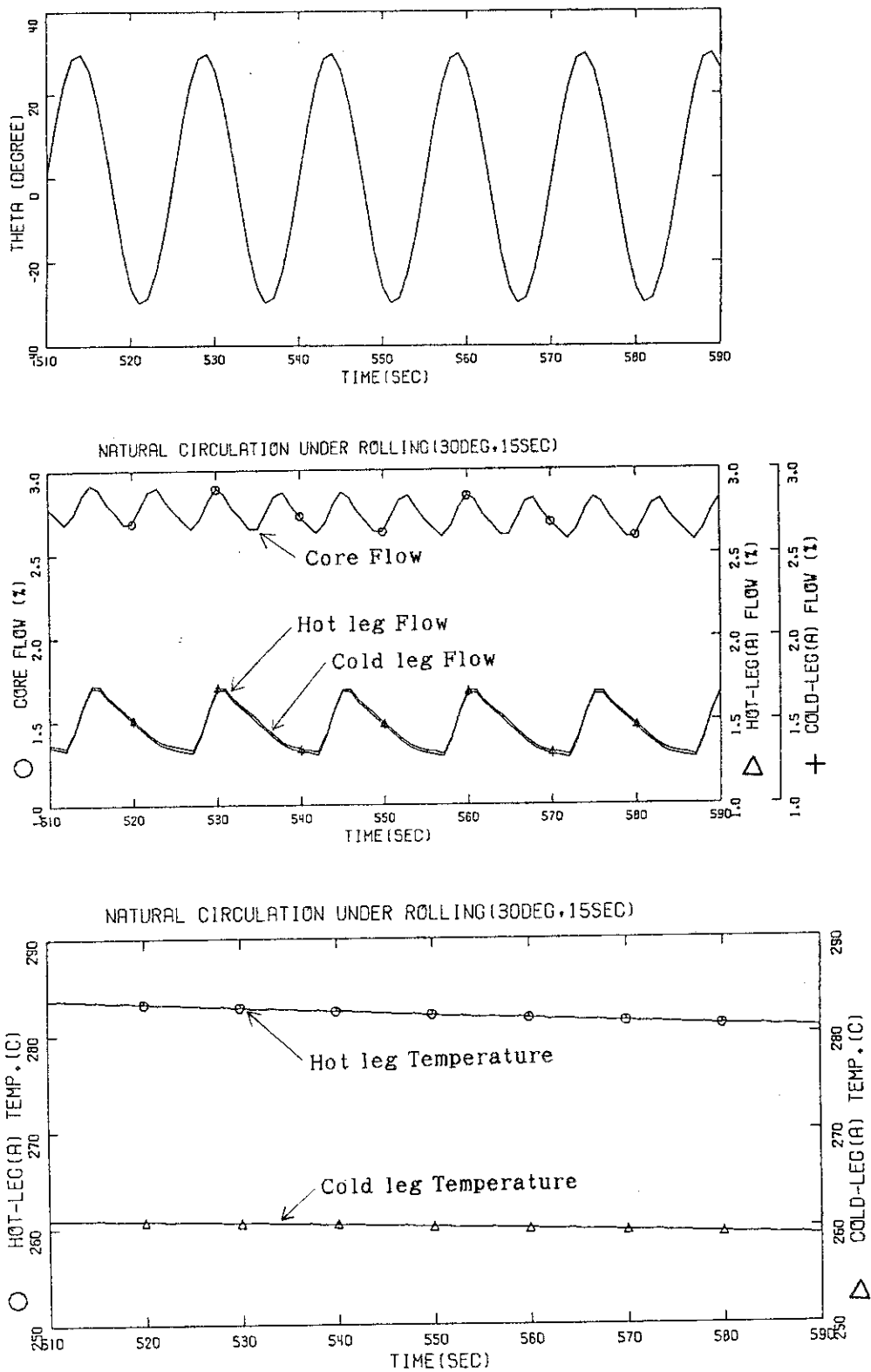


Fig. 4.4.2 Analysis of Natural Circulation Under Rolling (Rolling Angle=30 Degrees, Period=15 Seconds): Reactor Tripped at 30 Seconds and Main Coolant Pumps Tripped at 75 Seconds

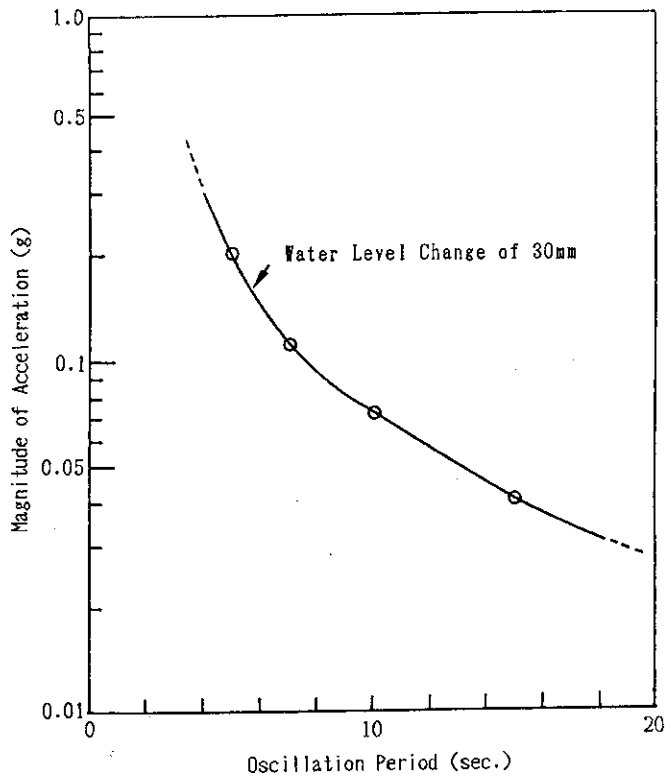


Fig. 4.5.1 Vertical Acceleration for 30mm Variation of SG Actual Water Level

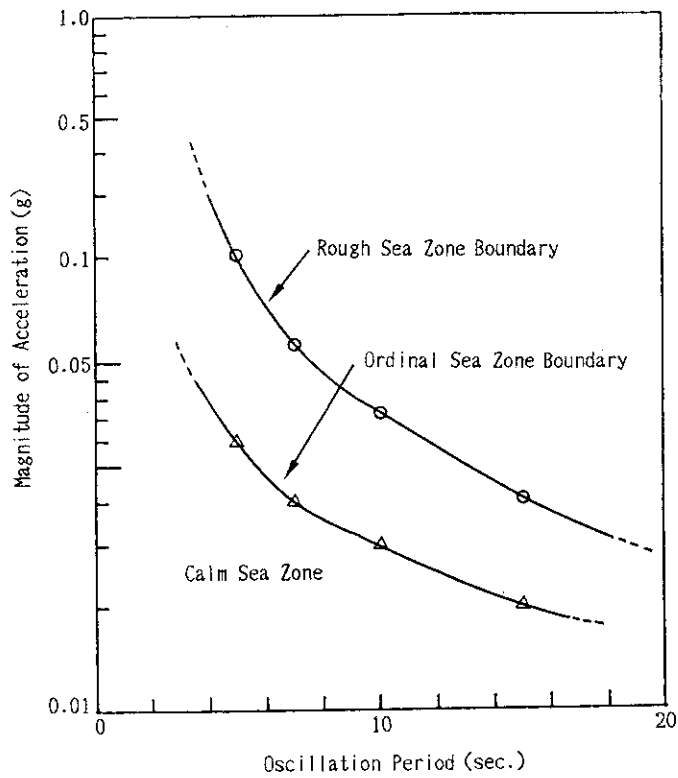


Fig. 4.5.2 Vertical Acceleration Recommended for Mutsu Experimental Voyage

5. Conclusions

We have been improved a thermal hydraulic code RETRAN-02 for analysis of marine reactor dynamics under ship motion such as heaving, rolling. For ship motion and inclination, the code has been modified for ship motion and inclination so as to treat two-dimensional or three-dimensional effects in the momentum equation and the energy equation, and to calculate the flow out enthalpy of the volume with water level, in connection with control logic model. Improvements on the following ship motions have been performed.

- (1) For stationary inclination of ship, the water head term in the equations and the water level model are modified so as to simulate inclination of the two-dimensional plane.
- (2) For heaving, the vertical time-dependent accelerations are added to the equations.
- (3) For rolling, the tangential force and centrifugal force together with time-dependent inclination are introduced in the equations.
- (4) Arbitrary rotation of ship is modelled by taking account of the three-dimensional movements by introducing the centrifugal force and the tangential force as well as the co-ordinate transformation matrix.

To verify the improved functions of the present code, the following experimental analyses have been performed.

- (1) Single-phase natural circulation experiment at some inclined attitudes
- (2) Single-phase and two-phase natural circulation flows under heaving
- (3) Single-phase natural circulation flow during rolling motion

The results show that the analyse have simulated well the experiments and that the validity of the improved code has been proved. However, the effect of acceleration or inclination due to ship motion on the heat transfer coefficient and the steam-water void fraction are not taken account in the present version. These correlations should be experimentally studied.

As applications of the improved code RETRAN-02/GRAV, the N.S. Mutsu has been analysed for providing quantitative bases for planning of the experiment in her experimental voyage. The acceleration conditions for her voyages are recommended.

Acknowledgements

The authors would like to express their appreciations to Mr. Masa-aki OCHIAI of JAERI and Mr. Yukihiisa YABUSHITA of IEA of Japan for their useful suggestions, Mr. Takeharu ISE for his laborious review of the present paper, and Katumi TODA first engineer and other engineers of N.S. Mutsu for their valuable information.

As applications of the improved code RETRAN-02/GRAV, the N.S. Mutsu has been analysed for providing quantitative bases for planning of the experiment in her experimental voyage. The acceleration conditions for her voyages are recommended.

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- (11) GKSS : Nuclear Research Ship "Otto Hahn" Safety Assessment, 1974.
- (12) US-MA : N.S. Savannah Safety Assessment Revision II, 1974

NOMENCLATURE

| | |
|-------------|---|
| A_k | = flow area of volume k |
| c | = elevation of volume center |
| e | = elevation |
| e^* | = total energy per unit mass |
| F_w | = friction pressure gradient due to wall |
| f_h | = horizontal acceleration |
| f_v | = vertical acceleration |
| g_z | = axial component of acceleration due to gravity |
| $g(t)$ | = time dependent gravitation acceleration |
| h_i | = specific fluid enthalpy of junction i |
| L_i | = length in volume i |
| M_i | = total mass in volume i |
| P_i | = thermodynamic pressure in volume i |
| Q_{wm} | = energy exchange rate between channel wall and fluid |
| R | = distance for co-ordinates |
| T_a | = period of oscillation |
| t | = time |
| U_i | = total internal energy in volume i |
| u_i | = average specific internal energy in volume i |
| V_k | = control volume used in the averaging procedure for volume k |
| v_k | = average fluid velocity in volume k |
| W | = net mass flow |
| W_i | = mass flow for junction i |
| \bar{W}_i | = average mass flow in volume i |
| Z_i | = volume center height above reference height z |
| Z_j | = junction height above reference height z |

G R E E K L E T T E R S

| | |
|----------------|--|
| α | = acceleration for each axis |
| β | = normalized gravitation acceleration |
| $\beta(t)$ | = time dependent normalized gravitation acceleration |
| γ | = flow length of volume for three-dimension |
| ζ | = rotation angle around x axis |
| θ | = rotation angle around y axis |
| ρ_i | = mixture density in volume i |
| $\bar{\rho}_i$ | = fluid density in volume i |
| ϕ | = rotation angle around z axis |
| $ $ | = absolute value |

APPENDIXES

A.1 Source list of improved program in RETRAN-02/GRAV

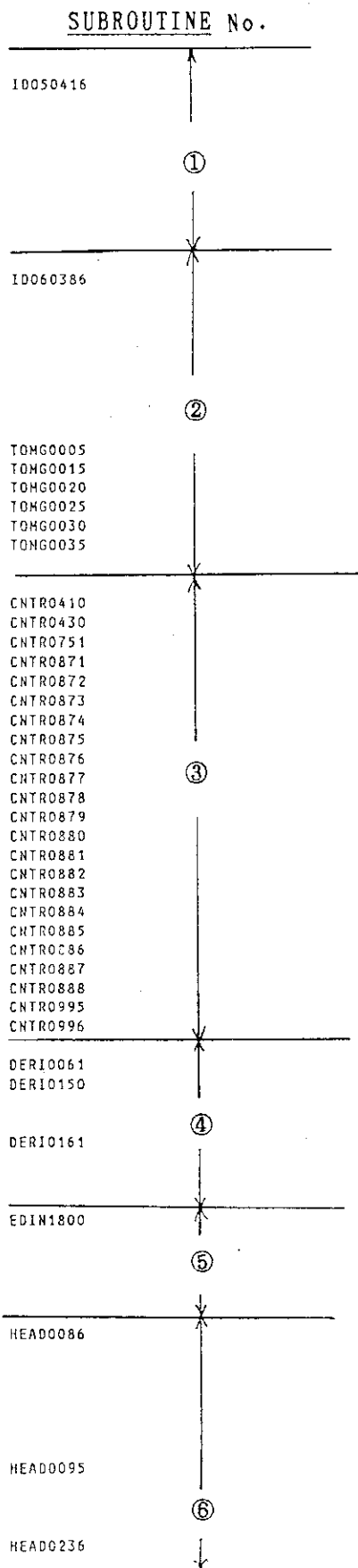
Following SUBROUTINES are modified.

| (No.) | <u>SUBROUTINE</u> name | (Remark) |
|-------|------------------------|--|
| ① | ID05 | Assign for Rolling variable |
| ② | ID06 | Assign for Rolling variable |
| ③ | CONTRL | Improvement for control block function |
| ④ | DERIVS | Improvement for control block function |
| ⑤ | EDINIT | Improvement for control block function |
| ⑥ | HEAD | Improvement for gravity and rolling |
| ⑦ | INCNT1 | Modification for input |
| ⑧ | INJUN | Modification for input |
| ⑨ | INPUT | Modification for input |
| ⑩ | INVOL | Modification for input |
| ⑪ | JSVEL | Modification for gravity |
| ⑫ | RETRAN | Modification for gravity |
| ⑬ | WATER | Modification for steam function |
| ⑭ | ENTRAN | Modification for slip SSI |
| ⑮ | HAVG | Modification for slip SSI |
| ⑯ | SFR | Modification for slip SSI |
| ⑰ | SLIPHW | Modification for slip SSI |
| ⑱ | TONGST(newly made) | Controller for gravity and rolling |
| ⑲ | MATMLT(newly made) | Controller for gravity and rolling |
| ⑳ | ROLXYZ(newly made) | Controller for gravity and rolling |

```

¥LOCATE 1005
CIEA
C   PARAMETERS REQUIRED FOR ROLLING OPTION
C
  DIMENSION RAD3DX(1),RAD3DY(1),RAD3DZ(1)
  DIMENSION VOL3DX(1),VOL3DY(1),VOL3DZ(1)
  EQUIVALENCE (RSTOR(100),RAD3DX(1)), (RSTOR(101),RAD3DY(1)),
  *           (RSTOR(102),RAD3DZ(1)), (RSTOR(103),VOL3DX(1)),
  *           (RSTOR(104),VOL3DY(1)), (RSTOR(105),VOL3DZ(1))
CIEA END
¥LOCATE 1006
CIEA START
C   PARAMETERS REQUIRED FOR ROLLING OPTIONS
C
  DIMENSION
  * IWT1(1), IWT2(1)
  EQUIVALENCE
  *(RSTOR(91),IWT1(1)), (RSTOR(92),IWT2(1))
CIEA END
¥INSERT
*COMDECK TOMG
  COMMON / TOMGFC /
  * TR(3,3), TOMGF, TOMGH
  *           ,ITOMGF,ITOMGH
  * , PH1Z, PH1ZD, PH12D, THEY, THEYD, THE2D, ZETX, ZETXD, ZET2D
  * ,IPH1Z,IPH1ZD,IPH12D,ITHEY,ITHEYD,ITHE2D,IZETX,IZETXD,IZET2D
*END
¥LOCATE CNTR XX
  IF(J1.LT.1.OR.J1.GT.19)GOTO 605
  GOTO(211,212,213,214,215,216,217,218,219),J2
  2210 CONTINUE
  GO TO 295
C
C   SINE BLOCK
  216 COUT(ID) = SIN(COUT(INC1(ID)))
  GO TO 295
C
C   COSINE BLOCK
  217 COUT(ID) = COS(COUT(INC1(ID)))
  GO TO 295
C
C   EXPONENTIAL BLOCK
  218 COUT(ID) = EXP(COUT(INC1(ID)))
  GO TO 295
C
C   ABSOLUTE BLOCK
  219 COUT(ID) = ABS(COUT(INC1(ID)))
C
C   CODING FOR ADDITIONAL TYPES OF CONTROL BLOCKS GOES HERE
  DIVISR = 1.0
  GO TO 2210
¥LOCATE DERI XX
*CALL TOMG
CIEA BTUFP = ONE/FPBTU
  TBTUFP = ONE/FPBTU
CIEA
CIEA
  BTUFP = TBTUFP*TOMGF
CIEA
¥LOCATE EDIN XX
CN150 RETURN
  150 CONTINUE
  CALL TOMGST(HODE,IDX,IFIL,DO)
  RETURN
CIEA
¥LOCATE HEAD XX
*CALL TOMG
  DIMENSION RELXYZ(3),ZMXYZ(3),CMSXYZ(3),ACCXYZ(3)
  EQUIVALENCE
  * (RELXYZ(1),RELZX),(RELXYZ(2),RELZY),(RELXYZ(3),RELZZ)
  * ,(ZMXYZ(1),ZMX),( ZMXYZ(2),ZMY), ( ZMXYZ(3),ZM2)
  * ,(CMSXYZ(1),CMSX),(CMSXYZ(2),CMSY),(CMSXYZ(3),CMSZ)
  * ,(ACCXYZ(1),ACCX),(ACCXYZ(2),ACCY),(ACCXYZ(3),ACCZ)
CIEA DATA ZERO / 0.0 /, HALF / 0.5 /, ONE / 1.0 /, TWO / 2.0 /
  DATA ZERO / 0.0 /, HALF / 0.5 /, ONE / 1.0 /, TWO / 2.0 /
  DATA EPS / 1.E-8 /
CIEA END
CIEA
  CALL ROLXYZ(1, RELZ,RELXYZ)
  CALL ROLXYZ(1, ZH(1), ZMXYZ)

```



```

CALL ROLXYZ(I,CMAS(1),CMSXYZ)
CALL ZFROUT(ACCXYZ,3)
CALL AXEXYZ(I,ACCXYZ)
CONSV = CONS*(TOMGF - ACCZ/GRAVTY)
CONSH = CONS*(TOMGH - ACCX/GRAVTY)
ZHEADR = ZERO
XHEADR = ZERO
CIEA END
CIEA HEADR(L,M) = CONS*(CMAS(1)-RELZ)*AVED(1) HEAD0290
      ZHEADR = CMAS(1) - RELZ
      XHEADR = ZERO
      IF ( ABS(ZHEADR/CMAS(1)).GT.EPS ) GO TO 3230
      IF ( IWT1(L+MP1) ) 3220, 3240, 3210
3210 CONTINUE
      ZHEADR = CMASZ
      GO TO 3240
3220 CONTINUE
      ZHEADR = -CMASZ
      GO TO 3240
3230 CONTINUE
      ZHEADR = CMASZ - RELZZ
3240 CONTINUE
      IF ( VOL3DX(I).NE.ZERO ) GO TO 3270
      IF ( IWT1(L+MP1) ) 3260, 3280, 3250
3250 CONTINUE
      XHEADR = CMASX
      GO TO 3280
3260 CONTINUE
      XHEADR = -CMASX
      GO TO 3280
3270 CONTINUE
      XHEADR = CMASX - RELZX
3280 CONTINUE
      HEADR(L,M) = AVED(1)*(CONSV*ZHEADR+CONSH*XHEADR)
CIEA WRITE(6,6881)M,1,HEADR(L,M),CMASZ,RELZZ,ZMZ,ACCZ,ACCX
CIEA * ,TOMGF,TOMGH,CONSV,CONSH,ZHEADR,XHEADR
6881 FORMAT (215,1P6E13.6/10X,6E13.6)
CIEA END HEAD0306

C
C      +-----+ +-----+
C      I      I      I      I
C      50 =>I      I      70 =>I      I
C      I--- ZM ---I      I      I
C      I      X      I      I      X      I
C      I      I      I      I--- ZM ---I
C      ** =>I      I      60 =>I      I
C      I      I      I      I      I      I
C      +-----+ +-----+
C
C
CIEA IF (CMAS(1) .LT. ZM(1)) GO TO 40 HEAD0315
      IF ( CMASZ .LT. ZMZ ) GO TO 40
CIEA IF (RELZ .LT. ZM(1)) GO TO 60 HEAD0320
      IF ( RELZZ .LT. ZMZ ) GO TO 60
CIEA END
CIEA IF (RELZ .GT. ZM(1)) GO TO 50 HEAD0335
      IF ( RELZZ .GT. ZMZ ) GO TO 50
CIEA END
C **
CIEA HEADR(L,M) = CONS*((CMAS(1)**2-RELZ**2)*HALF*E(1)/ZM(1) + HEAD0346
      (CMAS(1)-RELZ)*F(1)) HEAD0350
CIEA * (CMAS(1)-RELZ)*F(1) HEAD0355
      IF ( CMAS(1) .NE. RELZ ) GO TO 3330
      IF ( IWT1(L+MP1) ) 3320, 3340, 3310
3310 CONTINUE
      IF ( CMASZ.LT.ZERO ) GO TO 3315
      ZHEADR = E(1)/ZMZ*HALF*CMASZ**2 + F(1)*CMASZ
      GO TO 3340
3315 CONTINUE
      ZHEADR = -E(1)*HALF*(CMASZ**2/ZMZ-ZMZ)
      * -F(1)*(CMASZ-ZMZ) - (ZMZ-TWO*CMASZ)/VS(1)
      GO TO 3340
3320 CONTINUE
      IF ( CMASZ.LT.ZERO ) GO TO 3325
      ZHEADR = E(1)*HALF*(CMASZ**2/ZMZ-ZMZ) +
      * F(1)*(CMASZ-ZMZ) + (ZMZ-TWO*CMASZ)/VS(1)
      GO TO 3340
3325 CONTINUE
      ZHEADR = -E(1)/ZMZ*HALF*CMASZ**2 - F(1)*CMASZ
      GO TO 3340
3330 CONTINUE

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ZHEADR = E(I)/ZMZ*HALF*(CHASZ**2 - RELZ**2) +
* (CHASZ - RELZ)*F(I)
3340 CONTINUE
IF ( VOL3DX(I).NE.ZERO ) GO TO 3370
IF ( IWT1(L+HP1) ) 3360, 3380, 3350
3350 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3355
XHEADR = F(I)*CHASX
GO TO 3380
3355 CONTINUE
XHEADR = CHASX/VS(I)
GO TO 3380
3360 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3365
XHEADR = -CHASX/VS(I)
3365 CONTINUE
XHEADR = -F(I)*CHASX
GO TO 3380
3370 CONTINUE
XHEADR = (E(I)*RELZ/ZMZ + F(I))*(CHASX - RELZX)
3380 CONTINUE
HEADR(L,M) = CONSV*ZHEADR+CONSH*XHEADR
CIEA END
CNE50 HEADR(L,M) = CONSV*(HALF*E(I)*(CHAS(I)**2/ZM(I)-ZM(I)) + F(I) HEAD0375
CIEA * *(CHAS(I)-ZM(I)) + (ZM(I)-RELZ)/VS(I)) HEAD0380
50 CONTINUE
IF ( CHAS(I) .NE. RELZ ) GO TO 3530
IF ( IWT1(L+HP1) ) 3520, 3540, 3510
3510 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3515
ZHEADR = E(I)/ZMZ*HALF*CHASZ**2 + F(I)*CHASZ
GO TO 3540
3515 CONTINUE
ZHEADR = -E(I)*HALF*(CHASZ**2/ZMZ-ZMZ)
* -F(I)*(CHASZ-ZMZ) - (ZMZ-TWO*CHASZ)/VS(I)
GO TO 3540
3520 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3525
ZHEADR = E(I)*HALF*(CHASZ**2/ZMZ-ZMZ) +
* F(I)*(CHASZ-ZMZ) + (ZMZ-TWO*CHASZ)/VS(I)
GO TO 3540
3525 CONTINUE
ZHEADR = -E(I)/ZMZ*HALF*CHASZ**2 - F(I)*CHASZ
GO TO 3540
3530 CONTINUE
ZHEADR = E(I)/ZMZ*HALF*(CHASZ**2 - ZMZ**2) +
* (CHASZ - ZMZ)*F(I) + (ZMZ-RELZ)/VS(I)
3540 CONTINUE
IF ( VOL3DX(I).NE.ZERO ) GO TO 3570
IF ( IWT1(L+HP1) ) 3560, 3580, 3550
3550 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3555
XHEADR = F(I)*CHASX
GO TO 3580
3555 CONTINUE
XHEADR = CHASX/VS(I)
GO TO 3580
3560 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3565
XHEADR = -CHASX/VS(I)
3565 CONTINUE
XHEADR = -F(I)*CHASX
GO TO 3580
3570 CONTINUE
XHEADR = (CHASX - RELZX)/VS(I)
3580 CONTINUE
HEADR(L,M) = CONSV*ZHEADR+CONSH*XHEADR
CIEA END
CNE60 HEADR(L,M) = CONSV*((CHAS(I)-ZM(I))/VS(I) + F(I)*(ZM(I)-RELZ) HEAD0400
CIEA * + HALF*E(I)*(ZM(I)-RELZ**2/ZM(I))) HEAD0405
60 CONTINUE
IF ( CHAS(I) .NE. RELZ ) GO TO 3630
IF ( IWT1(L+HP1) ) 3620, 3640, 3610
3610 CONTINUE
IF ( CHASZ.LT.ZERO ) GO TO 3615
ZHEADR = E(I)*HALF*ZMZ + F(I)*ZMZ + (CHASZ-ZMZ)/VS(I)
GO TO 3640
3615 CONTINUE
ZHEADR = CHASZ/VS(I)
GO TO 3640

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3620 CONTINUE
      IF ( CMASZ.LT.ZERO ) GO TO 3625
      ZHEADR = -CHASZ/VS(I)
      GO TO 3640
3625 CONTINUE
      ZHEADR = -E(I)*HALF*ZHZ - F(I)*ZHZ - (CMASZ-ZHZ)/VS(I)
      GO TO 3640
3630 CONTINUE
      ZHEADR = E(I)/ZHZ*HALF*(ZHZ**2 - RELZZ**2) +
      * (ZMZ - RELZZ)*F(I) + (CMASZ-ZHZ)/VS(I)
3640 CONTINUE
      IF ( VOL3DX(I).NE.ZERO ) GO TO 3670
      IF ( IWT1(L+MP1) ) 3660, 3680, 3650
3650 CONTINUE
      IF ( CMASZ.LT.ZERO ) GO TO 3655
      XHEADR = F(I)*CHASX
      GO TO 3680
3655 CONTINUE
      XHEADR = CMASX/VS(I)
      GO TO 3680
3660 CONTINUE
      IF ( CMASZ.LT.ZERO ) GO TO 3665
      XHEADR = -CMASX/VS(I)
3665 CONTINUE
      XHEADR = -F(I)*CHASX
      GO TO 3680
3670 CONTINUE
      XHEADR = (E(I)*RELZZ/ZHZ + F(I))* (CHASX - RELZX)
3680 CONTINUE
      HEADR(L,M) = CONSV*ZHEADR+CONSH*XHEADR
CIEA ENO
CNE70 HEADR(L,M) = CONS*(CHAS(I)-RELZ)/VS(I) HEAD0425
70 CONTINUE
      IF ( CHAS(I) .NE. RELZ ) GO TO 3730
      IF ( IWT1(L+MP1) ) 3720, 3740, 3710
3710 CONTINUE
      IF ( CHASZ.LT.ZERO ) GO TO 3715
      ZHEADR = E(I)*HALF*ZHZ + F(I)*ZHZ + (CMASZ-ZMZ)/VS(I)
      GO TO 3740
3715 CONTINUE
      ZHEADR = CMASZ/VS(I)
      GO TO 3740
3720 CONTINUE
      IF ( CHASZ.LT.ZERO ) GO TO 3725
      ZHEADR = -CHASZ/VS(I)
      GO TO 3740
3725 CONTINUE
      ZHEADR = -E(I)*HALF*ZHZ - F(I)*ZHZ - (CMASZ-ZMZ)/VS(I)
      GO TO 3740
3730 CONTINUE
      ZHEADR = (CMASZ-RELZZ)/VS(I)
3740 CONTINUE
      IF ( VOL3DX(I).NE.ZERO ) GO TO 3770
      IF ( IWT1(L+MP1) ) 3760, 3780, 3750
3750 CONTINUE
      IF ( CHASZ.LT.ZERO ) GO TO 3755
      XHEADR = F(I)*CHASX
      GO TO 3780
3755 CONTINUE
      XHEADR = CMASX/VS(I)
      GO TO 3780
3760 CONTINUE
      IF ( CHASZ.LT.ZERO ) GO TO 3765
      XHEADR = -CMASX/VS(I)
3765 CONTINUE
      XHEADR = -F(I)*CHASX
      GO TO 3780
3770 CONTINUE
      XHEADR = (CHASX - RELZX)/VS(I)
3780 CONTINUE
      HEADR(L,M) = CONSV*ZHEADR+CONSH*XHEADR
CIEA ENO
*LOCATE INC1 XX
      * 3HSIN,3HCOS,3HEXP,3HABS,4H /
      DO 240 J = 1,19
      GO TO (340,350,350,350,350,350,350,350,350) ,J2
*LOCATE INJU XX
CIEA DIMENSION L3B(27)
      DIMENSION L3B(27),L3T(8)
      DATA L3T / 0,0, 0, 2,0,1,2*0 /

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INC10130
 INC10845
 INC11005

⑦

INJU0115

⑧

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CIEA END
CIEA 1SIZ06 = 90                                INJU0345
      1SIZ06 = 92
      NEWEQS(IDX02) = 0
CIEA END
CIEA L3B(2) = -L3B(1) - 8                        INJU0650
      L3B(2) = -L3B(1) - 7
CIEA END
CIEA START                                      INJU1394
CN134 IF (LRST) GO TO 140                        INJU1395
134 CONTINUE
      L3T(1) = 80000 + 10*DLJUNI + 9
      L3T(6) = 1
      CALL INP2 (ISTOR(IDXCRO),IWT1(IDX06),L3T)
      IF (L3T(6) .LE. 0) GO TO 139
      IF (IABS(IWT1(IDX06)) .LE. 1 .AND. IABS(IWT2(IDX06)) .LE. 1)
          *                                     GO TO 139
      WRITE(6,6670)
6670 FORMAT('O***** ERROR ON THE FOLLOWING CARD. VALUE FOR IWT1/2',
          * ' OUT OF RANGE. -1 <= VALUE <= 1')
      NOGO = .TRUE.
139 IF (LRST) GO TO 140
CIEA END
CIEA 2 CONCO(IDX06),ANGLJ(IDX06)                 INJU1425
      2 CONCO(IDX06),ANGLJ(IDX06),IWT1(IDX06),IWT2(IDX06)
CIEA END
CIEA START                                      INJU2244
CN380 IC = -L3B(2)                              INJU2245
      380 IC = -L3B(2) + 1
CIEA END
CIEA 4 ,5X,4(5H INDX),15X,4H(FT),24X,9H(DEGREES) INJU3020
      4 ,5X,4(5H INDX),15X,4H(FT),24X,9H(DEGREES),5X,' IWT1 IWT2'
CIEA END
CN610 FORMAT(1H ,4X,5I5,I6,2X,1P3E14.6)         INJU3035
      610 FORMAT(1H ,4X,5I5,I6,2X,1P3E14.6,2I5)
CIEA END
%LOCATE INPU XX
CIEA
      DIMENSION L3T(9)
CIEA END
CIEA DATA L3 / 010001, -010004, 1, 42, 0, 1, 2, 0, 0 / INPU0205
      DATA L3 / 010001, -010003, 1, 42, 0, 1, 2, 0, 0 /
C
      DATA L3T / 010004, 0, 0, 10, 0, 1, 2, 0, 0 /
CIEA END
CIEA ***** INPU0736
      ENDFILE 6
CIEA *****
CIEA ISIZ = ISIZ + 6                              INPU0955
      ISIZ = ISIZ + 16
CIEA END
CN145 IF (.NOT.NOGO) RETURN                      INPU1190
      145 CONTINUE
      IDXPRB = IDXPRB + ISIZ - 10
      CALL INP2 (ISTOR(IDXCRO),ISTOR(IDXPRB),L3T)
      IF (.NOT.NOGO) RETURN
CIEA END
%LOCATE INRP XX
CIEA IUP = FILSIZ(2) - 6                          INRP0150
      IUP = FILSIZ(2) - 16
CIEA END
CIEA IUP = IUP + 6                                INRP0615
      IUP = IUP + 16
CIEA END
%LOCATE INVO XX
CIEA DIMENSION L3(22)                            INV00130
      DIMENSION L3(22),L3T(9)
CIEA END
CIEA START                                      INV00366
      DATA L3T/ 0, 0, 0, 6, 0, 1, 2 ,1 ,1/
CIEA END
CIEA ISIZ = 99                                    INV00435
      ISIZ = 105
      NEWEQS(I2) = 0
CIEA END
CIEA L3(2) = -L3(1) - 8                          INV00705
      L3(2) = -L3(1) - 7
CIEA END
CIEA START                                      INV02194
CN400 IF (LRST) GO TO 410                        INV02195

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400 CONTINUE
  L3T(1) = L3(1) + 8
  L3T(6) = 1
  RAD3DX(15) = 0.0
  RAD3DY(15) = 0.0
  RAD3DZ(15) = 0.0
  VOL3DX(15) = 0.0
  VOL3DY(15) = 0.0
  VOL3DZ(15) = 1.0
  CALL INP2 (RSTOR(IDXCRD),RAD3DX(15),L3T)
C   IF (L3T(6) .LE. 0) GO TO 409
C   IF (VOL3DZ(15) .GE. 0.0) GO TO 409
C   WRITE(6,6670)
C6670 FORMAT('O***** ERROR ON THE FOLLOWING CARD.  VALUE FOR HLNGT',
C * ' OUT OF RANGE.  VALUE >= 0.0')
C   CALL FAIL
  409 IF (LRST) GO TO 410
CIEA END
CIEA * DPDMF(15)
* DPDMF(15)
* ,RAD3DX(15),RAD3DY(15),RAD3DZ(15)
* ,VOL3DX(15),VOL3DY(15),VOL3DZ(15)
CN410 IC = -L3(2)
  410 IC = L3T(1)
CIEA END
CN770 FORMAT(4X,215,6X,1P4E14.6)
  770 FORMAT(4X,215,6X,1P4E14.6/20X,6E14.6)
CIEA END
CIEA * 'RAIN OUT INTER REGION'
* 'RAIN OUT INTER REGION'
CIEA END
CIEA * 'VEL.(FT/SEC) HTC(B/H-F2)'
* 'VEL.(FT/SEC) HTC(B/H-F2)'
CIEA END
%LOCATE JSVE XX
*CALL TOMG
  READ (5,67700,END=9) TOMFCT
67700 FORMAT (F10.0)
  IF ( TOMFCT.EQ.ZERO ) GO TO 9
  GO TO 10
  9 TOMFCT = ONE
CIEA START
  GRAVTH = GRAVITY*TOMGF
CIEA END
CIEA SIGMA = SIGMA * GRAVITY
  SIGMA = SIGMA * GRAVTH
CIEA TERM1 = (RHOL-RHOG) * SIGMA * GRAVITY / (RHOL**2.0)
  TERM1 = (RHOL-RHOG) * SIGMA * GRAVTH / (RHOL**2.0)
CIEA * GRAVITY * 144.0 / DX
* GRAVTH * 144.0 / DX
CIEA * GRAVITY * 144.0 / DX
* GRAVTH * 144.0 / DX
CIEA DPDX = (SPVJG(1)-SPVJL(1)) * (P(L)-P(K)) * GRAVITY
  DPDX = (SPVJG(1)-SPVJL(1)) * (P(L)-P(K)) * GRAVTH
  SV = AMIN1( SV*TOMFCT, 0.0)
%LOCATE RTRN XX
CIEA *****
  ENDFILE 6
CIEA *****
%LOCATE STST XX
CIEA
  CALL TOMGFS
CIEA
%LOCATE TRAN XX
CIEA
  CALL TOMGFS
CIEA
CIEA IF (ICF(LPD).NE.1) GO TO 70
  IF (ICF(LPD).EQ.0) GO TO 70
CIEA
%LOCATE WATR XX
CIEA DIMENSION LAG(15), LAG2(8), LAG3(25), LAG4(12)
  DIMENSION LAG(42), LAG2(8), LAG3(25), LAG4(12)
CIEA DATA ONE, TWO, THREE, FOUR / 1.0E0, 2.0E0, 3.0E0, 4.0E0 /
  DATA ONE, TWO, THREE, FOUR, FIVE, SIX
  * / 1.0E0, 2.0E0, 3.0E0, 4.0E0, 5.0E0, 6.0E0 /
CIEA DATA LAG/ -.4117961750E+01, -.3811294543E-03, .4308265942E-05,
CIEA A -.9160120130E-08, .8017924673E-11, -.4816067020E-05,
CIEA B .7744786733E-07, -.6988467605E-09, .1916720525E-11,
CIEA C -.1760288590E-14, -.1820625039E-08, .1440785930E-10,

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INV02220
 INV02225
 INV03215
 INV03340
 INV03350
 JSVE0186
 JSVE0386
 JSVE0406
 JSVE0575
 JSVE0770
 JSVE2170
 JSVE2210
 JSVE2245
 JSVE2637
 RTRN0226
 STST0466
 TRAN0676
 TRAN0765
 WATRO360
 WATRO361
 WATRO390
 WATRO391
 WATRO392
 WATRO415
 WATRO416
 WATRO417
 WATRO418



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CIEA D      -.2082170753E-13, -.3603625114E-16, .7407124321E-19/  WATR0419
C           WATR0420
C           WATR0421
DATA LAG/  -.4134029589E+01, -.2441184054E-04, .2209870962E-05,  WATR0422
A          -.6070628894E-08, .1316350552E-10, -.1522929216E-13,  WATR0423
B          .8589240994E-17, -.3421502161E-05, .5157995569E-07,  WATR0424
C          -.7610491182E-09, .3333816472E-11, -.6337446779E-14,  WATR0425
D          .5400840762E-17, -.1866330638E-20, -.2182353803E-08,  WATR0426
E          .5762274970E-10, -.6869462033E-12, .3899888586E-14,  WATR0427
F          -.1073370946E-16, .1309877667E-19, -.5683523484E-23,  WATR0428
G          .2259079893E-11, -.6805783575E-13, .8026765479E-15,  WATR0429
H          -.4349228692E-17, .1157103300E-19, -.1389663618E-22,  WATR0430
I          .5988902843E-26, -.9015092027E-15, .2792720654E-16,  WATR0431
J          -.3238260469E-18, .1726010684E-20, -.4584612622E-23,  WATR0432
K          .5548851287E-26, -.2422095395E-29, .1221331859E-18,  WATR0433
L          -.3818512162E-20, .4338257722E-22, -.2281516843E-24,  WATR0434
H          .6066135172E-27, -.7396337791E-30, .3260076238E-33/  WATR0435
CIEA SPO = LAG(1) + H*( LAG(2) +H*( LAG(3) +H*( LAG(4) +H* LAG(5) )))WATR1206
CIEA SP1 = LAG(6) + H*( LAG(7) +H*( LAG(8) +H*( LAG(9) +H* LAG(10) )))WATR1207
CIEA SP2 = LAG(11)+ H*( LAG(12) +H*( LAG(13)+H*( LAG(14) +H* LAG(15) )))WATR1208
CIEA ARG = SPO + P * ( SP1 + P * SP2 ) WATR1209
C           WATR1210
SPO = LAG( 1) + H*( LAG( 2) + H*( LAG( 3) + H*( LAG( 4) WATR1211
*           + H*( LAG( 5) + H*( LAG( 6) + H * LAG( 7) )))) WATR1212
SP1 = LAG( 8) + H*( LAG( 9) + H*( LAG(10) + H*( LAG(11) WATR1213
*           + H*( LAG(12) + H*( LAG(13) + H * LAG(14) )))) WATR1214
SP2 = LAG(15) + H*( LAG(16) + H*( LAG(17) + H*( LAG(18) WATR1215
*           + H*( LAG(19) + H*( LAG(20) + H * LAG(21) )))) WATR1216
SP3 = LAG(22) + H*( LAG(23) + H*( LAG(24) + H*( LAG(25) WATR1217
*           + H*( LAG(26) + H*( LAG(27) + H * LAG(28) )))) WATR1218
SP4 = LAG(29) + H*( LAG(30) + H*( LAG(31) + H*( LAG(32) WATR1219
*           + H*( LAG(33) + H*( LAG(34) + H * LAG(35) )))) WATR1220
SP5 = LAG(36) + H*( LAG(37) + H*( LAG(38) + H*( LAG(39) WATR1221
*           + H*( LAG(40) + H*( LAG(41) + H * LAG(42) )))) WATR1222
C           WATR1223
ARG = SPO + P*( SP1 + P*(SP2 + P*(SP3 + P*(SP4 + P*SP5 ))) WATR1224
C           WATR1225
CIEA DVDPH = SPVOL * (SP1 + TWO * P * SP2) WATR2105
DVDPH = SPVOL *(SP1 + P*(TWO*SP2 + P*(THREE*SP3 + P*(FOUR*SPA WATR2106
*           + FIVE*P*SP5 ))) WATR2107
CIEA SH1 = LAG(2) + P*( LAG(7) + P* LAG(12) ) WATR2180
CIEA SH2 = LAG(3) + P*( LAG(8) + P* LAG(13) ) WATR2181
CIEA SH3 = LAG(4) + P*( LAG(9) + P* LAG(14) ) WATR2182
CIEA SH4 = LAG(5) + P*( LAG(10) + P* LAG(15) ) WATR2183
CIEA DVDPH = SPVOL *(SH1 +H*( TWO*SH2 + H*( THREE*SH3 + H *FOUR*SH4))) WATR2184
C           WATR2185
SH1 = LAG( 2) + P*( LAG( 9) + P*(LAG(16) + P*(LAG(23) WATR2186
*           + P*(LAG(30) + P* LAG(37) )))) WATR2187
SH2 = LAG( 3) + P*( LAG(10) + P*(LAG(17) + P*(LAG(24) WATR2188
*           + P*(LAG(31) + P* LAG(38) )))) WATR2189
SH3 = LAG( 4) + P*( LAG(11) + P*(LAG(18) + P*(LAG(25) WATR2190
*           + P*(LAG(32) + P* LAG(39) )))) WATR2191
SH4 = LAG( 5) + P*( LAG(12) + P*(LAG(19) + P*(LAG(26) WATR2192
*           + P*(LAG(33) + P* LAG(40) )))) WATR2193
SH5 = LAG( 6) + P*( LAG(13) + P*(LAG(20) + P*(LAG(27) WATR2194
*           + P*(LAG(34) + P* LAG(41) )))) WATR2195
SH6 = LAG( 7) + P*( LAG(14) + P*(LAG(21) + P*(LAG(28) WATR2196
*           + P*(LAG(35) + P* LAG(42) )))) WATR2197
C           WATR2198
DVDPH = SPVOL * (SH1 + H*(TWO *SH2 + H*(THREE*SH3 + H*(FOUR*SH4 WATR2199
*           + H*(FIVE*SH5 + SIX*H*SH6 ))) WATR2200
#LOCATE WAT7 XX
CIEA P=10. WAT71260
CIEA I RECOMENDE A BELOW VALUE FOR UPDATE STEAM TABLE WAT71261
C           WAT71262
P=1.0 WAT71263
#LOCATE ENTR XX
GO TO 20
#LOCATE HAVG XX
DIMENSION HWKEEP(4)
DATA HWKEEP /4*0.0/,HWTOM/0.0/,ITTON/0/,TOMFCT/0.005/
C READ (5,67700) TOMFCT
67700 FORMAT (F10.0)
IF ( LINEAR ) GO TO 6739
IF ( OLVOLN(K).NE.110 .AND. OLVOLN(K).NE.210) GO TO 6739
ITTON = ITTON + 1
C1 CALL SLIPHW (OLVOLN(K), HWTOM, AX)
C1 IF ( AX.EQ.ZERO ) GO TO 6739
C1 IF ( ITTON.CT.10 ) GO TO 6734
C1 IF ( HWKEEP(OLVOLN(K)/100).EQ.ZERO ) GO TO 6731

```

ENTR0395

HAVG0156
HAVG0176
HAVG0241
HAVG0242
HAVG1491

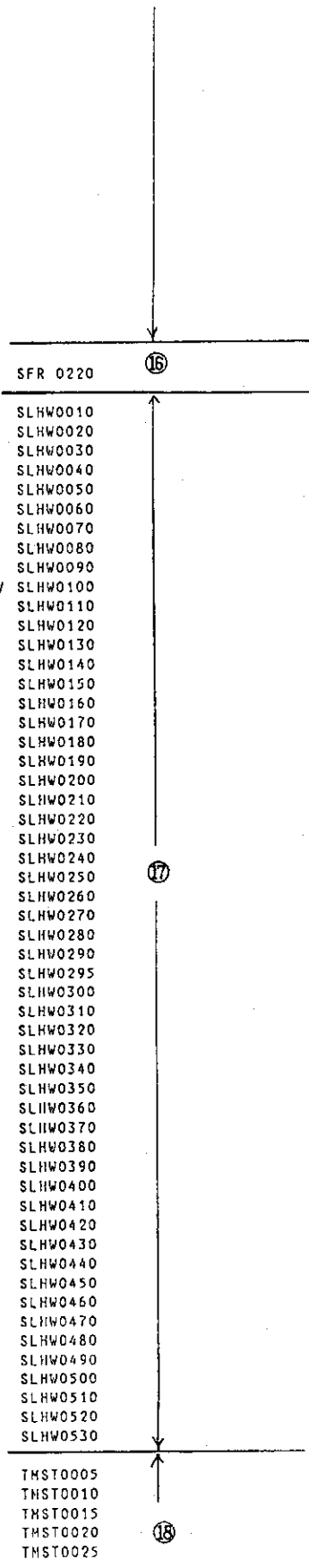
14

15


```

C1 HW(K) = 0.5*(HWKEEP(OLVOLN(K)/100) + HWTOM)
C1 GO TO 6732
C6731 IF ( HWTOM.NE.ZERO ) HW(K) = HWTOM
C6732 CONTINUE
C1 HWKEEP(OLVOLN(K)/100) = HWTOM
CXXX IF ( ITTOM.GT.200 ) TOMFCT = 0.008
      IF ( HWKEEP(OLVOLN(K)/100).NE.ZERO ) GO TO 6734
CCCC HWKEEP(OLVOLN(K)/100) = AMIN1(HW(K),500.0)
      HWKEEP(OLVOLN(K)/100) = HW(K)
      GO TO 6738
6734 CONTINUE
      HWKEEP(OLVOLN(K)/100) = HWKEEP(OLVOLN(K)/100) + FU(K)*TOMFCT
      HW(K) = HWKEEP(OLVOLN(K)/100)
6738 CONTINUE
C WRITE (6,67390) OLVOLN(K), HW(K), FU(K), AX
67390 FORMAT (' @@@@',I5,1P3E13.6)
6739 CONTINUE
*LOCATE SFR XX
      DATA ZERO / 0.E0/, ONE / 1.E0/, PT95 / 0.95/, PT999 / 0.99999 / SFR 0220
*INSERT XX
      SUBROUTINE SLPHW (NVHW, SLPHW, AX)
*CALL BKCM
*CALL I002
*CALL I005
*CALL I006
*CALL I007
      LOGICAL NTFIRST
C
*CALL UNIT
      DATA ZERO / 0.0E0 /, ONE / 1.0E0 /, TWO / 2.0E0 /, FOUR / 4.0E0 /
      DATA NTFIRST / .FALSE. /
C
      IF (NTFIRST) GO TO 5
      I2 = FILIDX(2)
      I5 = FILIDX(5)
      ISS = SETSI2(5)
      MS5 = 15 + (NVOL(I2)-1)*ISS
      I6 = FILIDX(6)
      I7 = FILIDX(7)
      IS6 = SETSI2(6)
      MS6 = 16 + (NJUN(I2)-1)*IS6
      DO 1 JIN = I6,MS6,IS6
          KK = IW2N(JIN) - 1
          K = I5 + KK*ISS
          IF ( OLVOLN(K).EQ.110 ) GO TO 5
1 CONTINUE
      STOP 6000
5 CONTINUE
C
      AX = ZERO
      DO 101 J = 16,MS6,IS6
          KK = IW1N(J) - 1
          K = I5 + KK*ISS
          IF ( OLVOLN(K).EQ.NVHW ) GO TO 120
101 CONTINUE
      STOP 6001
120 CONTINUE
      IF ( NVHW.NE.110 .AND. NVHW.GT.210 ) GO TO 900
      IF ( VSLPJ(J).GE.ZERO ) GO TO 900
      QSUM = ZERO
      DO 141 K = 15,MS5,ISS
          IF ( OLVOLN(K).EQ.NVHW
*           ) QSUM = QSUM + QSPL(K)
141 CONTINUE
      TOMTMP = AJUNT(J)*(HPG(J)-HPL(J))
      TOMAA = (WP(J))*(HPG(J)-HP(JIN))-QSUM)*SPVJL(J)/TOMTMP
      TOMBB = (WP(J))*(HP(JIN)-HPL(J))+QSUM)*SPVJG(J)/TOMTMP
      TOMTNP = VSLPJ(J) - TOMAA - TOMBB
      AX = (TOMTMP+SQRT(TOMTNP**2+FOUR*VSLPJ(J)*TOMBB))/(TWO*VSLPJ(J))
      XA = AX*SPVJL(J)/(AX*SPVJL(J)+(ONE-AX)*SPVJG(J))
      SLPHW = HPL(J) + XA*(HPG(J)-HPL(J))
900 CONTINUE
      RETURN
      END
*INSERT XX
      SUBROUTINE TOMGST
*      (MODE,IDX,IFIL,DD)
*CALL BKCM
*CALL TOMG
C

```



```

REAL NEXTID, IDXF(1), IFIL(1), DD(5,1)
INTEGER COUTX
C
DATA IEDT / 1 /, COUTX /4HCOUT/
DATA PI180 / 1.745329252E-2 /
C
CALL ZEROUT(TOMGH,16)
IZET2D = 0
CALL ROLAXS
CIEAJ WRITE (6,7120) ((TR(I,J),I=1,3),J=1,3)
7120 FORMAT (' ****TR ',1P3E13.6/8X,3E13.6)
TOMGF = 1.0
TEMPID = NEXTID(0)
LEN = LCONTG(1)
CALL RESERV(TEMPID,LEN,2,IDXVAR)
ISTOR(IDXVAR) = COUTX
C
C
C FOR VERTICAL FORCE
IF ( Istor(FILIDX(2)+28).LT.2 ) GOTO 100
ISTOR(IDXVAR+1) = -ISTOR(FILIDX(2)+28)
CALL SEARCH (ITOMGF,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
100 CONTINUE
C
C FOR HORIZONTAL FORCE
IF ( Istor(FILIDX(2)+48).EQ.0 ) GOTO 120
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+48)
CALL SEARCH (ITOMGH,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
120 CONTINUE
C
C FOR Z-AXIS ROLLING PHI
IF ( Istor(FILIDX(2)+49).EQ.0 ) GOTO 140
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+49)
CALL SEARCH (IPHI2,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
140 CONTINUE
C
C FOR Z-AXIS ROLLING PHI DOT
IF ( Istor(FILIDX(2)+50).EQ.0 ) GOTO 160
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+50)
CALL SEARCH (IPHI2D,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
160 CONTINUE
C
C FOR Z-AXIS ROLLING PHI 2DOT
IF ( Istor(FILIDX(2)+51).EQ.0 ) GOTO 180
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+51)
CALL SEARCH (IPHI2D,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
180 CONTINUE
C
C FOR Y-AXIS ROLLING THETA
IF ( Istor(FILIDX(2)+52).EQ.0 ) GOTO 200
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+52)
CALL SEARCH (ITHEY,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
200 CONTINUE
C
C FOR Y-AXIS ROLLING THETA DOT
IF ( Istor(FILIDX(2)+53).EQ.0 ) GOTO 220
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+53)
CALL SEARCH (ITHEYD,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
220 CONTINUE
C
C FOR Y-AXIS ROLLING THETA 2DOT
IF ( Istor(FILIDX(2)+54).EQ.0 ) GOTO 240
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+54)
CALL SEARCH (ITHE2D,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
240 CONTINUE
C
C FOR Z-AXIS ROLLING ZETA
IF ( Istor(FILIDX(2)+55).EQ.0 ) GOTO 260
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+55)
CALL SEARCH (IZETX,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
260 CONTINUE
C
C FOR Z-AXIS ROLLING ZETA DOT
IF ( Istor(FILIDX(2)+56).EQ.0 ) GOTO 280
ISTOR(IDXVAR+1) = Istor(FILIDX(2)+56)
CALL SEARCH (IZETXD,IDXVAR,IEDT,MODE,IDX,IFIL,DD,J,K)
280 CONTINUE
C
C FOR Z-AXIS ROLLING ZETA 2DOT
IF ( Istor(FILIDX(2)+57).EQ.0 ) GOTO 300

```

```

TMST0030
TMST0035
TMST0040
TMST0045
TMST0050
TMST0055
TMST0060
TMST0061
TMST0062
TMST0063
TMST0064
TMST0065
TMST0070
TMST0075
TMST0080
TMST0085
TMST0090
TMST0095
TMST0100
TMST0105
TMST0110
TMST0115
TMST0120
TMST0125
TMST0130
TMST0135
TMST0140
TMST0145
TMST0150
TMST0155
TMST0160
TMST0165
TMST0170
TMST0175
TMST0180
TMST0185
TMST0190
TMST0195
TMST0200
TMST0205
TMST0210
TMST0215
TMST0220
TMST0225
TMST0230
TMST0235
TMST0240
TMST0245
TMST0250
TMST0255
TMST0260
TMST0265
TMST0270
TMST0275
TMST0280
TMST0285
TMST0290
TMST0295
TMST0300
TMST0305
TMST0310
TMST0315
TMST0320
TMST0325
TMST0330
TMST0335
TMST0340
TMST0345
TMST0350
TMST0355
TMST0360
TMST0365
TMST0370
TMST0375
TMST0380
TMST0385
TMST0390
TMST0395
TMST0400
TMST0405

```

```

        ISTORE(IDXVAR+1) = ISTORE(FILIDX(2)+57)
        CALL SEARCH (IZET2D,IDXVAR,IEDT,MODE,IDXFI,IFIL,DD,J,K)
300 CONTINUE
        CALL DELETE(TEMPID)
                                           GOTO 900

C
        ENTRY TOMGFS
C
        TOMGF = 1.0
        TOMGH = 0.0
        CALL ZEROUT(PHI2,9)
        IF ( ISTORE(FILIDX(2)+28).GE. 2 )
*       TOMGF = FLOATR(RSTOR(ITOMGF))
        IF ( ISTORE(FILIDX(2)+48).NE. 0 )
*       TOMGH = FLOATR(RSTOR(ITOMGH))
        IF ( ISTORE(FILIDX(2)+49).NE. 0 )
*       PHIZ = FLOATR(RSTOR(IPHIZ ))*PI180
        IF ( ISTORE(FILIDX(2)+50).NE. 0 )
*       PHIZD = FLOATR(RSTOR(IPHIZD))*PI180
        IF ( ISTORE(FILIDX(2)+51).NE. 0 )
*       PHI2D = FLOATR(RSTOR(IPHI2D))*PI180
        IF ( ISTORE(FILIDX(2)+52).NE. 0 )
*       THEY = FLOATR(RSTOR(ITHEY ))*PI180
        IF ( ISTORE(FILIDX(2)+53).NE. 0 )
*       THEYD = FLOATR(RSTOR(ITHEYD))*PI180
        IF ( ISTORE(FILIDX(2)+54).NE. 0 )
*       THE2D = FLOATR(RSTOR(ITHE2D))*PI180
        IF ( ISTORE(FILIDX(2)+55).NE. 0 )
*       ZETX = FLOATR(RSTOR(IZETX ))*PI180
        IF ( ISTORE(FILIDX(2)+56).NE. 0 )
*       ZETXD = FLOATR(RSTOR(IZETXD))*PI180
        IF ( ISTORE(FILIDX(2)+57).NE. 0 )
*       ZET2D = FLOATR(RSTOR(IZET2D))*PI180
        CALL ROLAXS
CIEA WRITE (6,6881) TOMGF,PHIZ,THEY,ZETX
6881 FORMAT(' TOMGF=',1PE13.6,' PHIZ=',E13.6,' THEY=',E13.6
*         ' ZETX=', E13.6)
900 RETURN
        END
        SUBROUTINE AXEXYZ(I,ACCXYZ)
*CALL BKCM
*CALL IDOS
*CALL TOMG
        DIMENSION ACCXYZ(3),XYZ(3)
C
        CALL MATMLT(CTR,RAD3DX(I),XYZ,1)
C
        ACCXYZ(1) = ACCXYZ(1) + XYZ(1)*PHIZ**2 + XYZ(2)*PHI2D
        ACCXYZ(2) = ACCXYZ(2) + XYZ(2)*PHI2D**2 - XYZ(1)*PHI2D
        ACCXYZ(1) = ACCXYZ(1) + XYZ(1)*THEYD**2 + XYZ(3)*THE2D
        ACCXYZ(3) = ACCXYZ(3) + XYZ(3)*THEYD**2 - XYZ(1)*THE2D
        ACCXYZ(2) = ACCXYZ(2) + XYZ(2)*ZETXD**2 - XYZ(3)*ZET2D
        ACCXYZ(3) = ACCXYZ(3) + XYZ(3)*ZETXD**2 + XYZ(2)*ZET2D
        RETURN
        END
        SUBROUTINE ROLAXS
*CALL TOMG
C       PHIZ ..... ROLLING ANGLE FOR Z-AXIS
C       THEY ..... ROLLING ANGLE FOR Y-AXIS
C       ZETX ..... ROLLING ANGLE FOR X-AXIS
        DIMENSION YZ(3,3),TY(3,3),TX(3,3),TT(3,3)
        DATA TZ / 8*0.0, 1.0 /
        DATA TY / 4*0.0, 1.0, 4*0.0 /
        DATA TX / 1.0, 8*0.0 /
C
        TZ(1,1) = COS(PHI2)
        TZ(2,2) = TZ(1,1)
        TZ(2,1) = SIN(PHI2)
        TZ(1,2) = -TZ(2,1)
C
        TY(1,1) = COS(THEY)
        TY(3,3) = TY(1,1)
        TY(3,1) = SIN(THEY)
        TY(1,3) = -TY(3,1)
C
        TX(2,2) = COS(ZETX)
        TX(3,3) = TX(2,2)
        TX(2,3) = SIN(ZETX)
        TX(3,2) = -TX(2,3)
C

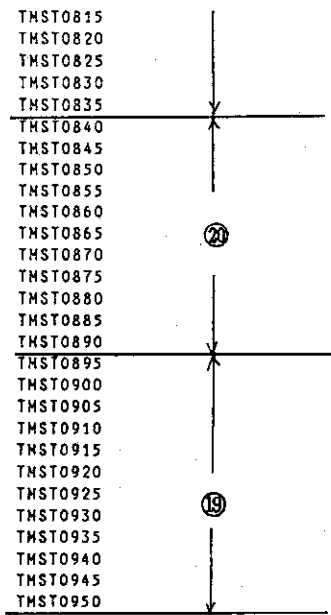
```

TMST0410
 TMST0415
 TMST0420
 TMST0425
 TMST0430
 TMST0435
 TMST0440
 TMST0445
 TMST0450
 TMST0455
 TMST0460
 TMST0475
 TMST0480
 TMST0485
 TMST0490
 TMST0495
 TMST0500
 TMST0505
 TMST0510
 TMST0515
 TMST0520
 TMST0525
 TMST0530
 TMST0535
 TMST0540
 TMST0545
 TMST0550
 TMST0555
 TMST0560
 TMST0565
 TMST0570
 TMST0575
 TMST0580
 TMST0582
 TMST0585
 TMST0590
 TMST0595
 TMST0600
 TMST0605
 TMST0610
 TMST0615
 TMST0620
 TMST0625
 TMST0630
 TMST0635
 TMST0640
 TMST0645
 TMST0650
 TMST0655
 TMST0660
 TMST0665
 TMST0670
 TMST0675
 TMST0680
 TMST0685
 TMST0690
 TMST0695
 TMST0700
 TMST0705
 TMST0710
 TMST0715
 TMST0720
 TMST0725
 TMST0730
 TMST0735
 TMST0740
 TMST0745
 TMST0750
 TMST0755
 TMST0760
 TMST0765
 TMST0770
 TMST0775
 TMST0780
 TMST0785
 TMST0790
 TMST0795
 TMST0800
 TMST0805
 TMST0810

```

CALL MATHLT(TZ,TY,TT,3)
CALL MATHLT(TT,TX,TR,3)
C
RETURN
END
SUBROUTINE MATHLT(A,B,C,N)
DIMENSION A(3,3),B(3,N),C(3,N)
C
DO 101 J=1,N
DO 101 I=1,3
C(I,J) = 0.0
DO 101 K=1,3
C(I,J) = C(I,J) + A(I,K)*B(K,J)
101 CONTINUE
RETURN
END
SUBROUTINE ROLXYZ(I,R,RXYZ)
*CALL BKCM
*CALL ID05
*CALL TONG
DIMENSION RXYZ(3)
C
CALL MATHLT(TR,VOL3DX(I),RXYZ,1)
C
DO 101 J=1,3
RXYZ(J) = RXYZ(J)*R
RETURN
END

```



A.2 Input specification of RETRAN-02/GRAV

The following input specifications are the input manuals of improved functions of RETRAN-02/GRAV for users. Input data besides the improved functions are the same as the original REATRAN/02.

2.1 Dimension Data Input Card (01004)

These cards identify the control block numbers (negative number) which specify the rotation angles, the angular velocity, the acceleration and the tangential forces. When zero is input or these cards are omitted, the calculation on the rotation is not done. Free format is applied. Card number 010001 ~ 010003 is used for the original dimension data card.

| | | |
|-------|---------|---|
| W1-I | ITOMGH | Control block number to calculate the horizontal force which is normalized by the gravity acceleration. |
| W2-I | IPHIZ | Control block number to calculate the rotation angular of degree around z axis. Positive value means the angular from the x axis toward the y axis. |
| W3-I | IPHIZD | Control block number to calculate the angular velocity by rotation around the z axis, unit of which is degree/second. |
| W4-I | IPHI2D | Control block number to calculate the angular acceleration by rotation around the z axis, unit of which is degree/second ² . |
| W5-I | ITHEY | Control block number to calculate the rotation angular of degree around the y axis. Positive value means the angular from the x axis toward the z axis. |
| W6-I | ITHEYD | Control block number to calculate the angular velocity by rotation around the y axis, unit of which is degree/second. |
| W7-I | ITHEY2D | Control block number to calculate the angular acceleration by rotation around the y axis, unit of which is degree/second ² . |
| W8-I | IZETX | Control block number to calculate the rotation angular of degree around the x axis. Positive value means the angular from the x axis toward the z axis. |
| W9-I | IZETXD | Control block number to calculate the angular velocity by rotation around the x axis, unit of which is degree/second. |
| W10-I | IZET2D | Control block number to calculate the angular acceleration by rotation around the y axis, unit of which is |

degree/second².

2.2 Volume Data Input Card (05xxx9)

These cards identify the position of volume center by rectangular co-ordinates from the center of gravity. The z axis means the vertical direction, the y axis means the direction from the bow to the stern of ship and the x axis means the direction from the starboard to the port of ship. When zero is inputted to RAD3DX, RAD3DY and RAD3DZ, the centrifugal and tangential forces become zero. Free format is applied. Card number 05xxx1 ~ 05xxx8 is used for the original volume data card.

| | | |
|------|------------|--|
| W1-R | RAD3DX(ft) | Distance from volume center to the center of gravity in x-axis. |
| W2-R | RAD3DY(ft) | Distance from volume center to the center of gravity in y-axis. |
| W3-R | RAD3DZ(ft) | Distance from volume center to the center of gravity in z-axis. |
| W4-R | VOL3DX(-) | Distance from volume center to the center of rotation in x-axis, normalized by ZVOL. |
| W5-R | VOL3DY(-) | Distance from volume center to the center of rotation in y-axis, normalized by ZVOL. |
| W6-R | VOL3DZ(-) | To be 1.0 |

2.3 Junction Data Input Card (08xxx9)

These cards identify the flag to specify the inlet or outlet junctions of the three-dimensional volume. In rotation, an elevation of junction will be calculated to be higher than another elevation of junction connected to the same volume. The junction of higher elevation means outlet at the volume (-) and the junction of lower elevation means inlet at the volume. Free format is applied. Card number 08xxx1 ~ 08xxx8 is used for the original junction data card.

| | | |
|------|------|--|
| W1-I | IWT1 | To specify a junction to be outlet(-) or inlet(+) for ~ from ~ volume. The zero of input data does not specify outlet and inlet of the volume. |
| W2-I | IWT2 | To specify junction to be outlet(-) or inlet(+) for ~ to ~ volume. The zero of input data does not specify outlet and inlet of the volume. |

A.3 Input sample of the N.S. Mutsu

As a sample, the input data of which noding is the same as one in Fig. 4.1.3 'RETRAN-02/GRAV Computational nodalization for Mutsu analysis'.

```

= MUTSU : (A0011 <FEED WATER CONTROL>)
*****
***** < 1990.10.11 ===== IEAJ> *****
***** CORE - SEPARATE 3 *****
***** S.G. 3 VOLUME *****
***** PRZ 2 VOLUME *****
***** 2 LOOP *****
***** BASE DATA = CASE11('90) *****
*****
*
* PROBLEM DESCRIPTION DATA CARDS
*
* D E N T V B T J P C N F S G M C H T N M L T I C S P T D I
* M D T R O U D U M K L I L O A O T M D W V D S H S R R N C
* P I C P L B V N P V K L B M T R X M L R C V F T T Z S B F
010001 -1 16 1 61 41 11 1 60 2 13 21 16 11 2 3 3 2 0 3 1 0 0 2 0 0 1 1 1 1
* M S S X S T V F F L S
* A V C P T S O I L Q E
* P L D L K H I T A S P
010002 1 0 0 1 0 0 0 0 0 0 0
* I R O L L I I R O L L D I T O M G H I R O L L D D
010004 -000 000 000 000 * NULL TRAN.
* I T O M G H I P H I Z I P H I Z D I P H I Z D I T H E Y I T H E Y D I T H E Z D I Z E T X I Z E T X D I Z E T Z D
010004 -000 -000 -000 -000 -000 -000 -000 -000 -000 -000
*
010005 25.0 * MW POWER (70%)
*
* TAPE NO.
010140 'MUTSU.CASE15' *
010141 'IE1435' 'GE' *
*
* MINOR EDLT VARIABLES
*
020000 WP**, 160 PRES, 160 PRES, 170 STVG, 101 STVF, 101 AJNT, 160 *
020000 COUT, -13 PRES, 31 LIQL, 101 WP**, 151 WP**, 153 PRES, 101 *
020001 POWR, 0 TEMP, 10 TEMP, 19 WP**, 106 HP**, 151 HP**, 251
020002 COUT, -73 WP**, 112 COUT, -134 AVEX, 110
*
* TIME STEP DATA CARDS
*
* NMIN NMAJ NDNP NCHK DELTM DTMIN TLAST
030010 10 250 1 0 0.2 0.0 10000. *
*
* TRIP CONTROL DATA CARDS
*
* IDTRP IOSIG IX1 IX2 SETPOINT DELAY
040010 1 1 0 0 779. 0. *END TRIP SIGNAL
040020 2 1 0 0 0. 0. *GENERAL TIME ZERO
040030 3 4 32 0 1792.20 0. *PRZER RELIEF VALVE OPEN
040040 -3 -4 32 0 1749.54 0. *PRZER RELIEF VALVE CLOSE
040050 4 1 0 0 5.0 1.E9 *DUMMY
040060 5 2 0 0 4.26 0. *HIGH POWER
040070 6 14 -44 0 1.-9 0. *LOW PRESS. CONTROL SYSTEM
040080 7 14 -31 0 1.-9 0. *HIGH TEMP. CONTROL SYSTEM
040090 8 14 -13 0 7.116 0. *PRZER HIGH LIQ.L
040100 9 -14 -286 0 7.044 0. *SG LOW LIQ.L
040110 10 14 -13 0 7.116 0. *PRZER LOW LIQ.L
040120 11 -4 20 0 1152.1 0. *HOT LEG LOW PRESS.
040130 12 13 10 11 0. 0. *SI SIGNAL
040140 13 12 5 6 0. 0. *IDTRIP 5 OR 6
040150 14 12 13 7 0. 0. *IDTRIP 13 OR 7
040160 15 12 14 8 0. 0. *IDTRIP 14 OR 8
040170 16 12 15 9 0. 0. *SCRAM SIGNAL
040180 17 12 16 0 0. 9. *FW STOP 9 SEC AFTER SCRAM
040190 18 12 12 16 0. 0. *SI OR IDTRIP16 (SCRAM)
040200 19 12 16 0 0. 15. *15 SEC AFTER SCRAM
040210 20 -4 31 0 1507.8 0. *LOW PRESS. BACK.HEATER ON
040220 -20 4 31 0 1550.46 0. *LOW PRESS. BACK.HEATER OFF
040230 21 14 -13 0 1.235 0. *V. HEATER INTERLOCK ON-0.0
040240 -21 -14 -13 0 1.235 0. *V. HEATER INTERLOCK OFF+0.0
040250 22 14 -73 0 5.0 0. * #2 ROD IN START
040260 -22 -14 -73 0 4.7 0. * #2 ROD IN STOP
040270 23 14 -73 0 1.2 0. * #1 ROD IN START
040280 -23 -14 -73 0 1.1 0. * #1 ROD IN STOP
040290 24 -14 -73 0 -1.2 0. * #1 ROD OUT START
040300 -24 14 -73 0 -1.1 0. * #1 ROD OUT STOP
040310 25 -14 -73 0 -5.0 0. * #2 ROD OUT START
040320 -25 14 -73 0 -4.7 0. * #2 ROD OUT STOP

```


JAERI-M 91-226

| | | | | | | | |
|--------|------|-----|-----|----|--------|-------|--------------------------------|
| 040330 | 26 | 14 | -13 | 0 | 6.508 | 0. | *60% LEVEL BACK.HEATER |
| 040340 | -26 | -14 | -13 | 0 | 6.508 | 0. | *60% LEVEL BACK.HEATER |
| 040350 | 1 | 12 | 18 | 0 | 0. | 1.+9 | *DUMMY |
| 040360 | 30 | 12 | 12 | 16 | 0. | 0.7 | *0.7 SEC AFTER SCRAM(CON.ROD) |
| 040370 | 130 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 040380 | 130 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 040390 | 140 | 4 | 160 | 0 | 991.84 | 0. | *ST-LINE SAFE.VAL OPEN/CLOSE |
| 040400 | 150 | 12 | 16 | 0 | 0. | 9.0 | *STOP VALVE CLOSE AFTER SCRAM |
| * | | | | | | | |
| 049010 | -901 | 5 | 103 | 0 | 10.5 | 0. | *VOL 103 LEVEL CAL. |
| 049020 | 901 | -6 | 101 | 0 | 0.1 | 0. | * |
| 049030 | 902 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 049040 | 902 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 049050 | -903 | 5 | 203 | 0 | 10.5 | 0. | *VOL 203 LEVEL CAL. |
| 049060 | 903 | -6 | 201 | 0 | 0.1 | 0. | * |
| 049070 | 904 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 049080 | 904 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 049090 | -905 | 5 | 110 | 0 | 10.0 | 0. | *VOL 110 LEVEL CAL. |
| 049100 | 905 | -6 | 101 | 0 | 0.1 | 0. | * |
| 049110 | -906 | 5 | 210 | 0 | 10.0 | 0. | *VOL 210 LEVEL CAL. |
| 049120 | 906 | -6 | 201 | 0 | 0.1 | 0. | * |
| 049130 | 151 | 1 | 0 | 0 | 1.+9 | 0. | *DUMMY |
| 049140 | 152 | 12 | 12 | 0 | 0. | 20. | *HPLS#1 START 20 SEC AFTER SI |
| 049150 | 153 | 12 | 12 | 0 | 0. | 30. | *HPLS#2 START 30 SEC AFTER SI |
| 049160 | 154 | 12 | 12 | 0 | 0. | 600. | *MSIV(A) CLOSE 600SEC AFTER SI |
| 049170 | 155 | 1 | 0 | 0 | 1.+9 | 0. | *HPLS STOP(MANUAL) |
| 049180 | 156 | 1 | 0 | 0 | 1.+9 | 0. | *AFW(A) START(MANUAL) |
| 049190 | 157 | 12 | 12 | 0 | 0. | 1200. | *AFW(B) START(MANUAL) |
| 049200 | 158 | 12 | 12 | 0 | 0. | 1200. | *DUMP VALVE OPEN(MANUAL) |
| 049210 | 500 | -2 | 0 | 0 | 0.1 | 0. | *INTERLOCK FOR DUMP VALVE |

*
* VOLUME DATA CARDS
*

| * IB | IR | PRESS | TORR | X | V | ZVOL | ZM | |
|---------|-------|-------|--------|-------|--------|---------|--------|------------------|
| 050011 | 0 | 0 | 0. | 0. | 41.690 | 4.212 | 4.212 | *LOWER PLENUM |
| 050021 | 0 | 0 | 0. | 508.0 | 0. | 12.233 | 4.433 | *GUIDE TUBE |
| 050031 | 0 | 0 | 0. | 0. | 0. | 6.877 | 1.081 | *AVE CORE (BOT) |
| 050041 | 0 | 0 | 0. | 0. | 0. | 7.951 | 1.250 | *AVE CORE (MID) |
| 050051 | 0 | 0 | 0. | 0. | 0. | 6.877 | 1.081 | *AVE CORE (TOP) |
| 050061 | 0 | 0 | 0. | 0. | 0. | 24.065 | 4.342 | *CORE BYPASS |
| 050071 | 0 | 0 | 0. | 0. | 0. | 96.9372 | 6.138 | *U.P.+ANNULUS |
| 050081 | 0 | 0 | 0. | 0. | 0. | 35.840 | 2.661 | *UPPER HEAD |
| 050091 | 0 | 0 | 0. | 0. | 0. | 52.865 | 11.238 | *DOWN COMER |
| 050101 | 0 | 0 | 0. | 0. | 0. | 7.539 | 11.983 | *HOT LEG 1 |
| 050111 | 0 | 0 | 0. | 0. | 0. | 5.120 | 2.690 | *SG 1 INLET |
| 050121 | 0 | 0 | 0. | 0. | 0. | 3.826 | 4.232 | *U-TUBE |
| 050131 | 0 | 0 | 0. | 0. | 0. | 4.794 | 5.719 | *U-TUBE |
| 050141 | 0 | 0 | 0. | 0. | 0. | 4.794 | 5.719 | *U-TUBE |
| 050151 | 0 | 0 | 0. | 0. | 0. | 3.826 | 4.232 | *U-TUBE |
| 050161 | 0 | 0 | 0. | 0. | 0. | 6.264 | 2.690 | *SG 1 OUTLET |
| 050171 | 0 | 0 | 0. | 0. | 0. | 3.823 | 5.645 | *CROSS OVER LEG |
| 050181 | 0 | 0 | 0. | 0. | 0. | 7.062 | 2.368 | *PUMP 1 |
| 050191 | 0 | 0 | 0. | 0. | 0. | 6.144 | 7.783 | *COLD LEG 1 |
| 050201 | 0 | 0 | 1579.6 | 0. | 0. | 7.539 | 11.983 | *HOT LEG 2 |
| 050211 | 0 | 0 | 0. | 0. | 0. | 5.120 | 2.690 | *SG 2 INLET |
| 050221 | 0 | 0 | 0. | 0. | 0. | 3.826 | 4.232 | *U-TUBE |
| 050231 | 0 | 0 | 0. | 0. | 0. | 4.794 | 5.719 | *U-TUBE |
| 050241 | 0 | 0 | 0. | 0. | 0. | 4.794 | 5.719 | *U-TUBE |
| 050251 | 0 | 0 | 0. | 0. | 0. | 3.826 | 4.232 | *U-TUBE |
| 050261 | 0 | 0 | 0. | 0. | 0. | 6.264 | 2.690 | *SG 2 OUTLET |
| 050271 | 0 | 0 | 0. | 0. | 0. | 3.823 | 5.645 | *CROSS OVER LEG |
| 050281 | 0 | 0 | 0. | 0. | 0. | 7.062 | 2.368 | *PUMP 2 |
| 050291 | 0 | 0 | 0. | 0. | 0. | 6.144 | 7.783 | *COLD LEG 2 |
| 050301 | 0 | 0 | 0. | 621.4 | 0. | 0.528 | 4.371 | *SURGE LINE |
| 050311 | 0 | 0 | 0. | 621.4 | 0. | 37.468 | 3.8 | *PRESSURIZER |
| 050321 | 1 | 0 | 0. | 0. | 0. | 54.338 | 5.511 | *PRESSURIZER |
| * | | | | | | | | |
| 051011 | 3 | 0 | 654.7 | 0. | 0. | 54.010 | 4.402 | * SG 1 DOME |
| 051031 | 4 | 0 | 0. | 0. | 0. | 34.618 | 10.711 | *SG 1 DC |
| 051101 | 6 | 0 | 0. | 0. | 0. | 56.849 | 15.0 | *SG 1 RISER |
| 051501 | 0 | 0 | 0. | 0. | 0. | 2.623 | 2.834 | * ST-LINE NO1 |
| * | | | | | | | | |
| 052011 | 8 | 0 | 654.7 | 0. | 0. | 54.010 | 4.402 | * SG 1 DOME |
| 052031 | 9 | 0 | 0. | 0. | 0. | 34.618 | 10.711 | *SG 2 DC |
| 052101 | 11 | 0 | 0. | 0. | 0. | 56.849 | 15.0 | *SG 2 RISER |
| 052501 | 0 | 0 | 0. | 0. | 0. | 2.623 | 2.834 | * ST-LINE NO2 |
| * | | | | | | | | |
| 051601 | 0 | 0 | 0. | 0. | 0. | 39.213 | 4.488 | *MAIN STEAM LINE |
| * | | | | | | | | |
| * FLOWL | FLOWA | DIAMV | ELEV | INQ | VRN | VLC | FB | NES |

| | | | | | | | | | |
|--------|---------|----------|---------|---------|---------|--------|--------|--|------------------|
| 050012 | 0. | 7.375 | 3.064 | -12.054 | | | | | *LOWER PLENUM |
| 050022 | 0. | 2.551 | 0.3186 | -10.703 | 0 | 0. | 0. 11 | | *GUIDE TUBE |
| 050032 | 0. | 6.3618 | 0.0465 | -6.27 | | | | | *AVE CORE (UOT) |
| 050042 | 0. | 6.3618 | 0.0465 | -5.189 | | | | | *AVE CORE (MID) |
| 050052 | 0. | 6.3618 | 0.0465 | -3.939 | | | | | *AVE CORE (TOP) |
| 050062 | 0. | 5.695 | 2.693 | -6.569 | | | | | *CORE BYPASS |
| 050072 | 0. | 9.027 | 3.390 | -2.858 | | | | | *U.P.+ ANNULUS |
| 050082 | 0. | 9.509 | 3.481 | 3.280 | | | | | *UPPER HEAD |
| 050092 | 0. | 5.715 | 2.698 | -7.842 | 0 | 0. | 0. 12 | | *DOWN COMER |
| 050102 | 0. | 0.349 | 0.666 | -11.650 | 0 | 0. | 0. 13 | | *HOT LEG 1 |
| 050112 | 0. | 2.010 | 1.510 | -8.799 | | | | | *SG 1 INLET |
| 050122 | 0. | 0.900 | 1.070 | -6.109 | | | | | *U-TUBE |
| 050132 | 0. | 0.900 | 1.070 | -1.877 | | | | | *U-TUBE |
| 050142 | 0. | 0.900 | 1.070 | -1.877 | | | | | *U-TUBE |
| 050152 | 0. | 0.900 | 1.070 | -6.109 | | | | | *U-TUBE |
| 050162 | 0. | 2.528 | 1.794 | -8.799 | | | | | *SG 1 OUTLET |
| 050172 | 0. | 0.349 | 0.666 | -11.665 | 0 | 0. | 0. 7 | | *CROSS OVER LEG |
| 050182 | 0. | 0.349 | 0.666 | -6.020 | | | | | *PUMP 1 |
| 050192 | 0. | 0.349 | 0.666 | -7.450 | 0 | 0. | 0. 11 | | *COLD LEG 1 |
| 050202 | 0. | 0.349 | 0.666 | -11.650 | 0 | 0. | 0. 13 | | *HOT LEG 2 |
| 050212 | 0. | 2.010 | 1.510 | -8.799 | | | | | *SG 2 INLET |
| 050222 | 0. | 0.900 | 1.070 | -6.109 | | | | | *U-TUBE |
| 050232 | 0. | 0.900 | 1.070 | -1.877 | | | | | *U-TUBE |
| 050242 | 0. | 0.900 | 1.070 | -1.877 | | | | | *U-TUBE |
| 050252 | 0. | 0.900 | 1.070 | -6.109 | | | | | *U-TUBE |
| 050262 | 0. | 2.528 | 1.794 | -8.799 | | | | | *SG 2 OUTLET |
| 050272 | 0. | 0.349 | 0.666 | -11.665 | 0 | 0. | 0. 7 | | *CROSS OVER LEG |
| 050282 | 0. | 0.349 | 0.666 | -6.020 | | | | | *PUMP 2 |
| 050292 | 0. | 0.349 | 0.666 | -7.450 | 0 | 0. | 0. 11 | | *COLD LEG 2 |
| 050302 | 0. | 0.028 | 0.188 | -8.989 | | | | | *SURGE LINE |
| 050312 | 0. | 9.586 | 3.543 | -4.818 | 0 | 0. | 0. 20 | | *PRESSURIZER |
| 050322 | 0. | 9.586 | 3.543 | -1.018 | 1 | 4. | 5000. | | *PRESSURIZER |
| * | | | | | | | | | |
| 051012 | 0. | 12.271 | 0. | 4.740 | | | | | * SG 1 DONE |
| 051032 | 0. | 1.302 | 0. | -5.971 | | | | | *SG 1 DOWNCOMER |
| 051102 | 0. | 2.024 | 0. | -5.971 | | | | | *SG 1 RISER |
| 051502 | 0. | 0.1402 | 0.4226 | 8.225 | | | | | * ST-LINE NO1 |
| * | | | | | | | | | |
| 052012 | 0. | 12.271 | 0. | 4.740 | | | | | * SG 2 DONE |
| 052032 | 0. | 1.302 | 0. | -5.971 | | | | | *SG 2 DOWNCOMER |
| 052102 | 0. | 2.024 | 0. | -5.971 | | | | | *SG 2 RISER |
| 052502 | 0 | 0.1402 | 0.4226 | 8.225 | | | | | * ST-LINE NO2 |
| * | | | | | | | | | |
| 051602 | 0. | 0.2736 | 0.5902 | 6.655 | | | | | *MAIN STEAM LINE |
| * | | | | | | | | | |
| | | RAD3DX | RAD3DY | RAD3DZ | VOL3DX | VOL3DY | VOL3DZ | | |
| 050019 | 0. | 0. | -13.065 | 0. | 0. | 0. | 1. | | |
| 050029 | 0. | 0. | -11.604 | 0. | 0. | 0. | 1. | | |
| 050039 | 0. | 0. | -8.847 | 0. | 0. | 0. | 1. | | |
| 050049 | 0. | 0. | -7.681 | 0. | 0. | 0. | 1. | | |
| 050059 | 0. | 0. | -6.516 | 0. | 0. | 0. | 1. | | |
| 050069 | 0. | 0. | -7.515 | 0. | 0. | 0. | 1. | | |
| 050079 | 0. | 0. | -2.906 | 0. | 0. | 0. | 1. | | |
| 050089 | 0. | 0. | 1.494 | 0. | 0. | 0. | 1. | | |
| 050099 | 0. | 0. | -5.340 | 0. | 0. | 0. | 1. | | |
| 050109 | 6.7957 | 6.7957 | -8.776 | 3.899 | -6.144 | 1. | | | |
| 050119 | 2.8315 | 10.6183 | -10.571 | 0. | 0. | 1. | | | |
| 050129 | 2.8315 | 10.6183 | -7.110 | 0. | 0. | 1. | | | |
| 050139 | 2.8315 | 10.6183 | -2.135 | 0. | 0. | 1. | | | |
| 050149 | 2.8315 | 10.6183 | -2.135 | 0. | 0. | 1. | | | |
| 050159 | 2.8315 | 10.6183 | -7.110 | 0. | 0. | 1. | | | |
| 050169 | 2.8315 | 10.6183 | -10.571 | 0. | 0. | 1. | | | |
| 050179 | 0.0 | 10.6183 | -11.960 | 0. | 0. | 1. | | | |
| 050189 | -3.5394 | 10.6183 | -7.953 | 0. | 0. | 1. | | | |
| 050199 | -6.7957 | 6.7957 | -6.676 | -4.730 | -10.551 | 1. | | | |
| 050209 | -6.7957 | -6.7957 | -8.776 | -3.899 | 6.144 | 1. | | | |
| 050219 | -2.8315 | -10.6183 | -10.571 | 0. | 0. | 1. | | | |
| 050229 | -2.8315 | -10.6183 | -7.110 | 0. | 0. | 1. | | | |
| 050239 | -2.8315 | -10.6183 | -2.135 | 0. | 0. | 1. | | | |
| 050249 | -2.8315 | -10.6183 | -2.135 | 0. | 0. | 1. | | | |
| 050259 | -2.8315 | -10.6183 | -7.110 | 0. | 0. | 1. | | | |
| 050269 | -2.8315 | -10.6183 | -10.571 | 0. | 0. | 1. | | | |
| 050279 | 0.0 | -10.6183 | -11.960 | 0. | 0. | 1. | | | |
| 050289 | 3.5394 | -10.6183 | -7.953 | 0. | 0. | 1. | | | |
| 050299 | 6.7957 | -6.7957 | -6.676 | 4.730 | 10.551 | 1. | | | |
| 050309 | 12.7419 | -8.495 | -9.921 | 0. | 0. | 1. | | | |
| 050319 | 12.7419 | -8.495 | -6.035 | 0. | 0. | 1. | | | |
| 050329 | 12.7419 | -8.495 | -1.379 | 0. | 0. | 1. | | | |
| 051019 | 2.8315 | 10.6183 | 3.825 | 0. | 0. | 1. | | | |
| 051039 | 2.8315 | 10.6183 | -3.733 | 0. | 0. | 1. | | | |

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| | | | | | | |
|--------|---------|----------|--------|----|----|----|
| 051109 | 2.8315 | 10.6183 | -3.487 | 0. | 0. | 1. |
| 051509 | -2.8315 | 10.6183 | 6.525 | 0. | 0. | 1. |
| 052019 | -2.8315 | -10.6183 | 3.825 | 0. | 0. | 1. |
| 052039 | -2.8315 | -10.6183 | -3.733 | 0. | 0. | 1. |
| 052109 | -2.8315 | -10.6183 | -3.487 | 0. | 0. | 1. |
| 052509 | -2.8315 | -10.6183 | 6.525 | 0. | 0. | 1. |
| 051609 | -2.8315 | -10.6183 | 5.782 | 0. | 0. | 1. |

*
* BUBBLE DATA CARDS
* ALPH VBUB A-ID V-ID

| | | | | | |
|--------|-----|------|------|------|-------------|
| 060011 | 0.8 | 3.0 | | | *PZR |
| 060021 | 0.8 | 3.0 | | | *NOT USE |
| 060031 | 0.8 | 1.E6 | | | *SG 1 SEP. |
| 060041 | 0.0 | 3.0 | -277 | -276 | *SG 1 D.C. |
| 060051 | 0.0 | 3.0 | | | *DUMMY |
| 060061 | 0.0 | 3.0 | -277 | -279 | *SG 1 RISER |
| 060071 | 0.8 | 0.0 | | | *NOT USE |
| 060081 | 0.8 | 1.E6 | | | *SG 2 SEP. |
| 060091 | 0.0 | 3.0 | -277 | -278 | *SG 2D.C. |
| 060101 | 0.0 | 3.0 | | | *DUMMY |
| 060111 | 0.0 | 3.0 | -277 | -280 | *SG 2 RISER |

*
* TIME DEPENDENT VOLUME
* TIME PRES TEMP QUA MIXL P

| | | | | | | | |
|--------|---|-------|-----|-------|----|-----|---------|
| 070101 | 7 | 0.0 | 0.0 | 495.7 | 1. | 50. | * 654.7 |
| 070102 | | 30.0 | 0.0 | 495.7 | 1. | 50. | * 654.7 |
| 070103 | | 167.0 | 0.0 | 494.2 | 1. | 50. | * 646.2 |
| 070104 | | 263.0 | 0.0 | 494.2 | 1. | 50. | * 646.2 |
| 070105 | | 323.0 | 0.0 | 495.4 | 1. | 50. | * 653.3 |
| 070106 | | 375.0 | 0.0 | 496.2 | 1. | 50. | * 657.6 |
| 070107 | | 420.0 | 0.0 | 496.2 | 1. | 50. | * 657.6 |

*
* JUNCTION DATA CARD

| | IW1 | IW2 | IP | VAL | WP | AJUN | ZJUN | INERT | FJUNF | FJUNR | |
|--------|-----|-----|----|-----|--------|--------|---------|--------|----------|-------------|--------------|
| 080011 | 1 | 2 | 0 | 0 | 0. | 2.551 | -10.703 | 1.323 | 1.610 | 0. | * |
| 080021 | 2 | 3 | 0 | 0 | 1212.9 | 6.365 | -6.270 | 0.8953 | 19.477 | 0. | * |
| 080031 | 3 | 4 | 0 | 0 | 0. | 6.365 | -5.189 | 0.1832 | 1.685 | 0. | * |
| 080041 | 4 | 5 | 0 | 0 | 0. | 6.365 | -3.939 | 0.1832 | 1.730 | 0. | * |
| 080051 | 5 | 7 | 0 | 0 | 0. | 6.365 | -2.858 | 0.692 | -1. | 0. | * |
| 080061 | 2 | 6 | 0 | 0 | 0. | 0.184 | -6.569 | 24.48 | 21.425 | 0. | * |
| 080071 | 6 | 7 | 0 | 0 | 0. | 1.196 | -2.227 | 3.520 | -1. | 0. | * |
| 080081 | 7 | 8 | 0 | 0 | 0. | 0.424 | 3.280 | 0.525 | 12.338 | 12.844 | * |
| 080091 | 9 | 1 | 0 | 0 | 0. | 3.972 | -7.842 | 2.167 | 5.829 | 0. | * |
| 080101 | 7 | 10 | 0 | 0 | 628.3 | 0.349 | 0. | 31.25 | 1.104 | 0. | * |
| 080111 | 10 | 11 | 0 | 0 | 628.3 | 0.349 | -8.562 | 34.59 | 0.7078 | 0. | * |
| 080121 | 11 | 12 | 0 | 0 | 0. | 0.900 | -6.109 | 2.985 | 1.533 | 0. | * |
| 080131 | 12 | 13 | 0 | 0 | 0. | 0.900 | -1.877 | 5.321 | 1.191 | 0. | * |
| 080141 | 13 | 14 | 0 | 0 | 0. | 0.900 | 3.202 | 5.919 | 3.583 | 0. | * |
| 080151 | 14 | 15 | 0 | 0 | 0. | 0.900 | -1.877 | 5.321 | 1.200 | 0. | * |
| 080161 | 15 | 16 | 0 | 0 | 0. | 0.900 | -6.109 | 2.852 | 0.059 | 0. | * |
| 080171 | 16 | 17 | 0 | 0 | 0. | 0.349 | -8.566 | 19.28 | 0.4121 | 0. | * |
| 080181 | 17 | 18 | -2 | 0 | 0. | 0.349 | -6.020 | 0. | 0.415 | 0. | * |
| 080191 | 18 | 19 | 2 | 0 | 0. | 0.349 | -3.986 | 0. | 0.684 | 0. | * |
| 080201 | 19 | 9 | 0 | 0 | 0. | 0.349 | 0. | 25.316 | -1. | 0. | * |
| 080211 | 7 | 20 | 0 | 0 | 628.3 | 0.349 | 0. | 31.25 | 1.104 | 0. | * |
| 080221 | 20 | 21 | 0 | 0 | 0.0 | 0.349 | -8.562 | 34.59 | 0.7078 | 0. | * |
| 080231 | 21 | 22 | 0 | 0 | 0. | 0.900 | -6.109 | 2.685 | 1.533 | 0. | * |
| 080241 | 22 | 23 | 0 | 0 | 0. | 0.900 | -1.877 | 5.321 | 1.191 | 0. | * |
| 080251 | 23 | 24 | 0 | 0 | 0. | 0.900 | 3.202 | 5.919 | 3.583 | 0. | * |
| 080261 | 24 | 25 | 0 | 0 | 0. | 0.900 | -1.877 | 5.321 | 1.200 | 0. | * |
| 080271 | 25 | 26 | 0 | 0 | 0. | 0.900 | -6.109 | 2.852 | 0.059 | 0. | * |
| 080281 | 26 | 27 | 0 | 0 | 0. | 0.349 | -8.566 | 19.28 | 0.4121 | 0. | * |
| 080291 | 27 | 28 | -1 | 0 | 0. | 0.349 | -6.020 | 0. | 0.4154 | 0. | * |
| 080301 | 28 | 29 | 1 | 0 | 0. | 0.349 | -3.986 | 0. | 0.1684 | 0. | * |
| 080311 | 29 | 9 | 0 | 0 | 0. | 0.349 | 0. | 25.316 | 1.567 | 0. | * |
| 080321 | 10 | 30 | 0 | 0 | 0. | 0.028 | -8.989 | 772.47 | 1.547 | 2.487 | * |
| 080331 | 30 | 31 | 0 | 0 | 0. | 0.028 | -4.618 | 500.61 | 1.547 | 2.487 | * |
| 080341 | 0 | 32 | 1 | 1 | 0. | 1. | 4.493 | 1. | 1. | 0. | *SPRAY |
| 080351 | 0 | 29 | 2 | 1 | 0. | 1. | -2.944 | 1. | 1. | 0. | *NEG.SPRAY |
| 080361 | 31 | 32 | 0 | 0 | 0. | 9.586 | -1.018 | 0. | 0. | 0. | * |
| 081061 | 103 | 110 | 0 | 0 | 0. | 5.296 | -5.970 | 3.882 | 20.0 | 19.5 | *SG1 DCM-RSR |
| 081121 | 110 | 101 | 0 | 0 | 154.7 | 1.249 | 9.029 | 1.374 | -1.43.67 | *SG1 SEP-DM | |
| 081011 | 101 | 103 | 0 | 0 | 141.8 | 1.302 | 4.74 | 2.361 | 4.2 | 3.7 | *SG1 DM-DCM |
| 081511 | 0 | 103 | 7 | 2 | 12.9 | 1. | 4.740 | 1. | 1. | 1. | *FW1 |
| 081521 | 101 | 150 | 0 | 0 | 12.9 | 0.2804 | 8.225 | 0. | 0.5 | 1. | * |
| 081531 | 150 | 160 | 0 | 10 | 12.9 | 0.1402 | 10.848 | 0. | 5.834 | 1.49 | * |

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| | | | | | | | | | | | | |
|---|--------|-----|-----|-----|----|-------|--------|---------|-------|------|-------|-----------------|
| * | 082061 | 203 | 210 | 0 | 0 | 0. | 5.296 | -5.970 | 3.882 | 20.0 | 19.5 | *SG1 DCM-RSR |
| | 082121 | 210 | 201 | 0 | 0 | 154.7 | 1.249 | 9.029 | 1.374 | -1. | 43.67 | *SG2 SEP-DM |
| | 082011 | 201 | 203 | 0 | 0 | 141.8 | 1.302 | 4.74 | 2.361 | 4.2 | 3.7 | *SG2 DM-DCM |
| * | 082511 | 0 | 203 | 8 | 2 | 12.9 | 1. | 4.740 | 1. | 1. | 1. | *FW2 |
| | 082521 | 201 | 250 | 0 | 0 | 12.9 | 0.2804 | 8.225 | 0. | 0.5 | 1. | * |
| | 082531 | 250 | 160 | 0 | 0 | 12.9 | 0.1402 | 10.848 | 0. | -1. | 1.+9 | * |
| * | 081601 | 0 | 160 | 16 | 0 | 0. | 1. | 6.777 | 0. | 0. | 0. | *TURBINE VALVE |
| | 081611 | 0 | 160 | 9 | 0 | 0. | 1. | 10.847 | 0.5 | 1.0 | 0. | *DUMP VALVE |
| | 081621 | 0 | 160 | 3 | 9 | 0. | 1. | 10.847 | 0.5 | 1.0 | 0. | *SV 1 |
| | 081631 | 0 | 160 | 4 | 9 | 0. | 1. | 10.847 | 0.5 | 1.0 | 0. | *SV 2 |
| | 080561 | 0 | 32 | 5 | 3 | 0. | 1. | 4.493 | 1. | 1. | 1. | *PORV |
| | 080571 | 0 | 32 | 6 | 4 | 0. | 1. | 4.493 | 1. | 1. | 1. | *PZR SV |
| * | 080911 | 0 | 9 | 10 | 5 | 0. | 1. | 0. | 0. | 0. | 0. | *HPIS#1 |
| | 080921 | 0 | 9 | 11 | 6 | 0. | 1. | 0. | 0. | 0. | 0. | *HPIS#2 |
| * | 081541 | 0 | 103 | 12 | 11 | 0. | 1. | 4.740 | 0. | 0. | 0. | *AFW(A) |
| | 082541 | 0 | 203 | 13 | 12 | 0. | 1. | 4.740 | 0. | 0. | 0. | *AFW(B) |
| * | 081641 | 0 | 160 | 14 | 13 | 0. | 1. | 10.847 | 0. | 0. | 0. | *DUMP(MANUAL) |
| | 083001 | 0 | 17 | 15 | 0 | 0. | 1. | -11.665 | 0. | 0. | 0. | *C.P.+LET-DOWN |
| * | | JV | JC | JCA | MV | DIAMJ | CONC | FRJ | TPMJ | ANGL | IHC | |
| | 080012 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080022 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 2 | * |
| | 080032 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080042 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080052 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 1 | * |
| | 080062 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080072 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080082 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080092 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080102 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080112 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080122 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 2 | * |
| | 080132 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080142 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080152 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080162 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 1 | * |
| | 080172 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080182 | 0 | -1 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080192 | 0 | -1 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080202 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080212 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080222 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080232 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 2 | * |
| | 080242 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080252 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080262 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 3 | * |
| | 080272 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 1 | * |
| | 080282 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080292 | 0 | -1 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080302 | 0 | -1 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080312 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080322 | 0 | -1 | 0 | 3 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080332 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080362 | 1 | -1 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080342 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 080352 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| * | 081122 | 0 | 0 | 0 | 0 | 0. | 1. | 2 | 1 | 0. | 1 | *SG1 SPRTR-DOME |
| | 081012 | 0 | 0 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | *SG1 DOME-DCMR |
| | 081062 | 1 | 0 | 0 | 0 | 0. | 1. | -99 | 2 | 0. | 2 | *SG1 DCMR-RISER |
| * | 081512 | 0 | -1 | 0 | 0 | 1. | 1. | -99 | 0 | 0. | 0 | * |
| | 081522 | 0 | 0 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 081532 | 0 | 0 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| * | 082122 | 0 | 0 | 0 | 0 | 0. | 1. | 2 | 1 | 0. | 1 | *SG2 SPRTR-DOME |
| | 082012 | 0 | 0 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | *SG2 DOME-DCMR |
| | 082062 | 1 | 0 | 0 | 0 | 0. | 1. | -99 | 2 | 0. | 2 | *SG2 DCMR-RISER |
| * | 082512 | 0 | -1 | 0 | 0 | 1. | 1. | -99 | 0 | 0. | 0 | * |
| | 082522 | 0 | 0 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| | 082532 | 0 | 0 | 2 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |

| | | | | | | | | | | | |
|--------|------|------|---|---|----|----|-----|---|----|---|---------------|
| 081602 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| 081612 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| 081622 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| 081632 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| 080562 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| 080572 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| * | | | | | | | | | | | |
| 080912 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| 080922 | 0 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | * |
| * | | | | | | | | | | | |
| 081542 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | *AFW(A) |
| 082542 | 1 | -1 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | *AFW(B) |
| * | | | | | | | | | | | |
| 081642 | 1 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | *DUMP(MANUAL) |
| * | | | | | | | | | | | |
| 083002 | 0 | 0 | 0 | 0 | 0. | 1. | -99 | 0 | 0. | 0 | *C.P+LET DOWN |
| * | | | | | | | | | | | |
| * | | | | | | | | | | | |
| | IWT1 | IWT2 | | | | | | | | | |
| 080019 | 0 | 0 | | | | | | | | | |
| 080029 | 0 | 0 | | | | | | | | | |
| 080039 | 0 | 0 | | | | | | | | | |
| 080049 | 0 | 0 | | | | | | | | | |
| 080059 | 0 | 0 | | | | | | | | | |
| 080069 | 0 | 0 | | | | | | | | | |
| 080079 | 0 | 0 | | | | | | | | | |
| 080089 | 0 | 0 | | | | | | | | | |
| 080099 | 0 | 0 | | | | | | | | | |
| 080109 | 0 | +1 | | | | | | | | | |
| 080119 | -1 | 0 | | | | | | | | | |
| 080129 | 0 | 0 | | | | | | | | | |
| 080139 | 0 | 0 | | | | | | | | | |
| 080149 | 0 | 0 | | | | | | | | | |
| 080159 | 0 | 0 | | | | | | | | | |
| 080169 | 0 | 0 | | | | | | | | | |
| 080179 | 0 | 0 | | | | | | | | | |
| 080189 | 0 | 0 | | | | | | | | | |
| 080199 | 0 | -1 | | | | | | | | | |
| 080209 | +1 | 0 | | | | | | | | | |
| 080219 | 0 | -1 | | | | | | | | | |
| 080229 | +1 | 0 | | | | | | | | | |
| 080239 | 0 | 0 | | | | | | | | | |
| 080249 | 0 | 0 | | | | | | | | | |
| 080259 | 0 | 0 | | | | | | | | | |
| 080269 | 0 | 0 | | | | | | | | | |
| 080279 | 0 | 0 | | | | | | | | | |
| 080289 | 0 | 0 | | | | | | | | | |
| 080299 | 0 | 0 | | | | | | | | | |
| 080309 | 0 | -1 | | | | | | | | | |
| 080319 | +1 | 0 | | | | | | | | | |
| 080329 | 0 | 0 | | | | | | | | | |
| 080339 | 0 | 0 | | | | | | | | | |
| 080349 | 0 | 0 | | | | | | | | | |
| 080359 | 0 | 0 | | | | | | | | | |
| 080369 | 0 | 0 | | | | | | | | | |
| 081019 | 0 | 0 | | | | | | | | | |
| 081069 | 0 | 0 | | | | | | | | | |
| 081129 | 0 | 0 | | | | | | | | | |
| 081519 | 0 | 0 | | | | | | | | | |
| 081529 | 0 | 0 | | | | | | | | | |
| 081539 | 0 | 0 | | | | | | | | | |
| 082019 | 0 | 0 | | | | | | | | | |
| 082069 | 0 | 0 | | | | | | | | | |
| 082129 | 0 | 0 | | | | | | | | | |
| 082519 | 0 | 0 | | | | | | | | | |
| 082529 | 0 | 0 | | | | | | | | | |
| 082539 | 0 | 0 | | | | | | | | | |
| 081609 | 0 | 0 | | | | | | | | | |
| 081619 | 0 | 0 | | | | | | | | | |
| 081629 | 0 | 0 | | | | | | | | | |
| 081639 | 0 | 0 | | | | | | | | | |
| 080569 | 0 | 0 | | | | | | | | | |
| 080579 | 0 | 0 | | | | | | | | | |
| 080919 | 0 | 0 | | | | | | | | | |
| 080929 | 0 | 0 | | | | | | | | | |
| 081549 | 0 | 0 | | | | | | | | | |
| 082549 | 0 | 0 | | | | | | | | | |
| 081649 | 0 | 0 | | | | | | | | | |
| 083009 | 0 | 0 | | | | | | | | | |

* PUMP DESCRIPTION DATA CARDS

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*
*      IP TRIP RP PM MT POMGAR PRAT PFLOWR PHEADR PTORKR PINRTA
090011 1 12 1 1 0 1770. 1. 5848.00 170. 477.52 159.17 *PUMP 2
090021 1 12 1 1 0 1770. 1. 5848.00 170. 477.52 159.17 *PUMP 1
*
*      VRHOI TRKMR TORKF1 TORKF2 TORKF3 TORKF4
090012 48.257 0. 0.0 20.0 477.56 0.0 *
090022 48.257 0. 0.0 20.0 477.56 0.0 *
*
*      PUMP HEAD MULTIPLIER
*
091010 -11 0.00 .00 0.10 .00 0.15 .05 0.24 .80 0.30 .96 0.40 .98 *
091011 0.60 .97 0.80 .90 0.90 .80 0.96 .50 1.00 .00 *
*
*      PUMP TORQUE MULTIPLIER
*
092010 -2 0. 0. 1. 0. *
*
*      PUMP CURVE SET INPUT DATA CARDS
*
*      NPC NC(J)
100000 0 16 *
*
*      PUMP HEAD & TORQUE DATA CARDS
*
101011 6 0.0 1.52 0.2 1.49 0.4 1.42 0.6 1.32 0.8 1.19 1.0 1.00
101021 6 0.0 -.81 0.2 -.55 0.4 -.27 0.6 0.00 0.8 0.48 1.0 1.00
101031 6 -1.0 2.95 -0.8 2.55 -0.6 2.09 -0.4 1.79 -0.2 1.60 0.0 1.52
101041 6 -1.0 2.95 -0.8 2.44 -0.6 1.94 -0.4 1.61 -0.2 1.33 0.0 1.14
101051 6 0.0 -.16 0.28 0.0 0.4 0.09 0.6 0.31 0.8 0.50 1.0 0.74
101061 6 0.0 1.14 0.2 0.97 0.4 0.84 0.6 0.75 0.8 0.72 1.0 0.74
101071 2 -1.0 0.00 0.0 0.00
101081 2 -1.0 0.00 0.0 0.00
101091 6 0.0 0.83 0.2 0.87 0.4 0.92 0.6 0.95 0.8 0.96 1.0 1.00
101101 6 0.0 -.67 0.2 -.38 0.3 -.22 0.4 -.04 .425 0.0 1.0 1.00
101111 6 -1.0 2.04 -0.8 1.60 0.6 1.24 -0.4 1.00 -0.2 0.88 0.0 0.83
101121 6 -1.0 2.04 -0.8 1.81 -0.6 1.67 -0.4 1.57 -0.2 1.38 0.0 1.21
101131 7 0.0 -1.0 .25 -0.6 0.4 -.37 0.5 -.25 0.6 -.16 0.8 0.00
101132 1.0 0.26
101141 6 0.0 1.21 0.2 1.04 0.4 0.85 0.6 0.63 0.8 0.44 1.0 0.26
101151 2 -1.0 0.00 0.0 0.00
101161 2 -1.0 0.00 0.0 0.00
*
*      VALVE DATA CARDS
*
*      ITCV IACV V2 PCV CV1 CV2 CV3
110010 -2 0 0 0. 0. 0. 0. *PRZER SPRAY VALVE
110020 17 0 0 0. 0. 0. 0. *SG FEED WATER (J151,251)
110030 -2 0 0 0. 0. 0. 0. *PRZER REL. VAL. (J56)
110040 -2 0 0 0. 0. 0. 0. *PRZER SAF. VAL. (J57)
110050 155 0 0 0. 0. 0. 0. *HPIS#1 STOP VALVE
110060 155 0 0 0. 0. 0. 0. *HPIS#2 STOP VALVE
110070 1000 -247 0 0. 0. 0. 0. *TURBINE CONTROL (J160)
110080 -4 0 0 0. 0. 0. 0. *NOT USE
110090 -140 0 0 0. 0. 0. 0. *ST-LINE SAF.VAL (J162,163)
110100 154 14 0 0. 0. 0. 0. *MSIV(A)
110110 -156 0 0 0. 0. 0. 0. *AFW(A) VALVE
110120 -157 0 0 0. 0. 0. 0. *AFW(B) VALVE
110130 -158 0 0 0. 0. 0. 0. *DUMP VALVE(MANUAL)
*
*      GENERAL DATA TABLE
*
120100 -4 0.0 0. 1572.12 0. 1643.23 1. 1.+9 1. *SPRAY OPEN RATE
* TABLE WAS SHIFTED, FOR INITIAL SPRAY FLOW IS ZERO
120100 -4 0.0 0. 1579.0 0. 1650.11 1. 1.+9 1. *SPRAY OPEN RATE
120200 -2 32.0 0. 41. 5. *CONV. FR FTEMP TO CTEMP
120300 -4 0.0 0. 1977.06 0. 2015.92 4.344 1.+9 4.344 *PZR SV FLOW
120400 -2 0.0 0.0 1.0 0.0 *DUMMY
120500 -12 0.0 0.0 0.1 1.0 0.2 1.4 0.3 2.0 0.4 3.0 *PRZER C-V VAL.
120501 0.5 4.8 0.6 8.0 0.7 14. 0.8 20. 0.9 24.
120502 1.0 26.8 1.+9 26.8
120600 -10 0.0 1770.0 0.1 1623.21 0.2 1488.83 0.3 1365.56 *PUMP RPM TABLE
120601 0.4 1252.18 0.5 1147.2 0.6 1049.31 0.7 957.55
120602 0.78 885.0 1.+9 885.0
120700 6 0. 0. 20. 1.7 40. 4.2 60. 8.3 80. 20.1 100. 44.9 *FW.VALVE V-LIFT
120800 -4 -1.+9 3.2 3.20582 3.20582 216.72087 216.72087 *FWP.COMP.SIG.
120801 1.+9 216.72087
120900 -4 -1.0 0. 0.5 0. 0.6 1. 5.0 1. *TRIP SIG. DELAY
121000 -2 0.0 0.0 1.0 0.0 *DUMMY
121100 -3 -1.0 1. 0.0 0. 1.0 -1. *M/T GOV.VALVE

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121200 -2 0.0 0.0 1.0 0.0 *DUMMY
121300 -2 0. 0. 21.40 1.+9 21.40 *DUMP FLOW
121400 -3 0. 1. 30. 0. 1000. 0. *MSIV(A) TIME VS. AREA
* FOR GRAVITY CHANGE
121500 -2 0.0 0.0 1.E6 0.0
* FOR PRZ LIQUID LEVEL CONT.
121600 -4 0.0 55.0 20.0 55.0 80.0 43.6 100.0 43.6 * S/F VS LREF
121700 -6 0. 0. 20. 0.1 40. 0.16 60. 0.24 80. 0.38 100. 0.59 *CV1
121800 -6 0. 0. 20. .13 40. 0.21 60. 0.31 80. 0.48 100. 1.03 *CV2
*
* TABLE 19 FOR LREF CHANGE
* TABLE 20 FOR TAVE CHANGE
*
* STEAM FLDW(KG/H) VS MAIN VALVE LIFT(MM)
122100 25 0. 0.0 11900. 4.46 13200. 5.54 13900. 6.61
122101 14500. 9.57 20500. 11.7 21600. 12.8 22100. 14.0
122102 22400. 16.4 27500. 18.5 28600. 19.5 29100. 20.8
122103 29400. 24.2 34000. 26.6 34900. 27.6 35400. 28.8
122104 35700. 32.1 41100. 35.4 41800. 36.3 42200. 37.5
122105 42300. 40.4 47800. 44.2 48600. 45.5 48900. 46.8
122106 49100. 52.9
*
* FILL TABLE DATA
*
130100 0 1000 -6 0 -9. -8. *SPRAY INTO PRZER
130200 1 1000 -7 0 0. 0. 0. *SPRAY FROM COLDLEG
130300 -4 2 1 0 100. 0. 1100. 1000. *STEAM LINE NO.1
130301 991.84 0. 1100. 1000. * SAFETY VALVE
130302 1010.33 -18.1393 1100. 1000. * (J162)
130303 2000. -18.1393 1100. 1000. * (LB/FT2,P-FUNC)
130400 -4 2 1 0 100. 0. 1100. 1000. *STEAM LINE NO.2
130401 991.84 0. 1100. 1000. * SAFETY VALVE
130402 1010.33 -18.1393 1100. 1000. * (J163)
130403 2000. -18.1393 1100. 1000. * (LB/FT2,P-FUNC)
130500 1 1000 -10 0 0. 0. 0. *PRZER RELIEF VALVE
130600 1 1000 -11 0 0. 0. 0. *PRZER SAFETY VALVE
130700 1 1000 -165 0 0. 0. 274.0 690. *SG 2 FEED WATER
130800 1 1000 -225 0 0. 0. 274.0 690. *SG 1 FEED WATER
130900 -4 16 0 0 0. -4.9125 1100. 1000. *DUMP FLOW
130901 9. -4.9125 1100. 1000. * (LB/FT2.S,P-FUNC)
130902 9.01 0. 1100. 1000. * (LB/FT2.S,P-FUNC)
130903 5000. 0. 1100. 1000. * (LB/FT2.S,P-FUNC)
131000 -14 152 1 1 0.0 198.1 63.05 15.0 * HPIS#1
131001 14.7 198.1 63.05 15.0 *
131002 325.7 176.1 63.05 15.0
131003 537.6 158.5 63.05 15.0
131004 714.0 140.9 63.05 15.0
131005 876.1 123.3 63.05 15.0
131006 1004.1 105.7 63.05 15.0
131007 1116.5 88.1 63.05 15.0
131008 1194.7 70.4 63.05 15.0
131009 1258.7 52.8 63.05 15.0
131010 1301.4 35.2 63.05 15.0
131011 1328.4 17.6 63.05 15.0
131012 1349.7 0.0 63.05 15.0
131013 1.+9 0.0 63.05 15.0
131100 -14 153 1 1 0.0 198.1 63.05 15.0 * HPIS#2
131101 14.7 198.1 63.05 15.0 *
131102 325.7 176.1 63.05 15.0
131103 537.6 158.5 63.05 15.0
131104 714.0 140.9 63.05 15.0
131105 876.1 123.3 63.05 15.0
131106 1004.1 105.7 63.05 15.0
131107 1116.5 88.1 63.05 15.0
131108 1194.7 70.4 63.05 15.0
131109 1258.7 52.8 63.05 15.0
131110 1301.4 35.2 63.05 15.0
131111 1328.4 17.6 63.05 15.0
131112 1349.7 0.0 63.05 15.0
131113 1.+9 0.0 63.05 15.0
131200 2 2 0 1 0.0 26.4 217.9 650.0 *AFW(A)
131201 1.+9 26.4 217.9 650.0 *
131300 2 2 0 1 0.0 26.4 217.9 650.0 *AFW(B)
131301 1.+9 26.4 217.9 650.0 *
131400 2 2 0 0 0.0 -3.675 1.0 1.0 *DUMP(MANUAL)
131401 1.+9 -3.675 1.0 1.0 *
131500 0 1000 -317 0 111. 112. * C.P.F + LET-DOWN FLOW
*
131600 -2 2 0 0 0. -26.4 1.0 1.0 *TOTAL STEAM FLOW
131601 1.E6 -26.4 1.0 1.0

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*
* KINETICS CONSTANTS DATA CARDS
*
140000 0.0 398.84 0. 1. *
*
* DELAYED NEUTRON DATA OVERRIDE CARDS
*
140001 0.0124 0.0305 0.111 0.301 1.13 3.00 *
140002 0.030 0.209 0.191 0.395 0.129 0.046 *
*
* REACTIVITY COEFFICIENT DATA CARDS
*
140010 0.2329 0.2329 -3.7504-4 -1.0504-2 *
140020 0.5342 0.5342 -8.6023-4 -2.4092-2 *
140030 0.2329 0.2329 -3.7504-4 -1.0504-2 *
*
* SCRAM TABLE DATA CARDS
*
141100 -9 18 *
141101 0.0 0.0 0.7 0.0 0.8 -1.021 0.9 -2.836 *
141102 1.1 -8.733 1.2 -11.796 1.4 -15.652 1.7 -17.581 *
141103 2.0 -17.581
*
* ROD CONTROL
*
141201 -82 1000 0. 0. *
*
* DENSITY REACTIVITY TABLE
*
142001 0 *
*
* DOPPLER TABLE DATA CARDS
*
143001 0 *
*
* HEAT CONDUCTOR DATA CARDS
*
* 1VSL 1VSR 1GOM CELEV IMCL IMCR ASUL ASUR VOLLS HDML
150011 0 3 1 .5405 0 2 0. 420.23 3.631 0. *
150021 0 4 1 .6250 0 2 0. 486.06 4.201 0. *
150031 0 5 1 .5405 0 2 0. 420.23 3.631 0. *
150041 12 110 2 2.116 2 2 312.315 312.315 1.4345 0.0531 *
150051 13 110 2 2.8595 2 2 391.465 391.465 1.798 0.0531 *
150061 15 110 2 2.116 2 2 312.315 312.315 1.4345 0.0531 *
150071 14 110 2 2.8595 2 2 391.465 391.465 1.798 0.0531 *
150081 22 210 2 2.116 2 2 312.315 312.315 1.4345 0.0531 *
150091 23 210 2 2.8595 2 2 391.465 391.465 1.798 0.0531 *
150101 25 210 2 2.116 2 2 312.315 312.315 1.4345 0.0531 *
150111 24 210 2 2.8595 2 2 391.465 391.465 1.798 0.0531 *
*
* HDNR DHEL DHER CHNL CHNR IHXQF
150012 0.054714 0. 0. 0. 3.412 *
150022 0.054714 0. 0. 0. 3.412 *
150032 0.054714 0. 0. 0. 3.412 *
150042 0.0863 0. 0. 9.578 9.578 1 *
150052 0.0863 0. 0. 9.578 9.578 1 *
150062 0.0863 0. 0. 9.578 9.578 1 *
150072 0.0863 0. 0. 9.578 9.578 1 *
150082 0.0863 0. 0. 9.578 9.578 2 *
150092 0.0863 0. 0. 9.578 9.578 2 *
150102 0.0863 0. 0. 9.578 9.578 2 *
150112 0.0863 0. 0. 9.578 9.578 2 *
*
* CORE SECTION DATA CARDS
*
* ISLB CLTI QRAC
160010 1 .001312 .2329 *
160020 2 .001312 .5342 *
160030 3 .001312 .2329 *
*
* CONDUCTOR GEOMETRY DATA CARDS
*
* 1G NR IM NDX XO XR PF
170101 2 3 1 15 0. 0.015762 1.0 *
170102 1 2 1 0.000199 0.0 *
170103 0 3 4 0.001312 0.0 *
170201 2 1 3 4 .02657 0.004593 0.0 *
*
* THERMAL CONDUCTIVITY OF UO2
*

```


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| | | | | | | | | | | |
|---|-----|---------|----------|---------|-----------|---------|-----------|--------|--------|------------------------|
| 180100 | -15 | 200. | 3.9 | 400. | 3.35 | 600. | 3.00 | 800. | 2.65 | * |
| 180101 | | 1000. | 2.35 | 1200. | 2.10 | 1500. | 1.85 | 1800. | 1.65 | * |
| 180102 | | 2000. | 1.55 | 2500. | 1.30 | 3000. | 1.25 | 3500. | 1.35 | * |
| 180103 | | 4000. | 1.50 | 4500. | 1.85 | 5000. | 2.45 | | | * |
| * THERMAL CONDUCTIVITY OF NANYARGNE * | | | | | | | | | | |
| 180200 | -2 | 500. | 0.0358 | 1000. | 0.0358 | | | | | * |
| * THERMAL CONDUCTIVITY OF SUS * | | | | | | | | | | |
| 180300 | -15 | 80.6 | 7.494 | 260.6 | 8.430 | 440.6 | 9.360 | 620.6 | 10.295 | * |
| 180301 | | 800.6 | 11.232 | 980.6 | 12.168 | 1160.6 | 13.098 | 1340.6 | 14.034 | * |
| 180302 | | 1520.6 | 14.970 | 1700.6 | 15.902 | 1880.6 | 16.837 | 2060.6 | 17.773 | * |
| 180303 | | 2240.6 | 18.709 | 2420.6 | 19.645 | 2600.6 | 20.575 | | | * |
| * VOLUMETRIC HEAT CAPACITY OF UO2 * | | | | | | | | | | |
| 190100 | -15 | 32. | 34.45 | 122. | 38.35 | 212. | 40.95 | 392. | 43.55 | * |
| 190101 | | 752. | 46.80 | 2012. | 51.35 | 2732. | 52.65 | 3092. | 56.55 | * |
| 190102 | | 3452. | 63.05 | 3812. | 72.80 | 4352. | 89.70 | 4532. | 94.25 | * |
| 190103 | | 4892. | 100.10 | 5144. | 101.40 | 8000. | 101.40 | | | * |
| * VOLUMETRIC HEAT CAPACITY OF STEAM * | | | | | | | | | | |
| 190200 | -3 | 600. | 0.54 | 1000. | 0.46 | 1500. | 0.45 | | | * |
| * VOLUMETRIC HEAT CAPACITY OF SUS * | | | | | | | | | | |
| 190300 | -7 | 80.33 | 60.053 | 440.33 | 62.637 | 800.33 | 65.134 | | | * |
| 190301 | | 1160.33 | 67.431 | 1520.33 | 69.565 | 1880.33 | 71.593 | | | * |
| 190302 | | 2600.6 | 75.035 | | | | | | | * |
| * LINEAR EXPANSION COEFFICIENTS OF UO2 * | | | | | | | | | | |
| 200100 | -2 | 0. | 3.718E-6 | 5000. | 1.2653E-6 | | | | | * |
| * LINEAR EXPANSION COEFFICIENTS OF STEAM * | | | | | | | | | | |
| 200200 | -2 | 0. | 0. | 5000. | 0. | | | | | * |
| * LINEAR EXPANSION COEFFICIENTS OF SUS * | | | | | | | | | | |
| 200300 | -3 | 440.33 | 8.46E-6 | 1520.33 | 10.47E-6 | 2600.6 | 12.772E-6 | | | * |
| * NON CONDUCTING HEAT EXCHANGER DATA * | | | | | | | | | | |
| * IHTX IHTXQ JVOL INTYPE TIME N-POEWR * | | | | | | | | | | |
| 210101 | -61 | 1000 | 32 | 7 | 0. | 0. | | | | *HEATER |
| 210201 | -60 | 1000 | 32 | 7 | 0. | 0. | | | | *BACK-UP HEATER |
| * STEADY-STATE * | | | | | | | | | | |
| 230000 | 100 | 0. | 7.E-6 | 0. | | | | | | * |
| 230000 | 100 | 0. | 4.E-5 | 0. | | | | | | * |
| 230011 | 1 | 151 | 152 | 0.5 | | | | | | * |
| 230021 | 2 | 251 | 252 | 0.5 | | | | | | * |
| * CONTROL SYSTEM PROBLEM DIMENIONS DATA CARDS * | | | | | | | | | | |
| 701000 | 115 | 308 | | | | | | | | * |
| * CONTROL INPUT DEFINITION DATA CARDS * | | | | | | | | | | |
| 702001 | 1 | 'PRES' | 32 | 1. | 1563.59 | | | | | *PRZER PRESS |
| 702002 | 2 | 'PRES' | 29 | 1. | 1593.48 | | | | | *COLDLEG-1 PRESS |
| 702003 | 3 | 'AVED' | 29 | 1. | 48.3974 | | | | | *COLDLEG-1 AVED |
| 702004 | 4 | 'PRES' | 19 | 1. | 1589.28 | | | | | *COLDLEG-1 PRESS |
| 702005 | 5 | 'HW**' | 29 | 1. | 508.965 | | | | | *COLDLEG-1 SPEC.ENTHL |
| 702006 | 6 | 'TRIP' | 3 | 1. | 0. | | | | | *TRIP FLAG-BL3 |
| 702007 | 7 | 'CONS' | 0 | 3.06 | 3.06 | | | | | *PRZER REL.VAL FLOW |
| 702008 | 8 | 'PRES' | 101 | 1. | 683.2 | | | | | *RELIEF VALVE SETPOINT |
| 702009 | 9 | 'PRES' | 201 | 1. | 683.2 | | | | | * |
| 702010 | 10 | 'TEMP' | 3 | 1. | 523.977 | | | | | * |
| 702011 | 11 | 'TEMP' | 4 | 1. | 532.927 | | | | | * |
| 702012 | 12 | 'TEMP' | 5 | 1. | 541.733 | | | | | * |
| 702013 | 13 | 'TEMP' | 10 | 1. | 529.571 | | | | | *HOT LEG-1 TEMP |
| 702014 | 14 | 'TEMP' | 19 | 1. | 518.057 | | | | | *COLD LEG-1 TEMP |
| 702015 | 15 | 'CONS' | 0 | 1. | 1. | | | | | *CONS. 1.0 |

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| | | | | | | |
|--------|----|--------|-----|----------|----------|--------------------------------|
| 702016 | 16 | 'CONS' | 0 | 75.0 | 75.0 | *IN HI.TEMP SCRAM |
| 702017 | 17 | 'CONS' | 0 | 305. | 305. | * |
| 702018 | 18 | 'CONS' | 0 | 0.5 | 0.5 | *PUHP SLOWDOWN AFT SCRAM |
| 702019 | 19 | 'TRIP' | 19 | 1. | 0. | * |
| 702020 | 20 | 'TRIP' | 20 | 1. | 0. | * |
| 702021 | 21 | 'TRIP' | 20 | 1. | 0. | * |
| 702022 | 22 | 'CONS' | 0 | 8.05 | 8.05 | *POWER REF.(KW) |
| 702023 | 23 | 'CONS' | 0 | 16.1 | 16.1 | * |
| 702024 | 24 | 'CONS' | 0 | 0. | 0. | * |
| 702025 | 25 | 'CONS' | 0 | 1578.00 | 1578.00 | *PRESS REF(PSI) |
| 702026 | 26 | 'WP**' | 153 | 1. | 10.7 | *STLINE-1 MASS FLOW RATE |
| 702027 | 27 | 'WP**' | 151 | 1. | 10.7 | *FEED-1 MASS FLOW RATE |
| 702028 | 28 | 'WP**' | 253 | 1. | 10.7 | *STLINE-2 MASS FLOW RATE |
| 702029 | 29 | 'WP**' | 251 | 1. | 10.7 | *FEED-2 MASS FLOW RATE |
| 702030 | 30 | 'LIQL' | 101 | 1. | 0.46 | *S.G.1 2ND STEAM MODEL |
| 702031 | 31 | 'LIQL' | 201 | 1. | 0.46 | *S.G.2 2ND STEAM MODEL |
| 702032 | 32 | 'LIQL' | 103 | 1. | 10.711 | *S.G.1 UPPER D/D |
| 702033 | 33 | 'LIQL' | 203 | 1. | 10.711 | *S.G.2 UPPER D/D |
| 702034 | 34 | 'PPOW' | 0 | 1.0 | 1. | *PROMPT POWER FRACTION |
| 702035 | 35 | 'WP**' | 160 | 0.26677 | -0.2433 | *STLINE-1 FLOW (WS) |
| 702036 | 36 | 'WP**' | 160 | -1. | 9.4 | *STLINE-2 FLOW (WS) |
| 702037 | 37 | 'TRIP' | 22 | 1. | 0. | *#2 ROD IN |
| 702038 | 38 | 'TRIP' | 23 | 1. | 0. | *#1 ROD OUT |
| 702039 | 39 | 'TRIP' | 24 | 1. | 0. | *#1 ROD IN |
| 702040 | 40 | 'TRIP' | 25 | 1. | 0. | *#2 ROD OUT |
| 702041 | 41 | 'TRIP' | 21 | 1. | 0. | * |
| 702042 | 42 | 'TRIP' | 30 | 1. | 0. | * |
| 702043 | 43 | 'PPOW' | 0 | 0.027778 | 0.2433 | * |
| 702044 | 44 | 'H012' | 10 | 1. | 523.038 | *HOTLEG MESH NO. 12 |
| 702045 | 45 | 'H001' | 10 | 1. | 523.038 | * |
| 702046 | 46 | 'H001' | 19 | 1. | 508.965 | *COLDLEG MESH NO.1 |
| 702047 | 47 | 'CONS' | 0 | 10. | 10. | * |
| 702048 | 48 | 'TRIP' | 26 | 1. | 0. | * |
| 702049 | 49 | 'AJNT' | 160 | 1. | 0.15048 | *J160 TDV AREA |
| 702050 | 50 | 'TRIP' | 18 | 1. | 0. | *SCRAM SIG.1 FOR M/T |
| 702051 | 51 | 'TRIP' | 150 | 1. | 0. | *SCRAM SIG.2 FOR M/T |
| 702052 | 52 | 'TRIP' | 130 | 1. | 0. | *DUMP VALVE ACTUATE SIG. |
| 702053 | 53 | 'TIMX' | 0 | 1. | 0. | * |
| 702054 | 54 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702055 | 55 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702056 | 56 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702057 | 57 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702058 | 58 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702059 | 59 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702060 | 60 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702061 | 61 | 'TRIP' | 901 | 3. | 0. | *VBUB SG 1 D.C. |
| 702062 | 62 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702063 | 63 | 'CONS' | 0 | 0. | 0. | *ALPHA FOR SG |
| 702064 | 64 | 'TRIP' | 903 | 3. | 0. | *VBUB SG 2 D.C. |
| 702065 | 65 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702066 | 66 | 'TRIP' | 905 | 3. | 0. | *VBUB SG 1 RISER |
| 702067 | 67 | 'TRIP' | 905 | 3. | 0. | *VBUB SG 2 RISER |
| 702068 | 68 | 'TRIP' | 16 | 1. | 0. | *SCRAM SIGNAL |
| 702069 | 69 | 'CONS' | 0 | 0. | 0. | *DUMMY |
| 702070 | 70 | 'MIXL' | 101 | 1. | 0.594 | *SG(A) DONE MIX.LEVEL |
| 702071 | 71 | 'MIXL' | 201 | 1. | 0.594 | *SG(B) DONE MIX.LEVEL |
| 702072 | 72 | 'MIXL' | 103 | 1. | 10.711 | *SG(A) D.C. MIX.LEVEL |
| 702073 | 73 | 'MIXL' | 203 | 1. | 10.711 | *SG(B) D.C. MIX.LEVEL |
| 702074 | 74 | 'CORQ' | 1 | 1. | 2.862+7 | *COND. 1 HEAT GEN. RATIO |
| 702075 | 75 | 'CORQ' | 2 | 1. | 6.564+7 | *COND. 2 HEAT GEN. RATIO |
| 702076 | 76 | 'CORQ' | 3 | 1. | 2.862+7 | *COND. 3 HEAT GEN. RATIO |
| 702077 | 77 | 'WQCR' | 4 | 1. | 1.792+7 | *COND. 4 HEAT REM. RATIO |
| 702078 | 78 | 'WQCR' | 5 | 1. | 1.868+7 | *COND. 5 HEAT REM. RATIO |
| 702079 | 79 | 'WQCR' | 6 | 1. | 1.006+7 | *COND. 6 HEAT REM. RATIO |
| 702080 | 80 | 'WQCR' | 7 | 1. | 1.519+7 | *COND. 7 HEAT REM. RATIO |
| 702081 | 81 | 'WQCR' | 8 | 1. | 1.792+7 | *COND. 8 HEAT REM. RATIO |
| 702082 | 82 | 'WQCR' | 9 | 1. | 1.868+7 | *COND. 9 HEAT REM. RATIO |
| 702083 | 83 | 'WQCR' | 10 | 1. | 1.006+7 | *COND.10 HEAT REM. RATIO |
| 702084 | 84 | 'WQCR' | 11 | 1. | 1.519+7 | *COND.11 HEAT REM. RATIO |
| 702085 | 85 | 'CONS' | 0 | 1.2288+8 | 1.2288+8 | *INITIAL HEAT GEN. RATIO |
| 702086 | 86 | 'CONS' | 0 | 6.185+7 | 6.185+7 | *INITIAL SG(A) HEAT REM. RATIO |
| 702087 | 87 | 'CONS' | 0 | 6.185+7 | 6.185+7 | *INITIAL SG(B) HEAT REM. RATIO |
| 702088 | 88 | 'WP**' | 161 | 1. | 0.0 | *S.L. DUMP VALVE FLOW |
| 702089 | 89 | 'WP**' | 162 | 1. | 0.0 | *S.L. SAFETY VALVE#1 FLOW |
| 702090 | 90 | 'WP**' | 163 | 1. | 0.0 | *S.L. SAFETY VALVE#2 FLOW |
| 702091 | 91 | 'WP**' | 56 | 1. | 0.0 | *PZR PORV FLOW |
| 702092 | 92 | 'WP**' | 57 | 1. | 0.0 | *PZR SV FLOW |
| 702093 | 93 | 'CONS' | 0 | 0. | 0.0 | * |
| 702094 | 94 | 'CONS' | 0 | 15.0 | 15.0 | *TAU |
| 702095 | 95 | 'CONS' | 0 | 3.14159 | 3.14159 | *PAI |

| | | | | | | | |
|--------|-----|--------|-----|----------|-----------|---|--------------------------|
| 702096 | 96 | 'CONS' | 0 | 6.28318 | 6.28318 | * | 2*PAI |
| 702097 | 97 | 'CONS' | 0 | 39.47835 | 39.47835 | * | 4*PAI**2 |
| 702098 | 98 | 'CONS' | 0 | .0174533 | .0174533 | * | PAI/180 |
| 702099 | 99 | 'CONS' | 0 | 0.4189 | 0.4189 | * | 2PAI/TG TG = 15. |
| 702100 | 100 | 'STVG' | 101 | 1. | 0.674583 | | |
| 702101 | 101 | 'STVF' | 101 | 1. | 2.04382-2 | | |
| 702102 | 102 | 'CONS' | 0 | 61.3784 | 61.3784 | | |
| 702103 | 103 | 'CONS' | 0 | 4.265 | 4.265 | | |
| 702104 | 104 | 'STVG' | 201 | 1. | 0.674583 | | |
| 702105 | 105 | 'STVF' | 201 | 1. | 2.04382-2 | | |
| 702106 | 106 | 'CONS' | 0 | 3.581 | 3.581 | | |
| 702107 | 107 | 'TRPT' | 16 | 1. | 0. | * | FOR TURBINE TRIP |
| 702108 | 108 | 'TRIP' | 500 | 1. | 0. | * | INTERLOCK FOR DUMP VALVE |
| 702109 | 109 | 'LIQL' | 31 | 1.0 | 4.49 | * | PRZ(2) LIQUID LEVEL |
| 702110 | 110 | 'CONS' | 0 | -0.1690 | -0.1690 | * | PRZ ZERO LEVEL |
| 702111 | 111 | 'HW**' | 17 | 1.0 | 508.801* | | C.O.L. ENTHALPY |
| 702112 | 112 | 'PRES' | 17 | 1.0 | 1546.08* | | C.O.L. PRES. |
| 702113 | 113 | 'TEMP' | 20 | 1.0 | 0. | * | LOOP2 THOT |
| 702114 | 114 | 'TEMP' | 29 | 1.0 | 0. | * | LOOP2 TCOLD |
| 702115 | 115 | 'LIQL' | 32 | 1.0 | 4.49 | * | PRZ(1) LIQUID LEVEL |

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PRZER SPRAY CONTROL

| IDC | TYPE | IN1 | IN2 | G | P1 | P2 | IC | |
|--------|------|-------|-----|----|--------|-----|-----|----------------------------|
| 703001 | -1 | 'FNG' | 1 | 1 | 1. | 0. | 0. | *SPRAY VALVE STROKE |
| 703002 | -2 | 'FNG' | -1 | 5 | 1. | 0. | 0. | *FLOW COEFF.(C-V) |
| 703003 | -3 | 'SUM' | 2 | 1 | 1. | -1. | -0. | *DIF.PRESS.(P 19-P31) |
| 703004 | -4 | 'MUL' | -3 | 3 | 1. | 0. | 0. | 0. 1.+75 *DEN19 DIF.PRESS. |
| 703005 | -5 | 'XPO' | -4 | 18 | 1. | 0. | 0. | *WQRT(DEN19*D P) |
| 703006 | -6 | 'MUL' | -2 | 5 | 0.0176 | 0. | 0. | *SPRAY MASS FLUX |
| 703007 | -7 | 'MUL' | -6 | 15 | -1. | 0. | 0. | *NEGATIVE SPRAY FLUX |
| 703008 | -8 | 'MUL' | 2 | 15 | -1. | 0. | 0. | *P19 |
| 703009 | -9 | 'MUL' | 5 | 15 | 1. | 0. | 0. | *N19 |

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PRZER SAFETY VALVE AND RELIEF VALVE MASS FLUX

| IDC | TYPE | IN1 | IN2 | G | P1 | P2 | IC | |
|--------|------|-------|-----|----|-----|----|----|---------------|
| 703010 | -10 | 'MUL' | 6 | 7 | -1. | 0. | 0. | *RELIEF VALVE |
| 703011 | -11 | 'FNG' | 1 | 3 | -1. | 0. | 0. | *SAFETY VALVE |
| 703012 | -12 | 'MUL' | 15 | 15 | 0. | 0. | 0. | *DUMMY |

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| | | | | | | | | | |
|--------|-----|-------|-----|-----|----|----|----|----|-----------|
| 703013 | -13 | 'SUM' | 109 | 115 | 1. | 1. | 1. | 0. | *PRZ LIQL |
|--------|-----|-------|-----|-----|----|----|----|----|-----------|

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HIGH TEMPERATURE SCRAM LOGIC

| IDC | TYPE | IN1 | IN2 | G | P1 | P2 | IC | | | |
|--------|------|-------|-----|-----|--------|-----|-------|---------|--------------------|------------|
| 703014 | -14 | 'SUM' | 44 | 45 | 0.7764 | 1. | -1. | 0. | * | |
| 703015 | -15 | 'SUM' | -14 | 13 | 1. | 1. | -0. | * | H.L TEMP. AT DETEC | |
| 703016 | -16 | 'SUM' | 46 | 5 | 0.8251 | 1. | -1. | 0. | * | |
| 703017 | -17 | 'SUM' | -16 | 14 | 1. | 1. | -0. | * | C.L TEMP. AT DETEC | |
| 703018 | -18 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | *DUMMY = 0.0 | |
| 703019 | -19 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | *DUMMY = 0.0 | |
| 703020 | -20 | 'FNG' | -15 | 2 | 1. | 0. | 0. | -0. | *H.L TEMP(C) | |
| 703021 | -21 | 'FNG' | -17 | 2 | 1. | 0. | 0. | -0. | *C.L TEMP(C) | |
| 703022 | -22 | 'LAG' | -20 | 0 | 1. | 1.8 | 0. | 278.148 | * | |
| 703023 | -23 | 'DER' | -22 | 0 | 2. | 0. | 0. | 0. | * | |
| 703024 | -24 | 'LAG' | -23 | 0 | 7.4 | 2. | 0. | 0. | * | |
| 703025 | -25 | 'SUM' | -24 | -22 | 1. | 1. | -0. | * | | |
| 703026 | -26 | 'LAG' | -21 | 0 | 1. | 1.7 | 0. | 269.585 | * | |
| 703027 | -27 | 'SUM' | -26 | 15 | 1. | 15. | -0. | * | | |
| 703028 | -28 | 'SUM' | -25 | -27 | -10.5 | 1. | -1. | -0. | * | |
| 703029 | -29 | 'SUM' | -28 | 15 | 1. | 1. | 279.7 | -0. | * | |
| 703030 | -30 | 'MIN' | -29 | 17 | 1. | 1. | 0. | -0. | * | |
| 703031 | -31 | 'SUM' | -30 | -26 | 1. | -1. | 1. | -0. | * | H.L T TRIP |

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LOW PRESSURE SCRAM LOGIC

| IDC | TYPE | IN1 | IN2 | G | P1 | P2 | IC | | | |
|--------|------|-------|-----|-----|------|-----|----------|---------|---|----------|
| 703032 | -32 | 'DER' | -20 | 0 | 2. | 0. | 0. | 0. | * | |
| 703033 | -33 | 'LAG' | -32 | 0 | 7.4 | 2. | 0. | 0. | * | |
| 703034 | -34 | 'SUM' | -33 | -20 | 1. | 1. | -0. | * | | |
| 703035 | -35 | 'LAG' | -34 | 0 | 1. | 1.8 | 0. | 278.148 | * | |
| 703036 | -36 | 'LAG' | -21 | 0 | 1. | 1.7 | 0. | 269.585 | * | |
| 703037 | -37 | 'SUM' | -35 | -36 | 1. | 1. | -1. | -0. | * | |
| 703038 | -38 | 'SUM' | -37 | 15 | 2.25 | 1. | 5. | -0. | * | |
| 703039 | -39 | 'SUM' | -36 | 15 | 1.26 | 1. | -235. | -0. | * | |
| 703040 | -40 | 'SUM' | -39 | 15 | 1. | 1. | 0.5 | -0. | * | 90/10/31 |
| 703041 | -41 | 'SUM' | -38 | -40 | 1. | 1. | 1. | -0. | * | |
| 703042 | -42 | 'MAX' | -41 | 16 | 1. | 0. | 0. | -0. | * | |
| 703043 | -43 | 'SUM' | -42 | 15 | 1. | 1. | 1. | -0. | * | |
| 703044 | -44 | 'SUM' | -43 | 1 | 1. | 1. | -0.07032 | -0. | * | L.P TRIP |

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*
* PUMP SPEED CONTROL
*
703045 -45 'INT' 19 0 1. 0. 0. 0. *
703046 -46 'FNG' -45 6 1. 0. 0. 1770. *
703047 -47 'MUL' 15 15 0. 0. 0. 0. *
703048 -48 'MUL' 15 15 0. 0. 0. 0. *
*
* P'ZER HEATER CONTROL
*
* IDC TYPE IN1 IN2 G P1 P2 IC
703049 -49 'SUM' 1 25 1. 1. -1. 0. *DELTA-P
703050 -50 'DER' -49 0 0.1667 0. 0. 0. *
703051 -51 'INT' -49 0 1200. 0. 0. 0. *
703052 -52 'SUM' -49 -50 1. 1. 1. 0. *
703053 -53 'SUM' -52 -51 -2.264-3 1. 1. 0. *K=-20PCT/K*16KW
703054 -54 'SUM' -53 22 1. 1. 0.0 0.0 *Q=Q+QREF(8.05KW)
703055 -55 'MIN' -54 23 1. 0. 0.0 0.0 *0.< Q < 16.1KW
703056 -56 'MAX' -55 24 -0.001 0. 0.0 0.0 *
703057 -57 'SUM' -56 15 1. 1. 0.0 0.0 *
703058 -58 'SUM' 42 15 6. -1. 1. 6. *(1-SCRAM)*6
703059 -59 'SUM' -58 15 1. 1. 7. *
703060 -60 'MUL' -59 -240 -0.0161 1. 1. 0. *HEAT BACK-UP OUT
703061 -61 'MUL' -57 41 1. 1. 1. 0. *HEATER PUT
*
* NUCLEAR POWER CONTROL
* TREF=-63
122000 -2 0.0 272.731 1.E6 272.731
703063 -63 'FNG' 53 20 1.0 0.0 0.0 272.731 * TREF(C)
* IDC TYPE IN1 IN2 G P1 P2 IC
703062 -62 'MUL' 15 43 1. 0. 0. 1. *
703064 -64 'SUM' -62 35 1. 1. 1. 0. *MISS MATCH
703065 -65 'DER' -64 0 40. 0. 0. 0. *
703066 -66 'LAG' -65 0 30. 40. 0. 0. *
703067 -67 'SUM' -20 -21 0.5 1. 1. -0. *(HL+CL)/2
703068 -68 'LAG' -67 0 1. 1.8 0. 273.866 *
703069 -69 'DER' -68 0 2. 0. 0. 0. *
703070 -70 'LAG' -69 0 10. 2. 0. 0. *
703071 -71 'SUM' -70 -68 1. 1. 1. -0. *COMP. SIG
703072 -72 'SUM' -66 -71 1. 1. 1. -0. *DEV. SIG
703073 -73 'SUM' -72 15 1. 1. -273.7 0. *EPSIRON
703074 -74 'INT' 37 0 -6.2-5 0. 0. 0. *#2 ROD IN INT
703075 -75 'INT' 38 0 -6.2-5 0. 0. 0. *#1 ROD IN INT
703076 -76 'INT' 39 0 6.2-5 0. 0. 0. *#1 ROD OUT INT
703077 -77 'INT' 40 0 6.2-5 0. 0. 0. *#2 ROD OUT INT
703078 -78 'SUM' -74 -75 1.33 1. 1. 0. *#2+#1 IN
703079 -79 'SUM' -76 -77 1.33 1. 1. 0. *#2+#1 OUT
703080 -80 'SUM' -78 -79 144.93 1. 1. 0. *REAC.(S)
703081 -81 'SUM' 42 15 1. -1. 1. 1. *TRIP SIG.
703082 -82 'MUL' -80 -81 1. 0. 0. 0. *TO SCRAM TABLE
703083 -83 'SUM' -71 15 1. 1. -274.697 0. *DUMMY DT
*****
*GRAVITY CAL*
*****
* IDC ITYPE INC1 INC2 CGAIN CP1 CP2 CIC
703084 -84 'FNG' 53 15 1.0 0.0 0.0 0.0 * THETA(CONS. 30.0 DEG)
* THETA = THETA*SIN(2PAI/TAU*TIME)
703085 -85 'DIV' 96 94 1.0 0.0 0.0 0.41888 * 2PAI/TAU
703086 -86 'MUL' -85 53 1.0 0.0 0.0 0.0 * 2PAI/TAU*TIME
703087 -87 'SIN' -86 00 1.0 0.0 0.0 0.0 *
703088 -88 'MUL' -84 -87 1.0 0.0 0.0 0.0 * THETA(DEG)
* DTHETA = THETA*2PAI/TAU*COS(2PAI/TAU*TIME)
703089 -89 'COS' -86 00 1.0 0.0 0.0 1.0 *
703090 -90 'MUL' -85 -89 1.0 0.0 0.0 0.41888 *
703091 -91 'MUL' -84 -90 1.0 0.0 0.0 0.0 * DTHETA
* DDTHETA = THETA*4PAI**2/TAU**2*SIN(2PAI/TAU*TIME)
703092 -92 'MUL' 94 94 1.0 0.0 0.0 225. * TAU**2
703093 -93 'DIV' 97 -92 1.0 0.0 0.0 0.17546 * 4PAI**2/TAU**2
703094 -94 'MUL' -93 -87 1.0 0.0 0.0 0.0 *
703095 -95 'MUL' -84 -94 1.0 0.0 0.0 0.0 * DDTHETA
*
703096 -96 'MUL' -88 98 1.0 0.0 0.0 0.0 * THETA(RAD)
703097 -97 'MUL' -91 98 1.0 0.0 0.0 0.0 * ROLLD(RAD)
703098 -98 'MUL' -95 98 1.0 0.0 0.0 0.0 * ROLDD(RAD)
703099 -99 'COS' -96 00 1.0 0.0 0.0 1.0 * COSROL
703100 -100 'SIN' -96 00 1.0 0.0 0.0 0.0 * SINROL
703101 -101 'MUL' -97 -97 1.0 0.0 0.0 0.0 * ROLLD**2
703102 -102 'MUL' -99 -101 1.0 0.0 0.0 0.0 * COSROL*ROLDD**2
703103 -103 'MUL' -100 -98 -1.0 0.0 0.0 0.0 * SINROL*ROLDD
703104 -104 'SUM' -102 -103 .031085 1.0 1.0 0.0 * FORCEV(NORN.)

```

| | | | | | | | | | | |
|----------------------------|------|-------|------|------|----------|----------|------------|----------|----|------------|
| 703105 | -105 | 'MUL' | -104 | 15 | 4.75 | 1.0 | 1.0 | 0.0 | * | FORCEV*R |
| 703106 | -106 | 'SUM' | -96 | 15 | 1.0 | 1.0 | 1.239 | 1.239 | * | THO+TH |
| 703107 | -107 | 'COS' | -106 | 00 | 1.0 | 0.0 | 0.0 | .326 | * | COS |
| 703108 | -108 | 'ABS' | -107 | 00 | 1.0 | 0.0 | 0.0 | .326 | * | |
| 703109 | -109 | 'DIV' | -107 | -108 | 1.0 | 0.0 | 0.0 | 1.0 | * | SIGN |
| 703110 | -110 | 'MUL' | -109 | -105 | 1.0 | 0.0 | 0.0 | 0.0 | * | FORCEV*R |
| 703111 | -111 | 'SUM' | -110 | 15 | 1.0 | 1.0 | 1.0 | 1.0 | * | FORCEV+1.0 |
| 703112 | -112 | 'MUL' | 15 | 15 | 0.0 | 0.0 | 0.0 | 0.0 | * | DUMMY |
| 703113 | -113 | 'MUL' | 15 | 15 | 0.0 | 0.0 | 0.0 | 0.0 | * | DUMMY |
| 703114 | -114 | 'MUL' | 15 | 15 | 0.0 | 0.0 | 0.0 | 0.0 | * | DUMMY |
| 703115 | -115 | 'MUL' | 15 | 15 | 0.0 | 0.0 | 0.0 | 0.0 | * | DUMMY |
| * LREF | | | | | | | | | | |
| 121900 | -2 | 0. | 0.46 | | 1.E6 | 0.46 | | | | |
| 703116 | -116 | 'FNG' | 53 | 19 | 1.0 | 0.0 | 0.0 | 0.46 | * | LREF |
| * S.G.-1 LIQL LEVEL * | | | | | | | | | | |
| 703120 | -120 | 'SUM' | -111 | 15 | 1. | -1. | 1. | 0. | | |
| 703121 | -121 | 'MUL' | 100 | 102 | 1. | 0. | 0. | -0. | | |
| 703122 | -122 | 'SUM' | -121 | 15 | 1. | 1. | -1. | -0. | | |
| 703123 | -123 | 'MUL' | -120 | -122 | 1. | 0. | 0. | 0. | | |
| 703124 | -124 | 'MUL' | -123 | 101 | 1. | 0. | 0. | 0. | | |
| 703125 | -125 | 'MUL' | -124 | 103 | 1. | 0. | 0. | 0. | | |
| 703126 | -126 | 'SUM' | 100 | 101 | 1. | 1. | -1. | -0. | | |
| 703127 | -127 | 'MUL' | -111 | -126 | 1. | 0. | 0. | -0. | | |
| 703128 | -128 | 'SUM' | 30 | 32 | 1. | 1. | 1. | -0. | * | |
| 703129 | -129 | 'SUM' | -128 | 15 | 1. | 1. | -7.7 | -0. | * | |
| 703130 | -130 | 'MUL' | -127 | -129 | 1. | 0. | 0. | -0. | * | |
| 703131 | -131 | 'SUM' | -125 | -130 | 1. | 1. | 1. | -0. | * | |
| 703132 | -132 | 'DIV' | -131 | -126 | 1. | 0. | 0. | -0. | * | |
| 703133 | -133 | 'LAG' | -132 | 0 | 1. | 2. | 0. | 3.471 | * | |
| *703134 | -134 | 'SUM' | -133 | 106 | 23.446 | -1. | 1. | 0. | * | (L-LO) |
| 703134 | -134 | 'SUM' | 30 | -116 | 23.446 | -1. | 1. | 0. | * | (L-LO) |
| 703135 | -135 | 'INT' | -134 | 0 | 0.00667 | 0. | 0. | 0. | * | |
| 703136 | -136 | 'SUM' | -135 | -134 | 0.75 | 1. | 1. | 0. | * | |
| 703137 | -137 | 'SUM' | -281 | -202 | 5.333 | 1. | -1. | 0. | * | +WS-FW |
| 703138 | -138 | 'SUM' | -136 | -137 | 1. | 1. | 1. | 0. | * | |
| 703139 | -139 | 'INT' | -138 | 0 | 0.05 | 0. | 0. | 0. | * | |
| 703140 | -140 | 'SUM' | -139 | -138 | 1. | 1. | 1. | 0. | * | |
| 703141 | -141 | 'LAG' | -140 | 0 | 1. | 10. | 0. | 0. | * | |
| 703142 | -142 | 'DLY' | -141 | 1000 | 1. | 1. | 0. | 0. | * | COMP SIG. |
| * TO FUNCTION GENERATOR * | | | | | | | | | | |
| 703149 | -149 | 'SUM' | -142 | 15 | 1. | 1. | 71.21596 | -0. | 0. | 100. |
| 703150 | -150 | 'FNG' | -149 | 7 | 1. | 0. | 0. | 12.3734* | | |
| * FEED WATER-1 FLOW RATE * | | | | | | | | | | |
| ***** 151 TO 153 NOT USE | | | | | | | | | | |
| 703151 | -151 | 'SUM' | -150 | 15 | 1. | 1. | 0. | 12.3733* | | |
| 703152 | -152 | 'SUM' | -151 | 15 | 1. | .0173566 | -1.0922034 | 0.12580 | * | |
| 703153 | -153 | 'XPD' | 47 | -152 | 1. | 0. | 0. | 1.33600 | * | |
| 703154 | -154 | 'MUL' | -153 | -153 | .0193488 | 0. | 0. | -0. | * | |
| 703154 | -154 | 'MUL' | -150 | -150 | .0193488 | 0. | 0. | -0. | * | |
| 703155 | -155 | 'DIV' | -166 | -154 | -1. | 0. | 0. | -0. | * | |
| 703156 | -156 | 'SUM' | -155 | 15 | 1. | 1. | 38.649 | 0. | * | |
| 703157 | -157 | 'INT' | -156 | 0 | 0.0333 | 0. | 0. | 0. | * | |
| 703158 | -158 | 'SUM' | -157 | -156 | 5. | 1. | 1. | 0. | * | |
| 703159 | -159 | 'SUM' | -158 | -170 | 1. | 1. | -1. | 0. | * | |
| 703160 | -160 | 'INT' | -159 | 0 | .0033333 | 0. | 0. | 0. | * | |
| 703161 | -161 | 'SUM' | -160 | -159 | .07031 | 1. | 1. | 0. | * | |
| 703162 | -162 | 'SUM' | -161 | 15 | 1. | 1. | 69.4444 | -0. | * | |
| 703163 | -163 | 'FNG' | -162 | 8 | 1. | 0. | 0. | -0. | * | |
| 703164 | -164 | 'LAG' | -163 | 0 | .194702 | 2. | 0. | 13.521 | * | |
| 703165 | -165 | 'SUM' | -164 | 15 | 1. | 1. | -0.621 | 12.9 | * | *FW 1 FLOW |
| 703166 | -166 | 'MUL' | -165 | -165 | 1. | 0. | 0. | 166.41 | * | |
| 703167 | -167 | 'SUM' | -165 | 15 | 1. | -14.64 | 954.39 | -0. | * | |
| 703168 | -168 | 'SUM' | -167 | 15 | 1. | 1. | 29.862 | -0. | * | |
| 703169 | -169 | 'SUM' | -168 | 15 | 1. | 1. | -16.353 | -0. | * | |
| 703170 | -170 | 'SUM' | -169 | 15 | 1. | 1. | -749.043 | 0. | * | |
| * SG-2 GRAVITY * | | | | | | | | | | |
| 703171 | -171 | 'SUM' | -96 | 15 | 1. | 1. | -1.239 | -1.239 | * | |
| 703172 | -172 | 'COS' | -171 | 00 | 1. | 0. | 0. | .326 | * | |
| 703173 | -173 | 'ABS' | -172 | 00 | 1. | 0. | 0. | .326 | * | |
| 703174 | -174 | 'DIV' | -172 | -173 | 1. | 0. | 0. | 1. | * | |

| | | | | | | | | | |
|----------------------------|------|-------|------|------|----------|----------|------------|-------------|--------------|
| 703175 | -175 | 'MUL' | -174 | -105 | 1. | 0. | 0. | 0. | * |
| 703176 | -176 | 'SUM' | -175 | 15 | 1. | 1. | 1. | 1. | * GRAV. |
| 703177 | -177 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| * S.G.-2 LIQL LEVEL * | | | | | | | | | |
| 703180 | -180 | 'SUM' | -176 | 15 | 1. | -1. | 1. | 0. | |
| 703181 | -181 | 'MUL' | 104 | 102 | 1. | 0. | 0. | -0. | |
| 703182 | -182 | 'SUM' | -181 | 15 | 1. | 1. | -1. | -0. | |
| 703183 | -183 | 'MUL' | -180 | -182 | 1. | 0. | 0. | 0. | |
| 703184 | -184 | 'MUL' | -183 | 105 | 1. | 0. | 0. | 0. | |
| 703185 | -185 | 'MUL' | -184 | 103 | 1. | 0. | 0. | 0. | |
| 703186 | -186 | 'SUM' | 104 | 105 | 1. | 1. | -1. | -0. | |
| 703187 | -187 | 'MUL' | -176 | -186 | 1. | 0. | 0. | -0. | |
| 703188 | -188 | 'SUM' | 31 | 33 | 1. | 1. | 1. | -0. | * |
| 703189 | -189 | 'SUM' | -188 | 15 | 1. | 1. | -7.7 | -0. | * |
| 703190 | -190 | 'MUL' | -187 | -189 | 1. | 0. | 0. | -0. | * |
| 703191 | -191 | 'SUM' | -185 | -190 | 1. | 1. | 1. | -0. | * |
| 703192 | -192 | 'DIV' | -191 | -186 | 1. | 0. | 0. | -0. | * |
| 703193 | -193 | 'LAG' | -192 | 0 | 1. | 2. | 0. | 3.471 | * |
| *703194 | -194 | 'SUM' | -193 | 106 | 23.446 | -1. | 1. | 0. | *(L-LO) |
| 703194 | -194 | 'SUM' | 31 | -116 | 23.446 | -1. | 1. | 0. | *(L-LO) |
| 703195 | -195 | 'INT' | -194 | 0 | 0.00667 | 0. | 0. | 0. | * |
| 703196 | -196 | 'SUM' | -195 | -194 | 0.75 | 1. | 1. | 0. | * |
| 703197 | -197 | 'SUM' | -283 | -284 | 5.333 | 1. | -1. | 0. | *+WS-FW |
| 703198 | -198 | 'SUM' | -196 | -197 | 1. | 1. | 1. | 0. | * |
| 703199 | -199 | 'INT' | -198 | 0 | 0.05 | 0. | 0. | 0. | * |
| 703200 | -200 | 'SUM' | -199 | -198 | 1. | 1. | 1. | 0. | * |
| 703201 | -201 | 'LAG' | -200 | 0 | 1. | 10. | 0. | 0. | * |
| 703202 | -202 | 'DLY' | -201 | 1000 | 1. | 1. | 0. | 0. | *COMP SIG. |
| * TO FUNCTION GENERATOR * | | | | | | | | | |
| 703209 | -209 | 'SUM' | -202 | 15 | 1. | 1. | 71.21596 | -0. 0. 100. | |
| 703210 | -210 | 'FNG' | -209 | 7 | 1. | 0. | 0. | -0. | * |
| * FEED WATER-2 FLOW RATE * | | | | | | | | | |
| * 211 TO 213 NOT USE | | | | | | | | | |
| 703211 | -211 | 'SUM' | -210 | 15 | 1. | 1. | 0. | 12.3734* | |
| 703212 | -212 | 'SUM' | -211 | 15 | 1. | .0173566 | -0.0922034 | 0.12580 * | |
| 703213 | -213 | 'XPO' | 47 | -212 | 1. | 0. | 0. | 1.33600 * | |
| 703214 | -214 | 'MUL' | -213 | -213 | .0193488 | 0. | 0. | -0. | * |
| 703214 | -214 | 'MUL' | -210 | -210 | .0193488 | 0. | 0. | -0. | * |
| 703215 | -215 | 'DIV' | -226 | -214 | -1. | 0. | 0. | -0. | * |
| 703216 | -216 | 'SUM' | -215 | 15 | 1. | 1. | 38.649 | 0. | * |
| 703217 | -217 | 'INT' | -216 | 0 | 0.0333 | 0. | 0. | 0. | * |
| 703218 | -218 | 'SUM' | -217 | -216 | 5. | 1. | 1. | 0. | * |
| 703219 | -219 | 'SUM' | -218 | -230 | 1. | 1. | -1. | 0. | * |
| 703220 | -220 | 'INT' | -219 | 0 | .0033333 | 0. | 0. | 0. | * |
| 703221 | -221 | 'SUM' | -220 | -219 | .07031 | 1. | 1. | 0. | * |
| 703222 | -222 | 'SUM' | -221 | 15 | 1. | 1. | 69.4444 | -0. | * |
| 703223 | -223 | 'FNG' | -222 | 8 | 1. | 0. | 0. | -0. | * |
| 703224 | -224 | 'LAG' | -223 | 0 | .194702 | 2. | 0. | 13.521 * | |
| 703225 | -225 | 'SUM' | -224 | 15 | 1. | 1. | -0.621 | 12.9 | *FW 2 FLOW |
| 703226 | -226 | 'MUL' | -225 | -225 | 1. | 0. | 0. | 166.41 * | |
| 703227 | -227 | 'SUM' | -225 | 15 | 1. | -14.64 | 954.39 | -0. | * |
| 703228 | -228 | 'SUM' | -227 | 15 | 1. | 1. | 29.862 | -0. | * |
| 703229 | -229 | 'SUM' | -228 | 15 | 1. | 1. | -16.353 | -0. | * |
| 703230 | -230 | 'SUM' | -229 | 15 | .1 | 1. | -779.043 | 0. | * |
| * DUMMY * | | | | | | | | | |
| 703231 | -231 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| 703232 | -232 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| 703233 | -233 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| 703234 | -234 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| 703235 | -235 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| 703236 | -236 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| 703237 | -237 | 'MUL' | 15 | 15 | 0. | 0. | 0. | 0. | * |
| * PZR HEATER CONTROL * | | | | | | | | | |
| 703238 | -238 | 'SUM' | 21 | 48 | 1. | 1. | 1. | 0. | *TRIP SIGNAL |
| 703239 | -239 | 'FNG' | -238 | 9 | 1. | 0. | 0. | 0. | *TRIP SIGNAL |
| 703240 | -240 | 'MUL' | -239 | 21 | 1. | 0. | 0. | 0. | *ID 703061 |

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*      MAIN STEAM FLOW GOVERNER CONTROL (NOT USED)
*
703241 -241 'SUM' 36 -250 1. 1. -1. 0. *
703242 -242 'SUM' -241 -244 .0267835 1. 32.5875 0. *
703243 -243 'FNG' -242 11 1. 0. 0. 0. *
703244 -244 'LAG' 50 0 1. 0.1 0. 0. *
703245 -245 'SUM' 49 -243 1. 3.65497 1. -0. *
703246 -246 'SUM' 15 51 1. 1. -1. 1. *
703247 -247 'MUL' -285 -246 1. 0. 0. 0.694444 0. 1. *
703248 -248 'SUM' 53 107 1. 1. -1. 0. *
703249 -249 'MUL' -240 100 1. 1. 1. 0. *
703250 -250 'FNG' -249 13 1. 0. 0. 25.8 *
*
*      EDIT CONTROL OUTPUT
*
703251 -251 'SUM' 13 14 0.5 1. 1. 0. *LOOP1 TAVE
703252 -252 'SUM' 113 114 0.5 1. 1. 0. *LOOP2 TAVE
703253 -253 'SUM' 15 15 0. 0. 0. 0. *DUMMY
703254 -254 'SUM' 70 72 1. 1. 1. 11.305 *SG(A) MIX.LEVEL
703255 -255 'SUM' 71 73 1. 1. 1. 11.305 *SG(B) MIX.LEVEL
703256 -256 'SUM' 74 75 1. 1. 1. 0. *TOTAL HEAT
703257 -257 'SUM' -256 76 1. 1. 1. 0. * GEN. RATIO
703258 -258 'SUM' 77 78 1. 1. 1. 0. *SG(A) TOTAL
703259 -259 'SUM' -258 79 1. 1. 1. 0. * HEAT REM.
703260 -260 'SUM' -259 80 1. 1. 1. 0. * RATIO
703261 -261 'SUM' 81 82 1. 1. 1. 0. *SG(B) TOTAL
703262 -262 'SUM' -261 83 1. 1. 1. 0. * HEAT REM.
703263 -263 'SUM' -262 84 1. 1. 1. 0. * RATIO
703264 -264 'DIV' -257 85 1. 0. 0. 1. *HEAT GEN. RATIO
703265 -265 'DIV' -260 86 1. 0. 0. 1. *SG(A) HEAT REM.RATIO
703266 -266 'DIV' -263 87 1. 0. 0. 1. *SG(B) HEAT REM.RATIO
703267 -267 'SUM' -260 -263 1. 1. 1. 0. *TOTAL HEAT REM.
703268 -268 'SUM' 86 87 1. 1. 1. 0. *INITIAL HEAT REM.
703269 -269 'DIV' -267 -268 1. 0. 0. 1. *TOTAL HEAT REM.RATIO
703270 -270 'INT' 88 0 1. 0. 0. 0. *S.L. DUMP OUT MASS
703271 -271 'INT' 89 0 1. 0. 0. 0. *S.L. SV#1 OUT MASS
703272 -272 'INT' 90 0 1. 0. 0. 0. *S.L. SV#2 OUT MASS
703273 -273 'INT' 91 0 1. 0. 0. 0. *PZR PORV OUT MASS
703274 -274 'INT' 92 0 1. 0. 0. 0. *PZR SV OUT MASS
703275 -275 'MUL' 15 15 0. 0. 0. 0. *DUMMY
* FOR BUBBLE DATA(MOD2 ==> MOD3 )
703276 -276 'MUL' 61 15 1. 0. 0. 0.
703277 -277 'MUL' 63 15 1. 0. 0. 0.
703278 -278 'MUL' 64 15 1. 0. 0. 0.
703279 -279 'MUL' 66 15 1. 0. 0. 0.
703280 -280 'MUL' 67 15 1. 0. 0. 0.
* FOR S.G.-1 F.W. CONT.
703281 -281 'LAG' 26 0 1. 2.0 0. 12.9 *
703282 -282 'LAG' -165 0 1. 2.0 0. 12.9 *
* FOR S.G.-2 F.W. CONT.
703283 -283 'LAG' 28 0 1. 2.0 0. 12.9 *
703284 -284 'LAG' -225 0 1. 2.0 0. 12.9 *
* FOR MAIN STEAM GOVERNER CONT.
703285 -285 'LAG' -245 0 1. 2.0 0. 0.694444 *
* FOR TRIP 9
703286 -286 'LAG' 32 0 1. 2.0 0. 10.711 *
*
***** ADD 90' *****
* C/R POSITION (FOR EDIT)
703287 -287 'INT' 37 0 -1.33 0. 0. 0. ##2 IN
703288 -288 'INT' 38 0 -1.33 0. 0. 0. ##1 IN
703289 -289 'INT' 39 0 1.33 0. 0. 0. ##1 OUT
703290 -290 'INT' 40 0 1.33 0. 0. 0. ##2 OUT
703291 -291 'SUM' -288 -289 1.0 1. 1. 0. ##1 POSITION(MM)
703292 -292 'SUM' -287 -290 1.0 1. 1. 0. ##2 POSITION(MM)
* PRZ LEVEL CONTROL
703293 -293 'SUM' 26 28 2.668 1. 1. -0. *XSTEAM FLOW
703294 -294 'FNG' -293 16 1.0 0. 0. -0. *LREF(X)
703295 -295 'SUM' -13 110 40. 0.3048 1. -0. *LIQL(X)
703296 -296 'SUM' -294 -295 1.0 1. -1. 0. *
703297 -297 'SUM' -296 15 1.0 1. -0.42162 0. *
703298 -298 'INT' -297 0 6.6667-4 0. 0. 0. *
703299 -299 'SUM' -297 -298 4.0 1. 1. 0. *
703300 -300 'SUM' 15 -299 1.0 50. -1. -0. *
703301 -301 'SUM' -300 -316 1.0 1. -90. 0. *
703302 -302 'INT' -301 0 0.16667 0. 0. 0. *
703303 -303 'SUM' -301 -302 0.33 1. 1. 0. *
703304 -304 'LAG' -303 0 1.0 1. 0. 0. *
* -305 INITIAL VALUE MUST BE ADJUST. (-317 OUTPUT =0.0)
703305 -305 'SUM' -304 15 1.0 1. 69.345 69.345 0. 100. *

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703306 -306 'FNG' -305 17 1.0 0. 0. -0. *CV1
703307 -307 'FNG' -305 18 1.0 0. 0. -0. *CV2
703308 -308 'DIV' -306 -307 1.0 0. 0. -0. *CV1/CV2
703309 -309 'MUL' -308 -308 1.0 0. 0. -0. *(CV1/CV2)**2
703310 -310 'SUM' 15 -309 1.0 1. 1. -0. *
703311 -311 'DIV' 3 -310 16.02 0. 0. -0. *
703312 -312 'SUM' 112 15 0.07031 1. -14.7 -0. *C/L PRES(KG/CM2.G)
703313 -313 'SUM' -312 15 1.0 1. -15.0 -0. *
703314 -314 'MUL' -311 -313 1.0 0. 0.0 -0. *
703315 -315 'XPD' -314 18 1.0 0. 0.0 -0. *
703316 -316 'MUL' -306 -315 .008565 0. 0.0 -0. *LET-DOWN(KG/S)
703317 -317 'SUM' -316 15 2.205 -1. 0.55556 0. *C.P.FLOW(LB/S)
* FOR EDIT
703318 -318 'INT' -317 0 1.0 0. 0. 0. *INT(C.P.FLOW)LB/S
703319 -319 'SUM' 27 26 1.0 1. -1. 0. *SG-1 FW-STEAM(LB/SEC)
703320 -320 'INT' -319 0 1.0 0. 0. 0. *INT(SG-1)
703321 -321 'SUM' 29 28 1.0 1. -1. 0. *SG-2 FW-STEAM(LB/SEC)
703322 -322 'INT' -321 0 1.0 0. 0. 0. *INT(SG-2)
*
* SPINDLE LIFT
703340 -340 'SUM' 36 15 1633. 1.0 -8.8 -0. *STEAM-(BASE STEAM)KG/H
703341 -341 'FNG' -340 21 1.0 0.0 0.0 -0. *VALVE LIFT(MM)
703342 -342 'SUM' -341 15 1.0 1.4684 17.0 -0. *SPINDLE LIFT(CZ)
*
* AUX. DNDR CALCULATION DATA
*
800100 1 0 1 1 0 11 3 *
800200 1. 2.061 1. 0.9136 1. 0.5 2.9 *
800300 .0492 .0345 .0547 0. 1. *
800400 .01 .051 .1 .5141 .2 .9289 .3 1.2566 *
800401 .4 1.4663 .5 1.5385 .6 1.4663 .7 1.2566 *
800402 .8 .9289 .9 .5141 .99 .0510 *
800500 3 4 5 *
*
* FOR SG1 FEED WATER FLOW CONTROL
* FOR SG STEAM PRESSURE BOUNDARY
010001 -1 16 1 61 42 11 1 60 2 13 23 16 11 2 3 3 2 0 3 1 0 0 2 0 0 1 1 1 1
130700 1 1000 -710 0 0. 0. 274.0 690. *SG 2 FEED WATER
130800 1 1000 -700 0 0. 0. 274.0 690. *SG 1 FEED WATER
701000 115 310 *
703700 -700 'FNG' 53 22 1.0 0.0 0.0 12.9 *FW 1
703710 -710 'FNG' 53 23 1.0 0.0 0.0 12.9 *FW 2
122200 10 * NO.1 S.G. FEED WATER FLOW (LB/S)
122201 .0 12.9 24. 12.9 51. 14.21 150. 14.7
122202 255. 14.58 261. 13.23 303. 12.31
122203 620. 12.31 630. 12.1 780. 12.1
122300 11 * NO.2 S.G. FEED WATER FLOW (LB/S)
122301 .0 12.9 24. 12.9 51. 14.21 150. 14.7
122302 251. 14.58 258. 13.0 276. 12.25 330. 11.7
122303 624. 11.70 627. 12.86 780. 12.86
*
* FOR SG STEAM PRESSURE BOUNDARY
010001 -1 16 1 61 42 11 1 60 2 13 23 16 11 2 3 3 2 0 3 1 0 0 2 0 0 1 1 1 1
*
051701 0 1 55.9 0. 1. 1.9 50.0 50.0 *MAIN TURBINE
051702 0. 1.97 0. -10.0 *MAIN TURBINE
051709 0. 0. 0. 0. 0. 1.
*
* TIME DEPENDENT VOLUME
*
TIME PRES TEMP QUA MIXL P
070101 7 0.0 0.0 494.1 1. 50. * 654.7
070102 30.0 0.0 494.1 1. 50. * 654.7
070103 167.0 0.0 492.6 1. 50. * 646.2
070104 263.0 0.0 492.6 1. 50. * 646.2
070105 323.0 0.0 493.8 1. 50. * 653.3
070106 375.0 0.0 494.6 1. 50. * 657.6
070107 420.0 0.0 494.6 1. 50. * 657.6
081601 160 170 0 0 25.8 0.2736 6.777 0. -1. 0. *TURBINE VALVE
081602 0 -1 2 0 0. 1. -99 0 0. 0 *
702035 35 'WP**' 160 -.026677 -0.2433 *STLINE-1 FLOW (WS)
702036 36 'WP**' 160 1. 9.4 *STLINE-2 FLOW (WS)
*
*****
* FOR GRAVITY CHANGE *
*****
* TABLE 24 = ROLL ANGLE(DEG)
* 25 = PITCH ANGLE(DEG)
* 26 = YAW ANGLE VELOCITY(DEG/S)
* 27 = LEFT & RIGHT ACCE.(G)
* 28 = SG2 Z-ACC.(G)
* 29 = PRZ Z-ACC.(G)

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*
010001 -1 16 1 61 42 11 1 60 2 13 29 16 11 2 3 3 2 0 3 1 0 0 2 0 0 1 1 1 1
*
ITONGH IPHIZ IPHLZD IPHLZD ITHEY ITHEYD ITHE2D IZCTX IZETXD IZET2D
010004 -609 -608 -606 -607 -600 -601 -602 -603 -604 -605
701000 120 336 *
703600 -600 'FNG' 53 24 1.0 0.0 0.0 -0.0 *ROLL ANGLE(DEG)
703601 -601 'DER' -600 0 1.0 0.0 0.0 -0.0 *ROLL ANGLE-D(DEG/S)
703602 -602 'DER' -601 0 1.0 0.0 0.0 -0.0 *ROLL ANGLE-2D(DEG/S2)
703603 -603 'FNG' 53 25 -1.0 0.0 0.0 -0.0 *PITCH ANGLE(DEG)
703604 -604 'DER' -603 0 1.0 0.0 0.0 -0.0 *PITCH ANGLE-D(DEG/S)
703605 -605 'DER' -604 0 1.0 0.0 0.0 -0.0 *PITCH ANGLE-2D(DEG/S2)
703606 -606 'FNG' 53 26 -1.0 0.0 0.0 -0.0 *YAW ANGLE-D(DEG/S)
703607 -607 'DER' -606 0 1.0 0.0 0.0 -0.0 *YAW ANGLE-2D(DEG/S2)
703608 -608 'INT' -606 0 1.0 0.0 0.0 -0.0 *YAW ANGLE(DEG)
703609 -609 'FNG' 53 27 0.102 0.0 0.0 -0.0 *L-R NORM. ACC.(-)
*
FDR S.G DETECTED LEVEL
702106 106 'CONS' 0 2.985 2.985 * L-REF
703110 -110 'FNG' 53 28 -1. 0.0 0.0 -0.0 *SG-Z ACC.(G)
703111 -111 'SUM' -110 15 0.102 1.0 9.8 -0.0 *SG-Z ACC.(NORM.)
703129 -129 'SUM' -128 15 1. 1.0 -8.186 -0.0
703133 -133 'LAG' -132 0 1. 2. 0. 2.985 *
703134 -134 'SUM' -133 106 23.446 -1. 1. 0.0 *
703176 -176 'SUM' -111 15 1. 1. 0. 0.0 *
703189 -189 'SUM' -188 15 1. 1.0 -8.186 -0.0
703193 -193 'LAG' -192 0 1. 2. 0. 2.985 *
703194 -194 'SUM' -193 106 23.446 -1. 1. 0.0 *
*
FDR PRZ DETECTED LEVEL
702116 116 'CONS' 0 8.2025 8.2025 * 2.5M
702117 117 'CONS' 0 61.67 61.67 * KIJJUN-KYAKU RHO
702118 118 'CONS' 0 0.5543 0.5543 * PRZ BASE LEVEL
702119 119 'VL**' 32 1.0 -0.0 * LIQ. SPECIFIC VOL
702120 120 'VS**' 32 1.0 -0.0 * GAS SPECIFIC VOL
*109=LIQL 31 115=LIQL 32
703401 -401 'FNG' 53 29 -1.0 0.0 0.0 -0.0 *PRZ-Z ACC(G)
703402 -402 'SUM' -401 15 0.102 1.0 9.8 -0.0 *PRZ-Z ACC(NORM.)
703410 -410 'DIV' 15 119 1.0 0.0 0.0 -0.0 *RHOL
703411 -411 'DIV' 15 120 1.0 0.0 0.0 -0.0 *RHOG
703412 -412 'SUM' 117 -411 8.2025 1.0 -1.0 -0.0 *(RHOL-RHOG)*8.2025
703413 -413 'SUM' 15 -402 1.0 1.0 -1.0 -0.0 *1-BETA
703414 -414 'MUL' -412 -413 1.0 0.0 0.0 -0.0 *
703415 -415 'SUM' -410 -411 1.0 1.0 -1.0 -0.0 *RHOL-RHOG
703416 -416 'SUM' -109 115 1.0 1.0 1.0 -0.0 *PRZ LIQL
703417 -417 'SUM' -416 118 1.0 1.0 -1.0 -0.0 *PRZ LIQL-0.5543
703418 -418 'MUL' -417 -415 1.0 0.0 0.0 -0.0 *
703419 -419 'MUL' -418 -402 1.0 0.0 0.0 -0.0 *
703420 -420 'SUM' -419 -414 1.0 1.0 1.0 -0.0 *
703421 -421 'DIV' -420 -415 1.0 0.0 0.0 -0.0 *DETECTED LEVEL(FT)
703422 -422 'DIV' -421 116 100. 0.0 0.0 -0.0 *DETECTED LEVEL(X)
703423 -423 'LAG' -422 0 1. 2.0 0.0 45.300 *DETECTED LEVEL(X)
703296 -296 'SUM' -294 -423 1.0 1. -1. -0. *
*
122400 781 * ROLL ANGLE (DEG)
122401 0.0 .5420E+00 1.0 .5420E+00 2.0 .5420E+00 3.0 .4248E+00
+ 4.0 .4248E+00 5.0 .6738E+00 6.0 .9229E+00 7.0 .1011E+01
+ 8.0 .1025E+01 9.0 .8057E+00 10.0 .1758E+00 11.0 -.4102E+00
122402 12.0 -.7764E+00 13.0 -.9082E+00 14.0 -.7471E+00 15.0 -.1611E+00
+ 16.0 .3369E+00 17.0 .1011E+01 18.0 .1099E+01 19.0 .8350E+00
+ 20.0 .4248E+00 21.0 -.4395E-01 22.0 -.6445E+00 23.0 -.1260E+01
122403 24.0 -.1846E+01 25.0 -.2563E+01 26.0 -.2915E+01 27.0 -.2959E+01
+ 28.0 -.2344E+01 29.0 -.1128E+01 30.0 .4102E+00 31.0 .1729E+01
+ 32.0 .2358E+01 33.0 .2212E+01 34.0 .1509E+01 35.0 .1904E+00
122404 36.0 -.1143E+01 37.0 -.2212E+01 38.0 -.2798E+01 39.0 -.2681E+01
+ 40.0 -.2080E+01 41.0 -.1172E+01 42.0 -.1758E+00 43.0 .8496E+00
+ 44.0 .1714E+01 45.0 .2153E+01 46.0 .2109E+01 47.0 .1421E+01
122405 48.0 .3223E+00 49.0 -.8643E+00 50.0 -.1729E+01 51.0 -.2314E+01
+ 52.0 -.2314E+01 53.0 -.1831E+01 54.0 -.8936E+00 55.0 .4102E+00
+ 56.0 .1743E+01 57.0 .2900E+01 58.0 .3208E+01 59.0 .2593E+01
122406 60.0 .1289E+01 61.0 -.1758E+00 62.0 -.1479E+01 63.0 -.2065E+01
+ 64.0 -.1846E+01 65.0 -.1216E+01 66.0 -.2783E+00 67.0 .6738E+00
+ 68.0 .1509E+01 69.0 .2109E+01 70.0 .2036E+01 71.0 .1509E+01
122407 72.0 .6445E+00 73.0 -.1904E+00 74.0 -.9814E+00 75.0 -.1362E+01
+ 76.0 -.1245E+01 77.0 -.9082E+00 78.0 -.4395E+00 79.0 .7324E-01
+ 80.0 .7910E+00 81.0 .1274E+01 82.0 .1758E+01 83.0 .2109E+01
122408 84.0 .2007E+01 85.0 .1509E+01 86.0 .5127E+00 87.0 -.2930E+00
+ 88.0 -.1392E+01 89.0 -.2446E+01 90.0 -.3047E+01 91.0 -.3149E+01
+ 92.0 -.2563E+01 93.0 -.1362E+01 94.0 .1904E+00 95.0 .1523E+01
122409 96.0 .2578E+01 97.0 .2944E+01 98.0 .2563E+01 99.0 .1450E+01
+ 100.0 -.4395E-01 101.0 -.1494E+01 102.0 -.2622E+01 103.0 -.2930E+01
+ 104.0 -.2813E+01 105.0 -.1963E+01 106.0 -.7471E+00 107.0 .6152E+00
122410 108.0 .1758E+01 109.0 .2227E+01 110.0 .1743E+01 111.0 .5420E+00

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| | | | | | | | | | |
|--------|---|-------|------------|-------|------------|-------|------------|-------|------------|
| | + | 112.0 | -.4395E+00 | 113.0 | -.1714E+01 | 114.0 | -.2798E+01 | 115.0 | -.3281E+01 |
| | + | 116.0 | -.3047E+01 | 117.0 | -.2227E+01 | 118.0 | -.9961E+00 | 119.0 | .2637E+00 |
| 122411 | | 120.0 | .1128E+01 | 121.0 | .1274E+01 | 122.0 | .1025E+01 | 123.0 | .3369E+00 |
| | + | 124.0 | -.6738E+00 | 125.0 | -.1699E+01 | 126.0 | -.2329E+01 | 127.0 | -.2314E+01 |
| | + | 128.0 | -.1714E+01 | 129.0 | -.4688E+00 | 130.0 | .6592E+00 | 131.0 | .1538E+01 |
| 122412 | | 132.0 | .2036E+01 | 133.0 | .2021E+01 | 134.0 | .1465E+01 | 135.0 | .4541E+00 |
| | + | 136.0 | -.7910E+00 | 137.0 | -.1992E+01 | 138.0 | -.2915E+01 | 139.0 | -.3179E+01 |
| | + | 140.0 | -.2622E+01 | 141.0 | -.1333E+01 | 142.0 | .2783E+00 | 143.0 | .1860E+01 |
| 122413 | | 144.0 | .3062E+01 | 145.0 | .3662E+01 | 146.0 | .3120E+01 | 147.0 | .1743E+01 |
| | + | 148.0 | -.1611E+00 | 149.0 | -.1948E+01 | 150.0 | -.3281E+01 | 151.0 | -.3882E+01 |
| | + | 152.0 | -.3530E+01 | 153.0 | -.2227E+01 | 154.0 | -.5420E+00 | 155.0 | .1318E+01 |
| 122414 | | 156.0 | .2534E+01 | 157.0 | .3062E+01 | 158.0 | .2725E+01 | 159.0 | .1743E+01 |
| | + | 160.0 | .3076E+00 | 161.0 | -.1084E+01 | 162.0 | -.1963E+01 | 163.0 | -.2080E+01 |
| | + | 164.0 | -.1582E+01 | 165.0 | -.4395E+00 | 166.0 | .7910E+00 | 167.0 | .1553E+01 |
| 122415 | | 168.0 | .1758E+01 | 169.0 | .1465E+01 | 170.0 | .6592E+00 | 171.0 | -.1611E+00 |
| | + | 172.0 | -.9814E+00 | 173.0 | -.1611E+01 | 174.0 | -.1934E+01 | 175.0 | -.1816E+01 |
| | + | 176.0 | -.1362E+01 | 177.0 | -.6592E+00 | 178.0 | -.4395E-01 | 179.0 | .5127E+00 |
| 122416 | | 180.0 | .5566E+00 | 181.0 | .4248E+00 | 182.0 | .7324E-01 | 183.0 | -.1611E+00 |
| | + | 184.0 | -.5713E+00 | 185.0 | -.9961E+00 | 186.0 | -.1479E+01 | 187.0 | -.1582E+01 |
| | + | 188.0 | -.1479E+01 | 189.0 | -.1128E+01 | 190.0 | -.7764E+00 | 191.0 | -.2051E+00 |
| 122417 | | 192.0 | .3076E+00 | 193.0 | .8643E+00 | 194.0 | .1055E+01 | 195.0 | .1025E+01 |
| | + | 196.0 | .5420E+00 | 197.0 | -.3662E+00 | 198.0 | -.1377E+01 | 199.0 | -.1948E+01 |
| | + | 200.0 | -.2358E+01 | 201.0 | -.2095E+01 | 202.0 | -.1245E+01 | 203.0 | -.4395E-01 |
| 122418 | | 204.0 | .1157E+01 | 205.0 | .1802E+01 | 206.0 | .1992E+01 | 207.0 | .1626E+01 |
| | + | 208.0 | .8203E+00 | 209.0 | -.5859E-01 | 210.0 | -.8789E+00 | 211.0 | -.1216E+01 |
| | + | 212.0 | -.1289E+01 | 213.0 | -.1143E+01 | 214.0 | -.7617E+00 | 215.0 | -.1611E+00 |
| 122419 | | 216.0 | .4395E+00 | 217.0 | .9375E+00 | 218.0 | .1274E+01 | 219.0 | .1406E+01 |
| | + | 220.0 | .1260E+01 | 221.0 | .1274E+01 | 222.0 | .1157E+01 | 223.0 | .9521E+00 |
| | + | 224.0 | .5566E+00 | 225.0 | .7324E-01 | 226.0 | -.5273E+00 | 227.0 | -.1011E+01 |
| 122420 | | 228.0 | -.1011E+01 | 229.0 | -.5273E+00 | 230.0 | .3273E+00 | 231.0 | .1392E+01 |
| | + | 232.0 | .2344E+01 | 233.0 | .2710E+01 | 234.0 | .2505E+01 | 235.0 | .1362E+01 |
| | + | 236.0 | .1904E+00 | 237.0 | -.1157E+01 | 238.0 | -.2080E+01 | 239.0 | -.2446E+01 |
| 122421 | | 240.0 | -.2314E+01 | 241.0 | -.1699E+01 | 242.0 | -.5859E+00 | 243.0 | .4248E+00 |
| | + | 244.0 | .1025E+01 | 245.0 | .1143E+01 | 246.0 | .1143E+01 | 247.0 | .7910E+00 |
| | + | 248.0 | .7324E-01 | 249.0 | -.7617E+00 | 250.0 | -.1377E+01 | 251.0 | -.1597E+01 |
| 122422 | | 252.0 | -.1348E+01 | 253.0 | -.7764E+00 | 254.0 | -.4102E+00 | 255.0 | .0000E+00 |
| | + | 256.0 | .1904E+00 | 257.0 | .1758E+00 | 258.0 | -.4395E-01 | 259.0 | -.5273E+00 |
| | + | 260.0 | -.1304E+01 | 261.0 | -.1846E+01 | 262.0 | -.2212E+01 | 263.0 | -.1978E+01 |
| 122423 | | 264.0 | -.1479E+01 | 265.0 | -.5273E+00 | 266.0 | .3076E+00 | 267.0 | .9082E+00 |
| | + | 268.0 | .1157E+01 | 269.0 | .9082E+00 | 270.0 | .4395E+00 | 271.0 | -.2783E+00 |
| | + | 272.0 | -.9521E+00 | 273.0 | -.1362E+01 | 274.0 | -.1479E+01 | 275.0 | -.1377E+01 |
| 122424 | | 276.0 | -.9229E+00 | 277.0 | -.5127E+00 | 278.0 | -.1611E+00 | 279.0 | .3076E+00 |
| | + | 280.0 | .7910E+00 | 281.0 | .1025E+01 | 282.0 | .1025E+01 | 283.0 | .9229E+00 |
| | + | 284.0 | .5420E+00 | 285.0 | .5859E-01 | 286.0 | -.4102E+00 | 287.0 | -.7617E+00 |
| 122425 | | 288.0 | -.1040E+01 | 289.0 | -.1113E+01 | 290.0 | -.7178E+00 | 291.0 | -.1025E+00 |
| | + | 292.0 | .4980E+00 | 293.0 | .9082E+00 | 294.0 | .1274E+01 | 295.0 | .1274E+01 |
| | + | 296.0 | .1274E+01 | 297.0 | .8057E+00 | 298.0 | .1172E+00 | 299.0 | -.5273E+00 |
| 122426 | | 300.0 | -.1128E+01 | 301.0 | -.1553E+01 | 302.0 | -.1260E+01 | 303.0 | -.5273E+00 |
| | + | 304.0 | .1611E+00 | 305.0 | .1143E+01 | 306.0 | .2021E+01 | 307.0 | .2710E+01 |
| | + | 308.0 | .2944E+01 | 309.0 | .2827E+01 | 310.0 | .2153E+01 | 311.0 | .1025E+01 |
| 122427 | | 312.0 | -.1904E+00 | 313.0 | -.1450E+01 | 314.0 | -.2314E+01 | 315.0 | -.2578E+01 |
| | + | 316.0 | -.2212E+01 | 317.0 | -.1362E+01 | 318.0 | -.2197E+00 | 319.0 | .1128E+01 |
| | + | 320.0 | .2344E+01 | 321.0 | .3193E+01 | 322.0 | .3442E+01 | 323.0 | .3047E+01 |
| 122428 | | 324.0 | .1978E+01 | 325.0 | .6592E+00 | 326.0 | -.6885E+00 | 327.0 | -.1846E+01 |
| | + | 328.0 | -.2637E+01 | 329.0 | -.2813E+01 | 330.0 | -.2432E+01 | 331.0 | -.1362E+01 |
| | + | 332.0 | -.1611E+00 | 333.0 | .1011E+01 | 334.0 | .1714E+01 | 335.0 | .1904E+01 |
| 122429 | | 336.0 | .1626E+01 | 337.0 | .9082E+00 | 338.0 | -.2197E+00 | 339.0 | -.1494E+01 |
| | + | 340.0 | -.2285E+01 | 341.0 | -.2563E+01 | 342.0 | -.1963E+01 | 343.0 | -.1055E+01 |
| | + | 344.0 | .7324E-01 | 345.0 | .1216E+01 | 346.0 | .1875E+01 | 347.0 | .1875E+01 |
| 122430 | | 348.0 | .1143E+01 | 349.0 | -.4395E-01 | 350.0 | -.1245E+01 | 351.0 | -.2212E+01 |
| | + | 352.0 | -.2607E+01 | 353.0 | -.2329E+01 | 354.0 | -.1714E+01 | 355.0 | -.7617E+00 |
| | + | 356.0 | -.4395E-01 | 357.0 | .4395E+00 | 358.0 | .7910E+00 | 359.0 | .9082E+00 |
| 122431 | | 360.0 | .6885E+00 | 361.0 | .3076E+00 | 362.0 | -.1904E+00 | 363.0 | -.5127E+00 |
| | + | 364.0 | -.8643E+00 | 365.0 | -.7764E+00 | 366.0 | -.3516E+00 | 367.0 | .7324E-01 |
| | + | 368.0 | .6738E+00 | 369.0 | .1157E+01 | 370.0 | .1392E+01 | 371.0 | .1260E+01 |
| 122432 | | 372.0 | .8496E+00 | 373.0 | .7324E-01 | 374.0 | -.3955E+00 | 375.0 | -.5420E+00 |
| | + | 376.0 | -.6299E+00 | 377.0 | -.4102E+00 | 378.0 | .5859E-01 | 379.0 | .6006E+00 |
| | + | 380.0 | .1143E+01 | 381.0 | .1494E+01 | 382.0 | .1538E+01 | 383.0 | .1274E+01 |
| 122433 | | 384.0 | .8203E+00 | 385.0 | .3076E+00 | 386.0 | -.2930E-01 | 387.0 | -.1611E+00 |
| | + | 388.0 | -.1611E+00 | 389.0 | -.2930E-01 | 390.0 | .1758E+00 | 391.0 | .4395E+00 |
| | + | 392.0 | .6738E+00 | 393.0 | .6299E+00 | 394.0 | .6592E+00 | 395.0 | .6299E+00 |
| 122434 | | 396.0 | .5566E+00 | 397.0 | .3076E+00 | 398.0 | .7324E-01 | 399.0 | -.8789E-01 |
| | + | 400.0 | -.2783E+00 | 401.0 | -.4980E+00 | 402.0 | -.6299E+00 | 403.0 | -.7617E+00 |
| | + | 404.0 | -.9229E+00 | 405.0 | -.8936E+00 | 406.0 | -.5420E+00 | 407.0 | .1025E+00 |
| 122435 | | 408.0 | .9229E+00 | 409.0 | .1494E+01 | 410.0 | .1523E+01 | 411.0 | .1040E+01 |
| | + | 412.0 | .1904E+00 | 413.0 | -.7764E+00 | 414.0 | -.1553E+01 | 415.0 | -.2007E+01 |
| | + | 416.0 | -.2095E+01 | 417.0 | -.1904E+01 | 418.0 | -.1611E+01 | 419.0 | -.1011E+01 |
| 122436 | | 420.0 | -.3955E+00 | 421.0 | .5859E-01 | 422.0 | .4541E+00 | 423.0 | .5566E+00 |
| | + | 424.0 | .1904E+00 | 425.0 | -.4102E+00 | 426.0 | -.9961E+00 | 427.0 | -.1465E+01 |
| | + | 428.0 | -.1611E+01 | 429.0 | -.1523E+01 | 430.0 | -.1113E+01 | 431.0 | -.5273E+00 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| 122437 | 432.0 | -.5859E+01 | 433.0 | .1465E+00 | 434.0 | .7324E-01 | 435.0 | -.1318E+00 |
| + | 436.0 | -.4834E+00 | 437.0 | -.7764E+00 | 438.0 | -.8350E+00 | 439.0 | -.8789E+00 |
| + | 440.0 | -.7617E+00 | 441.0 | -.7617E+00 | 442.0 | -.9668E+00 | 443.0 | -.1128E+01 |
| 122438 | 444.0 | -.1011E+01 | 445.0 | -.6885E+00 | 446.0 | -.2783E+00 | 447.0 | -.1904E+00 |
| + | 448.0 | .6738E+00 | 449.0 | .9082E+00 | 450.0 | .1157E+01 | 451.0 | .1113E+01 |
| + | 452.0 | .7910E+00 | 453.0 | .3369E+00 | 454.0 | -.4395E-01 | 455.0 | -.4102E+00 |
| 122439 | 456.0 | -.7471E+00 | 457.0 | -.7617E+00 | 458.0 | -.6592E+00 | 459.0 | -.3516E+00 |
| + | 460.0 | .4395E-01 | 461.0 | .5127E+00 | 462.0 | .7617E+00 | 463.0 | -.7764E+00 |
| + | 464.0 | .6738E+00 | 465.0 | .5566E+00 | 466.0 | .2490E+00 | 467.0 | -.7324E-01 |
| 122440 | 468.0 | .7324E-01 | 469.0 | .1758E+00 | 470.0 | .3076E+00 | 471.0 | .7617E+00 |
| + | 472.0 | -.1040E+01 | 473.0 | -.1143E+01 | 474.0 | .1099E+01 | 475.0 | -.6738E+00 |
| + | 476.0 | -.1318E+00 | 477.0 | -.8643E+00 | 478.0 | -.1274E+01 | 479.0 | -.1465E+01 |
| 122441 | 480.0 | -.1289E+01 | 481.0 | -.7617E+00 | 482.0 | .1904E+00 | 483.0 | -.1362E+01 |
| + | 484.0 | .2271E+01 | 485.0 | .2710E+01 | 486.0 | .2622E+01 | 487.0 | .1992E+01 |
| + | 488.0 | .9082E+00 | 489.0 | -.2783E+00 | 490.0 | -.1362E+01 | 491.0 | -.2095E+01 |
| 122442 | 492.0 | -.2314E+01 | 493.0 | -.1846E+01 | 494.0 | -.8789E+00 | 495.0 | -.8789E-01 |
| + | 496.0 | -.1040E+01 | 497.0 | .1465E+01 | 498.0 | .1274E+01 | 499.0 | .5859E+00 |
| + | 500.0 | -.3955E+00 | 501.0 | -.1128E+01 | 502.0 | -.1611E+01 | 503.0 | -.1611E+01 |
| 122443 | 504.0 | -.1392E+01 | 505.0 | -.8936E+00 | 506.0 | -.3955E+00 | 507.0 | -.1465E-01 |
| + | 508.0 | .3223E+00 | 509.0 | .1465E+00 | 510.0 | -.2637E+00 | 511.0 | -.6445E+00 |
| + | 512.0 | -.7617E+00 | 513.0 | -.6445E+00 | 514.0 | -.3076E+00 | 515.0 | .7324E-01 |
| 122444 | 516.0 | -.7324E-01 | 517.0 | -.2930E-01 | 518.0 | -.3516E+00 | 519.0 | -.6299E+00 |
| + | 520.0 | -.7617E+00 | 521.0 | -.5273E+00 | 522.0 | -.1318E+00 | 523.0 | .2051E+00 |
| + | 524.0 | .4248E+00 | 525.0 | .5420E+00 | 526.0 | .4248E+00 | 527.0 | .4248E+00 |
| 122445 | 528.0 | .1904E+00 | 529.0 | -.4395E-01 | 530.0 | -.5859E-01 | 531.0 | -.1611E+00 |
| + | 532.0 | -.3955E+00 | 533.0 | -.4248E+00 | 534.0 | -.5566E+00 | 535.0 | -.7324E+00 |
| + | 536.0 | -.6445E+00 | 537.0 | -.3955E+00 | 538.0 | -.4395E-01 | 539.0 | .4834E+00 |
| 122446 | 540.0 | .7910E+00 | 541.0 | .7910E+00 | 542.0 | .6885E+00 | 543.0 | .5566E+00 |
| + | 544.0 | .3076E+00 | 545.0 | .7324E-01 | 546.0 | -.4395E-01 | 547.0 | -.1611E+00 |
| + | 548.0 | .8789E-01 | 549.0 | .4395E+00 | 550.0 | .6738E+00 | 551.0 | .7910E+00 |
| 122447 | 552.0 | .6592E+00 | 553.0 | .4248E+00 | 554.0 | .7324E-01 | 555.0 | -.2930E+00 |
| + | 556.0 | -.6592E+00 | 557.0 | -.7910E+00 | 558.0 | -.5273E+00 | 559.0 | -.4395E-01 |
| + | 560.0 | .6738E+00 | 561.0 | .1025E+01 | 562.0 | .1025E+01 | 563.0 | .5420E+00 |
| 122448 | 564.0 | -.1611E+00 | 565.0 | -.9521E+00 | 566.0 | -.1494E+01 | 567.0 | -.1729E+01 |
| + | 568.0 | -.1494E+01 | 569.0 | -.8789E+00 | 570.0 | -.1611E+00 | 571.0 | .4688E+00 |
| + | 572.0 | .1025E+01 | 573.0 | .1157E+01 | 574.0 | .9082E+00 | 575.0 | .4248E+00 |
| 122449 | 576.0 | -.4248E+00 | 577.0 | -.1494E+01 | 578.0 | -.2212E+01 | 579.0 | -.2329E+01 |
| + | 580.0 | -.1948E+01 | 581.0 | -.1362E+01 | 582.0 | -.4980E+00 | 583.0 | .3516E+00 |
| + | 584.0 | .1128E+01 | 585.0 | .1509E+01 | 586.0 | .1260E+01 | 587.0 | .6738E+00 |
| 122450 | 588.0 | -.1465E-01 | 589.0 | -.6445E+00 | 590.0 | -.1128E+01 | 591.0 | -.1362E+01 |
| + | 592.0 | -.1245E+01 | 593.0 | -.7617E+00 | 594.0 | -.7324E-01 | 595.0 | .4248E+00 |
| + | 596.0 | .6592E+00 | 597.0 | .6738E+00 | 598.0 | .3223E+00 | 599.0 | .2783E+00 |
| 122451 | 600.0 | -.1055E+01 | 601.0 | -.1816E+01 | 602.0 | -.2314E+01 | 603.0 | -.2212E+01 |
| + | 604.0 | -.1567E+01 | 605.0 | -.2637E+00 | 606.0 | .1143E+01 | 607.0 | .2227E+01 |
| + | 608.0 | .2681E+01 | 609.0 | .2578E+01 | 610.0 | .1860E+01 | 611.0 | .5273E+00 |
| 122452 | 612.0 | -.4395E+00 | 613.0 | -.1494E+01 | 614.0 | -.2080E+01 | 615.0 | -.2197E+01 |
| + | 616.0 | -.1714E+01 | 617.0 | -.8643E+00 | 618.0 | -.2930E-01 | 619.0 | .6738E+00 |
| + | 620.0 | .1230E+01 | 621.0 | .1304E+01 | 622.0 | .1260E+01 | 623.0 | .1143E+01 |
| 122453 | 624.0 | .1040E+01 | 625.0 | .6738E+00 | 626.0 | .0000E+00 | 627.0 | -.6299E+00 |
| + | 628.0 | -.1069E+01 | 629.0 | -.1362E+01 | 630.0 | -.1128E+01 | 631.0 | -.5273E+00 |
| + | 632.0 | .7324E-01 | 633.0 | .6592E+00 | 634.0 | .1025E+01 | 635.0 | .1143E+01 |
| 122454 | 636.0 | .9082E+00 | 637.0 | .4248E+00 | 638.0 | -.4395E-01 | 639.0 | -.3955E+00 |
| + | 640.0 | -.5273E+00 | 641.0 | -.3955E+00 | 642.0 | -.1318E+00 | 643.0 | -.1465E-01 |
| + | 644.0 | -.1465E-01 | 645.0 | -.4395E-01 | 646.0 | -.1758E+00 | 647.0 | -.2490E+00 |
| 122455 | 648.0 | -.1611E+00 | 649.0 | -.5859E-01 | 650.0 | -.4395E-01 | 651.0 | .7324E-01 |
| + | 652.0 | .7324E-01 | 653.0 | .7324E-01 | 654.0 | -.2930E-01 | 655.0 | -.1611E+00 |
| + | 656.0 | -.5273E+00 | 657.0 | -.1128E+01 | 658.0 | -.1494E+01 | 659.0 | -.1479E+01 |
| 122456 | 660.0 | -.1245E+01 | 661.0 | -.6445E+00 | 662.0 | .7324E-01 | 663.0 | .7910E+00 |
| + | 664.0 | .1274E+01 | 665.0 | .1143E+01 | 666.0 | .6152E+00 | 667.0 | .8789E-01 |
| + | 668.0 | -.4102E+00 | 669.0 | -.5273E+00 | 670.0 | -.2783E+00 | 671.0 | -.1611E+00 |
| 122457 | 672.0 | -.5859E-01 | 673.0 | .1904E+00 | 674.0 | -.5859E-01 | 675.0 | -.5273E+00 |
| + | 676.0 | -.9082E+00 | 677.0 | -.1143E+01 | 678.0 | -.8350E+00 | 679.0 | -.2930E+00 |
| + | 680.0 | .1172E+00 | 681.0 | .4248E+00 | 682.0 | .6738E+00 | 683.0 | .7910E+00 |
| 122458 | 684.0 | .6592E+00 | 685.0 | .3076E+00 | 686.0 | .4395E-01 | 687.0 | -.2783E+00 |
| + | 688.0 | -.5273E+00 | 689.0 | -.5273E+00 | 690.0 | -.3955E+00 | 691.0 | -.2051E+00 |
| + | 692.0 | -.4395E-01 | 693.0 | .5859E-01 | 694.0 | .2051E+00 | 695.0 | .2930E+00 |
| 122459 | 696.0 | .2197E+00 | 697.0 | .1904E+00 | 698.0 | .1904E+00 | 699.0 | .7324E-01 |
| + | 700.0 | -.4395E-01 | 701.0 | -.2930E-01 | 702.0 | -.4395E-01 | 703.0 | .7324E-01 |
| + | 704.0 | .1904E+00 | 705.0 | .3076E+00 | 706.0 | .3516E+00 | 707.0 | .3076E+00 |
| 122460 | 708.0 | -.4395E-01 | 709.0 | -.1611E+00 | 710.0 | -.2783E+00 | 711.0 | -.4688E+00 |
| + | 712.0 | -.7471E+00 | 713.0 | -.1011E+01 | 714.0 | -.1128E+01 | 715.0 | -.7910E+00 |
| + | 716.0 | -.4102E+00 | 717.0 | .5859E-01 | 718.0 | .4248E+00 | 719.0 | .4248E+00 |
| 122461 | 720.0 | .3076E+00 | 721.0 | -.1465E+00 | 722.0 | -.5127E+00 | 723.0 | -.1011E+01 |
| + | 724.0 | -.1509E+01 | 725.0 | -.1846E+01 | 726.0 | -.1934E+01 | 727.0 | -.1670E+01 |
| + | 728.0 | -.1011E+01 | 729.0 | -.4395E-01 | 730.0 | .8203E+00 | 731.0 | .1523E+01 |
| 122462 | 732.0 | .1509E+01 | 733.0 | .1143E+01 | 734.0 | .4395E+00 | 735.0 | -.5273E+00 |
| + | 736.0 | -.1260E+01 | 737.0 | -.1729E+01 | 738.0 | -.1846E+01 | 739.0 | -.1729E+01 |
| + | 740.0 | -.1245E+01 | 741.0 | -.5127E+00 | 742.0 | .5420E+00 | 743.0 | .1392E+01 |
| 122463 | 744.0 | .2007E+01 | 745.0 | .2124E+01 | 746.0 | .1436E+01 | 747.0 | .3369E+00 |
| + | 748.0 | -.1230E+01 | 749.0 | -.2637E+01 | 750.0 | -.3413E+01 | 751.0 | -.3398E+01 |

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| | | | | | | | | |
|--------|-------|---------------------|-------|------------|-------|------------|-------|------------|
| + | 752.0 | -.2681E+01 | 753.0 | -.1230E+01 | 754.0 | .5127E+00 | 755.0 | .1875E+01 |
| 122464 | 756.0 | .2578E+01 | 757.0 | .2563E+01 | 758.0 | .1641E+01 | 759.0 | .2637E+00 |
| + | 760.0 | -.1333E+01 | 761.0 | -.2695E+01 | 762.0 | -.3223E+01 | 763.0 | -.2915E+01 |
| + | 764.0 | -.1963E+01 | 765.0 | -.6006E+00 | 766.0 | .7617E+00 | 767.0 | .1685E+01 |
| 122465 | 768.0 | .2212E+01 | 769.0 | .2227E+01 | 770.0 | .1860E+01 | 771.0 | .1260E+01 |
| + | 772.0 | .6299E+00 | 773.0 | -.4395E-01 | 774.0 | -.6592E+00 | 775.0 | -.1011E+01 |
| + | 776.0 | -.1011E+01 | 777.0 | -.5859E+00 | 778.0 | .0000E+00 | 779.0 | .5420E+00 |
| 122466 | 780.0 | .7910E+00 | | | | | | |
| 122500 | 781 | * PITCH ANGLE (DEG) | | | | | | |
| 122501 | .0 | .1904E+00 | 1.0 | .1904E+00 | 2.0 | .3516E+00 | 3.0 | .6152E+00 |
| + | 4.0 | .7764E+00 | 5.0 | .7617E+00 | 6.0 | .7617E+00 | 7.0 | .9229E+00 |
| + | 8.0 | .1055E+01 | 9.0 | .1084E+01 | 10.0 | .8496E+00 | 11.0 | .4980E+00 |
| 122502 | 12.0 | .1025E+00 | 13.0 | .1465E-01 | 14.0 | .1904E+00 | 15.0 | .7178E+00 |
| + | 16.0 | .1260E+01 | 17.0 | .1436E+01 | 18.0 | .9961E+00 | 19.0 | .4102E+00 |
| + | 20.0 | .2197E+00 | 21.0 | .3516E+00 | 22.0 | .6006E+00 | 23.0 | .7764E+00 |
| 122503 | 24.0 | .7324E+00 | 25.0 | .6885E+00 | 26.0 | .4688E+00 | 27.0 | .3955E+00 |
| + | 28.0 | .3662E+00 | 29.0 | .3516E+00 | 30.0 | .5273E+00 | 31.0 | .7178E+00 |
| + | 32.0 | .6885E+00 | 33.0 | .6885E+00 | 34.0 | .6006E+00 | 35.0 | .6006E+00 |
| 122504 | 36.0 | .7617E+00 | 37.0 | .1011E+01 | 38.0 | .1099E+01 | 39.0 | .1011E+01 |
| + | 40.0 | .6738E+00 | 41.0 | .3809E+00 | 42.0 | .3516E+00 | 43.0 | .3516E+00 |
| + | 44.0 | .5127E+00 | 45.0 | .5566E+00 | 46.0 | .4980E+00 | 47.0 | .4102E+00 |
| 122505 | 48.0 | .3955E+00 | 49.0 | .4395E+00 | 50.0 | .6299E+00 | 51.0 | .1099E+01 |
| + | 52.0 | .1436E+01 | 53.0 | .1187E+01 | 54.0 | .7617E+00 | 55.0 | .3076E+00 |
| + | 56.0 | .3955E+00 | 57.0 | .5273E+00 | 58.0 | .5127E+00 | 59.0 | .5127E+00 |
| 122506 | 60.0 | .5273E+00 | 61.0 | .6885E+00 | 62.0 | .9082E+00 | 63.0 | .1084E+01 |
| + | 64.0 | -.1172E+01 | 65.0 | .1099E+01 | 66.0 | .6152E+00 | 67.0 | .2637E+00 |
| + | 68.0 | -.1904E+00 | 69.0 | -.5859E-01 | 70.0 | .4980E+00 | 71.0 | .1069E+01 |
| 122507 | 72.0 | .1216E+01 | 73.0 | .9814E+00 | 74.0 | .6738E+00 | 75.0 | .7617E+00 |
| + | 76.0 | .1099E+01 | 77.0 | .1187E+01 | 78.0 | .9229E+00 | 79.0 | .3662E+00 |
| + | 80.0 | -.4395E-01 | 81.0 | .2930E-01 | 82.0 | .3662E+00 | 83.0 | .4395E+00 |
| 122508 | 84.0 | .2783E+00 | 85.0 | .2637E+00 | 86.0 | .5127E+00 | 87.0 | .1099E+01 |
| + | 88.0 | .1509E+01 | 89.0 | .1421E+01 | 90.0 | .1172E+01 | 91.0 | .7471E+00 |
| + | 92.0 | .5273E+00 | 93.0 | .5273E+00 | 94.0 | .3516E+00 | 95.0 | -.4395E-01 |
| 122509 | 96.0 | -.2197E+00 | 97.0 | .5859E-01 | 98.0 | .6885E+00 | 99.0 | .1099E+01 |
| + | 100.0 | .1084E+01 | 101.0 | .9229E+00 | 102.0 | .9375E+00 | 103.0 | .1011E+01 |
| + | 104.0 | .9375E+00 | 105.0 | .5859E+00 | 106.0 | .5127E+00 | 107.0 | .7764E+00 |
| 122510 | 108.0 | .1069E+01 | 109.0 | .9229E+00 | 110.0 | .5566E+00 | 111.0 | .2637E+00 |
| + | 112.0 | .3516E+00 | 113.0 | .6738E+00 | 114.0 | .7764E+00 | 115.0 | .6738E+00 |
| + | 116.0 | .5273E+00 | 117.0 | .5273E+00 | 118.0 | .6885E+00 | 119.0 | .7617E+00 |
| 122511 | 120.0 | .6299E+00 | 121.0 | .6738E+00 | 122.0 | .1011E+01 | 123.0 | .1260E+01 |
| + | 124.0 | .1289E+01 | 125.0 | .1011E+01 | 126.0 | .7324E+00 | 127.0 | .5713E+00 |
| + | 128.0 | .6738E+00 | 129.0 | .5127E+00 | 130.0 | .1758E+00 | 131.0 | .1465E-01 |
| 122512 | 132.0 | .1025E+00 | 133.0 | .5420E+00 | 134.0 | .8203E+00 | 135.0 | .8496E+00 |
| + | 136.0 | .5420E+00 | 137.0 | .6885E+00 | 138.0 | .8203E+00 | 139.0 | .7764E+00 |
| + | 140.0 | .6006E+00 | 141.0 | .5273E+00 | 142.0 | .7764E+00 | 143.0 | .9229E+00 |
| 122513 | 144.0 | .9082E+00 | 145.0 | .5420E+00 | 146.0 | .3516E+00 | 147.0 | .4248E+00 |
| + | 148.0 | .6885E+00 | 149.0 | .7764E+00 | 150.0 | .6152E+00 | 151.0 | .5127E+00 |
| + | 152.0 | .4248E+00 | 153.0 | .7471E+00 | 154.0 | .1084E+01 | 155.0 | .1157E+01 |
| 122514 | 156.0 | .7764E+00 | 157.0 | .3076E+00 | 158.0 | .3076E+00 | 159.0 | .5127E+00 |
| + | 160.0 | .6445E+00 | 161.0 | .6006E+00 | 162.0 | .3662E+00 | 163.0 | .3516E+00 |
| + | 164.0 | .5859E+00 | 165.0 | .9375E+00 | 166.0 | .1128E+01 | 167.0 | .9229E+00 |
| 122515 | 168.0 | .3955E+00 | 169.0 | .1465E-01 | 170.0 | .2930E-01 | 171.0 | .5273E+00 |
| + | 172.0 | .1011E+01 | 173.0 | .1099E+01 | 174.0 | .1011E+01 | 175.0 | .8496E+00 |
| + | 176.0 | .9229E+00 | 177.0 | .1011E+01 | 178.0 | .9229E+00 | 179.0 | .4980E+00 |
| 122516 | 180.0 | .1465E+00 | 181.0 | .1465E-01 | 182.0 | .4395E+00 | 183.0 | .1011E+01 |
| + | 184.0 | .1348E+01 | 185.0 | .1318E+01 | 186.0 | .1187E+01 | 187.0 | .1113E+01 |
| + | 188.0 | .1099E+01 | 189.0 | .8496E+00 | 190.0 | .4980E+00 | 191.0 | .1904E+00 |
| 122517 | 192.0 | .1465E+00 | 193.0 | .1465E+00 | 194.0 | .1025E+00 | 195.0 | .1758E+00 |
| + | 196.0 | .6006E+00 | 197.0 | .1099E+01 | 198.0 | .1421E+01 | 199.0 | .1318E+01 |
| + | 200.0 | .9375E+00 | 201.0 | .5566E+00 | 202.0 | .4395E+00 | 203.0 | .2930E+00 |
| 122518 | 204.0 | .2783E+00 | 205.0 | .1904E+00 | 206.0 | .1904E+00 | 207.0 | .2783E+00 |
| + | 208.0 | .3516E+00 | 209.0 | .4980E+00 | 210.0 | .9375E+00 | 211.0 | .1406E+01 |
| + | 212.0 | .1392E+01 | 213.0 | .1025E+01 | 214.0 | .6006E+00 | 215.0 | .5273E+00 |
| 122519 | 216.0 | .6592E+00 | 217.0 | .8496E+00 | 218.0 | .9229E+00 | 219.0 | .6738E+00 |
| + | 220.0 | .3516E+00 | 221.0 | .2637E+00 | 222.0 | .3516E+00 | 223.0 | .6006E+00 |
| + | 224.0 | .8496E+00 | 225.0 | .1011E+01 | 226.0 | .9229E+00 | 227.0 | .6299E+00 |
| 122520 | 228.0 | .7764E+00 | 229.0 | .1099E+01 | 230.0 | .1421E+01 | 231.0 | .1421E+01 |
| + | 232.0 | .1201E+01 | 233.0 | .8496E+00 | 234.0 | .5713E+00 | 235.0 | .6885E+00 |
| + | 236.0 | .8057E+00 | 237.0 | .6592E+00 | 238.0 | .3662E+00 | 239.0 | .2930E-01 |
| 122521 | 240.0 | .5859E-01 | 241.0 | .6006E+00 | 242.0 | .1011E+01 | 243.0 | .9229E+00 |
| + | 244.0 | .4541E+00 | 245.0 | .5127E+00 | 246.0 | .8496E+00 | 247.0 | .1260E+01 |
| + | 248.0 | .1157E+01 | 249.0 | .8496E+00 | 250.0 | .4834E+00 | 251.0 | .3955E+00 |
| 122522 | 252.0 | .5273E+00 | 253.0 | .7617E+00 | 254.0 | .7617E+00 | 255.0 | .5127E+00 |
| + | 256.0 | .1904E+00 | 257.0 | .1025E+00 | 258.0 | .4395E+00 | 259.0 | .7764E+00 |
| + | 260.0 | .7764E+00 | 261.0 | .5859E+00 | 262.0 | .6885E+00 | 263.0 | .1187E+01 |
| 122523 | 264.0 | .1509E+01 | 265.0 | .1421E+01 | 266.0 | .1143E+01 | 267.0 | .6885E+00 |
| + | 268.0 | .3662E+00 | 269.0 | .3516E+00 | 270.0 | .5273E+00 | 271.0 | .6006E+00 |
| + | 272.0 | .6152E+00 | 273.0 | .6152E+00 | 274.0 | .6006E+00 | 275.0 | .8496E+00 |
| 122524 | 276.0 | .8789E+00 | 277.0 | .6592E+00 | 278.0 | .3076E+00 | 279.0 | .3076E+00 |
| + | 280.0 | .3516E+00 | 281.0 | .5127E+00 | 282.0 | .6006E+00 | 283.0 | .7617E+00 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| + | 284.0 | .1172E+01 | 285.0 | .1523E+01 | 286.0 | .1377E+01 | 287.0 | .1099E+01 |
| 122525 | 288.0 | .6885E+00 | 289.0 | .3955E+00 | 290.0 | .2637E+00 | 291.0 | .1904E+00 |
| + | 292.0 | -.4395E-01 | 293.0 | -.2490E+00 | 294.0 | -.2197E+00 | 295.0 | .1025E+00 |
| + | 296.0 | .4248E+00 | 297.0 | .7617E+00 | 298.0 | .1099E+01 | 299.0 | .1450E+01 |
| 122526 | 300.0 | .1597E+01 | 301.0 | .1392E+01 | 302.0 | .1084E+01 | 303.0 | .7178E+00 |
| + | 304.0 | .5127E+00 | 305.0 | .3809E+00 | 306.0 | .2344E+00 | 307.0 | .2930E-01 |
| + | 308.0 | .1465E-01 | 309.0 | .3809E+00 | 310.0 | .9229E+00 | 311.0 | .1172E+01 |
| 122527 | 312.0 | .1011E+01 | 313.0 | .7764E+00 | 314.0 | .6445E+00 | 315.0 | .6885E+00 |
| + | 316.0 | .3955E+00 | 317.0 | .1172E+00 | 318.0 | .1025E+00 | 319.0 | .5420E+00 |
| + | 320.0 | .1099E+01 | 321.0 | .1333E+01 | 322.0 | .1143E+01 | 323.0 | .6885E+00 |
| 122528 | 324.0 | .5127E+00 | 325.0 | .5127E+00 | 326.0 | .5273E+00 | 327.0 | .3662E+00 |
| + | 328.0 | .2930E-01 | 329.0 | .2930E-01 | 330.0 | .2930E+00 | 331.0 | .6006E+00 |
| + | 332.0 | .7764E+00 | 333.0 | .6592E+00 | 334.0 | .5859E+00 | 335.0 | .7617E+00 |
| 122529 | 336.0 | .1099E+01 | 337.0 | .1187E+01 | 338.0 | .1011E+01 | 339.0 | .6592E+00 |
| + | 340.0 | .5713E+00 | 341.0 | .6885E+00 | 342.0 | .6885E+00 | 343.0 | .4395E+00 |
| + | 344.0 | .2637E+00 | 345.0 | .3369E+00 | 346.0 | .6152E+00 | 347.0 | .9229E+00 |
| 122530 | 348.0 | .9229E+00 | 349.0 | .7178E+00 | 350.0 | .4688E+00 | 351.0 | .5273E+00 |
| + | 352.0 | .6006E+00 | 353.0 | .6885E+00 | 354.0 | .6885E+00 | 355.0 | .4395E+00 |
| + | 356.0 | .4395E+00 | 357.0 | .6738E+00 | 358.0 | .9229E+00 | 359.0 | .9229E+00 |
| 122531 | 360.0 | .9229E+00 | 361.0 | .1172E+01 | 362.0 | .1362E+01 | 363.0 | .1172E+01 |
| + | 364.0 | .6006E+00 | 365.0 | .1904E+00 | 366.0 | .1758E+00 | 367.0 | .3516E+00 |
| + | 368.0 | .5127E+00 | 369.0 | .5273E+00 | 370.0 | .3516E+00 | 371.0 | .3662E+00 |
| 122532 | 372.0 | .5127E+00 | 373.0 | .7764E+00 | 374.0 | .8936E+00 | 375.0 | .1011E+01 |
| + | 376.0 | .1099E+01 | 377.0 | .1025E+01 | 378.0 | .6738E+00 | 379.0 | .3369E+00 |
| + | 380.0 | .3516E+00 | 381.0 | .5713E+00 | 382.0 | .7910E+00 | 383.0 | .9229E+00 |
| 122533 | 384.0 | .8496E+00 | 385.0 | .8496E+00 | 386.0 | .1011E+01 | 387.0 | .1099E+01 |
| + | 388.0 | .8496E+00 | 389.0 | .5127E+00 | 390.0 | .1025E+00 | 391.0 | -.2197E+00 |
| + | 392.0 | -.4688E+00 | 393.0 | -.3809E+00 | 394.0 | .2930E-01 | 395.0 | .6152E+00 |
| 122534 | 396.0 | .1099E+01 | 397.0 | .1406E+01 | 398.0 | .1509E+01 | 399.0 | .1670E+01 |
| + | 400.0 | .1685E+01 | 401.0 | .1597E+01 | 402.0 | .1392E+01 | 403.0 | .1348E-01 |
| + | 404.0 | .1011E+01 | 405.0 | .5273E+00 | 406.0 | .8789E-01 | 407.0 | .2930E-01 |
| 122535 | 408.0 | .2051E+00 | 409.0 | .3516E+00 | 410.0 | .2637E+00 | 411.0 | .1904E+00 |
| + | 412.0 | .3516E+00 | 413.0 | .7617E+00 | 414.0 | .1187E+01 | 415.0 | .1421E+01 |
| + | 416.0 | .1406E+01 | 417.0 | .1260E+01 | 418.0 | .1099E+01 | 419.0 | .8350E+00 |
| 122536 | 420.0 | .6738E+00 | 421.0 | .6006E+00 | 422.0 | .5859E+00 | 423.0 | .7764E+00 |
| + | 424.0 | .9375E+00 | 425.0 | .7617E+00 | 426.0 | .4395E+00 | 427.0 | .2783E+00 |
| + | 428.0 | .4541E+00 | 429.0 | .8057E+00 | 430.0 | .8496E+00 | 431.0 | .5273E+00 |
| 122537 | 432.0 | .2783E+00 | 433.0 | .2783E+00 | 434.0 | .6006E+00 | 435.0 | .7764E+00 |
| + | 436.0 | .7764E+00 | 437.0 | .9375E+00 | 438.0 | .1333E+01 | 439.0 | .1523E+01 |
| + | 440.0 | .1333E+01 | 441.0 | .8496E+00 | 442.0 | .6738E+00 | 443.0 | .7031E+00 |
| 122538 | 444.0 | .8350E+00 | 445.0 | .6738E+00 | 446.0 | .3516E+00 | 447.0 | .1465E-01 |
| + | 448.0 | -.1318E+00 | 449.0 | .2930E-01 | 450.0 | .4102E+00 | 451.0 | .9082E+00 |
| + | 452.0 | .1245E+01 | 453.0 | .1348E+01 | 454.0 | .1333E+01 | 455.0 | .1274E+01 |
| 122539 | 456.0 | .1187E+01 | 457.0 | .1011E+01 | 458.0 | .6885E+00 | 459.0 | .4395E+00 |
| + | 460.0 | .5127E+00 | 461.0 | .6885E+00 | 462.0 | .7910E+00 | 463.0 | .6445E+00 |
| + | 464.0 | .6152E+00 | 465.0 | .5127E+00 | 466.0 | .5127E+00 | 467.0 | .6152E+00 |
| 122540 | 468.0 | .6152E+00 | 469.0 | .6006E+00 | 470.0 | .5127E+00 | 471.0 | .5566E+00 |
| + | 472.0 | .7764E+00 | 473.0 | .1025E+01 | 474.0 | .1245E+01 | 475.0 | .1348E+01 |
| + | 476.0 | .1348E+01 | 477.0 | .1069E+01 | 478.0 | .7471E+00 | 479.0 | .5127E+00 |
| 122541 | 480.0 | .3516E+00 | 481.0 | .3662E+00 | 482.0 | .3662E+00 | 483.0 | .6592E+00 |
| + | 484.0 | .8203E+00 | 485.0 | .8496E+00 | 486.0 | .6445E+00 | 487.0 | .4980E+00 |
| + | 488.0 | .5127E+00 | 489.0 | .7764E+00 | 490.0 | .9375E+00 | 491.0 | .9229E+00 |
| 122542 | 492.0 | .8350E+00 | 493.0 | .8203E+00 | 494.0 | .1011E+01 | 495.0 | .1157E+01 |
| + | 496.0 | .1128E+01 | 497.0 | .9521E+00 | 498.0 | .6885E+00 | 499.0 | .3516E+00 |
| + | 500.0 | .1904E+00 | 501.0 | .1758E+00 | 502.0 | .4395E+00 | 503.0 | .5566E+00 |
| 122543 | 504.0 | .5127E+00 | 505.0 | .5273E+00 | 506.0 | .8203E+00 | 507.0 | .1099E+01 |
| + | 508.0 | .1011E+01 | 509.0 | .4541E+00 | 510.0 | .2930E-01 | 511.0 | .1904E+00 |
| + | 512.0 | .7617E+00 | 513.0 | .1011E+01 | 514.0 | .7910E+00 | 515.0 | .4395E+00 |
| 122544 | 516.0 | .3516E+00 | 517.0 | .6006E+00 | 518.0 | .9229E+00 | 519.0 | .1011E+01 |
| + | 520.0 | .9229E+00 | 521.0 | .6738E+00 | 522.0 | .4980E+00 | 523.0 | .4541E+00 |
| + | 524.0 | .3955E+00 | 525.0 | .1904E+00 | 526.0 | -.5859E-01 | 527.0 | -.1025E+00 |
| 122545 | 528.0 | .1904E+00 | 529.0 | .6006E+00 | 530.0 | .9375E+00 | 531.0 | .1084E+01 |
| + | 532.0 | .1040E+01 | 533.0 | .9229E+00 | 534.0 | .7617E+00 | 535.0 | .8350E+00 |
| + | 536.0 | .1099E+01 | 537.0 | .1260E+01 | 538.0 | .1143E+01 | 539.0 | .6006E+00 |
| 122546 | 540.0 | .1025E+00 | 541.0 | .4395E-01 | 542.0 | .2783E+00 | 543.0 | .4248E+00 |
| + | 544.0 | .5273E+00 | 545.0 | .5127E+00 | 546.0 | .6006E+00 | 547.0 | .7617E+00 |
| + | 548.0 | .8643E+00 | 549.0 | .8496E+00 | 550.0 | .7617E+00 | 551.0 | .6152E+00 |
| 122547 | 552.0 | .5273E+00 | 553.0 | .6006E+00 | 554.0 | .8496E+00 | 555.0 | .1011E+01 |
| + | 556.0 | .9229E+00 | 557.0 | .6006E+00 | 558.0 | .6885E+00 | 559.0 | .1011E+01 |
| + | 560.0 | .1099E+01 | 561.0 | .7324E+00 | 562.0 | .2783E+00 | 563.0 | .7324E-01 |
| 122548 | 564.0 | .2783E+00 | 565.0 | .7617E+00 | 566.0 | .1099E+01 | 567.0 | .1025E+01 |
| + | 568.0 | .6885E+00 | 569.0 | .6738E+00 | 570.0 | .1084E+01 | 571.0 | .1348E+01 |
| + | 572.0 | .1348E+01 | 573.0 | .1333E+01 | 574.0 | .1216E+01 | 575.0 | .8350E+00 |
| 122549 | 576.0 | .2637E+00 | 577.0 | -.4395E-01 | 578.0 | .2930E-01 | 579.0 | .1904E+00 |
| + | 580.0 | .2490E+00 | 581.0 | .3223E+00 | 582.0 | .5273E+00 | 583.0 | .7617E+00 |
| + | 584.0 | .1084E+01 | 585.0 | .1216E+01 | 586.0 | .1099E+01 | 587.0 | .8496E+00 |
| 122550 | 588.0 | .6885E+00 | 589.0 | .7617E+00 | 590.0 | .7617E+00 | 591.0 | .3809E+00 |
| + | 592.0 | .0000E+00 | 593.0 | -.4395E-01 | 594.0 | .4395E+00 | 595.0 | .8350E+00 |
| + | 596.0 | .7471E+00 | 597.0 | .4834E+00 | 598.0 | .3662E+00 | 599.0 | .6885E+00 |
| 122551 | 600.0 | .1099E+01 | 601.0 | .1099E+01 | 602.0 | .9229E+00 | 603.0 | .7324E+00 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| + | 604.0 | .7764E+00 | 605.0 | .7617E+00 | 606.0 | .7471E+00 | 607.0 | .6738E+00 |
| + | 608.0 | .6006E+00 | 609.0 | .3809E+00 | 610.0 | .2637E+00 | 611.0 | .2637E+00 |
| 122552 | 612.0 | .3662E+00 | 613.0 | .5127E+00 | 614.0 | .6152E+00 | 615.0 | .6006E+00 |
| + | 616.0 | .6885E+00 | 617.0 | .7764E+00 | 618.0 | .8350E+00 | 619.0 | .8496E+00 |
| + | 620.0 | .8496E+00 | 621.0 | .8496E+00 | 622.0 | .7617E+00 | 623.0 | .6299E+00 |
| 122553 | 624.0 | .5127E+00 | 625.0 | .6006E+00 | 626.0 | .7617E+00 | 627.0 | .6592E+00 |
| + | 628.0 | .3662E+00 | 629.0 | .3516E+00 | 630.0 | .4248E+00 | 631.0 | .4688E+00 |
| + | 632.0 | .3809E+00 | 633.0 | .3516E+00 | 634.0 | .3516E+00 | 635.0 | .6006E+00 |
| 122554 | 636.0 | .9229E+00 | 637.0 | .1172E+01 | 638.0 | .1187E+01 | 639.0 | .9229E+00 |
| + | 640.0 | .7471E+00 | 641.0 | .8496E+00 | 642.0 | .1113E+01 | 643.0 | .1187E+01 |
| + | 644.0 | .8496E+00 | 645.0 | .3662E+00 | 646.0 | .1172E+00 | 647.0 | .3516E+00 |
| 122555 | 648.0 | .6885E+00 | 649.0 | .7764E+00 | 650.0 | .6006E+00 | 651.0 | .3223E+00 |
| + | 652.0 | .1025E+00 | 653.0 | .1904E+00 | 654.0 | .4395E+00 | 655.0 | .7617E+00 |
| + | 656.0 | .1011E+01 | 657.0 | .1172E+01 | 658.0 | .1113E+01 | 659.0 | .1099E+01 |
| 122556 | 660.0 | .1245E+01 | 661.0 | .1494E+01 | 662.0 | .1597E+01 | 663.0 | .1128E+01 |
| + | 664.0 | .3516E+00 | 665.0 | -.1611E+00 | 666.0 | -.2197E+00 | 667.0 | -.1318E+00 |
| + | 668.0 | .2930E-01 | 669.0 | .8789E-01 | 670.0 | .3516E+00 | 671.0 | .1011E+01 |
| 122557 | 672.0 | .1670E+01 | 673.0 | .1919E+01 | 674.0 | .1465E+01 | 675.0 | .7324E+00 |
| + | 676.0 | .3662E+00 | 677.0 | .3516E+00 | 678.0 | .5273E+00 | 679.0 | .3516E+00 |
| + | 680.0 | .1904E+00 | 681.0 | .2051E+00 | 682.0 | .5127E+00 | 683.0 | .6006E+00 |
| 122558 | 684.0 | .4102E+00 | 685.0 | .3516E+00 | 686.0 | .5127E+00 | 687.0 | .8643E+00 |
| + | 688.0 | .1011E+01 | 689.0 | .9375E+00 | 690.0 | .7617E+00 | 691.0 | .8203E+00 |
| + | 692.0 | .1187E+01 | 693.0 | .1406E+01 | 694.0 | .1157E+01 | 695.0 | .6738E+00 |
| 122559 | 696.0 | .3516E+00 | 697.0 | .4395E+00 | 698.0 | .6152E+00 | 699.0 | .5127E+00 |
| + | 700.0 | .2930E-01 | 701.0 | -.3076E+00 | 702.0 | -.1611E+00 | 703.0 | .5127E+00 |
| + | 704.0 | .1172E+01 | 705.0 | .1348E+01 | 706.0 | .1099E+01 | 707.0 | .6006E+00 |
| 122560 | 708.0 | .5127E+00 | 709.0 | .9375E+00 | 710.0 | .1348E+01 | 711.0 | .1201E+01 |
| + | 712.0 | .6445E+00 | 713.0 | .1904E+00 | 714.0 | .2197E+00 | 715.0 | .6885E+00 |
| + | 716.0 | .7764E+00 | 717.0 | .3662E+00 | 718.0 | .1758E+00 | 719.0 | .5127E+00 |
| 122561 | 720.0 | .1172E+01 | 721.0 | .1348E+01 | 722.0 | .1011E+01 | 723.0 | .6006E+00 |
| + | 724.0 | .8496E+00 | 725.0 | .1187E+01 | 726.0 | .1128E+01 | 727.0 | .6592E+00 |
| + | 728.0 | .2783E+00 | 729.0 | .2637E+00 | 730.0 | .5273E+00 | 731.0 | .5273E+00 |
| 122562 | 732.0 | .3516E+00 | 733.0 | .3516E+00 | 734.0 | .5127E+00 | 735.0 | .7178E+00 |
| + | 736.0 | .7764E+00 | 737.0 | .9229E+00 | 738.0 | .1187E+01 | 739.0 | .1348E+01 |
| + | 740.0 | .1172E+01 | 741.0 | .7764E+00 | 742.0 | .3369E+00 | 743.0 | .1904E+00 |
| 122563 | 744.0 | .3662E+00 | 745.0 | .6738E+00 | 746.0 | .7617E+00 | 747.0 | .5127E+00 |
| + | 748.0 | .2783E+00 | 749.0 | .3662E+00 | 750.0 | .7617E+00 | 751.0 | .9375E+00 |
| + | 752.0 | .8350E+00 | 753.0 | .6738E+00 | 754.0 | .5127E+00 | 755.0 | .3369E+00 |
| 122564 | 756.0 | .3516E+00 | 757.0 | .6738E+00 | 758.0 | .1099E+01 | 759.0 | .1216E+01 |
| + | 760.0 | .1128E+01 | 761.0 | .1055E+01 | 762.0 | .9961E+00 | 763.0 | .6006E+00 |
| + | 764.0 | .1172E+00 | 765.0 | .1465E-01 | 766.0 | .3516E+00 | 767.0 | .6738E+00 |
| 122565 | 768.0 | .6885E+00 | 769.0 | .5127E+00 | 770.0 | .3516E+00 | 771.0 | .5273E+00 |
| + | 772.0 | .9229E+00 | 773.0 | .1172E+01 | 774.0 | .1099E+01 | 775.0 | .7617E+00 |
| + | 776.0 | .6006E+00 | 777.0 | .6885E+00 | 778.0 | .8203E+00 | 779.0 | .7031E+00 |
| 122566 | 780.0 | .3955E+00 | | | | | | |
| 122600 | 781 | | | | | | | |
| | | | | | | | | |
| 122601 | .0 | .8301E-01 | 1.0 | .1953E+00 | 2.0 | .2539E+00 | 3.0 | .2295E+00 |
| + | 4.0 | .1270E+00 | 5.0 | -.2441E-01 | 6.0 | -.1465E+00 | 7.0 | -.3271E+00 |
| + | 8.0 | -.4688E+00 | 9.0 | -.5127E+00 | 10.0 | -.4248E+00 | 11.0 | -.1563E+00 |
| 122602 | 12.0 | .2588E+00 | 13.0 | .4688E+00 | 14.0 | .3613E+00 | 15.0 | .1953E+00 |
| + | 16.0 | .1611E+00 | 17.0 | .1904E+00 | 18.0 | .1318E+00 | 19.0 | .5371E-01 |
| + | 20.0 | -.1025E+00 | 21.0 | .1514E+00 | 22.0 | .7813E-01 | 23.0 | -.8301E-01 |
| 122603 | 24.0 | -.2148E+00 | 25.0 | -.1953E+00 | 26.0 | -.9277E-01 | 27.0 | .9766E-02 |
| + | 28.0 | .1660E+00 | 29.0 | .3516E+00 | 30.0 | .4883E+00 | 31.0 | .4248E+00 |
| + | 32.0 | .2441E+00 | 33.0 | .2930E-01 | 34.0 | -.1953E+00 | 35.0 | -.2441E+00 |
| 122604 | 36.0 | -.1465E+00 | 37.0 | -.7324E-01 | 38.0 | .5371E-01 | 39.0 | .1758E+00 |
| + | 40.0 | .2197E+00 | 41.0 | .7324E-01 | 42.0 | -.2051E+00 | 43.0 | -.4150E+00 |
| + | 44.0 | -.5371E+00 | 45.0 | -.5762E+00 | 46.0 | -.5078E+00 | 47.0 | -.2881E+00 |
| 122605 | 48.0 | -.5859E-01 | 49.0 | .1416E+00 | 50.0 | .1807E+00 | 51.0 | .3906E-01 |
| + | 52.0 | -.1074E+00 | 53.0 | -.2441E+00 | 54.0 | -.3125E+00 | 55.0 | -.3223E+00 |
| + | 56.0 | -.4053E+00 | 57.0 | -.4443E+00 | 58.0 | -.3809E+00 | 59.0 | -.2441E+00 |
| 122606 | 60.0 | -.1221E+00 | 61.0 | -.1025E+00 | 62.0 | -.6836E-01 | 63.0 | -.9766E-02 |
| + | 64.0 | -.4395E-01 | 65.0 | -.1221E+00 | 66.0 | -.2002E+00 | 67.0 | -.3320E+00 |
| + | 68.0 | -.5127E+00 | 69.0 | -.5322E+00 | 70.0 | -.4102E+00 | 71.0 | -.2197E+00 |
| 122607 | 72.0 | -.9277E-01 | 73.0 | -.3906E-01 | 74.0 | -.4883E-02 | 75.0 | .4883E-01 |
| + | 76.0 | .1172E+00 | 77.0 | .1709E+00 | 78.0 | .2393E+00 | 79.0 | .3125E+00 |
| + | 80.0 | .2441E+00 | 81.0 | -.6836E-01 | 82.0 | -.3857E+00 | 83.0 | -.5029E+00 |
| 122608 | 84.0 | -.4004E+00 | 85.0 | -.2490E+00 | 86.0 | -.1221E+00 | 87.0 | .8789E-01 |
| + | 88.0 | .3076E+00 | 89.0 | .4248E+00 | 90.0 | .3076E+00 | 91.0 | .1074E+00 |
| + | 92.0 | .2441E-01 | 93.0 | .4395E-01 | 94.0 | -.4883E-02 | 95.0 | -.1025E+00 |
| 122609 | 96.0 | -.1270E+00 | 97.0 | -.6348E-01 | 98.0 | .0000E+00 | 99.0 | .6836E-01 |
| + | 100.0 | .1904E+00 | 101.0 | .3271E+00 | 102.0 | .3613E+00 | 103.0 | .3369E+00 |
| + | 104.0 | .2686E+00 | 105.0 | .6348E-01 | 106.0 | -.6348E-01 | 107.0 | -.1025E+00 |
| 122610 | 108.0 | -.1318E+00 | 109.0 | -.2637E+00 | 110.0 | -.3027E+00 | 111.0 | -.1221E+00 |
| + | 112.0 | .8301E-01 | 113.0 | .2344E+00 | 114.0 | .2490E+00 | 115.0 | .2100E+00 |
| + | 116.0 | .1807E+00 | 117.0 | .1855E+00 | 118.0 | .2148E+00 | 119.0 | .2197E+00 |
| 122611 | 120.0 | .2490E+00 | 121.0 | .3027E+00 | 122.0 | .2441E+00 | 123.0 | -.1953E-01 |
| + | 124.0 | -.3027E+00 | 125.0 | -.4053E+00 | 126.0 | -.3857E+00 | 127.0 | -.3369E+00 |
| + | 128.0 | -.2783E+00 | 129.0 | -.1953E+00 | 130.0 | -.1367E+00 | 131.0 | -.6836E-01 |
| 122612 | 132.0 | -.9766E-02 | 133.0 | .1953E-01 | 134.0 | -.1172E+00 | 135.0 | -.2246E+00 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| + | 135.0 | -.1172E+00 | 137.0 | -.5371E-01 | 138.0 | -.1465E+00 | 139.0 | -.2002E+00 |
| + | 140.0 | -.1123E+00 | 141.0 | -.1172E+00 | 142.0 | -.2686E+00 | 143.0 | -.4346E+00 |
| 122613 | 144.0 | -.5127E+00 | 145.0 | -.5518E+00 | 146.0 | -.5420E+00 | 147.0 | -.4492E+00 |
| + | 148.0 | -.2002E+00 | 149.0 | .8789E-01 | 150.0 | .2197E+00 | 151.0 | .1904E+00 |
| + | 152.0 | -.6836E-01 | 153.0 | .5371E-01 | 154.0 | .8301E-01 | 155.0 | .3418E-01 |
| 122614 | 156.0 | -.1465E+00 | 157.0 | -.3711E+00 | 158.0 | -.4834E+00 | 159.0 | -.2783E+00 |
| + | 160.0 | -.1074E+00 | 161.0 | .3955E+00 | 162.0 | .3857E+00 | 163.0 | .2295E+00 |
| + | 164.0 | .6348E-01 | 165.0 | -.1221E+00 | 166.0 | -.2539E+00 | 167.0 | -.2490E+00 |
| 122615 | 168.0 | -.1318E+00 | 169.0 | .4395E-01 | 170.0 | .1758E+00 | 171.0 | .2881E+00 |
| + | 172.0 | .3955E+00 | 173.0 | .3809E+00 | 174.0 | .2148E+00 | 175.0 | .4883E-01 |
| + | 176.0 | -.4395E-01 | 177.0 | .1465E-01 | 178.0 | .1514E+00 | 179.0 | .2246E+00 |
| 122616 | 180.0 | -.1318E+00 | 181.0 | -.1465E-01 | 182.0 | -.6836E-01 | 183.0 | -.1465E-01 |
| + | 184.0 | -.2441E-01 | 185.0 | .9766E-01 | 186.0 | .1611E+00 | 187.0 | .1709E+00 |
| + | 188.0 | .2100E+00 | 189.0 | .2344E+00 | 190.0 | .1318E+00 | 191.0 | -.1465E-01 |
| 122617 | 192.0 | -.1123E+00 | 193.0 | -.2393E+00 | 194.0 | -.2832E+00 | 195.0 | -.2588E+00 |
| + | 196.0 | -.2100E+00 | 197.0 | -.1855E+00 | 198.0 | -.1514E+00 | 199.0 | -.1563E+00 |
| + | 200.0 | -.2002E+00 | 201.0 | -.2393E+00 | 202.0 | -.1807E+00 | 203.0 | -.1221E+00 |
| 122618 | 204.0 | -.1416E+00 | 205.0 | -.2197E+00 | 206.0 | -.2148E+00 | 207.0 | -.2100E+00 |
| + | 208.0 | -.2588E+00 | 209.0 | -.3516E+00 | 210.0 | -.3711E+00 | 211.0 | -.2100E+00 |
| + | 212.0 | -.5371E-01 | 213.0 | .1465E-01 | 214.0 | -.9766E-02 | 215.0 | -.1514E+00 |
| 122619 | 216.0 | -.3516E+00 | 217.0 | -.4395E+00 | 218.0 | -.3711E+00 | 219.0 | -.2881E+00 |
| + | 220.0 | -.2686E+00 | 221.0 | -.1416E+00 | 222.0 | .0000E+00 | 223.0 | .9277E-01 |
| + | 224.0 | .8789E-01 | 225.0 | -.2930E-01 | 226.0 | -.2051E+00 | 227.0 | -.2734E+00 |
| 122620 | 228.0 | -.2051E+00 | 229.0 | .1465E-01 | 230.0 | .1758E+00 | 231.0 | .1807E+00 |
| + | 232.0 | .1074E+00 | 233.0 | .0000E+00 | 234.0 | -.1318E+00 | 235.0 | -.1660E+00 |
| + | 236.0 | -.2051E+00 | 237.0 | -.2881E+00 | 238.0 | -.2002E+00 | 239.0 | .6836E-01 |
| 122621 | 240.0 | .2490E+00 | 241.0 | .2832E+00 | 242.0 | .2783E+00 | 243.0 | .2148E+00 |
| + | 244.0 | .1025E+00 | 245.0 | -.4883E-02 | 246.0 | -.4883E-02 | 247.0 | .1318E+00 |
| + | 248.0 | .3174E+00 | 249.0 | .4248E+00 | 250.0 | .4102E+00 | 251.0 | .2734E+00 |
| 122622 | 252.0 | .1367E+00 | 253.0 | .1025E+00 | 254.0 | .4883E-01 | 255.0 | -.3906E-01 |
| + | 256.0 | -.6348E-01 | 257.0 | -.5371E-01 | 258.0 | -.8789E-01 | 259.0 | -.1123E+00 |
| + | 260.0 | -.8789E-01 | 261.0 | -.9766E-02 | 262.0 | .4883E-02 | 263.0 | .0000E+00 |
| 122623 | 264.0 | .1123E+00 | 265.0 | .2832E+00 | 266.0 | .3271E+00 | 267.0 | .2588E+00 |
| + | 268.0 | .1416E+00 | 269.0 | .1172E+00 | 270.0 | .4395E-01 | 271.0 | -.7813E-01 |
| + | 272.0 | -.2002E+00 | 273.0 | -.3564E+00 | 274.0 | -.4247E+00 | 275.0 | -.3320E+00 |
| 122624 | 276.0 | -.2148E+00 | 277.0 | -.7813E-01 | 278.0 | .1025E+00 | 279.0 | .2588E+00 |
| + | 280.0 | .2295E+00 | 281.0 | .5371E-01 | 282.0 | -.8789E-01 | 283.0 | -.1953E+00 |
| + | 284.0 | -.3125E+00 | 285.0 | -.3711E+00 | 286.0 | -.3125E+00 | 287.0 | -.1758E+00 |
| 122625 | 288.0 | -.1025E+00 | 289.0 | -.1221E+00 | 290.0 | -.1074E+00 | 291.0 | -.9277E-01 |
| + | 292.0 | -.1123E+00 | 293.0 | -.1660E+00 | 294.0 | -.2588E+00 | 295.0 | -.4639E+00 |
| + | 296.0 | -.5957E+00 | 297.0 | -.5615E+00 | 298.0 | -.3857E+00 | 299.0 | -.1221E+00 |
| 122626 | 300.0 | .4395E-01 | 301.0 | .1318E+00 | 302.0 | .2197E+00 | 303.0 | .2148E+00 |
| + | 304.0 | .6348E-01 | 305.0 | -.1074E+00 | 306.0 | -.1416E+00 | 307.0 | -.2246E+00 |
| + | 308.0 | -.3955E+00 | 309.0 | -.5078E+00 | 310.0 | -.4785E+00 | 311.0 | -.4590E+00 |
| 122627 | 312.0 | -.4590E+00 | 313.0 | -.3662E+00 | 314.0 | -.2441E+00 | 315.0 | -.1123E+00 |
| + | 316.0 | .4395E-01 | 317.0 | .2148E+00 | 318.0 | .3271E+00 | 319.0 | .2881E+00 |
| + | 320.0 | .1318E+00 | 321.0 | .5371E-01 | 322.0 | .9277E-01 | 323.0 | .6348E-01 |
| 122628 | 324.0 | -.7813E-01 | 325.0 | -.2490E+00 | 326.0 | -.3027E+00 | 327.0 | -.1611E+00 |
| + | 328.0 | .5371E-01 | 329.0 | .2148E+00 | 330.0 | .2637E+00 | 331.0 | .3076E+00 |
| + | 332.0 | .3418E+00 | 333.0 | .2881E+00 | 334.0 | .1074E+00 | 335.0 | -.3906E-01 |
| 122629 | 336.0 | -.3906E-01 | 337.0 | .0000E+00 | 338.0 | -.1465E-01 | 339.0 | -.5371E-01 |
| + | 340.0 | .4883E-02 | 341.0 | .1172E+00 | 342.0 | .1465E+00 | 343.0 | .1123E+00 |
| + | 344.0 | .1514E+00 | 345.0 | .3027E+00 | 346.0 | .4541E+00 | 347.0 | .4541E+00 |
| 122630 | 348.0 | .2734E+00 | 349.0 | .7324E-01 | 350.0 | -.1270E+00 | 351.0 | -.2979E+00 |
| + | 352.0 | -.3369E+00 | 353.0 | -.3467E+00 | 354.0 | -.2686E+00 | 355.0 | -.1611E+00 |
| + | 356.0 | -.9766E-01 | 357.0 | -.8301E-01 | 358.0 | -.3906E-01 | 359.0 | -.9277E-01 |
| 122631 | 360.0 | -.2393E+00 | 361.0 | -.2148E+00 | 362.0 | -.9766E-01 | 363.0 | -.4883E-01 |
| + | 364.0 | -.4395E-01 | 365.0 | .9277E-01 | 366.0 | .2148E+00 | 367.0 | .1172E+00 |
| + | 368.0 | -.1563E+00 | 369.0 | -.4150E+00 | 370.0 | -.5615E+00 | 371.0 | -.5273E+00 |
| 122632 | 372.0 | -.4248E+00 | 373.0 | -.3906E+00 | 374.0 | -.3662E+00 | 375.0 | -.3564E+00 |
| + | 376.0 | -.3223E+00 | 377.0 | -.2393E+00 | 378.0 | -.1855E+00 | 379.0 | -.1904E+00 |
| + | 380.0 | -.1563E+00 | 381.0 | -.1025E+00 | 382.0 | -.5371E-01 | 383.0 | -.9766E-02 |
| 122633 | 384.0 | .1465E-01 | 385.0 | -.2930E-01 | 386.0 | -.1367E+00 | 387.0 | -.3076E+00 |
| + | 388.0 | -.3955E+00 | 389.0 | -.3271E+00 | 390.0 | -.1221E+00 | 391.0 | .1025E+00 |
| + | 392.0 | .2092E+00 | 393.0 | .1221E+00 | 394.0 | .0000E+00 | 395.0 | -.3906E-01 |
| 122634 | 396.0 | -.9766E-01 | 397.0 | -.2393E+00 | 398.0 | -.2783E+00 | 399.0 | -.2295E+00 |
| + | 400.0 | -.1904E+00 | 401.0 | -.6836E-01 | 402.0 | .9766E-02 | 403.0 | .4395E-01 |
| + | 404.0 | -.5371E-01 | 405.0 | .1416E+00 | 406.0 | .2588E+00 | 407.0 | .3418E+00 |
| 122635 | 408.0 | .3320E+00 | 409.0 | .2832E+00 | 410.0 | .2002E+00 | 411.0 | .1514E+00 |
| + | 412.0 | .2100E+00 | 413.0 | .2393E+00 | 414.0 | .1221E+00 | 415.0 | -.8301E-01 |
| + | 416.0 | -.1367E+00 | 417.0 | -.3906E-01 | 418.0 | -.5371E-01 | 419.0 | -.9766E-01 |
| 122636 | 420.0 | -.4395E-01 | 421.0 | .8301E-01 | 422.0 | .1807E+00 | 423.0 | .2686E+00 |
| + | 424.0 | .2734E+00 | 425.0 | .2148E+00 | 426.0 | .2051E+00 | 427.0 | .2881E+00 |
| + | 428.0 | .3271E+00 | 429.0 | .3027E+00 | 430.0 | .2637E+00 | 431.0 | .2002E+00 |
| 122637 | 432.0 | .1123E+00 | 433.0 | .6836E-01 | 434.0 | -.1318E+00 | 435.0 | -.2979E+00 |
| + | 436.0 | -.3809E+00 | 437.0 | -.3760E+00 | 438.0 | -.3809E+00 | 439.0 | -.2979E+00 |
| + | 440.0 | -.3418E-01 | 441.0 | .2686E+00 | 442.0 | .3613E+00 | 443.0 | .2637E+00 |
| 122638 | 444.0 | .1123E+00 | 445.0 | .4883E-02 | 446.0 | -.1953E-01 | 447.0 | .5859E-01 |
| + | 448.0 | -.1123E+00 | 449.0 | -.3613E+00 | 450.0 | -.4150E+00 | 451.0 | -.2588E+00 |
| + | 452.0 | -.2002E+00 | 453.0 | -.2930E+00 | 454.0 | -.4150E+00 | 455.0 | -.4883E+00 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| 122639 | 456.0 | -.3955E+00 | 457.0 | -.2393E+00 | 458.0 | -.2246E+00 | 459.0 | -.2246E+00 |
| + | 460.0 | -.7324E-01 | 461.0 | -.8789E-01 | 462.0 | -.1514E+00 | 463.0 | -.1123E+00 |
| + | 464.0 | -.7324E-01 | 465.0 | -.3076E+00 | 466.0 | -.4346E+00 | 467.0 | -.3662E+00 |
| 122640 | 468.0 | -.2246E+00 | 469.0 | -.1514E+00 | 470.0 | -.1416E+00 | 471.0 | -.1904E+00 |
| + | 472.0 | -.2295E+00 | 473.0 | -.1660E+00 | 474.0 | -.6348E-01 | 475.0 | -.4395E-01 |
| + | 476.0 | -.5371E-01 | 477.0 | -.3906E-01 | 478.0 | -.1172E+00 | 479.0 | -.1660E+00 |
| 122641 | 480.0 | -.1123E+00 | 481.0 | -.1953E-01 | 482.0 | -.1758E+00 | 483.0 | -.2539E+00 |
| + | 484.0 | -.2832E+00 | 485.0 | -.2344E+00 | 486.0 | -.1611E+00 | 487.0 | -.4395E-01 |
| + | 488.0 | -.1172E+00 | 489.0 | -.2686E+00 | 490.0 | -.3418E+00 | 491.0 | -.3125E+00 |
| 122642 | 492.0 | -.2393E+00 | 493.0 | -.2148E+00 | 494.0 | -.1172E+00 | 495.0 | -.3418E-01 |
| + | 496.0 | -.1855E+00 | 497.0 | -.3076E+00 | 498.0 | -.4492E+00 | 499.0 | -.5127E+00 |
| + | 500.0 | -.4053E+00 | 501.0 | -.7813E-01 | 502.0 | -.2100E+00 | 503.0 | -.3027E+00 |
| 122643 | 504.0 | -.3760E+00 | 505.0 | -.4590E+00 | 506.0 | -.5029E+00 | 507.0 | -.4199E+00 |
| + | 508.0 | -.1807E+00 | 509.0 | -.1465E-01 | 510.0 | -.5371E-01 | 511.0 | -.9766E-01 |
| + | 512.0 | -.1123E+00 | 513.0 | -.1660E+00 | 514.0 | -.2490E+00 | 515.0 | -.3613E+00 |
| 122644 | 516.0 | -.4688E+00 | 517.0 | -.4688E+00 | 518.0 | -.3564E+00 | 519.0 | -.1807E+00 |
| + | 520.0 | -.1465E-01 | 521.0 | -.7813E-01 | 522.0 | -.1855E+00 | 523.0 | -.3076E+00 |
| + | 524.0 | -.3369E+00 | 525.0 | -.3125E+00 | 526.0 | -.2295E+00 | 527.0 | -.2930E-01 |
| 122645 | 528.0 | -.3223E+00 | 529.0 | -.6290E+00 | 530.0 | -.8252E+00 | 531.0 | -.7861E+00 |
| + | 532.0 | -.5713E+00 | 533.0 | -.3271E+00 | 534.0 | -.3418E-01 | 535.0 | -.4590E+00 |
| + | 536.0 | -.6299E+00 | 537.0 | -.4639E+00 | 538.0 | -.1318E+00 | 539.0 | -.1416E+00 |
| 122646 | 540.0 | -.2783E+00 | 541.0 | -.4102E+00 | 542.0 | -.4932E+00 | 543.0 | -.4785E+00 |
| + | 544.0 | -.3027E+00 | 545.0 | -.0000E+00 | 546.0 | -.1904E+00 | 547.0 | -.1367E+00 |
| + | 548.0 | -.4395E-01 | 549.0 | -.4883E-01 | 550.0 | -.4883E-01 | 551.0 | -.6348E-01 |
| 122647 | 552.0 | -.2930E-01 | 553.0 | -.1855E+00 | 554.0 | -.1465E+00 | 555.0 | -.2441E-01 |
| + | 556.0 | -.8301E-01 | 557.0 | -.1172E+00 | 558.0 | -.1514E+00 | 559.0 | -.1025E+00 |
| + | 560.0 | -.8789E-01 | 561.0 | -.1953E-01 | 562.0 | -.6836E-01 | 563.0 | -.1709E+00 |
| 122648 | 564.0 | -.2051E+00 | 565.0 | -.1123E+00 | 566.0 | -.5371E-01 | 567.0 | -.1416E+00 |
| + | 568.0 | -.1709E+00 | 569.0 | -.3076E+00 | 570.0 | -.4443E+00 | 571.0 | -.3955E+00 |
| + | 572.0 | -.2588E+00 | 573.0 | -.1514E+00 | 574.0 | -.6836E-01 | 575.0 | -.5371E-01 |
| 122649 | 576.0 | -.1660E+00 | 577.0 | -.2490E+00 | 578.0 | -.3027E+00 | 579.0 | -.2002E+00 |
| + | 580.0 | -.3418E-01 | 581.0 | -.3906E-01 | 582.0 | -.1465E-01 | 583.0 | -.6348E-01 |
| + | 584.0 | -.7813E-01 | 585.0 | -.0000E+00 | 586.0 | -.1025E+00 | 587.0 | -.1416E+00 |
| 122650 | 588.0 | -.1904E+00 | 589.0 | -.2783E+00 | 590.0 | -.3125E+00 | 591.0 | -.1563E+00 |
| + | 592.0 | -.5859E-01 | 593.0 | -.2002E+00 | 594.0 | -.3564E+00 | 595.0 | -.5273E+00 |
| + | 596.0 | -.5469E+00 | 597.0 | -.5029E+00 | 598.0 | -.5811E+00 | 599.0 | -.5908E+00 |
| 122651 | 600.0 | -.3467E+00 | 601.0 | -.6348E-01 | 602.0 | -.3516E+00 | 603.0 | -.3369E+00 |
| + | 604.0 | -.2734E+00 | 605.0 | -.2393E+00 | 606.0 | -.1514E+00 | 607.0 | -.2441E-01 |
| + | 608.0 | -.1904E+00 | 609.0 | -.4004E+00 | 610.0 | -.5273E+00 | 611.0 | -.5176E+00 |
| 122652 | 612.0 | -.4199E+00 | 613.0 | -.3662E+00 | 614.0 | -.2637E+00 | 615.0 | -.1953E-01 |
| + | 616.0 | -.2100E+00 | 617.0 | -.1123E+00 | 618.0 | -.7813E-01 | 619.0 | -.1367E+00 |
| + | 620.0 | -.1953E-01 | 621.0 | -.3906E-01 | 622.0 | -.5371E-01 | 623.0 | -.2002E+00 |
| 122653 | 624.0 | -.2637E+00 | 625.0 | -.1270E+00 | 626.0 | -.3418E-01 | 627.0 | -.1904E+00 |
| + | 628.0 | -.2979E+00 | 629.0 | -.2197E+00 | 630.0 | -.1953E-01 | 631.0 | -.9277E-01 |
| + | 632.0 | -.1807E+00 | 633.0 | -.1904E+00 | 634.0 | -.1367E+00 | 635.0 | -.6348E-01 |
| 122654 | 636.0 | -.5371E-01 | 637.0 | -.4883E-01 | 638.0 | -.6836E-01 | 639.0 | -.1563E+00 |
| + | 640.0 | -.1855E+00 | 641.0 | -.6348E-01 | 642.0 | -.1318E+00 | 643.0 | -.3564E+00 |
| + | 644.0 | -.5078E+00 | 645.0 | -.4590E+00 | 646.0 | -.2783E+00 | 647.0 | -.6836E-01 |
| 122655 | 648.0 | -.8301E-01 | 649.0 | -.1611E+00 | 650.0 | -.1758E+00 | 651.0 | -.1855E+00 |
| + | 652.0 | -.2393E+00 | 653.0 | -.2686E+00 | 654.0 | -.2100E+00 | 655.0 | -.1318E+00 |
| + | 656.0 | -.5371E-01 | 657.0 | -.1465E-01 | 658.0 | -.8789E-01 | 659.0 | -.2393E+00 |
| 122656 | 660.0 | -.2783E+00 | 661.0 | -.1855E+00 | 662.0 | -.5371E-01 | 663.0 | -.4395E-01 |
| + | 664.0 | -.5859E-01 | 665.0 | -.0000E+00 | 666.0 | -.1465E-01 | 667.0 | -.8301E-01 |
| + | 668.0 | -.1172E+00 | 669.0 | -.1367E+00 | 670.0 | -.2979E+00 | 671.0 | -.5078E+00 |
| 122657 | 672.0 | -.5176E+00 | 673.0 | -.3564E+00 | 674.0 | -.1611E+00 | 675.0 | -.2441E-01 |
| + | 676.0 | -.9277E-01 | 677.0 | -.7813E-01 | 678.0 | -.1367E+00 | 679.0 | -.2881E+00 |
| + | 680.0 | -.2490E+00 | 681.0 | -.4883E-02 | 682.0 | -.3027E+00 | 683.0 | -.5273E+00 |
| 122658 | 684.0 | -.5273E+00 | 685.0 | -.3125E+00 | 686.0 | -.2441E-01 | 687.0 | -.2100E+00 |
| + | 688.0 | -.2246E+00 | 689.0 | -.8789E-01 | 690.0 | -.3418E-01 | 691.0 | -.1025E+00 |
| + | 692.0 | -.1465E+00 | 693.0 | -.1904E+00 | 694.0 | -.2490E+00 | 695.0 | -.3613E+00 |
| 122659 | 696.0 | -.3418E+00 | 697.0 | -.1172E+00 | 698.0 | -.2295E+00 | 699.0 | -.5176E+00 |
| + | 700.0 | -.4883E+00 | 701.0 | -.2344E+00 | 702.0 | -.2930E-01 | 703.0 | -.2588E+00 |
| + | 704.0 | -.3418E+00 | 705.0 | -.2832E+00 | 706.0 | -.1465E+00 | 707.0 | -.5859E-01 |
| 122660 | 708.0 | -.4883E-01 | 709.0 | -.0000E+00 | 710.0 | -.1318E+00 | 711.0 | -.3174E+00 |
| + | 712.0 | -.3369E+00 | 713.0 | -.2100E+00 | 714.0 | -.3418E-01 | 715.0 | -.6348E-01 |
| + | 716.0 | -.8789E-01 | 717.0 | -.1416E+00 | 718.0 | -.2344E+00 | 719.0 | -.2002E+00 |
| 122661 | 720.0 | -.1465E-01 | 721.0 | -.1465E+00 | 722.0 | -.1953E+00 | 723.0 | -.2051E+00 |
| + | 724.0 | -.2686E+00 | 725.0 | -.3662E+00 | 726.0 | -.3955E+00 | 727.0 | -.3516E+00 |
| + | 728.0 | -.1611E+00 | 729.0 | -.4883E-01 | 730.0 | -.2441E+00 | 731.0 | -.3955E+00 |
| 122662 | 732.0 | -.3955E+00 | 733.0 | -.3271E+00 | 734.0 | -.3271E+00 | 735.0 | -.3369E+00 |
| + | 736.0 | -.2100E+00 | 737.0 | -.4883E-02 | 738.0 | -.1709E+00 | 739.0 | -.2930E+00 |
| + | 740.0 | -.2783E+00 | 741.0 | -.2441E+00 | 742.0 | -.2100E+00 | 743.0 | -.7813E-01 |
| 122663 | 744.0 | -.1563E+00 | 745.0 | -.3271E+00 | 746.0 | -.3467E+00 | 747.0 | -.3027E+00 |
| + | 748.0 | -.3564E+00 | 749.0 | -.3662E+00 | 750.0 | -.3516E+00 | 751.0 | -.2588E+00 |
| + | 752.0 | -.1660E+00 | 753.0 | -.3418E-01 | 754.0 | -.2295E+00 | 755.0 | -.3390E+00 |
| 122664 | 756.0 | -.2197E+00 | 757.0 | -.1953E-01 | 758.0 | -.1807E+00 | 759.0 | -.3418E+00 |
| + | 760.0 | -.3271E+00 | 761.0 | -.2637E+00 | 762.0 | -.2441E+00 | 763.0 | -.2588E+00 |
| + | 764.0 | -.2295E+00 | 765.0 | -.1514E+00 | 766.0 | -.1074E+00 | 767.0 | -.7813E-01 |
| 122665 | 768.0 | -.5859E-01 | 769.0 | -.4395E-01 | 770.0 | -.1563E+00 | 771.0 | -.3418E+00 |
| + | 772.0 | -.3809E+00 | 773.0 | -.2734E+00 | 774.0 | -.2295E+00 | 775.0 | -.2148E+00 |

| | | | | | | | | |
|--------|-------|-----------------------------------|-------|------------|-------|------------|-------|------------|
| | 776.0 | -.1660E+00 | 777.0 | -.1660E+00 | 778.0 | -.1074E+00 | 779.0 | -.3418E-01 |
| 122666 | 780.0 | -.7813E-01 | | | | | | |
| 122700 | 781 | * RIGHT AND LEFT ACCELERATION (G) | | | | | | |
| 122701 | .0 | -.1465E-01 | 1.0 | -.8789E-02 | 2.0 | .2441E-02 | 3.0 | .1416E-01 |
| + | 4.0 | -.1855E-01 | 5.0 | .1123E-01 | 6.0 | .4883E-03 | 7.0 | -.3906E-02 |
| + | 8.0 | -.5859E-02 | 9.0 | -.5859E-02 | 10.0 | -.5859E-02 | 11.0 | -.7324E-02 |
| 122702 | 12.0 | -.4883E-03 | 13.0 | .1172E-01 | 14.0 | .1514E-01 | 15.0 | .4883E-02 |
| + | 16.0 | -.1953E-02 | 17.0 | .0000E+00 | 18.0 | .4883E-02 | 19.0 | .6348E-02 |
| + | 20.0 | .3906E-02 | 21.0 | .2441E-02 | 22.0 | -.7813E-02 | 23.0 | -.1465E-01 |
| 122703 | 24.0 | -.1563E-01 | 25.0 | -.8789E-02 | 26.0 | .4883E-02 | 27.0 | .1563E-01 |
| + | 28.0 | .1758E-01 | 29.0 | .1025E-01 | 30.0 | -.7813E-02 | 31.0 | -.1416E-01 |
| + | 32.0 | -.1367E-01 | 33.0 | -.1074E-01 | 34.0 | -.9766E-03 | 35.0 | -.9766E-02 |
| 122704 | 36.0 | .1025E-01 | 37.0 | .3418E-02 | 38.0 | -.9766E-02 | 39.0 | -.9766E-02 |
| + | 40.0 | -.1465E-02 | 41.0 | .7813E-02 | 42.0 | .9766E-02 | 43.0 | .6836E-02 |
| + | 44.0 | -.4883E-03 | 45.0 | -.6836E-02 | 46.0 | -.1172E-01 | 47.0 | -.1465E-01 |
| 122705 | 48.0 | -.8301E-02 | 49.0 | -.7813E-02 | 50.0 | -.1514E-01 | 51.0 | -.8301E-02 |
| + | 52.0 | .1270E-01 | 53.0 | .2539E-01 | 54.0 | .2686E-01 | 55.0 | .1953E-01 |
| + | 56.0 | .4883E-03 | 57.0 | -.2344E-01 | 58.0 | -.3809E-01 | 59.0 | -.2441E-01 |
| 122706 | 60.0 | .4883E-02 | 61.0 | .1563E-01 | 62.0 | .1221E-01 | 63.0 | -.1465E-02 |
| + | 64.0 | -.3418E-02 | 65.0 | .6836E-02 | 66.0 | .1123E-01 | 67.0 | .7324E-02 |
| + | 68.0 | -.7813E-02 | 69.0 | -.2344E-01 | 70.0 | -.2100E-01 | 71.0 | -.7324E-02 |
| 122707 | 72.0 | .5859E-02 | 73.0 | .7813E-02 | 74.0 | .6836E-02 | 75.0 | -.3418E-02 |
| + | 76.0 | -.9766E-02 | 77.0 | -.1367E-01 | 78.0 | -.1514E-01 | 79.0 | -.2930E-02 |
| + | 80.0 | .1416E-01 | 81.0 | .1318E-01 | 82.0 | .1074E-01 | 83.0 | .4395E-02 |
| 122708 | 84.0 | .1953E-02 | 85.0 | -.1465E-02 | 86.0 | -.1318E-01 | 87.0 | -.2588E-01 |
| + | 88.0 | -.2246E-01 | 89.0 | -.5371E-02 | 90.0 | .3418E-02 | 91.0 | .2930E-02 |
| + | 92.0 | .7813E-02 | 93.0 | .1416E-01 | 94.0 | .1025E-01 | 95.0 | -.4883E-03 |
| 122709 | 96.0 | -.1172E-01 | 97.0 | -.1318E-01 | 98.0 | -.1318E-01 | 99.0 | -.1221E-01 |
| + | 100.0 | -.6836E-02 | 101.0 | -.7324E-02 | 102.0 | -.1953E-02 | 103.0 | .4395E-02 |
| + | 104.0 | .2002E-01 | 105.0 | .2637E-01 | 106.0 | .1318E-01 | 107.0 | -.9766E-03 |
| 122710 | 108.0 | -.7813E-02 | 109.0 | -.1318E-01 | 110.0 | -.1416E-01 | 111.0 | -.1123E-01 |
| + | 112.0 | -.4883E-03 | 113.0 | .3418E-02 | 114.0 | .2930E-02 | 115.0 | .1025E-01 |
| + | 116.0 | .2246E-01 | 117.0 | .1807E-01 | 118.0 | .3906E-02 | 119.0 | -.1709E-01 |
| 122711 | 120.0 | -.2734E-01 | 121.0 | -.1563E-01 | 122.0 | -.2930E-02 | 123.0 | .3418E-02 |
| + | 124.0 | .1465E-02 | 125.0 | .4883E-02 | 126.0 | .1660E-01 | 127.0 | .1465E-01 |
| + | 128.0 | -.9766E-03 | 129.0 | -.1416E-01 | 130.0 | -.1709E-01 | 131.0 | -.1660E-01 |
| 122712 | 132.0 | -.1123E-01 | 133.0 | -.9277E-02 | 134.0 | -.1221E-01 | 135.0 | -.2051E-01 |
| + | 136.0 | -.1221E-01 | 137.0 | .7813E-02 | 138.0 | .1514E-01 | 139.0 | .7324E-02 |
| + | 140.0 | .1953E-02 | 141.0 | .0000E+00 | 142.0 | .8789E-02 | 143.0 | .5371E-02 |
| 122713 | 144.0 | -.9277E-02 | 145.0 | -.2051E-01 | 146.0 | -.2881E-01 | 147.0 | -.3076E-01 |
| + | 148.0 | -.2148E-01 | 149.0 | -.6348E-02 | 150.0 | .6836E-02 | 151.0 | .1172E-01 |
| + | 152.0 | .7813E-02 | 153.0 | -.1465E-02 | 154.0 | -.4883E-03 | 155.0 | .1465E-02 |
| 122714 | 156.0 | -.1465E-02 | 157.0 | -.5859E-02 | 158.0 | -.2148E-01 | 159.0 | -.2588E-01 |
| + | 160.0 | -.1221E-01 | 161.0 | .6348E-02 | 162.0 | .1416E-01 | 163.0 | .1123E-01 |
| + | 164.0 | .5859E-02 | 165.0 | -.4395E-02 | 166.0 | -.7813E-02 | 167.0 | -.4883E-02 |
| 122715 | 168.0 | -.1465E-02 | 169.0 | -.3906E-02 | 170.0 | -.8789E-02 | 171.0 | -.5371E-02 |
| + | 172.0 | .4883E-02 | 173.0 | .1416E-01 | 174.0 | .1807E-01 | 175.0 | .1025E-01 |
| + | 176.0 | .9766E-03 | 177.0 | -.3418E-02 | 178.0 | -.3418E-02 | 179.0 | .1953E-02 |
| 122716 | 180.0 | .7813E-02 | 181.0 | .5371E-02 | 182.0 | -.1465E-02 | 183.0 | -.4395E-02 |
| + | 184.0 | -.4883E-03 | 185.0 | .3418E-02 | 186.0 | -.4395E-02 | 187.0 | -.1123E-01 |
| + | 188.0 | -.6836E-02 | 189.0 | .3418E-02 | 190.0 | .2930E-02 | 191.0 | .5859E-02 |
| 122717 | 192.0 | .7813E-02 | 193.0 | .5371E-02 | 194.0 | -.5859E-02 | 195.0 | -.1416E-01 |
| + | 196.0 | -.1855E-01 | 197.0 | -.1904E-01 | 198.0 | -.1367E-01 | 199.0 | .1953E-02 |
| + | 200.0 | .1563E-01 | 201.0 | .1660E-01 | 202.0 | .5859E-02 | 203.0 | -.1221E-01 |
| 122718 | 204.0 | -.2588E-01 | 205.0 | -.2832E-01 | 206.0 | -.1904E-01 | 207.0 | .4883E-03 |
| + | 208.0 | .1270E-01 | 209.0 | .1025E-01 | 210.0 | -.4883E-02 | 211.0 | -.7324E-02 |
| + | 212.0 | -.4883E-03 | 213.0 | .1465E-02 | 214.0 | -.8789E-02 | 215.0 | -.1270E-01 |
| 122719 | 216.0 | .0000E+00 | 217.0 | .1221E-01 | 218.0 | .1904E-01 | 219.0 | .7813E-02 |
| + | 220.0 | -.9766E-02 | 221.0 | -.1611E-01 | 222.0 | -.1172E-01 | 223.0 | -.4883E-02 |
| + | 224.0 | -.4883E-03 | 225.0 | .3418E-02 | 226.0 | .6348E-02 | 227.0 | .9277E-02 |
| 122720 | 228.0 | .1221E-01 | 229.0 | .1953E-01 | 230.0 | .1270E-01 | 231.0 | -.9277E-02 |
| + | 232.0 | -.1904E-01 | 233.0 | -.1563E-01 | 234.0 | -.2930E-02 | 235.0 | .5859E-02 |
| + | 236.0 | .3906E-02 | 237.0 | -.5371E-02 | 238.0 | -.1953E-02 | 239.0 | .6836E-02 |
| 122721 | 240.0 | .6836E-02 | 241.0 | -.2930E-02 | 242.0 | -.5371E-02 | 243.0 | .1953E-02 |
| + | 244.0 | .4395E-02 | 245.0 | -.4883E-03 | 246.0 | -.6348E-02 | 247.0 | .9766E-03 |
| + | 248.0 | .3418E-02 | 249.0 | .1465E-02 | 250.0 | -.2441E-02 | 251.0 | -.4883E-02 |
| 122722 | 252.0 | -.2441E-02 | 253.0 | .3906E-02 | 254.0 | .1074E-01 | 255.0 | .7813E-02 |
| + | 256.0 | .2930E-02 | 257.0 | -.4883E-02 | 258.0 | -.1221E-01 | 259.0 | -.1123E-01 |
| + | 260.0 | -.3906E-02 | 261.0 | .6836E-02 | 262.0 | .7813E-02 | 263.0 | .4883E-02 |
| 122723 | 264.0 | -.4883E-03 | 265.0 | -.5859E-02 | 266.0 | -.2441E-02 | 267.0 | -.7813E-02 |
| + | 268.0 | -.1123E-01 | 269.0 | -.2441E-02 | 270.0 | .6836E-02 | 271.0 | .1123E-01 |
| + | 272.0 | .6836E-02 | 273.0 | .4883E-03 | 274.0 | -.3418E-02 | 275.0 | -.2930E-02 |
| 122724 | 276.0 | -.1465E-02 | 277.0 | .1465E-02 | 278.0 | .0000E+00 | 279.0 | .4883E-03 |
| + | 280.0 | .4883E-03 | 281.0 | .5371E-02 | 282.0 | .3418E-02 | 283.0 | .1953E-02 |
| + | 284.0 | .9277E-02 | 285.0 | .2441E-02 | 286.0 | -.8789E-02 | 287.0 | -.5859E-02 |
| 122725 | 288.0 | .5371E-02 | 289.0 | .1465E-02 | 290.0 | -.8789E-02 | 291.0 | -.7324E-02 |
| + | 292.0 | .2930E-02 | 293.0 | .4883E-02 | 294.0 | .2930E-02 | 295.0 | -.3906E-02 |
| + | 296.0 | -.1025E-01 | 297.0 | -.5859E-02 | 298.0 | .0000E+00 | 299.0 | .1465E-02 |
| 122726 | 300.0 | -.9766E-03 | 301.0 | -.6348E-02 | 302.0 | -.4395E-02 | 303.0 | .3906E-02 |
| + | 304.0 | .8301E-02 | 305.0 | .1123E-01 | 306.0 | .1758E-01 | 307.0 | .1318E-01 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| + | 308.0 | -.4395E-02 | 309.0 | -.1953E-01 | 310.0 | -.2148E-01 | 311.0 | -.1074E-01 |
| 122727 | 312.0 | .3418E-02 | 313.0 | .3418E-02 | 314.0 | -.5371E-02 | 315.0 | -.7813E-02 |
| + | 316.0 | .0000E+00 | 317.0 | .1074E-01 | 318.0 | .1514E-01 | 319.0 | .1025E-01 |
| + | 320.0 | -.7813E-02 | 321.0 | -.1416E-01 | 322.0 | -.6348E-02 | 323.0 | .6348E-02 |
| 122728 | 324.0 | .2441E-02 | 325.0 | -.9766E-02 | 326.0 | -.1367E-01 | 327.0 | -.4395E-02 |
| + | 328.0 | -.1465E-01 | 329.0 | -.2295E-01 | 330.0 | .1563E-01 | 331.0 | .2441E-02 |
| + | 332.0 | -.4395E-02 | 333.0 | -.7324E-02 | 334.0 | -.1025E-01 | 335.0 | -.4395E-02 |
| 122729 | 336.0 | .1953E-02 | 337.0 | .2441E-02 | 338.0 | .4883E-03 | 339.0 | -.1953E-02 |
| + | 340.0 | .9277E-02 | 341.0 | .1514E-01 | 342.0 | .1172E-01 | 343.0 | .3906E-02 |
| + | 344.0 | -.6836E-02 | 345.0 | -.1172E-01 | 346.0 | -.1660E-01 | 347.0 | -.2246E-01 |
| 122730 | 348.0 | -.2148E-01 | 349.0 | -.3906E-02 | 350.0 | .1758E-01 | 351.0 | .3027E-01 |
| + | 352.0 | .2490E-01 | 353.0 | -.8789E-02 | 354.0 | -.8301E-02 | 355.0 | -.1514E-01 |
| + | 356.0 | -.1318E-01 | 357.0 | -.1172E-01 | 358.0 | -.8301E-02 | 359.0 | -.2441E-02 |
| 122731 | 360.0 | .9766E-03 | 361.0 | -.6836E-02 | 362.0 | .1025E-01 | 363.0 | .3418E-02 |
| + | 364.0 | -.5371E-02 | 365.0 | -.3418E-02 | 366.0 | .1953E-02 | 367.0 | .4395E-02 |
| + | 368.0 | .0000E+00 | 369.0 | -.5859E-02 | 370.0 | -.1953E-02 | 371.0 | .1465E-02 |
| 122732 | 372.0 | -.4883E-03 | 373.0 | -.4395E-02 | 374.0 | -.2441E-02 | 375.0 | .2930E-02 |
| + | 376.0 | .3906E-02 | 377.0 | .3418E-02 | 378.0 | .1953E-02 | 379.0 | -.9766E-03 |
| + | 380.0 | -.4883E-02 | 381.0 | -.8789E-02 | 382.0 | -.1660E-01 | 383.0 | -.9277E-02 |
| 122733 | 384.0 | .6836E-02 | 385.0 | .1416E-01 | 386.0 | .1123E-01 | 387.0 | .2441E-02 |
| + | 388.0 | -.5859E-02 | 389.0 | -.7813E-02 | 390.0 | -.4395E-02 | 391.0 | .0000E+00 |
| + | 392.0 | .3418E-02 | 393.0 | .0000E+00 | 394.0 | .0000E+00 | 395.0 | -.1953E-02 |
| 122734 | 396.0 | .6836E-02 | 397.0 | .6836E-02 | 398.0 | .5371E-02 | 399.0 | .5371E-02 |
| + | 400.0 | .0000E+00 | 401.0 | -.9766E-02 | 402.0 | -.2002E-01 | 403.0 | -.2295E-01 |
| + | 404.0 | -.4883E-02 | 405.0 | .1611E-01 | 406.0 | .1807E-01 | 407.0 | .1416E-01 |
| 122735 | 408.0 | -.1953E-02 | 409.0 | -.1563E-01 | 410.0 | -.1904E-01 | 411.0 | -.1221E-01 |
| + | 412.0 | -.4883E-03 | 413.0 | .1025E-01 | 414.0 | .1074E-01 | 415.0 | .1025E-01 |
| + | 416.0 | .6836E-02 | 417.0 | .4395E-02 | 418.0 | -.4395E-02 | 419.0 | -.1465E-01 |
| 122736 | 420.0 | -.1318E-01 | 421.0 | -.7813E-02 | 422.0 | -.4883E-02 | 423.0 | .4883E-02 |
| + | 424.0 | .1953E-02 | 425.0 | -.5371E-02 | 426.0 | -.9766E-02 | 427.0 | -.2441E-02 |
| + | 428.0 | .1465E-01 | 429.0 | .1611E-01 | 430.0 | .1221E-01 | 431.0 | -.1953E-02 |
| 122737 | 432.0 | -.1172E-01 | 433.0 | -.1855E-01 | 434.0 | -.1563E-01 | 435.0 | -.2930E-02 |
| + | 436.0 | .1758E-01 | 437.0 | .2734E-01 | 438.0 | .1318E-01 | 439.0 | -.6836E-02 |
| + | 440.0 | -.1855E-01 | 441.0 | -.1855E-01 | 442.0 | -.1221E-01 | 443.0 | -.3418E-02 |
| 122738 | 444.0 | .1465E-02 | 445.0 | .6348E-02 | 446.0 | .9766E-02 | 447.0 | .9277E-02 |
| + | 448.0 | .4395E-02 | 449.0 | -.4395E-02 | 450.0 | -.7324E-02 | 451.0 | -.9766E-02 |
| + | 452.0 | -.5371E-02 | 453.0 | -.3906E-02 | 454.0 | -.9766E-03 | 455.0 | .2930E-02 |
| 122739 | 456.0 | .2930E-02 | 457.0 | .4883E-02 | 458.0 | .2930E-02 | 459.0 | -.5859E-02 |
| + | 460.0 | -.7324E-02 | 461.0 | -.5859E-02 | 462.0 | -.7813E-02 | 463.0 | -.8789E-02 |
| + | 464.0 | -.5859E-02 | 465.0 | .4883E-03 | 466.0 | .9277E-02 | 467.0 | .1953E-01 |
| 122740 | 468.0 | .1416E-01 | 469.0 | .2930E-02 | 470.0 | -.2441E-02 | 471.0 | -.2930E-02 |
| + | 472.0 | -.1953E-02 | 473.0 | -.3418E-02 | 474.0 | -.6836E-02 | 475.0 | .3906E-02 |
| + | 476.0 | -.4883E-03 | 477.0 | -.6348E-02 | 478.0 | -.9766E-03 | 479.0 | .9766E-02 |
| 122741 | 480.0 | .1367E-01 | 481.0 | .1465E-01 | 482.0 | .1465E-01 | 483.0 | .7324E-02 |
| + | 484.0 | .9766E-03 | 485.0 | -.5859E-02 | 486.0 | -.1025E-01 | 487.0 | -.1123E-01 |
| + | 488.0 | -.1221E-01 | 489.0 | -.1221E-01 | 490.0 | -.2441E-02 | 491.0 | .1318E-01 |
| 122742 | 492.0 | .2295E-01 | 493.0 | .1563E-01 | 494.0 | .7813E-02 | 495.0 | -.4883E-02 |
| + | 496.0 | -.1025E-01 | 497.0 | -.1465E-02 | 498.0 | .6836E-02 | 499.0 | .3906E-02 |
| + | 500.0 | -.7324E-02 | 501.0 | -.1025E-01 | 502.0 | -.3906E-02 | 503.0 | .1953E-02 |
| 122743 | 504.0 | .2930E-02 | 505.0 | .2930E-02 | 506.0 | .4395E-02 | 507.0 | -.3418E-02 |
| + | 508.0 | -.8301E-02 | 509.0 | -.8301E-02 | 510.0 | -.4883E-03 | 511.0 | .1123E-01 |
| + | 512.0 | .1367E-01 | 513.0 | .9766E-02 | 514.0 | -.5371E-02 | 515.0 | -.1416E-01 |
| 122744 | 516.0 | -.1123E-01 | 517.0 | -.9766E-03 | 518.0 | .7324E-02 | 519.0 | .8789E-02 |
| + | 520.0 | .9766E-03 | 521.0 | -.9766E-02 | 522.0 | -.1465E-01 | 523.0 | -.1270E-01 |
| + | 524.0 | -.9277E-02 | 525.0 | -.4395E-02 | 526.0 | -.4883E-03 | 527.0 | .2930E-02 |
| 122745 | 528.0 | .1709E-01 | 529.0 | .2441E-01 | 530.0 | .1514E-01 | 531.0 | .2930E-02 |
| + | 532.0 | -.6348E-02 | 533.0 | -.1953E-01 | 534.0 | -.2295E-01 | 535.0 | -.1074E-01 |
| + | 536.0 | .1465E-02 | 537.0 | .9766E-03 | 538.0 | -.5371E-02 | 539.0 | .3418E-02 |
| 122746 | 540.0 | .2246E-01 | 541.0 | .2197E-01 | 542.0 | .4883E-02 | 543.0 | -.1367E-01 |
| + | 544.0 | -.1514E-01 | 545.0 | -.3906E-02 | 546.0 | .5859E-02 | 547.0 | .9766E-03 |
| + | 548.0 | -.6348E-02 | 549.0 | .1465E-02 | 550.0 | .1172E-01 | 551.0 | .1221E-01 |
| 122747 | 552.0 | -.2930E-02 | 553.0 | -.1514E-01 | 554.0 | -.1074E-01 | 555.0 | .6348E-02 |
| + | 556.0 | .1563E-01 | 557.0 | .1074E-01 | 558.0 | -.4883E-03 | 559.0 | -.7813E-02 |
| + | 560.0 | -.5371E-02 | 561.0 | -.3906E-02 | 562.0 | .2930E-02 | 563.0 | .4395E-02 |
| 122748 | 564.0 | .9766E-03 | 565.0 | .1953E-02 | 566.0 | .4395E-02 | 567.0 | -.9766E-03 |
| + | 568.0 | -.5371E-02 | 569.0 | -.1465E-02 | 570.0 | .4883E-02 | 571.0 | -.9766E-03 |
| + | 572.0 | -.8789E-02 | 573.0 | -.1270E-01 | 574.0 | -.6836E-02 | 575.0 | .1953E-02 |
| 122749 | 576.0 | .5371E-02 | 577.0 | .4883E-02 | 578.0 | -.5371E-02 | 579.0 | -.5859E-02 |
| + | 580.0 | .8301E-02 | 581.0 | .1660E-01 | 582.0 | .1318E-01 | 583.0 | -.3418E-02 |
| + | 584.0 | -.2100E-01 | 585.0 | -.2295E-01 | 586.0 | -.1025E-01 | 587.0 | -.9766E-03 |
| 122750 | 588.0 | .2441E-02 | 589.0 | -.9766E-03 | 590.0 | -.9766E-03 | 591.0 | .3418E-02 |
| + | 592.0 | -.4883E-03 | 593.0 | -.5859E-02 | 594.0 | -.2930E-02 | 595.0 | .4883E-02 |
| + | 596.0 | .9766E-02 | 597.0 | .5859E-02 | 598.0 | -.1172E-01 | 599.0 | -.3223E-01 |
| 122751 | 600.0 | -.3223E-01 | 601.0 | -.1172E-01 | 602.0 | .8789E-02 | 603.0 | .9277E-02 |
| + | 604.0 | -.1465E-02 | 605.0 | -.6836E-02 | 606.0 | -.2930E-02 | 607.0 | .1465E-02 |
| + | 608.0 | -.3906E-02 | 609.0 | -.1025E-01 | 610.0 | -.1367E-01 | 611.0 | -.8301E-02 |
| 122752 | 612.0 | .4395E-02 | 613.0 | .9766E-02 | 614.0 | .4395E-02 | 615.0 | -.1465E-02 |
| + | 616.0 | -.4883E-02 | 617.0 | -.1172E-01 | 618.0 | -.9766E-02 | 619.0 | -.4883E-02 |
| + | 620.0 | .8789E-02 | 621.0 | .1904E-01 | 622.0 | .1709E-01 | 623.0 | .4883E-03 |
| 122753 | 624.0 | -.1123E-01 | 625.0 | -.1172E-01 | 626.0 | -.2441E-02 | 627.0 | .1465E-02 |

| | | | | | | | | |
|--------|-------|--------------------------------|-------|------------|-------|------------|-------|------------|
| + | 628.0 | .1465E-02 | 629.0 | .8301E-02 | 630.0 | .1270E-01 | 631.0 | .1514E-01 |
| + | 632.0 | .1123E-01 | 633.0 | -.4883E-02 | 634.0 | -.1611E-01 | 635.0 | -.1514E-01 |
| 122754 | 636.0 | -.7813E-02 | 637.0 | .5859E-02 | 638.0 | .1660E-01 | 639.0 | .1465E-01 |
| + | 640.0 | .1465E-02 | 641.0 | -.4883E-02 | 642.0 | -.1270E-01 | 643.0 | -.1563E-01 |
| + | 644.0 | -.1025E-01 | 645.0 | .1465E-02 | 646.0 | .1611E-01 | 647.0 | .1855E-01 |
| 122755 | 648.0 | .6836E-02 | 649.0 | -.7324E-02 | 650.0 | -.1318E-01 | 651.0 | .1953E-02 |
| + | 652.0 | .1270E-01 | 653.0 | .1025E-01 | 654.0 | -.4883E-02 | 655.0 | -.1904E-01 |
| + | 656.0 | -.1318E-01 | 657.0 | -.4395E-02 | 658.0 | -.9766E-03 | 659.0 | .8301E-02 |
| 122756 | 660.0 | .1758E-01 | 661.0 | .1060E-01 | 662.0 | .6348E-02 | 663.0 | -.1172E-01 |
| + | 664.0 | -.2100E-01 | 665.0 | -.2002E-01 | 666.0 | -.8301E-02 | 667.0 | .8789E-02 |
| + | 668.0 | .2197E-01 | 669.0 | .2393E-01 | 670.0 | .1465E-01 | 671.0 | -.1953E-02 |
| 122757 | 672.0 | -.1709E-01 | 673.0 | -.1807E-01 | 674.0 | -.1416E-01 | 675.0 | -.1953E-02 |
| + | 676.0 | .8301E-02 | 677.0 | .3418E-02 | 678.0 | -.5371E-02 | 679.0 | -.1025E-01 |
| + | 680.0 | -.3418E-02 | 681.0 | .1123E-01 | 682.0 | .2100E-01 | 683.0 | .1514E-01 |
| 122758 | 684.0 | -.2930E-02 | 685.0 | -.1611E-01 | 686.0 | -.6836E-02 | 687.0 | .7324E-02 |
| + | 688.0 | .1465E-02 | 689.0 | -.1025E-01 | 690.0 | -.1563E-01 | 691.0 | -.3418E-02 |
| + | 692.0 | .1367E-01 | 693.0 | .1318E-01 | 694.0 | .8789E-02 | 695.0 | .1953E-02 |
| 122759 | 696.0 | -.9766E-02 | 697.0 | -.1221E-01 | 698.0 | -.1270E-01 | 699.0 | -.1025E-01 |
| + | 700.0 | -.4395E-02 | 701.0 | .5371E-02 | 702.0 | .1953E-01 | 703.0 | .1855E-01 |
| + | 704.0 | .4883E-02 | 705.0 | -.7324E-02 | 706.0 | -.3418E-02 | 707.0 | .6836E-02 |
| 122760 | 708.0 | .9766E-03 | 709.0 | -.1074E-01 | 710.0 | -.1660E-01 | 711.0 | -.1025E-01 |
| + | 712.0 | .2930E-02 | 713.0 | .1270E-01 | 714.0 | .1514E-01 | 715.0 | .4395E-02 |
| + | 716.0 | -.4395E-02 | 717.0 | -.9766E-03 | 718.0 | .5371E-02 | 719.0 | .1025E-01 |
| 122761 | 720.0 | .5371E-02 | 721.0 | -.6348E-02 | 722.0 | -.1465E-01 | 723.0 | -.2295E-01 |
| + | 724.0 | -.1807E-01 | 725.0 | -.1953E-02 | 726.0 | .8789E-02 | 727.0 | -.1270E-01 |
| + | 728.0 | .1465E-01 | 729.0 | .1465E-02 | 730.0 | -.2930E-02 | 731.0 | -.6348E-02 |
| 122762 | 732.0 | -.3418E-02 | 733.0 | .0000E+00 | 734.0 | .9766E-03 | 735.0 | -.4395E-02 |
| + | 736.0 | -.5859E-02 | 737.0 | -.2441E-02 | 738.0 | -.1465E-02 | 739.0 | .2441E-02 |
| + | 740.0 | .4883E-03 | 741.0 | -.4883E-03 | 742.0 | .3418E-02 | 743.0 | .1172E-01 |
| 122763 | 744.0 | .2441E-02 | 745.0 | -.1060E-01 | 746.0 | -.2295E-01 | 747.0 | -.7813E-02 |
| + | 748.0 | .2930E-02 | 749.0 | .4883E-02 | 750.0 | .7324E-02 | 751.0 | .8789E-02 |
| + | 752.0 | -.4383E-03 | 753.0 | -.1465E-01 | 754.0 | -.1709E-01 | 755.0 | -.1416E-01 |
| 122764 | 756.0 | -.1514E-01 | 757.0 | -.1611E-01 | 758.0 | -.9766E-02 | 759.0 | .1953E-02 |
| + | 760.0 | .1367E-01 | 761.0 | .1904E-01 | 762.0 | .1465E-01 | 763.0 | .3418E-02 |
| + | 764.0 | -.9766E-02 | 765.0 | -.1709E-01 | 766.0 | -.1807E-01 | 767.0 | -.8789E-02 |
| 122765 | 768.0 | .2441E-02 | 769.0 | .4395E-02 | 770.0 | -.4883E-03 | 771.0 | -.2930E-02 |
| + | 772.0 | -.1465E-02 | 773.0 | .2441E-02 | 774.0 | .7813E-02 | 775.0 | .5859E-02 |
| + | 776.0 | -.1465E-02 | 777.0 | -.8789E-02 | 778.0 | -.1318E-01 | 779.0 | -.4395E-02 |
| 122766 | 780.0 | .8789E-02 | | | | | | |
| 122800 | 781 | * NO.2 S.G. Z-ACCELERATION (G) | | | | | | |
| 122801 | .0 | .4433E-01 | 1.0 | .4494E-01 | 2.0 | .4190E-01 | 3.0 | .3158E-01 |
| 122801 | .0 | .0 | 1.0 | .4494E-01 | 2.0 | .4190E-01 | 3.0 | .3158E-01 |
| + | 4.0 | .2611E-01 | 5.0 | .2429E-01 | 6.0 | .2186E-01 | 7.0 | .2247E-01 |
| + | 8.0 | .2794E-01 | 9.0 | .3583E-01 | 10.0 | .4494E-01 | 11.0 | .4616E-01 |
| 122802 | 12.0 | .3522E-01 | 13.0 | .3097E-01 | 14.0 | .2854E-01 | 15.0 | .3280E-01 |
| + | 16.0 | .3401E-01 | 17.0 | .3158E-01 | 18.0 | .3280E-01 | 19.0 | .4008E-01 |
| + | 20.0 | .3948E-01 | 21.0 | .3522E-01 | 22.0 | .2854E-01 | 23.0 | .2004E-01 |
| 122803 | 24.0 | .3158E-01 | 25.0 | .4251E-01 | 26.0 | .4676E-01 | 27.0 | .4312E-01 |
| + | 28.0 | .2915E-01 | 29.0 | .2308E-01 | 30.0 | .2490E-01 | 31.0 | .3948E-01 |
| + | 32.0 | .4373E-01 | 33.0 | .3280E-01 | 34.0 | .1640E-01 | 35.0 | .1032E-01 |
| 122804 | 36.0 | .2126E-01 | 37.0 | .4312E-01 | 38.0 | .5466E-01 | 39.0 | .5101E-01 |
| + | 40.0 | .4616E-01 | 41.0 | .3765E-01 | 42.0 | .2794E-01 | 43.0 | .1761E-01 |
| + | 44.0 | .1518E-01 | 45.0 | .3097E-01 | 46.0 | .4919E-01 | 47.0 | .5284E-01 |
| 122805 | 48.0 | .3280E-01 | 49.0 | .1579E-01 | 50.0 | .1154E-01 | 51.0 | .3158E-01 |
| + | 52.0 | .4859E-01 | 53.0 | .4859E-01 | 54.0 | .3948E-01 | 55.0 | .3887E-01 |
| + | 56.0 | .3097E-01 | 57.0 | .1943E-01 | 58.0 | .1640E-01 | 59.0 | .2976E-01 |
| 122806 | 60.0 | .3644E-01 | 61.0 | .3644E-01 | 62.0 | .3158E-01 | 63.0 | .3097E-01 |
| + | 64.0 | .3705E-01 | 65.0 | .4494E-01 | 66.0 | .4008E-01 | 67.0 | .2915E-01 |
| + | 68.0 | .2915E-01 | 69.0 | .3644E-01 | 70.0 | .4008E-01 | 71.0 | .3037E-01 |
| 122807 | 72.0 | .1943E-01 | 73.0 | .1822E-01 | 74.0 | .3158E-01 | 75.0 | .4555E-01 |
| + | 76.0 | .4798E-01 | 77.0 | .3644E-01 | 78.0 | .2126E-01 | 79.0 | .1700E-01 |
| + | 80.0 | .3887E-01 | 81.0 | .5769E-01 | 82.0 | .5769E-01 | 83.0 | .3644E-01 |
| 122808 | 84.0 | .1275E-01 | 85.0 | .8502E-02 | 86.0 | .1943E-01 | 87.0 | .3462E-01 |
| + | 88.0 | .3887E-01 | 89.0 | .3280E-01 | 90.0 | .2915E-01 | 91.0 | .3644E-01 |
| + | 92.0 | .4798E-01 | 93.0 | .5405E-01 | 94.0 | .4373E-01 | 95.0 | .2854E-01 |
| 122809 | 96.0 | .2611E-01 | 97.0 | .2611E-01 | 98.0 | .2429E-01 | 99.0 | .1397E-01 |
| + | 100.0 | .1458E-01 | 101.0 | .2794E-01 | 102.0 | .5891E-01 | 103.0 | .6802E-01 |
| + | 104.0 | .4433E-01 | 105.0 | .1883E-01 | 106.0 | .1032E-01 | 107.0 | .2915E-01 |
| 122810 | 108.0 | .3705E-01 | 109.0 | .3705E-01 | 110.0 | .3037E-01 | 111.0 | .3097E-01 |
| + | 112.0 | .4069E-01 | 113.0 | .4008E-01 | 114.0 | .3401E-01 | 115.0 | .3583E-01 |
| + | 116.0 | .3765E-01 | 117.0 | .3705E-01 | 118.0 | .2490E-01 | 119.0 | .1275E-01 |
| 122811 | 120.0 | .1458E-01 | 121.0 | .3583E-01 | 122.0 | .4616E-01 | 123.0 | .4859E-01 |
| + | 124.0 | .3583E-01 | 125.0 | .2854E-01 | 126.0 | .3522E-01 | 127.0 | .4251E-01 |
| + | 128.0 | .3705E-01 | 129.0 | .3158E-01 | 130.0 | .2794E-01 | 131.0 | .2915E-01 |
| 122812 | 132.0 | .3097E-01 | 133.0 | .2490E-01 | 134.0 | .1883E-01 | 135.0 | .2854E-01 |
| + | 136.0 | .4676E-01 | 137.0 | .5891E-01 | 138.0 | .5041E-01 | 139.0 | .2429E-01 |
| + | 140.0 | .1822E-01 | 141.0 | .2672E-01 | 142.0 | .3705E-01 | 143.0 | .3097E-01 |
| 122813 | 144.0 | .2065E-01 | 145.0 | .2186E-01 | 146.0 | .4130E-01 | 147.0 | .5527E-01 |
| + | 148.0 | .4251E-01 | 149.0 | .2186E-01 | 150.0 | .1458E-01 | 151.0 | .2733E-01 |
| + | 152.0 | .4737E-01 | 153.0 | .5284E-01 | 154.0 | .3522E-01 | 155.0 | .8502E-02 |

| | | | | | | | | |
|--------|-------|-----------|-------|-----------|-------|-----------|-------|-----------|
| 122814 | 156.0 | .1822E-02 | 157.0 | .2126E-01 | 158.0 | .5405E-01 | 159.0 | .7166E-01 |
| + | 160.0 | .6316E-01 | 161.0 | .2976E-01 | 162.0 | .2429E-02 | 163.0 | .6073E-03 |
| + | 164.0 | .1640E-01 | 165.0 | .4312E-01 | 166.0 | .5891E-01 | 167.0 | .5830E-01 |
| 122815 | 168.0 | .4251E-01 | 169.0 | .2611E-01 | 170.0 | .1883E-01 | 171.0 | .2004E-01 |
| + | 172.0 | .2672E-01 | 173.0 | .3158E-01 | 174.0 | .3826E-01 | 175.0 | .3340E-01 |
| + | 176.0 | .3705E-01 | 177.0 | .3765E-01 | 178.0 | .3887E-01 | 179.0 | .4190E-01 |
| 122816 | 180.0 | .4069E-01 | 181.0 | .3765E-01 | 182.0 | .3037E-01 | 183.0 | .2065E-01 |
| + | 184.0 | .1093E-01 | 185.0 | .1761E-01 | 186.0 | .3462E-01 | 187.0 | .5344E-01 |
| + | 188.0 | .5101E-01 | 189.0 | .4373E-01 | 190.0 | .3340E-01 | 191.0 | .3462E-01 |
| 122817 | 192.0 | .2733E-01 | 193.0 | .2854E-01 | 194.0 | .2672E-01 | 195.0 | .3462E-01 |
| + | 196.0 | .4008E-01 | 197.0 | .3401E-01 | 198.0 | .2490E-01 | 199.0 | .2126E-01 |
| + | 200.0 | .2733E-01 | 201.0 | .3522E-01 | 202.0 | .4433E-01 | 203.0 | .4616E-01 |
| 122818 | 204.0 | .4190E-01 | 205.0 | .4069E-01 | 206.0 | .3219E-01 | 207.0 | .1700E-01 |
| + | 208.0 | .1275E-01 | 209.0 | .2915E-01 | 210.0 | .4859E-01 | 211.0 | .4859E-01 |
| + | 212.0 | .3219E-01 | 213.0 | .1943E-01 | 214.0 | .2247E-01 | 215.0 | .3583E-01 |
| 122819 | 216.0 | .4980E-01 | 217.0 | .4555E-01 | 218.0 | .3219E-01 | 219.0 | .2126E-01 |
| + | 220.0 | .2733E-01 | 221.0 | .3644E-01 | 222.0 | .4251E-01 | 223.0 | .3644E-01 |
| + | 224.0 | .2854E-01 | 225.0 | .2794E-01 | 226.0 | .3765E-01 | 227.0 | .4616E-01 |
| 122820 | 228.0 | .4008E-01 | 229.0 | .3219E-01 | 230.0 | .2004E-01 | 231.0 | .9717E-02 |
| + | 232.0 | .1700E-01 | 233.0 | .3644E-01 | 234.0 | .5284E-01 | 235.0 | .5344E-01 |
| + | 236.0 | .3887E-01 | 237.0 | .2672E-01 | 238.0 | .2369E-01 | 239.0 | .3219E-01 |
| 122821 | 240.0 | .4312E-01 | 241.0 | .4190E-01 | 242.0 | .2429E-01 | 243.0 | .1640E-01 |
| + | 244.0 | .2429E-01 | 245.0 | .4980E-01 | 246.0 | .5284E-01 | 247.0 | .3583E-01 |
| + | 248.0 | .9110E-02 | 249.0 | .1275E-01 | 250.0 | .3583E-01 | 251.0 | .5527E-01 |
| 122822 | 252.0 | .6498E-01 | 253.0 | .3948E-01 | 254.0 | .1397E-01 | 255.0 | .3644E-02 |
| + | 256.0 | .1640E-01 | 257.0 | .5344E-01 | 258.0 | .7470E-01 | 259.0 | .5891E-01 |
| + | 260.0 | .1822E-01 | 261.0 | .0000E+00 | 262.0 | .1458E-01 | 263.0 | .3401E-01 |
| 122823 | 264.0 | .4555E-01 | 265.0 | .3765E-01 | 266.0 | .3644E-01 | 267.0 | .4312E-01 |
| + | 268.0 | .4798E-01 | 269.0 | .4433E-01 | 270.0 | .2611E-01 | 271.0 | .1458E-01 |
| + | 272.0 | .1397E-01 | 273.0 | .3158E-01 | 274.0 | .4433E-01 | 275.0 | .4798E-01 |
| 122824 | 276.0 | .3522E-01 | 277.0 | .2915E-01 | 278.0 | .3037E-01 | 279.0 | .3765E-01 |
| + | 280.0 | .3887E-01 | 281.0 | .3583E-01 | 282.0 | .2976E-01 | 283.0 | .2247E-01 |
| + | 284.0 | .2794E-01 | 285.0 | .3522E-01 | 286.0 | .3522E-01 | 287.0 | .2672E-01 |
| 122825 | 288.0 | .3583E-01 | 289.0 | .5284E-01 | 290.0 | .5769E-01 | 291.0 | .3522E-01 |
| + | 292.0 | .1275E-01 | 293.0 | .1336E-01 | 294.0 | .3522E-01 | 295.0 | .4798E-01 |
| + | 296.0 | .4069E-01 | 297.0 | .2672E-01 | 298.0 | .2308E-01 | 299.0 | .2733E-01 |
| 122826 | 300.0 | .2611E-01 | 301.0 | .2611E-01 | 302.0 | .3705E-01 | 303.0 | .5162E-01 |
| + | 304.0 | .5709E-01 | 305.0 | .4616E-01 | 306.0 | .3037E-01 | 307.0 | .2065E-01 |
| + | 308.0 | .2065E-01 | 309.0 | .2490E-01 | 310.0 | .2429E-01 | 311.0 | .2247E-01 |
| 122827 | 312.0 | .2915E-01 | 313.0 | .5162E-01 | 314.0 | .6498E-01 | 315.0 | .5284E-01 |
| + | 316.0 | .2369E-01 | 317.0 | .4859E-02 | 318.0 | .1518E-01 | 319.0 | .3097E-01 |
| + | 320.0 | .3705E-01 | 321.0 | .2976E-01 | 322.0 | .2794E-01 | 323.0 | .3522E-01 |
| 122828 | 324.0 | .4980E-01 | 325.0 | .5344E-01 | 326.0 | .3826E-01 | 327.0 | .1336E-01 |
| + | 328.0 | .1215E-01 | 329.0 | .3522E-01 | 330.0 | .5466E-01 | 331.0 | .5466E-01 |
| + | 332.0 | .3037E-01 | 333.0 | .1215E-01 | 334.0 | .9110E-02 | 335.0 | .2976E-01 |
| 122829 | 336.0 | .4008E-01 | 337.0 | .3583E-01 | 338.0 | .2915E-01 | 339.0 | .3401E-01 |
| + | 340.0 | .4798E-01 | 341.0 | .5223E-01 | 342.0 | .4190E-01 | 343.0 | .3037E-01 |
| + | 344.0 | .1518E-01 | 345.0 | .2004E-01 | 346.0 | .2672E-01 | 347.0 | .3219E-01 |
| 122830 | 348.0 | .4373E-01 | 349.0 | .4859E-01 | 350.0 | .4190E-01 | 351.0 | .2551E-01 |
| + | 352.0 | .2004E-01 | 353.0 | .2854E-01 | 354.0 | .4130E-01 | 355.0 | .4373E-01 |
| + | 356.0 | .3765E-01 | 357.0 | .2186E-01 | 358.0 | .1640E-01 | 359.0 | .2369E-01 |
| 122831 | 360.0 | .4069E-01 | 361.0 | .5587E-01 | 362.0 | .4555E-01 | 363.0 | .2429E-01 |
| + | 364.0 | .2186E-01 | 365.0 | .4069E-01 | 366.0 | .5223E-01 | 367.0 | .4737E-01 |
| + | 368.0 | .2369E-01 | 369.0 | .1822E-02 | 370.0 | .8902E-02 | 371.0 | .3522E-01 |
| 122832 | 372.0 | .6073E-01 | 373.0 | .6984E-01 | 374.0 | .5101E-01 | 375.0 | .1822E-01 |
| + | 376.0 | .6073E-03 | 377.0 | .7288E-02 | 378.0 | .3462E-01 | 379.0 | .5769E-01 |
| + | 380.0 | .6073E-01 | 381.0 | .4616E-01 | 382.0 | .1640E-01 | 383.0 | .6073E-03 |
| 122833 | 384.0 | .7895E-02 | 385.0 | .3705E-01 | 386.0 | .5830E-01 | 387.0 | .5830E-01 |
| + | 388.0 | .4069E-01 | 389.0 | .2490E-01 | 390.0 | .2247E-01 | 391.0 | .3705E-01 |
| + | 392.0 | .4737E-01 | 393.0 | .4494E-01 | 394.0 | .3522E-01 | 395.0 | .2186E-01 |
| 122834 | 396.0 | .2004E-01 | 397.0 | .2126E-01 | 398.0 | .2429E-01 | 399.0 | .2733E-01 |
| + | 400.0 | .3097E-01 | 401.0 | .4251E-01 | 402.0 | .5587E-01 | 403.0 | .5041E-01 |
| + | 404.0 | .3280E-01 | 405.0 | .1518E-01 | 406.0 | .2065E-01 | 407.0 | .4555E-01 |
| 122835 | 408.0 | .5466E-01 | 409.0 | .4312E-01 | 410.0 | .2369E-01 | 411.0 | .1761E-01 |
| + | 412.0 | .2065E-01 | 413.0 | .3462E-01 | 414.0 | .3765E-01 | 415.0 | .3401E-01 |
| + | 416.0 | .2369E-01 | 417.0 | .2915E-01 | 418.0 | .4737E-01 | 419.0 | .4980E-01 |
| 122836 | 420.0 | .4008E-01 | 421.0 | .2186E-01 | 422.0 | .1579E-01 | 423.0 | .3158E-01 |
| + | 424.0 | .4555E-01 | 425.0 | .4919E-01 | 426.0 | .4008E-01 | 427.0 | .2733E-01 |
| + | 428.0 | .2308E-01 | 429.0 | .1579E-01 | 430.0 | .2308E-01 | 431.0 | .3765E-01 |
| 122837 | 432.0 | .6377E-01 | 433.0 | .6316E-01 | 434.0 | .4069E-01 | 435.0 | .8502E-02 |
| + | 436.0 | .3644E-02 | 437.0 | .1458E-01 | 438.0 | .4433E-01 | 439.0 | .6012E-01 |
| + | 440.0 | .5284E-01 | 441.0 | .3765E-01 | 442.0 | .2429E-01 | 443.0 | .1093E-01 |
| 122838 | 444.0 | .6680E-02 | 445.0 | .3158E-01 | 446.0 | .6012E-01 | 447.0 | .7470E-01 |
| + | 448.0 | .6680E-01 | 449.0 | .3097E-01 | 450.0 | .1822E-02 | 451.0 | .1154E-01 |
| + | 452.0 | .5466E-02 | 453.0 | .3826E-01 | 454.0 | .6680E-01 | 455.0 | .6680E-01 |
| 122839 | 456.0 | .4190E-01 | 457.0 | .2308E-01 | 458.0 | .2065E-01 | 459.0 | .2854E-01 |
| + | 460.0 | .3826E-01 | 461.0 | .3644E-01 | 462.0 | .2733E-01 | 463.0 | .2308E-01 |
| + | 464.0 | .5462E-01 | 465.0 | .4494E-01 | 466.0 | .4130E-01 | 467.0 | .3158E-01 |
| 122840 | 468.0 | .2794E-01 | 469.0 | .4190E-01 | 470.0 | .4737E-01 | 471.0 | .3705E-01 |
| + | 472.0 | .2369E-01 | 473.0 | .1336E-01 | 474.0 | .1275E-01 | 475.0 | .2794E-01 |

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| | | | | | | | | |
|--------|-------|-----------|--------------------------|-----------|-------|-----------|-------|-----------|
| + | 476.0 | .4494E-01 | 477.0 | .5405E-01 | 478.0 | .5101E-01 | 479.0 | .3887E-01 |
| 122841 | 480.0 | .2794E-01 | 481.0 | .2247E-01 | 482.0 | .2976E-01 | 483.0 | .3826E-01 |
| + | 484.0 | .4008E-01 | 485.0 | .3401E-01 | 486.0 | .2247E-01 | 487.0 | .1397E-01 |
| + | 488.0 | .3037E-01 | 489.0 | .4676E-01 | 490.0 | .5041E-01 | 491.0 | .3583E-01 |
| 122842 | 492.0 | .2490E-01 | 493.0 | .2490E-01 | 494.0 | .3280E-01 | 495.0 | .3401E-01 |
| + | 496.0 | .3765E-01 | 497.0 | .4008E-01 | 498.0 | .3826E-01 | 499.0 | .3887E-01 |
| + | 500.0 | .2854E-01 | 501.0 | .3037E-01 | 502.0 | .3280E-01 | 503.0 | .2915E-01 |
| 122843 | 504.0 | .2854E-01 | 505.0 | .3158E-01 | 506.0 | .4190E-01 | 507.0 | .3948E-01 |
| + | 508.0 | .2976E-01 | 509.0 | .2308E-01 | 510.0 | .3158E-01 | 511.0 | .5101E-01 |
| + | 512.0 | .4251E-01 | 513.0 | .2733E-01 | 514.0 | .1458E-01 | 515.0 | .1883E-01 |
| 122844 | 516.0 | .4190E-01 | 517.0 | .6134E-01 | 518.0 | .5527E-01 | 519.0 | .2915E-01 |
| + | 520.0 | .6073E-03 | 521.0 | .4251E-02 | 522.0 | .2794E-01 | 523.0 | .6620E-01 |
| + | 524.0 | .7409E-01 | 525.0 | .5101E-01 | 526.0 | .1822E-01 | 527.0 | .4859E-02 |
| 122845 | 528.0 | .2429E-01 | 529.0 | .4008E-01 | 530.0 | .4616E-01 | 531.0 | .4008E-01 |
| + | 532.0 | .2915E-01 | 533.0 | .1883E-01 | 534.0 | .2065E-01 | 535.0 | .3340E-01 |
| + | 536.0 | .4676E-01 | 537.0 | .4798E-01 | 538.0 | .3219E-01 | 539.0 | .3219E-01 |
| 122846 | 540.0 | .4251E-01 | 541.0 | .5466E-01 | 542.0 | .4433E-01 | 543.0 | .1822E-01 |
| + | 544.0 | .6073E-03 | 545.0 | .9110E-02 | 546.0 | .3280E-01 | 547.0 | .5466E-01 |
| + | 548.0 | .6316E-01 | 549.0 | .5648E-01 | 550.0 | .2915E-01 | 551.0 | .1154E-01 |
| 122847 | 552.0 | .7288E-02 | 553.0 | .2611E-01 | 554.0 | .4190E-01 | 555.0 | .4798E-01 |
| + | 556.0 | .3948E-01 | 557.0 | .3705E-01 | 558.0 | .3765E-01 | 559.0 | .2915E-01 |
| + | 560.0 | .2004E-01 | 561.0 | .2308E-01 | 562.0 | .3280E-01 | 563.0 | .4859E-01 |
| 122848 | 564.0 | .5162E-01 | 565.0 | .4616E-01 | 566.0 | .3340E-01 | 567.0 | .1700E-01 |
| + | 568.0 | .2065E-01 | 569.0 | .2976E-01 | 570.0 | .3340E-01 | 571.0 | .2733E-01 |
| + | 572.0 | .2308E-01 | 573.0 | .3158E-01 | 574.0 | .4373E-01 | 575.0 | .4980E-01 |
| 122849 | 576.0 | .4616E-01 | 577.0 | .4251E-01 | 578.0 | .3705E-01 | 579.0 | .2551E-01 |
| + | 580.0 | .2308E-01 | 581.0 | .1761E-01 | 582.0 | .2611E-01 | 583.0 | .3765E-01 |
| + | 584.0 | .4494E-01 | 585.0 | .4069E-01 | 586.0 | .2490E-01 | 587.0 | .1458E-01 |
| 122850 | 588.0 | .3462E-01 | 589.0 | .5284E-01 | 590.0 | .4737E-01 | 591.0 | .3644E-01 |
| + | 592.0 | .2854E-01 | 593.0 | .2976E-01 | 594.0 | .3340E-01 | 595.0 | .2551E-01 |
| + | 596.0 | .2551E-01 | 597.0 | .3219E-01 | 598.0 | .4130E-01 | 599.0 | .4373E-01 |
| 122851 | 600.0 | .3462E-01 | 601.0 | .2611E-01 | 602.0 | .2915E-01 | 603.0 | .3705E-01 |
| + | 604.0 | .3705E-01 | 605.0 | .3097E-01 | 606.0 | .2247E-01 | 607.0 | .2551E-01 |
| + | 608.0 | .3826E-01 | 609.0 | .5405E-01 | 610.0 | .5527E-01 | 611.0 | .4069E-01 |
| 122852 | 612.0 | .2186E-01 | 613.0 | .1032E-01 | 614.0 | .1458E-01 | 615.0 | .3340E-01 |
| + | 616.0 | .4859E-01 | 617.0 | .4798E-01 | 618.0 | .3219E-01 | 619.0 | .1336E-01 |
| + | 620.0 | .1822E-01 | 621.0 | .4190E-01 | 622.0 | .5830E-01 | 623.0 | .5648E-01 |
| 122853 | 624.0 | .3826E-01 | 625.0 | .1518E-01 | 626.0 | .8502E-02 | 627.0 | .1579E-01 |
| + | 628.0 | .3462E-01 | 629.0 | .5587E-01 | 630.0 | .6134E-01 | 631.0 | .4737E-01 |
| + | 632.0 | .3097E-01 | 633.0 | .1032E-01 | 634.0 | .9110E-02 | 635.0 | .2369E-01 |
| 122854 | 636.0 | .4616E-01 | 637.0 | .5587E-01 | 638.0 | .4433E-01 | 639.0 | .2186E-01 |
| + | 640.0 | .1579E-01 | 641.0 | .3097E-01 | 642.0 | .4798E-01 | 643.0 | .4555E-01 |
| + | 644.0 | .3280E-01 | 645.0 | .2369E-01 | 646.0 | .2794E-01 | 647.0 | .4312E-01 |
| 122855 | 648.0 | .4069E-01 | 649.0 | .3340E-01 | 650.0 | .1822E-01 | 651.0 | .2126E-01 |
| + | 652.0 | .3401E-01 | 653.0 | .4737E-01 | 654.0 | .5648E-01 | 655.0 | .4798E-01 |
| + | 656.0 | .3876E-01 | 657.0 | .1579E-01 | 658.0 | .6073E-02 | 659.0 | .1275E-01 |
| 122856 | 660.0 | .2854E-01 | 661.0 | .4555E-01 | 662.0 | .4980E-01 | 663.0 | .4130E-01 |
| + | 664.0 | .3644E-01 | 665.0 | .3887E-01 | 666.0 | .4494E-01 | 667.0 | .4555E-01 |
| + | 668.0 | .2429E-01 | 669.0 | .1215E-01 | 670.0 | .1579E-01 | 671.0 | .3583E-01 |
| 122857 | 672.0 | .4555E-01 | 673.0 | .3522E-01 | 674.0 | .1883E-01 | 675.0 | .2247E-01 |
| + | 676.0 | .4555E-01 | 677.0 | .5891E-01 | 678.0 | .4676E-01 | 679.0 | .2490E-01 |
| + | 680.0 | .2065E-01 | 681.0 | .3219E-01 | 682.0 | .4676E-01 | 683.0 | .3705E-01 |
| 122858 | 684.0 | .1761E-01 | 685.0 | .2004E-01 | 686.0 | .3462E-01 | 687.0 | .4676E-01 |
| + | 688.0 | .4251E-01 | 689.0 | .3340E-01 | 690.0 | .2611E-01 | 691.0 | .2733E-01 |
| + | 692.0 | .3401E-01 | 693.0 | .3462E-01 | 694.0 | .3522E-01 | 695.0 | .3644E-01 |
| 122859 | 696.0 | .3705E-01 | 697.0 | .3826E-01 | 698.0 | .4130E-01 | 699.0 | .3401E-01 |
| + | 700.0 | .2429E-01 | 701.0 | .2004E-01 | 702.0 | .2976E-01 | 703.0 | .5041E-01 |
| + | 704.0 | .5709E-01 | 705.0 | .4190E-01 | 706.0 | .1032E-01 | 707.0 | .6073E-03 |
| 122860 | 708.0 | .1458E-01 | 709.0 | .4312E-01 | 710.0 | .6073E-01 | 711.0 | .4859E-01 |
| + | 712.0 | .3644E-01 | 713.0 | .3097E-01 | 714.0 | .4008E-01 | 715.0 | .3887E-01 |
| + | 716.0 | .1943E-01 | 717.0 | .1640E-01 | 718.0 | .2794E-01 | 719.0 | .5344E-01 |
| 122861 | 720.0 | .5162E-01 | 721.0 | .2672E-01 | 722.0 | .1275E-01 | 723.0 | .1579E-01 |
| + | 724.0 | .3462E-01 | 725.0 | .4616E-01 | 726.0 | .4555E-01 | 727.0 | .3644E-01 |
| + | 728.0 | .4008E-01 | 729.0 | .3522E-01 | 730.0 | .3097E-01 | 731.0 | .2854E-01 |
| 122862 | 732.0 | .3280E-01 | 733.0 | .4494E-01 | 734.0 | .4312E-01 | 735.0 | .2794E-01 |
| + | 736.0 | .4251E-02 | 737.0 | .1032E-01 | 738.0 | .3401E-01 | 739.0 | .6316E-01 |
| + | 740.0 | .6741E-01 | 741.0 | .3826E-01 | 742.0 | .1275E-01 | 743.0 | .9110E-02 |
| 122863 | 744.0 | .3097E-01 | 745.0 | .4798E-01 | 746.0 | .4494E-01 | 747.0 | .3219E-01 |
| + | 748.0 | .2854E-01 | 749.0 | .3097E-01 | 750.0 | .2854E-01 | 751.0 | .3158E-01 |
| + | 752.0 | .3887E-01 | 753.0 | .3705E-01 | 754.0 | .3462E-01 | 755.0 | .3583E-01 |
| 122864 | 756.0 | .3522E-01 | 757.0 | .3280E-01 | 758.0 | .2733E-01 | 759.0 | .2369E-01 |
| + | 760.0 | .2429E-01 | 761.0 | .3401E-01 | 762.0 | .3765E-01 | 763.0 | .4130E-01 |
| + | 764.0 | .4676E-01 | 765.0 | .4373E-01 | 766.0 | .2915E-01 | 767.0 | .1275E-01 |
| 122865 | 768.0 | .1458E-01 | 769.0 | .3826E-01 | 770.0 | .5891E-01 | 771.0 | .5830E-01 |
| + | 772.0 | .3340E-01 | 773.0 | .7895E-02 | 774.0 | .3037E-02 | 775.0 | .1458E-01 |
| + | 776.0 | .4798E-01 | 777.0 | .7470E-01 | 778.0 | .6863E-01 | 779.0 | .3583E-01 |
| 122866 | 780.0 | .0000E+00 | | | | | | |
| 122900 | 781 | | * PRZ 2-ACCELERATION (G) | | | | | |
| 122901 | .0 | .2692E-01 | 1.0 | .2815E-01 | 2.0 | .2325E-01 | 3.0 | .1407E-01 |
| 122901 | .0 | .0 | 1.0 | .2815E-01 | 2.0 | .2325E-01 | 3.0 | .1407E-01 |

| | | | | | | | | | |
|--------|---|-------|-----------|-------|-----------|-------|-----------|-------|-----------|
| | + | 4.0 | .9178E-02 | 5.0 | .5507E-02 | 6.0 | .3671E-02 | 7.0 | .3671E-02 |
| | + | 8.0 | .4283E-02 | 9.0 | .1346E-01 | 10.0 | .2509E-01 | 11.0 | .2876E-01 |
| 122902 | | 12.0 | .2080E-01 | 13.0 | .1958E-01 | 14.0 | .1530E-01 | 15.0 | .1346E-01 |
| | + | 16.0 | .9178E-02 | 17.0 | .4895E-02 | 18.0 | .1163E-01 | 19.0 | .2325E-01 |
| | + | 20.0 | .2264E-01 | 21.0 | .1530E-01 | 22.0 | .7343E-02 | 23.0 | .6119E-03 |
| 122903 | | 24.0 | .1224E-01 | 25.0 | .2509E-01 | 26.0 | .3304E-01 | 27.0 | .2937E-01 |
| | + | 28.0 | .1652E-01 | 29.0 | .6731E-02 | 30.0 | .1836E-02 | 31.0 | .1407E-01 |
| | + | 32.0 | .1897E-01 | 33.0 | .9790E-02 | 34.0 | .5507E-02 | 35.0 | .7343E-02 |
| 122904 | | 36.0 | .4895E-02 | 37.0 | .2631E-01 | 38.0 | .3671E-01 | 39.0 | .3610E-01 |
| | + | 40.0 | .3243E-01 | 41.0 | .2203E-01 | 42.0 | .1101E-01 | 43.0 | .2448E-02 |
| | + | 44.0 | .9178E-02 | 45.0 | .7343E-02 | 46.0 | .2631E-01 | 47.0 | .3059E-01 |
| 122905 | | 48.0 | .1530E-01 | 49.0 | .6119E-03 | 50.0 | .1836E-02 | 51.0 | .1591E-01 |
| | + | 52.0 | .3121E-01 | 53.0 | .3121E-01 | 54.0 | .2570E-01 | 55.0 | .2325E-01 |
| | + | 56.0 | .8566E-02 | 57.0 | .5507E-02 | 58.0 | .1040E-01 | 59.0 | .7954E-02 |
| 122906 | | 60.0 | .1774E-01 | 61.0 | .1958E-01 | 62.0 | .1836E-01 | 63.0 | .1713E-01 |
| | + | 64.0 | .2203E-01 | 65.0 | .2753E-01 | 66.0 | .1958E-01 | 67.0 | .1040E-01 |
| | + | 68.0 | .1163E-01 | 69.0 | .1713E-01 | 70.0 | .1713E-01 | 71.0 | .7343E-02 |
| 122907 | | 72.0 | .1224E-02 | 73.0 | .2448E-02 | 74.0 | .1897E-01 | 75.0 | .3059E-01 |
| | + | 76.0 | .2937E-01 | 77.0 | .1530E-01 | 78.0 | .1836E-02 | 79.0 | .3671E-02 |
| | + | 80.0 | .2509E-01 | 81.0 | .3855E-01 | 82.0 | .3549E-01 | 83.0 | .1346E-01 |
| 122908 | | 84.0 | .6731E-02 | 85.0 | .9790E-02 | 86.0 | .2448E-02 | 87.0 | .1407E-01 |
| | + | 88.0 | .1713E-01 | 89.0 | .1652E-01 | 90.0 | .1774E-01 | 91.0 | .2509E-01 |
| | + | 92.0 | .3549E-01 | 93.0 | .3671E-01 | 94.0 | .2703E-01 | 95.0 | .9178E-02 |
| 122909 | | 96.0 | .4895E-02 | 97.0 | .3059E-02 | 98.0 | .2448E-02 | 99.0 | .9790E-02 |
| | + | 100.0 | .4283E-02 | 101.0 | .1407E-01 | 102.0 | .4589E-01 | 103.0 | .5446E-01 |
| | + | 104.0 | .3059E-01 | 105.0 | .4283E-02 | 106.0 | .4895E-02 | 107.0 | .5507E-02 |
| 122910 | | 108.0 | .9178E-02 | 109.0 | .9178E-02 | 110.0 | .9178E-02 | 111.0 | .1407E-01 |
| | + | 112.0 | .2325E-01 | 113.0 | .2142E-01 | 114.0 | .1713E-01 | 115.0 | .2448E-01 |
| | + | 116.0 | .2692E-01 | 117.0 | .2142E-01 | 118.0 | .4283E-02 | 119.0 | .9178E-02 |
| 122911 | | 120.0 | .6119E-02 | 121.0 | .1346E-01 | 122.0 | .2448E-01 | 123.0 | .2631E-01 |
| | + | 124.0 | .1652E-01 | 125.0 | .1285E-01 | 126.0 | .2325E-01 | 127.0 | .2815E-01 |
| | + | 128.0 | .2019E-01 | 129.0 | .1101E-01 | 130.0 | .6731E-02 | 131.0 | .1163E-01 |
| 122912 | | 132.0 | .1040E-01 | 133.0 | .1224E-02 | 134.0 | .6731E-02 | 135.0 | .7954E-02 |
| | + | 136.0 | .3059E-01 | 137.0 | .4344E-01 | 138.0 | .3549E-01 | 139.0 | .1163E-01 |
| | + | 140.0 | .6731E-02 | 141.0 | .1163E-01 | 142.0 | .1774E-01 | 143.0 | .5507E-02 |
| 122913 | | 144.0 | .5507E-02 | 145.0 | .3671E-02 | 146.0 | .1713E-01 | 147.0 | .3304E-01 |
| | + | 148.0 | .2203E-01 | 149.0 | .4895E-02 | 150.0 | .3059E-02 | 151.0 | .1836E-01 |
| | + | 152.0 | .3732E-01 | 153.0 | .3855E-01 | 154.0 | .1407E-01 | 155.0 | .1713E-01 |
| 122914 | | 156.0 | .2570E-01 | 157.0 | .1224E-02 | 158.0 | .3182E-01 | 159.0 | .4895E-01 |
| | + | 160.0 | .4283E-01 | 161.0 | .1530E-01 | 162.0 | .6731E-02 | 163.0 | .7954E-02 |
| | + | 164.0 | .1836E-02 | 165.0 | .2264E-01 | 166.0 | .3243E-01 | 167.0 | .3243E-01 |
| 122915 | | 168.0 | .2019E-01 | 169.0 | .7954E-02 | 170.0 | .1224E-02 | 171.0 | .1224E-02 |
| | + | 172.0 | .6731E-02 | 173.0 | .1469E-01 | 174.0 | .2386E-01 | 175.0 | .2019E-01 |
| | + | 176.0 | .1958E-01 | 177.0 | .1530E-01 | 178.0 | .1774E-01 | 179.0 | .2019E-01 |
| 122916 | | 180.0 | .2509E-01 | 181.0 | .2203E-01 | 182.0 | .1163E-01 | 183.0 | .2448E-02 |
| | + | 184.0 | .9790E-02 | 185.0 | .1224E-02 | 186.0 | .1958E-01 | 187.0 | .3610E-01 |
| | + | 188.0 | .3427E-01 | 189.0 | .2570E-01 | 190.0 | .1836E-01 | 191.0 | .1774E-01 |
| 122917 | | 192.0 | .9178E-02 | 193.0 | .5507E-02 | 194.0 | .7343E-02 | 195.0 | .1407E-01 |
| | + | 196.0 | .2019E-01 | 197.0 | .1346E-01 | 198.0 | .5507E-02 | 199.0 | .3671E-02 |
| | + | 200.0 | .1346E-01 | 201.0 | .2386E-01 | 202.0 | .2876E-01 | 203.0 | .2386E-01 |
| 122918 | | 204.0 | .1958E-01 | 205.0 | .1897E-01 | 206.0 | .1101E-01 | 207.0 | .4283E-02 |
| | + | 208.0 | .4283E-02 | 209.0 | .1530E-01 | 210.0 | .3182E-01 | 211.0 | .2753E-01 |
| | + | 212.0 | .1163E-01 | 213.0 | .3059E-02 | 214.0 | .8566E-02 | 215.0 | .1897E-01 |
| 122919 | | 216.0 | .2998E-01 | 217.0 | .2325E-01 | 218.0 | .9178E-02 | 219.0 | .6119E-03 |
| | + | 220.0 | .1040E-01 | 221.0 | .1897E-01 | 222.0 | .2325E-01 | 223.0 | .1774E-01 |
| | + | 224.0 | .9178E-02 | 225.0 | .7343E-02 | 226.0 | .2142E-01 | 227.0 | .3243E-01 |
| 122920 | | 228.0 | .2753E-01 | 229.0 | .1652E-01 | 230.0 | .0000E+00 | 231.0 | .1101E-01 |
| | + | 232.0 | .6119E-02 | 233.0 | .1530E-01 | 234.0 | .2998E-01 | 235.0 | .3243E-01 |
| | + | 236.0 | .1713E-01 | 237.0 | .7343E-02 | 238.0 | .9790E-02 | 239.0 | .2325E-01 |
| 122921 | | 240.0 | .3243E-01 | 241.0 | .2448E-01 | 242.0 | .1224E-02 | 243.0 | .5507E-02 |
| | + | 244.0 | .6731E-02 | 245.0 | .3059E-01 | 246.0 | .3182E-01 | 247.0 | .1163E-01 |
| | + | 248.0 | .1101E-01 | 249.0 | .4283E-02 | 250.0 | .2019E-01 | 251.0 | .4344E-01 |
| 122922 | | 252.0 | .4773E-01 | 253.0 | .2019E-01 | 254.0 | .7343E-02 | 255.0 | .2264E-01 |
| | + | 256.0 | .2448E-02 | 257.0 | .3549E-01 | 258.0 | .5262E-01 | 259.0 | .3610E-01 |
| | + | 260.0 | .6119E-03 | 261.0 | .1224E-01 | 262.0 | .6119E-03 | 263.0 | .1897E-01 |
| 122923 | | 264.0 | .2448E-01 | 265.0 | .1530E-01 | 266.0 | .1652E-01 | 267.0 | .2264E-01 |
| | + | 268.0 | .2815E-01 | 269.0 | .2448E-01 | 270.0 | .6731E-02 | 271.0 | .4895E-02 |
| | + | 272.0 | .1224E-02 | 273.0 | .1652E-01 | 274.0 | .2815E-01 | 275.0 | .2815E-01 |
| 122924 | | 276.0 | .1530E-01 | 277.0 | .9790E-02 | 278.0 | .1346E-01 | 279.0 | .1958E-01 |
| | + | 280.0 | .1958E-01 | 281.0 | .1591E-01 | 282.0 | .1101E-01 | 283.0 | .4283E-02 |
| | + | 284.0 | .7954E-02 | 285.0 | .1285E-01 | 286.0 | .1346E-01 | 287.0 | .8566E-02 |
| 122925 | | 288.0 | .2080E-01 | 289.0 | .3794E-01 | 290.0 | .3916E-01 | 291.0 | .1530E-01 |
| | + | 292.0 | .6731E-02 | 293.0 | .2448E-02 | 294.0 | .1652E-01 | 295.0 | .2692E-01 |
| | + | 296.0 | .1836E-01 | 297.0 | .6731E-02 | 298.0 | .5507E-02 | 299.0 | .7343E-02 |
| 122926 | | 300.0 | .7954E-02 | 301.0 | .1101E-01 | 302.0 | .2203E-01 | 303.0 | .3610E-01 |
| | + | 304.0 | .3855E-01 | 305.0 | .2631E-01 | 306.0 | .9178E-02 | 307.0 | .0000E+00 |
| | + | 308.0 | .6119E-03 | 309.0 | .3059E-02 | 310.0 | .6119E-03 | 311.0 | .0000E+00 |
| 122927 | | 312.0 | .1224E-01 | 313.0 | .3610E-01 | 314.0 | .4834E-01 | 315.0 | .3671E-01 |
| | + | 316.0 | .9790E-02 | 317.0 | .6119E-02 | 318.0 | .6119E-03 | 319.0 | .1163E-01 |
| | + | 320.0 | .1163E-01 | 321.0 | .3059E-02 | 322.0 | .1836E-02 | 323.0 | .1407E-01 |

| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| 122928 | 324.0 | .3059E-01 | 325.0 | .3304E-01 | 326.0 | .1836E-01 | 327.0 | -.1224E-02 |
| + | 328.0 | .6119E-03 | 329.0 | .2386E-01 | 330.0 | .4161E-01 | 331.0 | .3549E-01 |
| + | 332.0 | .9790E-02 | 333.0 | -.1101E-01 | 334.0 | -.1040E-01 | 335.0 | .7954E-02 |
| 122929 | 336.0 | .1774E-01 | 337.0 | .1163E-01 | 338.0 | .8566E-02 | 339.0 | .2142E-01 |
| + | 340.0 | .3671E-01 | 341.0 | .3610E-01 | 342.0 | .2570E-01 | 343.0 | .1346E-01 |
| + | 344.0 | -.2448E-02 | 345.0 | -.1224E-02 | 346.0 | .3059E-02 | 347.0 | .4895E-02 |
| 122930 | 348.0 | .1897E-01 | 349.0 | .3243E-01 | 350.0 | .2753E-01 | 351.0 | .1285E-01 |
| + | 352.0 | .5507E-02 | 353.0 | .1224E-01 | 354.0 | .2264E-01 | 355.0 | .2692E-01 |
| + | 356.0 | .1897E-01 | 357.0 | .1836E-02 | 358.0 | -.5507E-02 | 359.0 | .2448E-02 |
| 122931 | 360.0 | .2264E-01 | 361.0 | .3671E-01 | 362.0 | .2203E-01 | 363.0 | .3671E-02 |
| + | 364.0 | .6119E-02 | 365.0 | .2570E-01 | 366.0 | .3671E-01 | 367.0 | .2937E-01 |
| + | 368.0 | .1224E-02 | 369.0 | -.1713E-01 | 370.0 | -.1224E-01 | 371.0 | .1591E-01 |
| 122932 | 372.0 | .3977E-01 | 373.0 | .5140E-01 | 374.0 | .3427E-01 | 375.0 | .2448E-02 |
| + | 376.0 | -.1836E-01 | 377.0 | -.1224E-01 | 378.0 | .1652E-01 | 379.0 | .4100E-01 |
| + | 380.0 | .4222E-01 | 381.0 | .2448E-01 | 382.0 | -.6119E-02 | 383.0 | -.2142E-01 |
| 122933 | 384.0 | -.7954E-02 | 385.0 | .2019E-01 | 386.0 | .3977E-01 | 387.0 | .3794E-01 |
| + | 388.0 | .2080E-01 | 389.0 | .5507E-02 | 390.0 | .4895E-02 | 391.0 | .1897E-01 |
| + | 392.0 | .3059E-01 | 393.0 | .3059E-01 | 394.0 | .1836E-01 | 395.0 | .2448E-02 |
| 122934 | 396.0 | -.6119E-03 | 397.0 | .1224E-02 | 398.0 | .5507E-02 | 399.0 | .7343E-02 |
| + | 400.0 | .9790E-02 | 401.0 | .2386E-01 | 402.0 | .3671E-01 | 403.0 | .3059E-01 |
| + | 404.0 | .1469E-01 | 405.0 | .6119E-03 | 406.0 | .6119E-02 | 407.0 | .3121E-01 |
| 122935 | 408.0 | .3427E-01 | 409.0 | .1774E-01 | 410.0 | .1224E-02 | 411.0 | -.1224E-02 |
| + | 412.0 | .5507E-02 | 413.0 | .1774E-01 | 414.0 | .2080E-01 | 415.0 | .1469E-01 |
| + | 416.0 | .7343E-02 | 417.0 | .1163E-01 | 418.0 | .2753E-01 | 419.0 | .3059E-01 |
| 122936 | 420.0 | .2142E-01 | 421.0 | .3671E-02 | 422.0 | -.3059E-02 | 423.0 | .9790E-02 |
| + | 424.0 | .2142E-01 | 425.0 | .2876E-01 | 426.0 | .2325E-01 | 427.0 | .1469E-01 |
| + | 428.0 | .9178E-02 | 429.0 | -.3059E-02 | 430.0 | .1836E-02 | 431.0 | .1958E-01 |
| 122937 | 432.0 | .4589E-01 | 433.0 | .4406E-01 | 434.0 | .1774E-01 | 435.0 | -.1101E-01 |
| + | 436.0 | -.1897E-01 | 437.0 | -.6119E-03 | 438.0 | .2448E-01 | 439.0 | .3549E-01 |
| + | 440.0 | .3182E-01 | 441.0 | .2030E-01 | 442.0 | .8566E-02 | 443.0 | -.7343E-02 |
| 122938 | 444.0 | -.1101E-01 | 445.0 | .1407E-01 | 446.0 | .3977E-01 | 447.0 | .5813E-01 |
| + | 448.0 | .4895E-01 | 449.0 | .1224E-01 | 450.0 | -.2080E-01 | 451.0 | -.3427E-01 |
| + | 452.0 | -.1346E-01 | 453.0 | .1897E-01 | 454.0 | .4834E-01 | 455.0 | .5017E-01 |
| 122939 | 456.0 | .2570E-01 | 457.0 | .3671E-02 | 458.0 | .3671E-02 | 459.0 | .1285E-01 |
| + | 460.0 | .2019E-01 | 461.0 | .1469E-01 | 462.0 | .6119E-02 | 463.0 | .3671E-02 |
| + | 464.0 | .1530E-01 | 465.0 | .2692E-01 | 466.0 | .2570E-01 | 467.0 | .1469E-01 |
| 122940 | 468.0 | .9790E-02 | 469.0 | .2386E-01 | 470.0 | .3121E-01 | 471.0 | .1958E-01 |
| + | 472.0 | .3059E-02 | 473.0 | -.6119E-02 | 474.0 | -.8566E-02 | 475.0 | .6731E-02 |
| + | 476.0 | .2509E-01 | 477.0 | .3732E-01 | 478.0 | .3488E-01 | 479.0 | .2386E-01 |
| 122941 | 480.0 | .1285E-01 | 481.0 | .8566E-02 | 482.0 | .1407E-01 | 483.0 | .1652E-01 |
| + | 484.0 | .1774E-01 | 485.0 | .8566E-02 | 486.0 | -.6119E-03 | 487.0 | -.7343E-02 |
| + | 488.0 | .1163E-01 | 489.0 | .2876E-01 | 490.0 | .3243E-01 | 491.0 | .2080E-01 |
| 122942 | 492.0 | .1346E-01 | 493.0 | .1163E-01 | 494.0 | .1285E-01 | 495.0 | .1285E-01 |
| + | 496.0 | .1346E-01 | 497.0 | .1713E-01 | 498.0 | .1530E-01 | 499.0 | .1836E-01 |
| + | 500.0 | .1346E-01 | 501.0 | .1591E-01 | 502.0 | .1591E-01 | 503.0 | .1346E-01 |
| 122943 | 504.0 | .1285E-01 | 505.0 | .1530E-01 | 506.0 | .2264E-01 | 507.0 | .1346E-01 |
| + | 508.0 | .3671E-02 | 509.0 | .4283E-02 | 510.0 | .1958E-01 | 511.0 | .3610E-01 |
| + | 512.0 | .2386E-01 | 513.0 | .7343E-02 | 514.0 | -.5507E-02 | 515.0 | -.6119E-03 |
| 122944 | 516.0 | .2264E-01 | 517.0 | .4222E-01 | 518.0 | .3610E-01 | 519.0 | .1163E-01 |
| + | 520.0 | -.1713E-01 | 521.0 | -.2142E-01 | 522.0 | .1101E-01 | 523.0 | .4589E-01 |
| + | 524.0 | .5323E-01 | 525.0 | .3243E-01 | 526.0 | .6119E-03 | 527.0 | -.1040E-01 |
| 122945 | 528.0 | .6731E-02 | 529.0 | .2080E-01 | 530.0 | .2631E-01 | 531.0 | .1958E-01 |
| + | 532.0 | .9790E-02 | 533.0 | -.6119E-03 | 534.0 | .3671E-02 | 535.0 | .1652E-01 |
| + | 536.0 | .2998E-01 | 537.0 | .2631E-01 | 538.0 | .1101E-01 | 539.0 | .9790E-02 |
| 122946 | 540.0 | .2570E-01 | 541.0 | .3671E-01 | 542.0 | .2325E-01 | 543.0 | -.1836E-02 |
| + | 544.0 | -.1713E-01 | 545.0 | -.7343E-02 | 546.0 | .1652E-01 | 547.0 | .3794E-01 |
| + | 548.0 | .4711E-01 | 549.0 | .3671E-01 | 550.0 | .9178E-02 | 551.0 | -.7954E-02 |
| 122947 | 552.0 | -.1101E-01 | 553.0 | .6119E-02 | 554.0 | .2203E-01 | 555.0 | .2692E-01 |
| + | 556.0 | .2448E-01 | 557.0 | .2570E-01 | 558.0 | .2080E-01 | 559.0 | .6119E-02 |
| + | 560.0 | -.2448E-02 | 561.0 | .0000E+00 | 562.0 | .1407E-01 | 563.0 | .3182E-01 |
| 122948 | 564.0 | .3549E-01 | 565.0 | .2815E-01 | 566.0 | .1407E-01 | 567.0 | .6119E-03 |
| + | 568.0 | .7343E-02 | 569.0 | .1469E-01 | 570.0 | .1469E-01 | 571.0 | .6119E-02 |
| + | 572.0 | .1836E-02 | 573.0 | .9178E-02 | 574.0 | .2080E-01 | 575.0 | .2815E-01 |
| 122949 | 576.0 | .2815E-01 | 577.0 | .2815E-01 | 578.0 | .2142E-01 | 579.0 | .1101E-01 |
| + | 580.0 | .7954E-02 | 581.0 | .3059E-02 | 582.0 | .7954E-02 | 583.0 | .1774E-01 |
| + | 584.0 | .2264E-01 | 585.0 | .1346E-01 | 586.0 | .1836E-02 | 587.0 | -.3059E-02 |
| 122950 | 588.0 | .1897E-01 | 589.0 | .3304E-01 | 590.0 | .2753E-01 | 591.0 | .2019E-01 |
| + | 592.0 | .1591E-01 | 593.0 | .1652E-01 | 594.0 | .1224E-01 | 595.0 | .1836E-02 |
| + | 596.0 | .4283E-02 | 597.0 | .1285E-01 | 598.0 | .2386E-01 | 599.0 | .2325E-01 |
| 122951 | 600.0 | .1224E-01 | 601.0 | .9178E-02 | 602.0 | .1652E-01 | 603.0 | .2509E-01 |
| + | 604.0 | .2264E-01 | 605.0 | .1346E-01 | 606.0 | .0000E+00 | 607.0 | .6119E-03 |
| + | 608.0 | .1469E-01 | 609.0 | .2937E-01 | 610.0 | .3365E-01 | 611.0 | .2386E-01 |
| 122952 | 612.0 | .5507E-02 | 613.0 | -.5507E-02 | 614.0 | -.1224E-02 | 615.0 | .1897E-01 |
| + | 616.0 | .3365E-01 | 617.0 | .2998E-01 | 618.0 | -.1163E-01 | 619.0 | -.7343E-02 |
| + | 620.0 | -.2448E-02 | 621.0 | .2142E-01 | 622.0 | .3855E-01 | 623.0 | .3549E-01 |
| 122953 | 624.0 | .1897E-01 | 625.0 | -.4895E-02 | 626.0 | -.1285E-01 | 627.0 | -.3059E-02 |
| + | 628.0 | .2142E-01 | 629.0 | .4344E-01 | 630.0 | .4528E-01 | 631.0 | .2937E-01 |
| + | 632.0 | .1101E-01 | 633.0 | -.7954E-02 | 634.0 | -.1163E-01 | 635.0 | .3059E-02 |
| 122954 | 636.0 | .2509E-01 | 637.0 | .3549E-01 | 638.0 | .2448E-01 | 639.0 | .5507E-02 |
| + | 640.0 | .1224E-02 | 641.0 | .1407E-01 | 642.0 | .2386E-01 | 643.0 | .2142E-01 |

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| | | | | | | | | |
|--------|-------|------------|-------|------------|-------|------------|-------|------------|
| + | 644.0 | .1285E-01 | 645.0 | .9178E-02 | 646.0 | .1346E-01 | 647.0 | .2509E-01 |
| 122955 | 648.0 | .2019E-01 | 649.0 | .1285E-01 | 650.0 | -.6119E-03 | 651.0 | .4283E-02 |
| + | 652.0 | .1652E-01 | 653.0 | .2876E-01 | 654.0 | .3671E-01 | 655.0 | .2815E-01 |
| + | 656.0 | .1652E-01 | 657.0 | -.3059E-02 | 658.0 | -.8566E-02 | 659.0 | -.6119E-03 |
| 122956 | 660.0 | .1469E-01 | 661.0 | .2692E-01 | 662.0 | .2509E-01 | 663.0 | .1897E-01 |
| + | 664.0 | .1285E-01 | 665.0 | .2142E-01 | 666.0 | .2815E-01 | 667.0 | .2753E-01 |
| + | 668.0 | .8566E-02 | 669.0 | -.6119E-03 | 670.0 | .1836E-02 | 671.0 | .1774E-01 |
| 122957 | 672.0 | .2142E-01 | 673.0 | .8566E-02 | 674.0 | -.2448E-02 | 675.0 | .7343E-02 |
| + | 676.0 | .3304E-01 | 677.0 | .4406E-01 | 678.0 | .2570E-01 | 679.0 | .6119E-02 |
| + | 680.0 | .3671E-02 | 681.0 | .1713E-01 | 682.0 | .2509E-01 | 683.0 | .1407E-01 |
| 122958 | 684.0 | -.1224E-02 | 685.0 | .3059E-02 | 686.0 | .1652E-01 | 687.0 | .2753E-01 |
| + | 688.0 | .2386E-01 | 689.0 | .1591E-01 | 690.0 | .9790E-02 | 691.0 | .1040E-01 |
| + | 692.0 | .1530E-01 | 693.0 | .1224E-01 | 694.0 | .1346E-01 | 695.0 | .1774E-01 |
| 122959 | 696.0 | .2080E-01 | 697.0 | .1958E-01 | 698.0 | .1897E-01 | 699.0 | .1163E-01 |
| + | 700.0 | .9178E-02 | 701.0 | .7954E-02 | 702.0 | .1652E-01 | 703.0 | .3243E-01 |
| + | 704.0 | .3365E-01 | 705.0 | .1652E-01 | 706.0 | -.9178E-02 | 707.0 | -.1469E-01 |
| 122960 | 708.0 | -.6119E-03 | 709.0 | .2509E-01 | 710.0 | .3610E-01 | 711.0 | .2692E-01 |
| + | 712.0 | .2019E-01 | 713.0 | .1836E-01 | 714.0 | .2631E-01 | 715.0 | .1774E-01 |
| + | 716.0 | -.1836E-02 | 717.0 | -.6119E-03 | 718.0 | .1346E-01 | 719.0 | .3365E-01 |
| 122961 | 720.0 | .2692E-01 | 721.0 | .4283E-02 | 722.0 | -.4895E-02 | 723.0 | .6119E-03 |
| + | 724.0 | .1774E-01 | 725.0 | .2815E-01 | 726.0 | .2631E-01 | 727.0 | .2325E-01 |
| + | 728.0 | .2815E-01 | 729.0 | .1530E-01 | 730.0 | .6731E-02 | 731.0 | .4283E-02 |
| 122962 | 732.0 | .1163E-01 | 733.0 | .2631E-01 | 734.0 | .2264E-01 | 735.0 | .8566E-02 |
| + | 736.0 | -.9790E-02 | 737.0 | -.5507E-02 | 738.0 | .1774E-01 | 739.0 | .4589E-01 |
| + | 740.0 | .5017E-01 | 741.0 | .2142E-01 | 742.0 | -.3059E-02 | 743.0 | -.1040E-01 |
| 122963 | 744.0 | .8566E-02 | 745.0 | .1958E-01 | 746.0 | .1713E-01 | 747.0 | .1346E-01 |
| + | 748.0 | .1407E-01 | 749.0 | .1774E-01 | 750.0 | .1407E-01 | 751.0 | .1713E-01 |
| + | 752.0 | .2264E-01 | 753.0 | .1897E-01 | 754.0 | .1407E-01 | 755.0 | .1346E-01 |
| 122964 | 756.0 | .1224E-01 | 757.0 | .9178E-02 | 758.0 | .3059E-02 | 759.0 | .3671E-02 |
| + | 760.0 | .8566E-02 | 761.0 | .2019E-01 | 762.0 | .2386E-01 | 763.0 | .2753E-01 |
| + | 764.0 | .3243E-01 | 765.0 | .2753E-01 | 766.0 | .6731E-02 | 767.0 | -.1163E-01 |
| 122965 | 768.0 | -.7343E-02 | 769.0 | .1897E-01 | 770.0 | .4100E-01 | 771.0 | .3977E-01 |
| + | 772.0 | .1530E-01 | 773.0 | -.1224E-01 | 774.0 | -.1958E-01 | 775.0 | .6119E-03 |
| + | 776.0 | .3304E-01 | 777.0 | .5691E-01 | 778.0 | .4711E-01 | 779.0 | .1224E-01 |
| 122966 | 780.0 | -.1836E-01 | | | | | | |

END OF DATA

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| ERRATA |
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JAERI-M 91-226

DEVELOPMENT OF ANALYSIS CODE FOR THERMAL HYDRO-DYNAMICS OF MARINE
REACTOR UNDER MULTI-DIMENSIONAL SHIP MOTIONS, RETRAN-02/GRAV
(IMPROVEMENT OF RETRAN-02 AND EXPERIMENTAL ANALYSES)

Some words are typed in duplicate in sentences of Chapter Two in the
report, JAERI-M 91-226. They should be eliminated as follows:

| <u>(page)</u> | <u>(line)</u> | <u>(to be eliminated:underlined words)</u> |
|---------------|---------------|---|
| 4 | 4 | ... code and <u>by</u> |
| 4 | 9 | ... were listed <u>in</u> |
| 4 | 16 | ... a number of <u>control</u> |
| 4 | 17 | ... equations <u>for</u> |
| 4 | 24 | ... inflow at <u>point</u> |
| 4 | 25 | ... equation <u>of</u> |
| 5 | 15 | ... energy <u>for</u> |
| 5 | 17 | ... is <u>given</u> |
| 6 | 6 | ... momentum <u>flux,</u> |
| 6 | 8 | ... and the <u>eighth</u> |
| 6 | 9 | ... tenth <u>terms</u> |
| 6 | 19 | ... the <u>vertical</u> |
| 6 | 25 | ... as shown <u>in</u> |
| 7 | 6 | ... will <u>have</u> |
| 7 | 7 | ... is <u>inclined</u> |
| 7 | 8 | ... between <u>upper</u> |
| 7 | 9 | ... : The <u>volume</u> |

7 10 ... and to
7 14 ... than the water
7 15 ... is lower
7 16 ... occur that
7 18 ... that an
7 23 ... be modified
7 24 ... center of
8 1 ... height from a
8 4 ... The blank circle
8 5 ... the geometric
8 6 ... junction connected
8 7 ... CMAS is the
8 9 ... from
8 10 We
8 12 ... is given using
8 17 ... the right side
8 18 ... RETRAN code
8 23 ... position goes
8 25 ... bottom of
9 2 ... should be
9 6 ... level is
9 7 Steam
9 9 ... the water
9 18 ... vertical acceleration.
10 8 ... acceleration g(t), we
10 11 ... , we obtain,
11 8 ... by even gravitational
11 12 ... original RETRAN
11 16 ... energy term in

End